

A creative workspace featuring a laptop with a Windows 8 interface, various art supplies like colored pencils and markers, and a notebook with sketches. The scene is set on a white desk with a wire mesh organizer in the background.

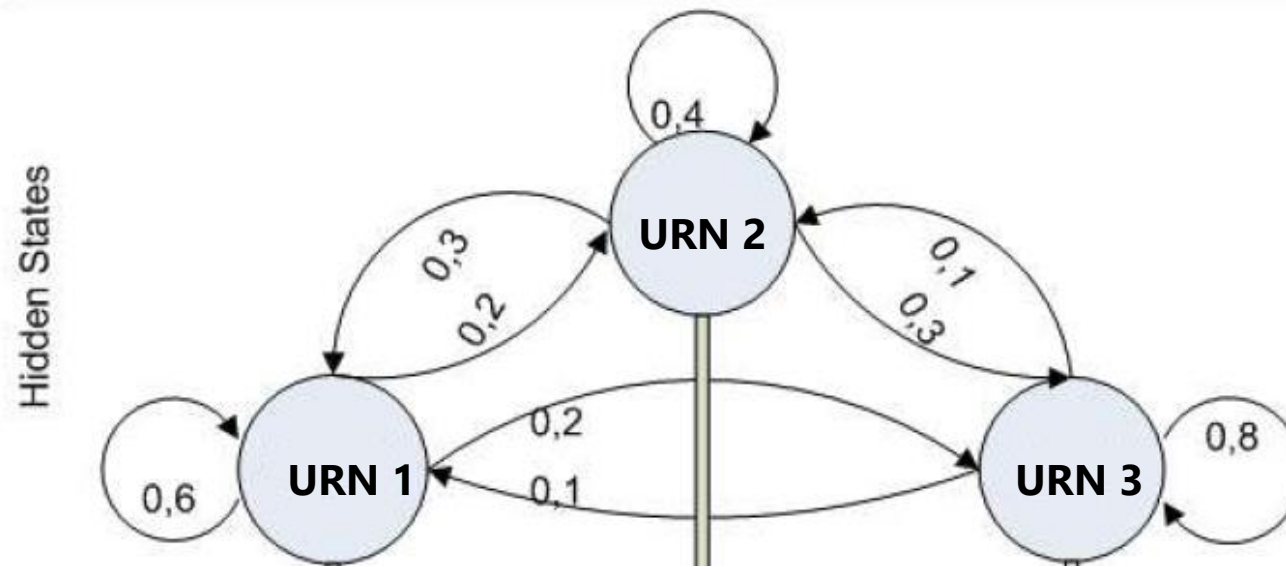
Hidden Markov Model



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HMM

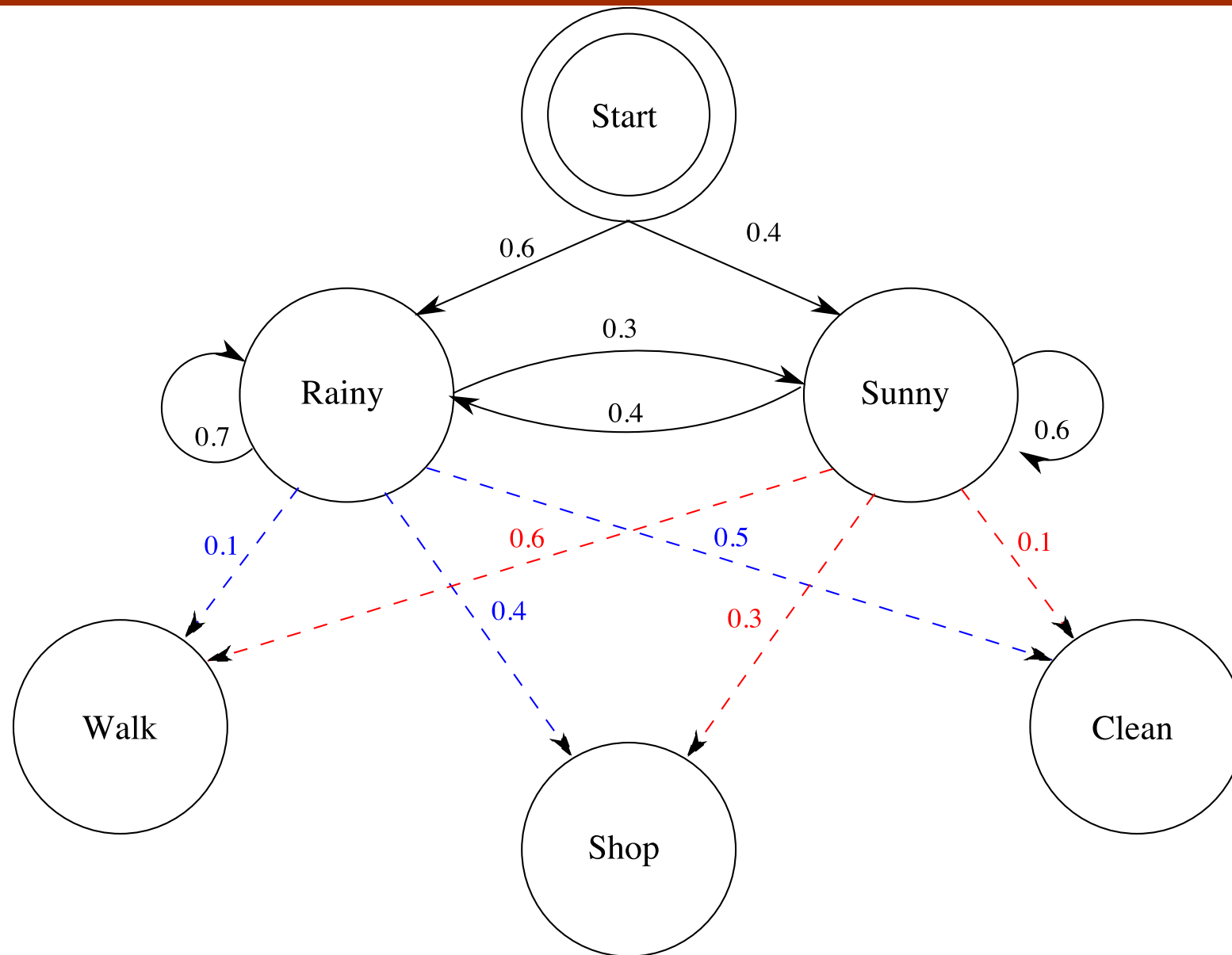


Elements of an HMM

- T = the length of the observation sequence
- N = the number of states in the model
- M = the number of observation symbols
- Q = $\{q_0, q_1, \dots, q_{N-1}\}$ = the states of the Markov process
- V = $\{0, 1, \dots, M - 1\}$ = set of possible observations
- A = the state transition probabilities
- B = the observation probability matrix
- π = the initial state distribution
- \mathcal{O} = $(\mathcal{O}_0, \mathcal{O}_1, \dots, \mathcal{O}_{T-1})$ = observation sequence.

→ HMM completely characterized by: $\lambda = (A, B, \pi)$.

Example



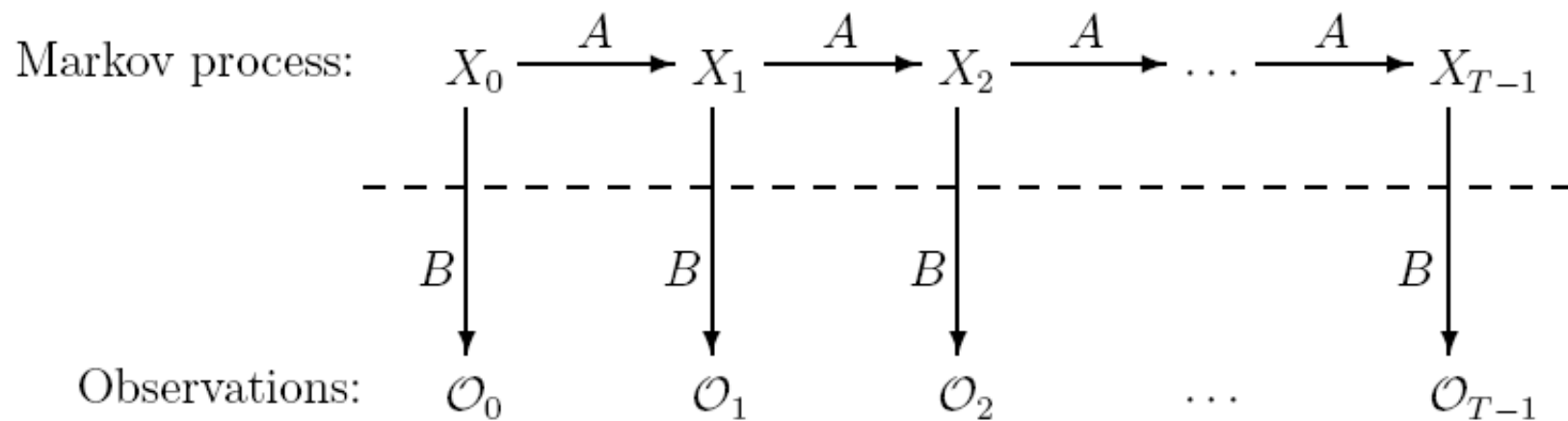
HMM = triple $\lambda = (A, B, \pi)$

The matrix $A = \{a_{ij}\}$ is $N \times N$ with

$$a_{ij} = P(\text{state } q_j \text{ at } t + 1 \mid \text{state } q_i \text{ at } t)$$

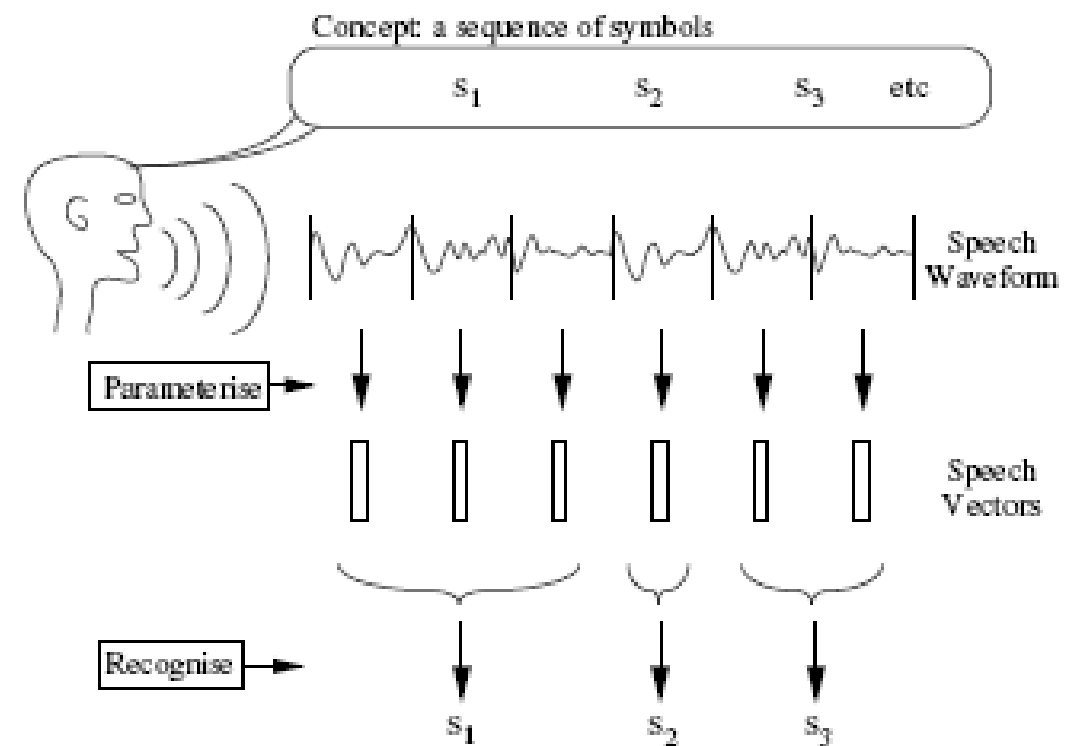
$B = \{b_j(k)\}$ is an $N \times M$ with

$$b_j(k) = P(\text{observation } k \text{ at } t \mid \text{state } q_j \text{ at } t).$$



Why HMM?

- No one-to-one mapping: speech – word symbol
- Different symbols – same sound
- Large variation in speech
 - Speaker variability
 - Mood
 - Environment
- No explicit symbol boundary detection



→ Speech waveform is NOT a concatenation of static patterns

Three classical problems for HMM

Efficient algorithms exist for solving the following three HMM problems.

Problem 1: Given the model $\lambda = (A, B, \pi)$ and a series of observations \mathcal{O} , find $P(\mathcal{O} | \lambda)$, that is, find the probability of the observed sequence given the (putative) model.

Problem 2: Given the model $\lambda = (A, B, \pi)$ and the observations \mathcal{O} , determine the most likely state sequence. In other words, we want to uncover the hidden part of the HMM.

Problem 3: Given the observations \mathcal{O} , “train” the model to best fit the observations. Note that the dimensions of the matrices are fixed, but the elements of A , B and π can vary, subject only to the row stochastic condition.

Three problems (Rabiner, 1989)

Given an observation sequence $\mathbf{O}=(o_0,o_1,\dots,o_{T-1})$, and an HMM $\lambda=(\mathbf{A},\mathbf{B},\pi)$

Problem 1:

How to compute $P(\mathbf{O}/\lambda)$ efficiently ?

⇒ **Evaluation Problem**

Problem 2:

How to choose an optimal state sequence $\mathbf{Q}=(q_1,q_2,\dots,q_T)$ which best explains the observations?

⇒ **Decoding Problem**

$$P(Q^* | O, \lambda) = \max_Q P(Q | O, \lambda)$$

Problem 3:

How to adjust the model parameters $\lambda=(\mathbf{A},\mathbf{B},\pi)$ to maximize $P(\mathbf{O}/\lambda)$?

⇒ **Learning/Training Problem**

PROBLEM 1: Evaluation

- Straightforward calculation is too time consuming: $O(TN^T)$ multiplications and additions

$$\begin{aligned}P(\mathcal{O} | \lambda) &= \sum_X P(\mathcal{O}, X | \lambda) \\&= \sum_X P(\mathcal{O} | X, \lambda) P(X | \lambda) \\&= \sum_X \pi_{x_0} b_{x_0}(\mathcal{O}_0) a_{x_0, x_1} b_{x_1}(\mathcal{O}_1) \cdots a_{x_{T-2}, x_{T-1}} b_{x_{T-1}}(\mathcal{O}_{T-1}).\end{aligned}$$

Alpha-pass

For $i = 0, \dots, T-1$ and $t = 0, \dots, N-1$ we define

$$\alpha_t(i) = P(\mathcal{O}_0, \mathcal{O}_1, \dots, \mathcal{O}_t, x_t = q_i \mid \lambda). \quad (8)$$

ALGORITHM „alpha-pass”: forward method

1. Let $\alpha_0(i) = \pi_i b_i(\mathcal{O}_0)$, for $i = 0, 1, \dots, N - 1$
2. For $t = 1, 2, \dots, T - 1$ and $i = 0, 1, \dots, N - 1$, compute

$$\alpha_t(i) = \left[\sum_{j=0}^{N-1} \alpha_{t-1}(j) a_{ji} \right] b_i(\mathcal{O}_t)$$

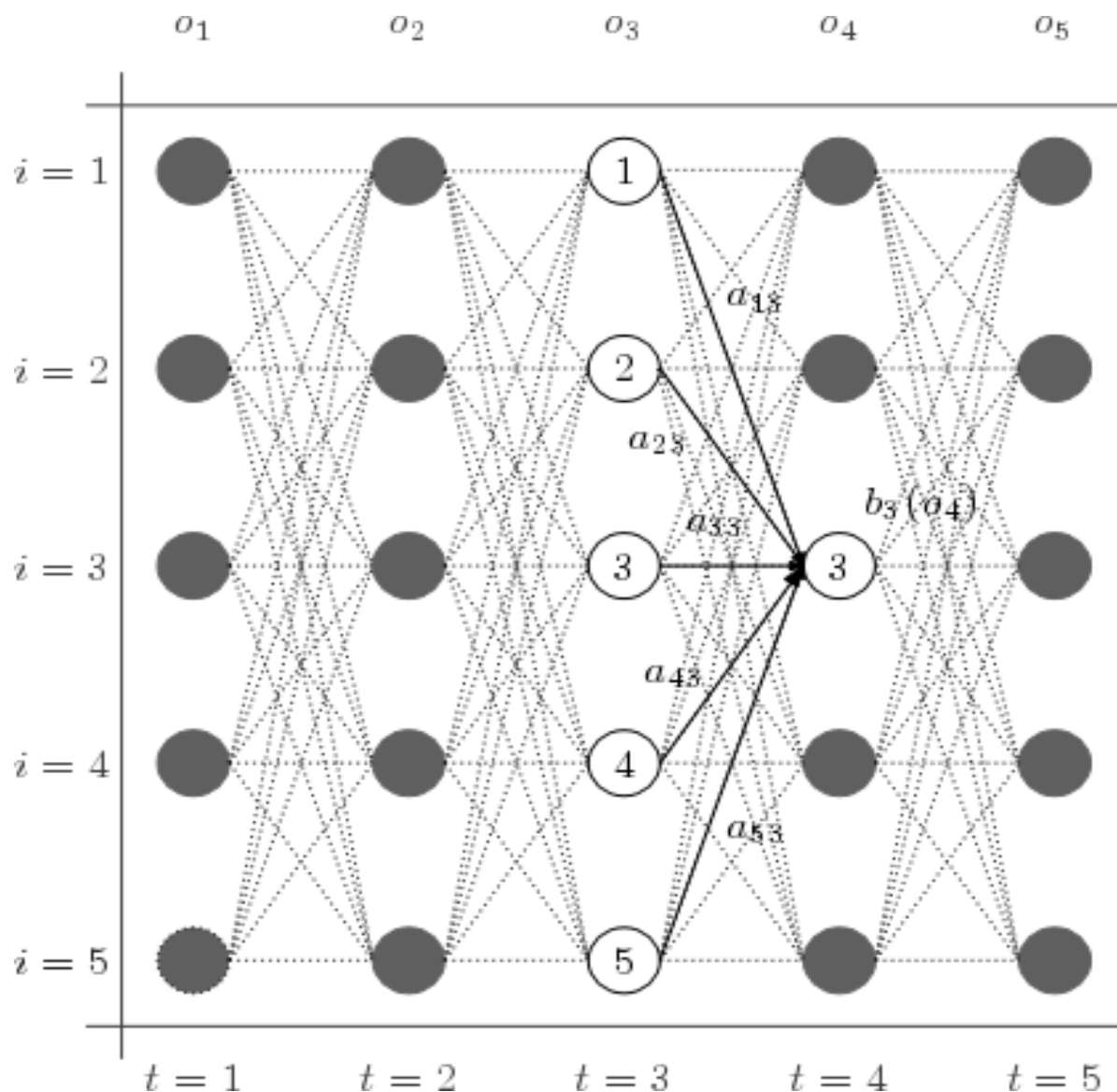
3. Then from (8) it is clear that

$$P(\mathcal{O} \mid \lambda) = \sum_{i=0}^{N-1} \alpha_{T-1}(i).$$

Alpha-pass

$$\alpha_t(i) = P(\mathcal{O}_0, \mathcal{O}_1, \dots, \mathcal{O}_t, x_t = q_i \mid \lambda).$$

$$\alpha_t(i) = \left[\sum_{j=0}^{N-1} \alpha_{t-1}(j) a_{ji} \right] b_i(\mathcal{O}_t)$$



Problem 2: Decoding – „beta-pass”

For $i = 0, \dots, T-1$ and $t = 0, \dots, N-1$ we define

$$\beta_t(i) = P(\mathcal{O}_{t+1}, \mathcal{O}_{t+2}, \dots, \mathcal{O}_{T-1} \mid x_t = q_i, \lambda).$$

ALGORITHM: „beta-pass”: backward calculation

1. Let $\beta_{T-1}(i) = 1$, for $i = 0, 1, \dots, N-1$.
2. For $t = T-2, T-1, \dots, 0$ and $i = 0, 1, \dots, N-1$ compute

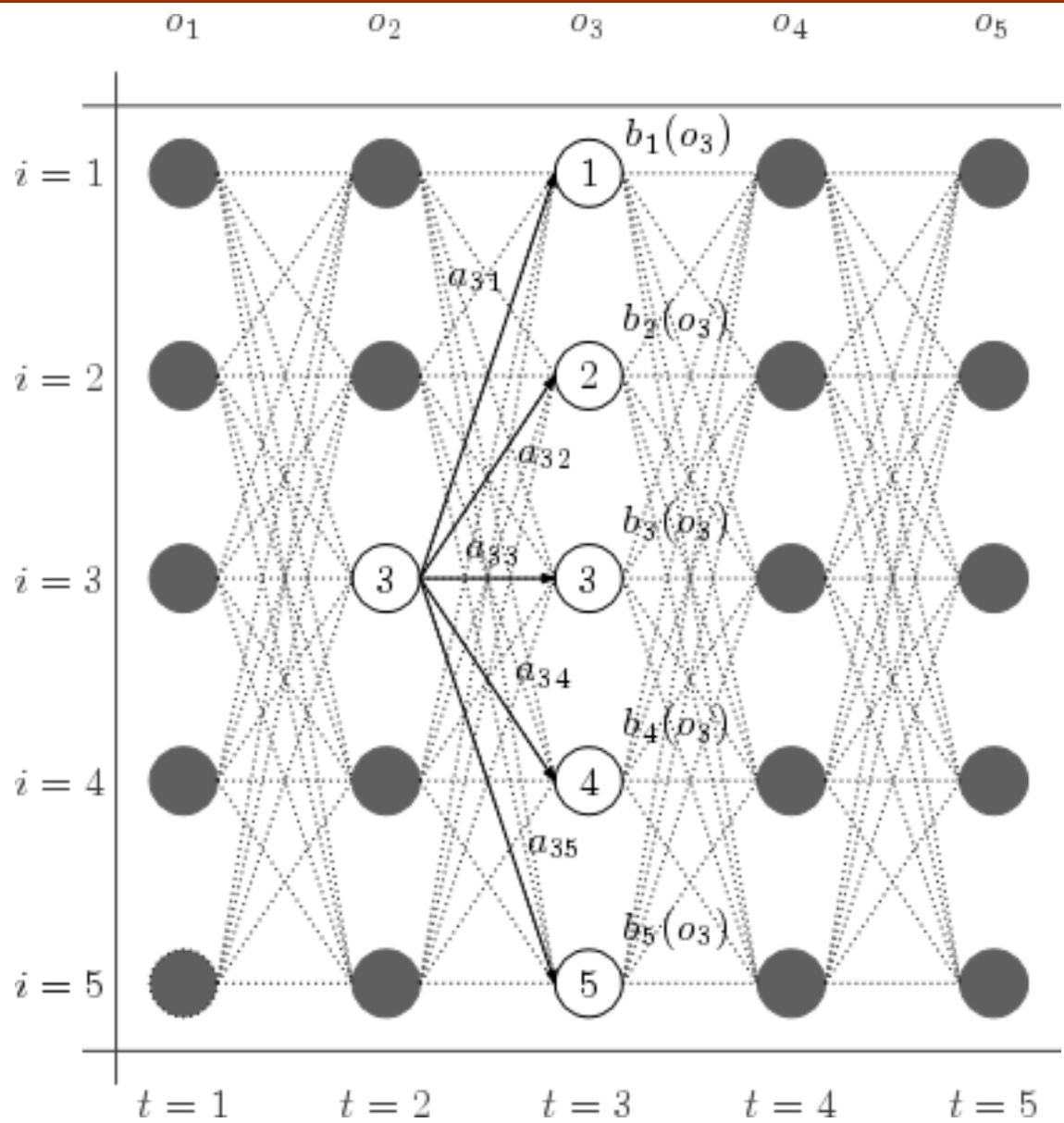
$$\beta_t(i) = \sum_{j=0}^{N-1} a_{ij} b_j(\mathcal{O}_{t+1}) \beta_{t+1}(j).$$

For $t = 0, 1, \dots, T-2$ and $i = 0, 1, \dots, N-1$, define

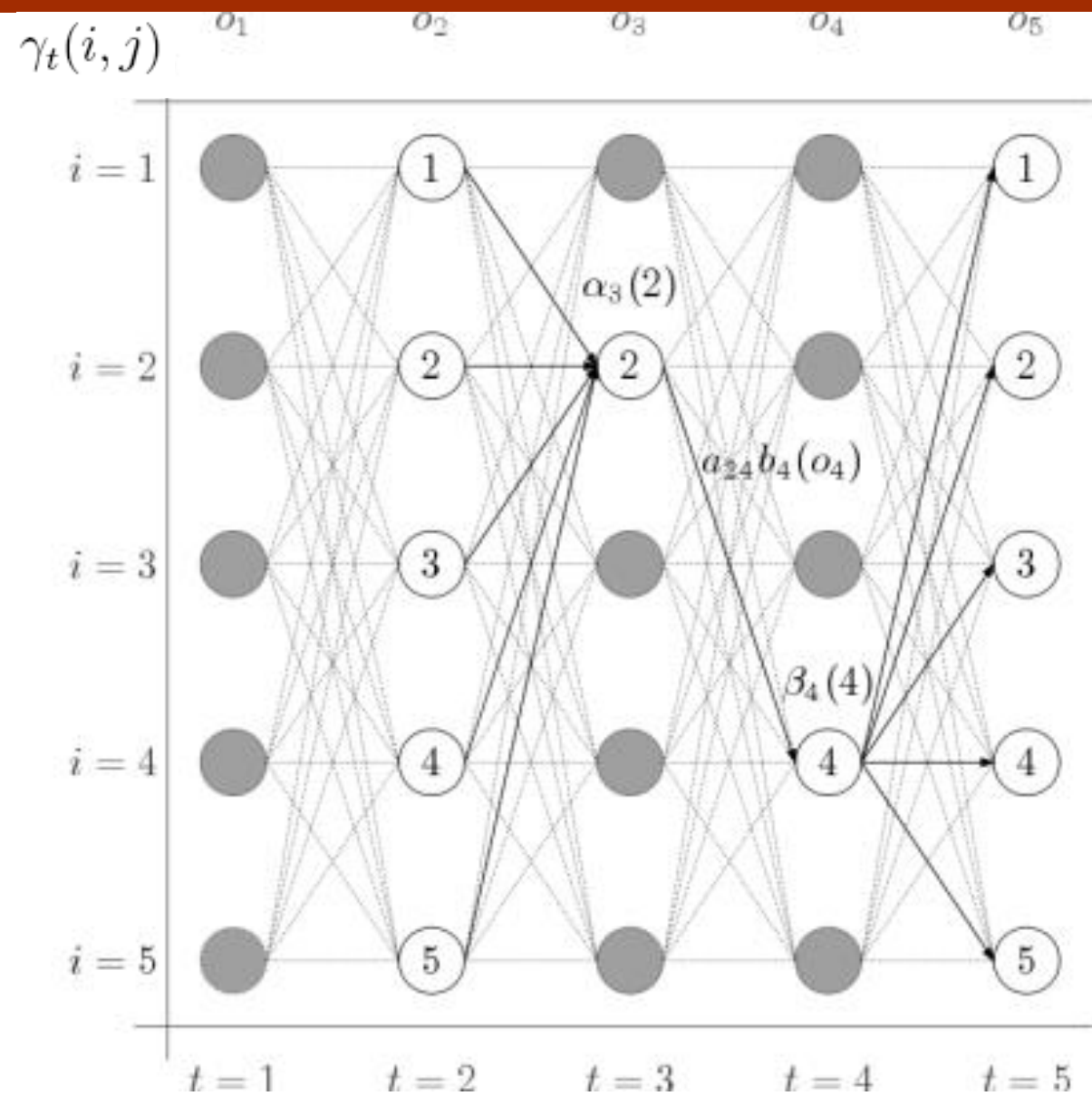
$$\gamma_t(i) = P(x_t = q_i \mid \mathcal{O}, \lambda) = \frac{\alpha_t(i) \beta_t(i)}{P(\mathcal{O} \mid \lambda)}$$

Beta-pass

$$\beta_t(i) = \sum_{j=0}^{N-1} a_{ij} b_j(\mathcal{O}_{t+1}) \beta_{t+1}(j).$$



Gamma



Beta-pass: best state sequence

Q: Is the sequence $Q = (q, \dots)$,
where

$$q_t^* = \arg \max_i \gamma_t(i)$$

the optimal sequence?

Answer: No

Example:

$\gamma_t(i)$	element			
	0	1	2	3
$P(H)$	0.188170	0.519432	0.228878	0.803979
$P(C)$	0.811830	0.480568	0.771122	0.196021

state	probability	normalized probability
<i>HHHH</i>	.000412	.042743
<i>HHHC</i>	.000035	.003664
<i>HHCH</i>	.000706	.073274
<i>HHCC</i>	.000212	.021982
<i>HCHH</i>	.000050	.005234
<i>HCHC</i>	.000004	.000449
<i>HCCH</i>	.000302	.031403
<i>HCCC</i>	.000091	.009421
<i>CHHH</i>	.001098	.113982
<i>CHHC</i>	.000094	.009770
<i>CHCH</i>	.001882	.195398
<i>CHCC</i>	.000564	.058619
<i>CCHH</i>	.000470	.048849
<i>CCHC</i>	.000040	.004187
<i>CCCH</i>	.002822	.293096
<i>CCCC</i>	.000847	.087929

Problem 2 and Viterbi's Algorithm

1. Initialization

$$\begin{aligned}\delta_1(i) &= \pi_i b_{iY_1}, & 1 \leq i \leq N \\ \psi_1(i) &= 0\end{aligned}$$

2. Recursion

$$\begin{aligned}\delta_t(j) &= \max_{1 \leq i \leq N} [\delta_{t-1}(i) a_{ij}] b_{jY_t}, & 2 \leq t \leq T \\ \psi_t(j) &= \arg \max_{1 \leq i \leq N} [\delta_{t-1}(i) a_{ij}], & 2 \leq t \leq T\end{aligned}$$

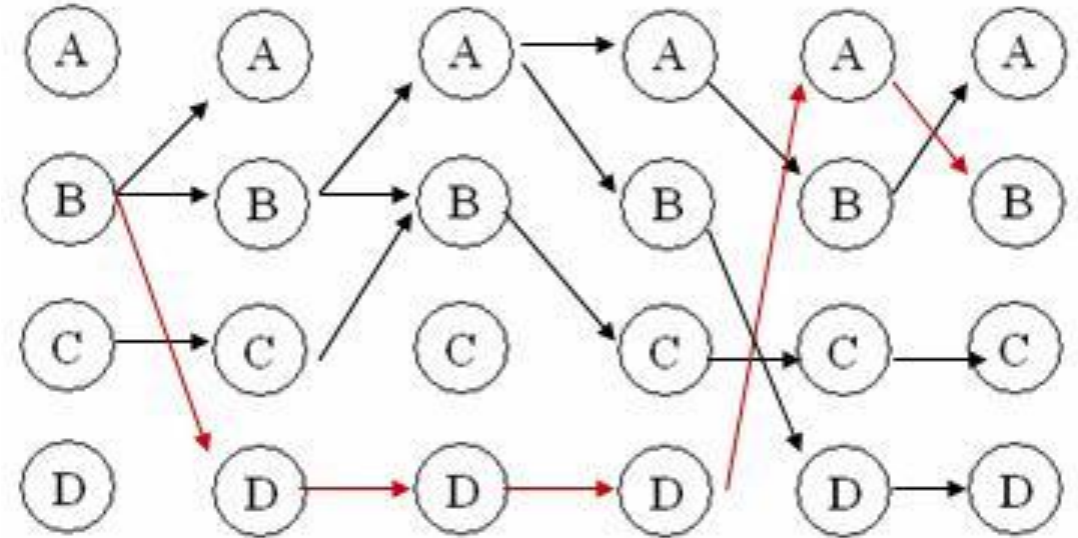
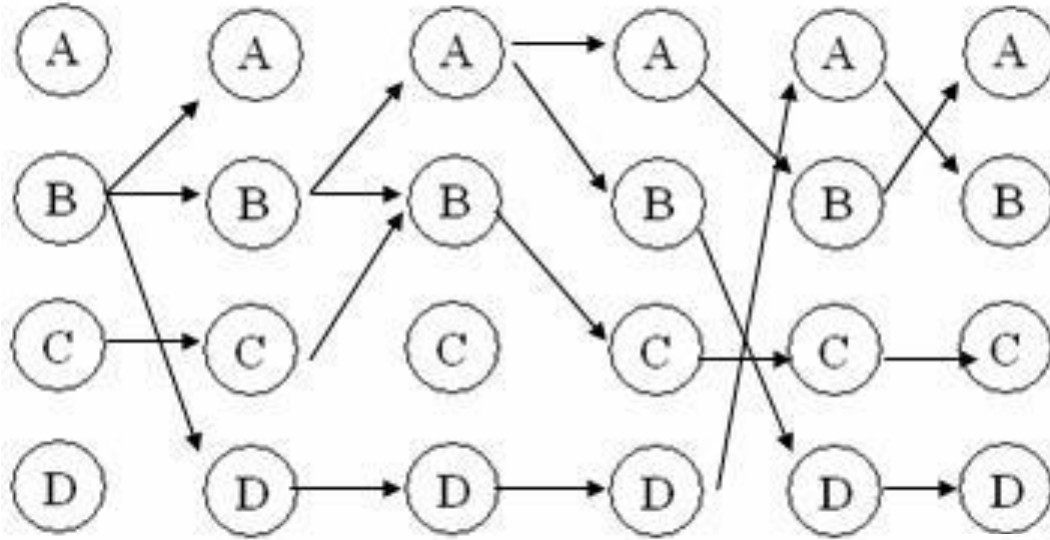
3. Termination

$$\begin{aligned}P^* &= \max_{1 \leq i \leq N} [\delta_T(i)] \\ X_T^* &= \arg \max_{1 \leq i \leq N} [\delta_T(i)]\end{aligned}$$

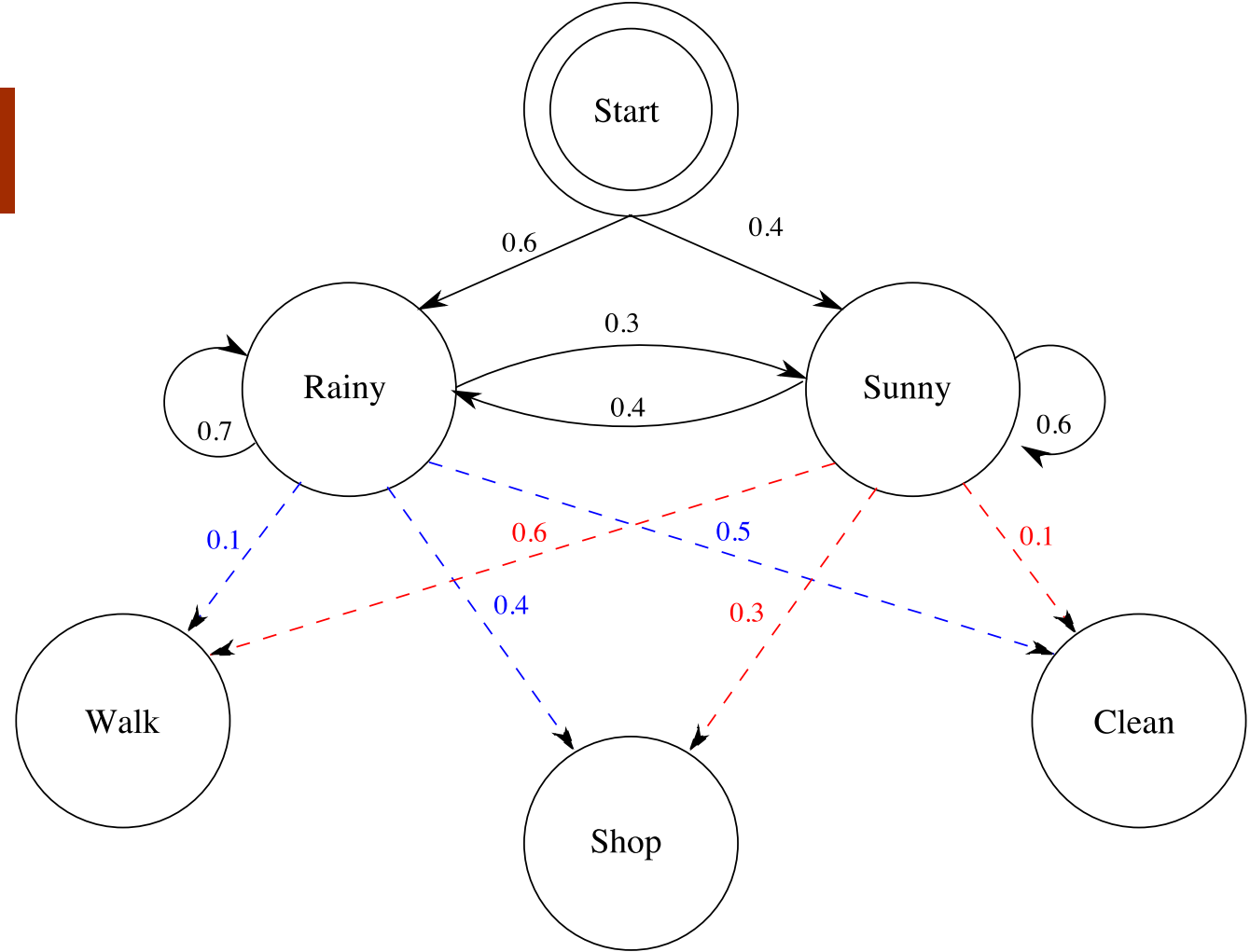
4. Path backtracking

$$X_t^* = \psi_{t+1}(X_{t+1}^*), \quad t = T - 1, T - 2, \dots, 1$$

Viterbi - backtracking



Example



Observation sequence: ['walk', 'shop', 'clean']

Viterbi Solution: ['Sunny', 'Rainy', 'Rainy', 'Rainy']

Problem 3: „learning” and Baum-Welch method

We define

$$\gamma_t(i, j) = \frac{\alpha_t(i) a_{ij} b_j(\mathcal{O}_{t+1}) \beta_{t+1}(j)}{P(\mathcal{O} | \lambda)} \equiv P(q_t = S_i, q_{t+1} = S_j | \mathcal{O}, \lambda)$$

Thus

$$\gamma_t(i) = \sum_{j=0}^{N-1} \gamma_t(i, j).$$

Algorithm EM (Baum-Welch)

1. Initialize, $\lambda = (A, B, \pi)$.
2. Compute $\alpha_t(i)$, $\beta_t(i)$, $\gamma_t(i, j)$ and $\gamma_t(i)$.
3. Re-estimate the model $\lambda = (A, B, \pi)$.
4. If $P(\mathcal{O} | \lambda)$ increases, goto 2.

Algorithm Baum-Welc: reestimation step

For $i = 0, 1, \dots, N - 1$, let

$$\pi_i = \gamma_0(i)$$

For $i = 0, 1, \dots, N - 1$ and $j = 0, 1, \dots, N - 1$, compute

$$a_{ij} = \sum_{t=0}^{T-2} \gamma_t(i, j) \bigg/ \sum_{t=0}^{T-2} \gamma_t(i)$$

For $j = 0, 1, \dots, N - 1$ and $k = 0, 1, \dots, M - 1$, compute

$$b_j(k) = \sum_{\substack{t \in \{0, 1, \dots, T-2\} \\ O_t = k}} \gamma_t(j) \bigg/ \sum_{t=0}^{T-2} \gamma_t(j)$$

Cave and Neuwirth Experiments

- They selected the Brown Corpus as a representative sample of English.
 - This corpus of more than 1,000,000 words was carefully compiled (in the early 1960's) so as to contain a diverse selection of written English.
 - Cave and Neuwirth eliminated all numbers, punctuation and special characters, and converted all letters to lower-case, leaving 27 distinct symbols—the letters plus inter-word space.
- They then assumed that there exists a Markov process with two hidden states, with the observations given by the symbols (i.e., letters) that appear in the Brown Corpus.
- This results in an A matrix that is 2×2 and a B matrix that is 2×27 .
- They then solved HMM Problem 3 for the optimal matrices

Cave - Neuwirth

Results after:

- 10,000 observation and
- about 200 iterations

$$\pi = [0.51316 \quad 0.48684]$$

$$A = \begin{bmatrix} 0.47468 & 0.52532 \\ 0.51656 & 0.48344 \end{bmatrix}$$

$$\pi = [0.00000 \quad 1.00000]$$

$$A = \begin{bmatrix} 0.25596 & 0.74404 \\ 0.71571 & 0.28429 \end{bmatrix}$$

letter	Initial B		Final B	
	state 0	state 1	state 0	state 1
a	0.0372642	0.0366080	0.0044447	0.1306242
b	0.0386792	0.0389249	0.0241154	0.0000000
c	0.0358491	0.0338276	0.0522168	0.0000000
d	0.0353774	0.0370714	0.0714247	0.0003260
e	0.0349057	0.0352178	0.0000000	0.2105809
f	0.0344340	0.0370714	0.0374685	0.0000000
g	0.0400943	0.0370714	0.0296958	0.0000000
h	0.0344340	0.0347544	0.0670510	0.0085455
i	0.0349057	0.0370714	0.0000000	0.1216511
j	0.0391509	0.0366080	0.0065769	0.0000000
k	0.0363208	0.0356812	0.0067762	0.0000000
l	0.0353774	0.0403151	0.0717349	0.0000135
m	0.0344340	0.0366080	0.0382657	0.0000000
n	0.0410377	0.0370714	0.1088182	0.0000000
o	0.0396226	0.0398517	0.0000000	0.1282757
p	0.0377358	0.0338276	0.0388589	0.0000047
q	0.0377358	0.0398517	0.0011958	0.0000000
r	0.0344340	0.0403151	0.1084196	0.0000000
s	0.0358491	0.0366080	0.1034371	0.0000000
t	0.0377358	0.0352178	0.1492508	0.0134756
u	0.0349057	0.0361446	0.0000000	0.0489816
v	0.0405660	0.0370714	0.0169406	0.0000000
w	0.0377358	0.0384615	0.0286993	0.0000000
x	0.0382075	0.0370714	0.0035874	0.0000000
y	0.0382075	0.0389249	0.0269053	0.0000003
z	0.0382075	0.0338276	0.0005979	0.0000000
space	0.0367925	0.0389249	0.0035184	0.3375209



Letter classification

<i>V</i>	Vowel
<i>SP</i>	Space
<i>C</i>	Consonant
<i>FL</i>	First Letter
<i>LL</i>	Last Letter
<i>VF</i>	Vowel Follower
<i>VP</i>	Vowel Proceeder
<i>CP</i>	Consonant Follower.

Cave Neuwirth experiment with 12 states

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X	Y	Z	SP
V	*				*				*						*						*						
SP																											*
C						*	*			*	*																
LL											*													*			
FL	*									*					*		*										
VF																											
VP									*								*										
CF																								*			
1				*				*					*	*				*	*						*		
2					*				*						*						*						
3		*	*	*					*			*		*		*		*	*	*						*	
4								*				*			*			*		*	*						
5	*				*				*						*						*						
6		*	*	*		*	*	*		*		*	*	*		*	*	*	*	*		*	*		*	*	
7			*	*			*				*	*	*	*		*		*	*	*		*			*		
8					*							*								*							
9						*					*	*	*	*		*		*	*		*		*	*			
10	*				*				*						*												
11																											*
12			*			*	*									*			*				*				

Table 2: Cave and Neuwirth's 12 states result interpretation