

Linear Potentials in Nonlinear Potential Theory

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Abstract

Pointwise gradient bounds via Riesz potentials, such as those available for the linear Poisson equation, actually hold for general quasilinear degenerate equations of p -Laplacian type. The regularity theory of such equations completely reduces to that of the classical Poisson equation up to the C^1 -level.

1. Results

In this paper we prove the following:

Theorem 1.1. *Let $u \in C^1(\Omega)$ be a weak solution to the equation*

$$-\operatorname{div}(|Du|^{p-2}Du) = \mu, \quad (1.1)$$

where μ is a Borel measure with finite mass, $p \geq 2$, and $\Omega \subset \mathbb{R}^n$ is an open set with $n \geq 2$. Then there exists a constant c , depending only on n and p , such that the pointwise Riesz potential estimate

$$|Du(x)|^{p-1} \leq c\mathbf{I}_1^{|\mu|}(x, R) + c \left(\int_{B(x, R)} |Du| \, dy \right)^{p-1} \quad (1.2)$$

holds whenever $B(x, R) \subseteq \Omega$ is a ball centered at x and with radius R .

In (1.2), \mathbf{I}_1 denotes the classical, linear (truncated) Riesz potential of $|\mu|$, which is suited to problems defined in bounded domains, and which is defined by

$$\mathbf{I}_1^{|\mu|}(x, R) := \int_0^R \frac{|\mu|(B(x, \varrho))}{\varrho^{n-1}} \frac{d\varrho}{\varrho}.$$

We refer the reader to Section 2 below for further notation. Theorem 1.1, proposed above in the form of an a priori estimate valid for energy solutions, actually extends

to the case in which u is, rather, a so-called very weak solution not necessarily belonging to $W^{1,p}(\Omega)$. This type of low integrability is typical when dealing with measure data problems [1, 2, 7, 15, 24]. The extension goes via a standard approximation argument briefly recalled in Section 5 below.

The surprising character of Theorem 1.1 lies mainly in the fact that, although it is concerned with degenerate quasilinear equations, the gradient can be pointwise estimated via Riesz potentials exactly as it would be for solutions to the hyper-classical Poisson equation

$$-\Delta u = \mu, \tag{1.3}$$

for which estimate (1.2) is an immediate consequence of the classical representation formula via Green’s functions. Indeed, we have

Corollary 1.2. *Let $u \in W^{1,p}(\mathbb{R}^n)$ be a local weak solution to the equation (1.1) with $p \geq 2$ and μ being a Borel measure with locally finite mass. Then there exists a constant c , depending only on n, p , such that the following estimate holds for every Lebesgue point $x \in \mathbb{R}^n$ of Du :*

$$|Du(x)|^{p-1} \leq c \int_{\mathbb{R}^n} \frac{d|\mu|(y)}{|x - y|^{n-1}}.$$

The other thing that makes Theorem 1.1 somehow unexpected is that, starting from the seminal papers of KILPELÄINEN and MALÝ [18, 19], with different approaches offered by TRUDINGER and WANG [38, 39] (that also worked in the subelliptic setting, starting from the ideas in [37, 36]) and KORTE and KUUSI [20] and DUZAAR and MINGIONE [9], it is a standard fact that solutions to non-homogeneous Laplacean equations with measure data as (1.1) can be pointwise estimated in a natural way by means of classical nonlinear Wolff potentials [14], that is,

$$\mathbf{W}_{\beta,p}^\mu(x, R) := \int_0^R \left(\frac{|\mu|(B(x, \varrho))}{\varrho^{n-\beta p}} \right)^{1/(p-1)} \frac{d\varrho}{\varrho} \quad \beta \in (0, n/p).$$

In particular, the main result of [18, 19] (see also [9, 20, 38] different approaches) claims that the following pointwise estimate holds:

$$|u(x)|^{p-1} \leq c \left[\mathbf{W}_{1,p}^\mu(x, R) \right]^{p-1} + c \left(\int_{B(x,R)} |u| dy \right)^{p-1}. \tag{1.4}$$

The previous inequality is *sharp*, in the sense that $\mathbf{W}_{1,p}^\mu$ cannot be replaced by any other weaker potential. It plays a crucial role in the theory of quasilinear elliptic equations, as shown, for instance, in the work of PHUC and VERBITSKY [34, 35] and, more recently, in the one of JAYE and VERBITSKY [17]. Estimate (1.4) was eventually upgraded to the gradient level in [9, 32], where a gradient estimate has been provided, again using Wolff potentials:

$$|Du(x)|^{p-1} \leq c \left[\mathbf{W}_{1/p,p}^\mu(x, R) \right]^{p-1} + c \left(\int_{B(x,R)} |Du| dy \right)^{p-1}. \tag{1.5}$$

Finally, a unifying approach allowing one to view both estimate (1.4) and estimate (1.5) as particular cases of a general family of “universal potential estimates” was finally given by the authors in [21]. Estimate (1.2) obviously improves the one in (1.5) as, by using elementary manipulations together with the fact that $p \geq 2$, we have

$$\begin{aligned}
 \mathbf{I}_1^{|\mu|}(x, R) &= \int_0^R \frac{|\mu|(B(x_0, \varrho))}{\varrho^{n-1}} \frac{d\varrho}{\varrho} \\
 &\lesssim \sum_{k=0}^{\infty} \frac{|\mu|(B(x, R/2^k))}{(R/2^k)^{n-1}} \\
 &\lesssim \left[\sum_{k=0}^{\infty} \left(\frac{|\mu|(B(x, R/2^k))}{(R/2^k)^{n-1}} \right)^{1/(p-1)} \right]^{p-1} \\
 &\lesssim \left[\int_0^{2R} \left(\frac{|\mu|(B(x_0, \varrho))}{\varrho^{n-1}} \right)^{1/(p-1)} \frac{d\varrho}{\varrho} \right]^{p-1} \\
 &= \left[\mathbf{W}_{1/p,p}^\mu(x, 2R) \right]^{p-1}. \tag{1.6}
 \end{aligned}$$

The main novelty of this paper is actually the fact that, when switching to the gradient regularity theory, Wolff potentials are no longer necessary and *the whole theory “linearizes” as in the case of the standard Poisson equation $-\Delta u = \mu$* . As a matter of fact—taking into account Theorem 1.5 below—this paper shows the surprising fact that, when considered up to the C^1 -level, *there is no difference between the regularity theory of general quasilinear degenerate equations and that of the classical Poisson equation*. We interpret this fact by observing that, while an equation as (1.1) looks genuinely nonlinear in terms of the solution u , it looks *linear* when considering the “stress tensor” $|Du|^{p-2}Du$; see Section 1.2 below and, in particular, system (1.11).

We conjecture that estimate (1.2) is sharp in the sense that it cannot be improved by using different types of nonlinear potentials. We also observe that the case $p < 2$ of estimate (1.2) has been proved in [10], but in this case it does not improve (1.5) in that (1.6) is, in general, false for $p < 2$. The real problematic issue is in passing from nonlinear potentials to linear ones when the latter provide better bounds and Wolff potentials must be bypassed.

From the viewpoint of standard regularity theory, the ultimate effect of the validity of estimate (1.2), as already mentioned above, is that *the integrability theory of solutions to p -Laplacean type equations is now completely reduced to the linear case*, that is, there is basically no difference between degenerate quasilinear equations such as (1.1) and the classical, linear Poisson equation. As explained, for instance, in [31] (where the case $p = 2$ is considered for general quasilinear equations), estimate (1.9) allows one to recover, in a sharp way, all the gradient integrability results available for Du obtainable in terms of the measure μ and additional borderline cases. For instance, when the model equation (1.1) is considered, the results in [1, 2, 6, 9, 16, 31] can then be recovered. For an overview of the relevant *Nonlinear Calderón–Zygmund theory* we refer the reader to [33].

We also note that a connection between Riesz potentials and the p -Laplacean operator has been found by LINDQVIST and MANFREDI [26], where it is proved that certain Riesz potentials are p -superharmonic functions.

Theorem 1.1 is a particular case of a result valid for more general equations, and in turn opens the way to providing a new, sharp continuity criterium for the gradient; see Theorems 1.3 and 1.5 below. We also observe that the results of this paper provide an alternative viewpoint to those in [21].

1.1. General Elliptic Equations

We describe the general context to which our results apply. In the rest of the paper, Ω denotes a bounded and open domain of \mathbb{R}^n , with $n \geq 2$, while $p \geq 2$. We shall consider general nonlinear, possibly degenerate elliptic equations with p -growth of the type

$$-\operatorname{div} a(Du) = \mu \quad \text{in } \Omega, \tag{1.7}$$

whenever μ is a Borel measure with finite mass. The vector field $a: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is assumed to be C^1 -regular and to satisfy the following *growth and ellipticity assumptions*:

$$\begin{cases} |a(z)| + |a_z(z)|(|z|^2 + s^2)^{1/2} \leq L(|z|^2 + s^2)^{(p-1)/2} \\ \nu(|z|^2 + s^2)^{(p-2)/2} |\xi|^2 \leq \langle a_z(z)\xi, \xi \rangle \end{cases} \tag{1.8}$$

whenever $z, \xi \in \mathbb{R}^n$, where $0 < \nu \leq L$ and $s \geq 0$ are fixed parameters. A model case for the previous situation is clearly given by considering the p -Laplacean equation in (1.1) or its nondegenerate version (when $s > 0$)

$$-\operatorname{div} [(|Du|^2 + s^2)^{(p-2)/2} Du] = \mu.$$

The result is now

Theorem 1.3. *Let $u \in W^{1,p}(\Omega)$ be a weak solution to the equation (1.7) under the assumptions of (1.8) with $p \geq 2$, where μ is a Borel measure with finite total mass defined on Ω . Then there exists a constant c , depending only on n, p, ν, L , such that the pointwise estimate*

$$|Du(x)|^{p-1} \leq c \mathbf{I}_1^{|\mu|}(x, R) + c \left(\int_{B(x, R)} (|Du| + s) \, dy \right)^{p-1} \tag{1.9}$$

holds whenever $B(x, R) \subseteq \Omega$ and $x \in \Omega$ is a Lebesgue point of Du .

More general cases when $u \notin W^{1,p}(\Omega)$ also follow via approximation; see Section 5 below. Theorem 1.3 yields, in turn, the following, immediate

Corollary 1.4. *Let $u \in W^{1,p}(\Omega)$ be as in Theorem 1.3. Then*

$$\mathbf{I}_1^{|\mu|}(\cdot, R) \in L^\infty_{\text{loc}}(\Omega) \text{ for some } R > 0 \implies Du \in L^\infty_{\text{loc}}(\Omega, \mathbb{R}^n).$$

In particular, there exists a constant c , depending only on n, p, v, L , such that the following estimate holds whenever $B_R \subseteq \Omega$:

$$\|Du\|_{L^\infty(B_{R/2})} \leq c \left\| \mathbf{I}_1^{|\mu|}(\cdot, R) \right\|_{L^\infty(B_R)}^{1/(p-1)} + c \int_{B_R} (|Du| + s) \, dy.$$

The above result is striking as it states that the classical, sharp Riesz potential criterion implying the Lipschitz continuity of solutions to the Poisson equations remains valid when considering the p -Laplacean operator. More analogies actually emerge. Indeed, the techniques used for Theorem 1.1 also yield gradient continuity criteria for solutions to nonlinear equations, and we have

Theorem 1.5. *Let $u \in W^{1,p}(\Omega)$ be as in Theorem 1.3. If*

$$\lim_{R \rightarrow 0} \mathbf{I}_1^{|\mu|}(x, R) = 0 \quad \text{locally uniformly in } \Omega \text{ w.r.t. } x, \tag{1.10}$$

then Du is continuous in Ω .

An intermediate VMO-regularity result for Du is also given in Theorem 4.3 below. Theorem 1.5 admits the following relevant corollary, providing gradient continuity when μ is a function belonging to a borderline Lorentz space:

Corollary 1.6. *Let $u \in W^{1,p}(\Omega)$ be as in Theorem 1.3. If $\mu \in L(n, 1)$ locally holds in Ω , that is, if*

$$\int_0^\infty |\{x \in \Omega' : |\mu(x)| > t\}|^{1/n} \, dt < \infty \quad \text{for every open subset } \Omega' \Subset \Omega,$$

then Du is continuous in Ω .

We recall that Lorentz spaces interpolate Lebesgue spaces in the sense that $L^\gamma \subset L(n, 1) \subset L^n$ holds for every $\gamma > n$, all the inclusions being strict. Corollary 1.6 strikingly extends the known results available in the literature where the condition $\mu \in L(n, 1)$ is found to be a sufficient one for gradient boundedness of solutions [4, 12]. This condition is already sharp in the case of the Poisson equation [3] and we remark that the two-dimensional case $n = 2$ oddly remained an open problem in [4, 12], essentially for technical reasons; this gap is settled here. Moreover, in these papers the gradient boundedness was proved, while here we prove the continuity. The results extend also to fully nonlinear elliptic equations as $F(D^2u) = 0$, as eventually shown in [8], and upgrade to the optimal level a previous continuity criterion obtained in [11], claiming the continuity of the gradient in the case $\mu \in L(n, 1/(p - 1))$. Indeed, $L(n, 1) \subset L(n, 1/(p - 1))$, this inclusion being strict for $p > 2$. For more on Lorentz spaces we refer the reader, for instance, to [13].

Finally, another immediate corollary of Theorem 1.5 is concerned with those measures satisfying special density properties.

Corollary 1.7. *Let $u \in W^{1,p}(\Omega)$ be as in Theorem 1.3. Assume that the measure μ satisfies the density condition*

$$|\mu|(B_R) \leq cR^{n-1}h(R) \quad \text{with} \quad \int_0^R h(\varrho) \frac{d\varrho}{\varrho} < \infty$$

for every ball $B_R \subset \mathbb{R}^n$, where $c \geq 0$. Then Du is continuous in Ω .

The previous results upgrade, in an optimal fashion and to the gradient level, analogous criteria for the continuity of u obtained by LIEBERMAN [23].

1.2. Techniques

The techniques introduced in this paper depart considerably from those used in the literature to obtain nonlinear potential estimates in that here, in order to obtain linear type estimates for solutions to a non-linear equation, *we introduce a local linearization technique* that incorporates, in a pointwise fashion and perhaps in a way that may not be obvious, several ingredients from several different theories. In particular, since estimate (1.2) provides integrability estimates for the gradient, then exit time arguments of the type used in the classical linear Calderón–Zygmund theory are used here. On the other hand, since in the best possible cases the arguments provide $C^{0,1} - C^1$ -regularity results (as in Theorem 1.5), basic elements of the classical De Giorgi-Nash-Moser theory must be used in the proof. Finally, since the a priori estimates found cover the case when μ is assumed to be a Borel measure, then the technology for measure data problems must be employed, as well [1,2,7]. Combining all these different ingredients in a single proof is very delicate, and the final result is a proof that probably would be best approached via a preliminary road-map.

Let us disclose the heuristic strategy for the model case (1.1). The idea is to conceive equation (1.1) as a decoupled system

$$-\operatorname{div} v = \mu \quad \text{and} \quad v := |Du|^{p-2} Du, \tag{1.11}$$

and therefore to proceed to a linear estimate for v via a Riesz potential. This brave argument immediately finds an obstruction in the fact that the first equation in (1.11) does not necessarily yield a solution of the type $v := |Du|^{p-2} Du$. To bypass it we introduce a delicate linearization argument allowing, in a sense, to treat $|Du|^{p-2}$ as a Muckenhoupt weight, thanks to the fact that, in a certain sense, we can reduce to the case that u is “almost” a solution to the p -harmonic equation

$$\operatorname{div} (|Du|^{p-2} Du) = 0. \tag{1.12}$$

First of all, since the function $\tilde{u} := \varepsilon u$ solves

$$-\operatorname{div} (|D\tilde{u}|^{p-2} D\tilde{u}) = \varepsilon^{p-1} \mu,$$

we can always assume that the total variation of μ is very small by taking ε small. This is actually a version of the good- λ inequality principle, which allows us to consider, via a delicate comparison argument, that u is almost a solution to (1.12) (see Lemmas 2.4 and 3.1 below), in the sense that its distance to a real p -harmonic function is quantitatively small. At this stage we make crucial use of the methods and the regularity results from the theory of measure data equations [1,2], which we have to exploit carefully here. Using this information we can then start the linearization method via an exit time argument. More precisely, let us set

$$\lambda^{p-1} \approx \mathbf{I}_1^{|\mu|}(x, R) + \left(\int_{B(x,R)} |Du| \, dy \right)^{p-1}, \tag{1.13}$$

and let us consider a sequence of shrinking balls $B_i(x) \equiv B(x, \delta^i R)$, where $\delta \equiv \delta(n, p)$ is a suitably small, yet universal, parameter. There are now two possibilities. The first is when the gradient averages are dominated by λ , that is,

$$|(Du)_{B_i}| \leq \lambda$$

happens for infinitely many indexes i , and, at this stage, (1.2) follows at any Lebesgue point of the gradient. The other case, on which we obviously concentrate, is that there exists an “exit time index” $i_e \in \mathbb{N}$ such that

$$|(Du)_{B_i}| > \lambda \tag{1.14}$$

whenever $i > i_e$. Now, since Du is almost harmonic in B_i , we can commute the information in average in (1.14) in an everywhere information

$$|Du(x)| \geq \lambda/M \tag{1.15}$$

for another universal, possibly large, constant $M \geq 1$. In other words, we see that the equation becomes non-degenerate. We now look at the equation (1.1) and use the information in (1.15) to get, formally

$$-\Delta v = -\lambda^{p-2} \Delta u \text{ “} \lesssim \text{” } \operatorname{div}(|Du|^{p-2} Du) = \mu, \tag{1.16}$$

where $v := \lambda^{p-2}u$, and therefore the standard linear Riesz representation formula for solutions to the Poisson equation—this time applied to v —states that

$$\lambda^{p-2}|Du(x)| \lesssim \mathbf{I}_1^{|\mu|}(x, R) + \lambda^{p-2} \int_{B(x,R)} |Du| \, dy, \tag{1.17}$$

from which estimate (1.2) follows by the definition of λ . Notice that, while the scheme of our proof of Theorem 1.1 follows the heuristic outlined above until (1.16), we cannot, of course, use the representation formula as in (1.17) since (1.16) holds only *formally*. At this stage the final linear type representation formula will be obtained in the course of the proof by a careful induction argument. Needless to say, the whole heuristic argument outlined above must be made rigorous through an extremely careful control of all the constants involved.

The proof of Theorem 1.5 relies, instead, on a more sophisticated argument, and on the analysis of a potentially countable number of exit time moments. This marks a considerable difference between the case of potential estimates for u and those for Du . In fact, in the case of potential bounds for u , this can be obtained for lower semicontinuous and positive solutions by using the KILPELÄINEN and MALÝ [19] Wolff potential bound (1.4), the fact that the equation is invariant under translation (subtracting a constant from the solution still yields a solution) and the fact that positive solutions satisfy the weak Harnack inequality. None of these ingredients is available for Du , therefore a different path must be taken.

The results in this paper have been announced in the CRAS note [22].

2. Preliminary Results and Notations

In the following we denote

$$B(x, R) := \{y \in \mathbb{R}^n : |x - y| < R\}.$$

When the center is not relevant we shall simply denote $B_R \equiv B(x, R)$; moreover, we shall also denote by σB the ball, concentric to B , whose radius equals that of B multiplied by $\sigma > 0$. A similar meaning is adopted when considering B/σ . We shall denote by c, δ, ε , etc., general positive constants; relevant functional dependence on the parameters will be emphasized by displaying them in parentheses. For example, to indicate a dependence of c on the real parameters n, p, ν, L we shall write $c \equiv c(n, p, \nu, L)$. Special constants will be denoted as c_0, c_h , etc. *All such constants, that is, those beginning with c , are assumed to be greater than or equal to one.*

In the following, given a set $A \subset \mathbb{R}^n$ with positive measure and a map $g \in L^1(A, \mathbb{R}^n)$, we shall denote by

$$(g)_A := \int_A g(y) \, dy$$

its integral average over the set A . Finally, we recall that, under the assumptions of Theorems 1.1–1.3, a weak solution $u \in W^{1,p}(\Omega)$ to (1.7) is a function such that

$$\int_{\Omega} \langle a(Du), D\varphi \rangle \, dy = \int_{\Omega} \varphi \, d\mu$$

holds whenever $\varphi \in W_0^{1,p}(\Omega) \cap L^\infty(\Omega)$.

With $s \geq 0$ introduced in (1.8), we define

$$V(z) \equiv V_s(z) := (s^2 + |z|^2)^{(p-2)/4} z, \quad z \in \mathbb{R}^n, \tag{2.1}$$

which is easily seen to be a locally bi-Lipschitz bijection of \mathbb{R}^n . A basic property of the map $V(\cdot)$ is the following: For any $z_1, z_2 \in \mathbb{R}^n$, and any $s \geq 0$, the inequalities

$$\begin{aligned} c^{-1} \left(s^2 + |z_1|^2 + |z_2|^2 \right)^{(p-2)/2} &\leq \frac{|V(z_2) - V(z_1)|^2}{|z_2 - z_1|^2} \\ &\leq c \left(s^2 + |z_1|^2 + |z_2|^2 \right)^{(p-2)/2} \end{aligned} \tag{2.2}$$

hold for a constant $c \equiv c(n, p)$. We refer the reader, for instance, to [30] for the last inequality and more properties of the map $V(\cdot)$. The strict monotonicity properties of the vector field $a(\cdot)$ implied by the left-hand side in (1.8)₂ can be recast using the map V . Indeed, there exist constants $c, \tilde{c} \equiv c, \tilde{c}(n, p, \nu) \geq 1$ such that the following inequality holds whenever $z_1, z_2 \in \mathbb{R}^n$:

$$\tilde{c}^{-1} |z_2 - z_1|^p \leq c^{-1} |V(z_2) - V(z_1)|^2 \leq \langle a(z_2) - a(z_1), z_2 - z_1 \rangle. \tag{2.3}$$

Let us now consider a weak solution $v \in W^{1,p}(A)$ to

$$\operatorname{div} a(Dv) = 0 \quad \text{in } A, \tag{2.4}$$

where $A \subseteq \Omega$ is an open subset of Ω . The next lemma encodes, in a suitable integral way, the Hölder continuity properties of the Dv (see [9, Theorem 3.1] for a proof).

Theorem 2.1. *Let $v \in W^{1,p}(A)$ be a weak solution to (2.4) under the assumptions (1.8). Then there exist constants $\beta \in (0, 1]$ and $c_0 \geq 1$, both depending only on n, p, ν, L , such that the estimate*

$$\int_{B_\rho} |Dv - (Dv)_{B_\rho}| \, dy \leq c_0 \left(\frac{\rho}{R}\right)^\beta \int_{B_R} |Dv - (Dv)_{B_R}| \, dy \tag{2.5}$$

holds whenever $B_\rho \subseteq B_R \subseteq A$ are concentric balls.

The following result, which can be also obtained from the previous one, is essentially proved in [5, 21, 27, 28]. See for instance [27, (2.4)–(2.5)]

Theorem 2.2. *Let $v \in W^{1,p}(A)$ be a weak solution to (2.4) under the assumptions (1.8). Then there exist constants $\beta \in (0, 1]$ and $c_l, c_h \geq 1$, all depending only on n, p, ν, L , such that the estimates*

$$\|Dv\|_{L^\infty(B_{R/2})} \leq c_l \int_{B_R} (|Dv| + s) \, dy \tag{2.6}$$

and

$$|Dv(x_1) - Dv(x_2)| \leq c_h \left(\int_{B_R} (|Dv| + s) \, dy \right) \left(\frac{\rho}{R}\right)^\beta \tag{2.7}$$

hold whenever $B_R \subseteq A$ is a ball and $x_1, x_2 \in B_\rho \subset B_{R/2}$.

Next, we present a “density improvement lemma” based on Theorem 2.2.

Lemma 2.3. *Under the assumptions of Theorem 2.2, let $B \subset A$ be a ball and*

$$\frac{\lambda}{\Gamma} \leq \int_{\sigma^m B} (|Dv| + s) \, dy \quad \sup_{B/2} (|Dv| + s) \leq \Gamma \lambda \tag{2.8}$$

hold for some integer $m \geq 1$ and for numbers $\Gamma \geq 1, \lambda \geq 0$ and $\sigma \in (0, 1/4)$, such that

$$0 < \sigma \leq \left(\frac{1}{8c_h \Gamma^2}\right)^{1/\beta}, \tag{2.9}$$

where β and c_h are the constants appearing in Theorem 2.2. Then

$$\frac{\lambda}{4\Gamma} \leq |Dv| + s \quad \text{holds in } \sigma B.$$

Proof. The first inequality in (2.8) implies that there exists a point $x_0 \in \sigma^m B$ such that $|Dv(x_0)| + s > \lambda/(2\Gamma)$. On the other hand, as (2.7) and the second inequality in (2.8) give $|Dv(x) - Dv(x_0)| \leq c_h \Gamma \lambda (2\sigma)^\beta$ whenever $x \in \sigma B$, the last two inequalities and (2.9) then give

$$|Dv(x)| + s \geq |Dv(x_0)| + s - |Dv(x) - Dv(x_0)| \geq \frac{\lambda}{2\Gamma} - \frac{\lambda}{4\Gamma} = \frac{\lambda}{4\Gamma},$$

for all $x \in \sigma B$. \square

In the rest of the section, the function $u \in W^{1,p}(\Omega)$ shall always be the one considered in Theorem 1.3. Let us now consider a ball $B_R \subset \Omega$ and define $v \in u + W_0^{1,p}(B_R)$ as the unique solution to the following Dirichlet problem:

$$\begin{cases} \operatorname{div} a(Dv) = 0 & \text{in } B_R \\ v = u & \text{on } \partial B_R. \end{cases} \quad (2.10)$$

Then, we give a comparison lemma.

Lemma 2.4. *Under the assumptions of (1.8), let $u \in W^{1,p}(\Omega)$ be a solution to (1.7), and $v \in u + W_0^{1,p}(B_R)$ be as in (2.10). Then*

$$\int_{B_R} \frac{|V(Du) - V(Dv)|^2}{(\alpha + |u - v|)^\xi} \, dy \leq c \frac{\alpha^{1-\xi}}{\xi - 1} |\mu|(B_R) \quad (2.11)$$

holds whenever $\alpha > 0$ and $\xi > 1$, where $c \equiv c(n, p, v) \geq 1$. Here, the function $V(\cdot)$ has been defined in (2.1).

Proof. We begin with testing the weak formulation

$$\int_{B_R} \langle a(Du) - a(Dv), D\varphi \rangle \, dy = \int_{B_R} \varphi \, d\mu, \quad (2.12)$$

valid whenever $\varphi \in W_0^{1,p}(B) \cap L^\infty(B)$, by the functions

$$\eta_{1,\varepsilon} := \pm \min\{1, (u - v)_\pm/\varepsilon\},$$

where $\varepsilon > 0$, and

$$\eta_{2,\varepsilon} := (\alpha + (u - v)_\pm)^{1-\xi} \eta_{1,\varepsilon},$$

which both obviously belong to $W_0^{1,p}(B) \cap L^\infty(B)$. We recall the standard notation

$$(u - v)_+ := \max\{u - v, 0\} \quad \text{and} \quad (u - v)_- := \max\{v - u, 0\}.$$

Testing (2.12) by $\eta_{1,\varepsilon}$, yields

$$0 \leq \int_{B_R} \langle a(Du) - a(Dv), D\eta_{1,\varepsilon} \rangle \, dy = \int_{B_R} \eta_{1,\varepsilon} \, d\mu \leq |\mu|(B_R). \quad (2.13)$$

We then test (2.12) by $\eta_{2,\varepsilon}$. As for the resulting term on the left-hand side we notice

$$\begin{aligned} & \int_{B_R} \langle a(Du) - a(Dv), D\eta_{2,\varepsilon} \rangle \, dy \\ &= \int_{B_R} \langle a(Du) - a(Dv), D\eta_{1,\varepsilon} \rangle \frac{1}{(\alpha + (u - v)_\pm)^{\xi-1}} \, dy \\ & \quad + (1 - \xi) \int_{B_R} \langle a(Du) - a(Dv), D(u - v)_\pm \rangle \frac{\eta_{1,\varepsilon}}{(\alpha + (u - v)_\pm)^\xi} \, dy. \end{aligned}$$

The first integral on the right can be majorized using (2.13) and the nonnegativity of the first integrand in (2.13), as, whenever $\varepsilon > 0$, it holds

$$\begin{aligned} & \int_{B_R} \langle a(Du) - a(Dv), D\eta_{1,\varepsilon} \rangle \frac{1}{(\alpha + (u - v)_\pm)^{\xi-1}} dy \\ & \leq \alpha^{1-\xi} \int_{\Omega} \langle a(Du) - a(Dv), D\eta_{1,\varepsilon} \rangle dy \leq \alpha^{1-\xi} |\mu|(B_R). \end{aligned}$$

But since

$$\left| \int_{B_R} \eta_{2,\varepsilon} d\mu \right| \leq \alpha^{1-\xi} |\mu|(B_R),$$

we obtain

$$(\xi - 1) \int_Q \frac{\langle a(Du) - a(Dv), D(u - v)_\pm \rangle}{(\alpha + (u - v)_\pm)^\xi} \eta_{1,\varepsilon} dy \leq 2\alpha^{1-\xi} |\mu|(B_R)$$

and therefore, using (2.3) and the definition of $\eta_{1,\varepsilon}$, we conclude with

$$\int_{B_R} \frac{|V(Du) - V(Dv)|^2}{(\alpha + |u - v|)^\xi} \min\{1, |u - v|/\varepsilon\} dy \leq \frac{c\alpha^{1-\xi}}{\xi - 1} |\mu|(B_R).$$

Letting $\varepsilon \rightarrow 0$ yields (2.11). \square

Another comparison result is

Lemma 2.5. *Under the assumptions of (1.8), let $u \in W^{1,p}(\Omega)$ be a solution to (1.7) as considered in Theorem 1.3, and $v \in u + W_0^{1,p}(B_R)$ be as in (2.10). Then*

$$\int_{B_R} |Du - Dv|^q dy \leq c_1 \left[\frac{|\mu|(B_R)}{R^{n-1}} \right]^{q/(p-1)} \tag{2.14}$$

holds whenever

$$0 < q < \min \left\{ p, \frac{n(p-1)}{n-1} \right\} =: p_M, \quad \text{with } c_1 \equiv c_1(n, p, v, q). \tag{2.15}$$

Proof. By approximation we can restrict our inquiry to the case $\mu \in L^1$. Indeed, notice that with the assumption $u \in W^{1,p}(\Omega)$, it immediately follows that, as μ belongs to the dual $W^{-1,p'}$ (with dual norm depending on $\|u\|_{W^{1,p}(\Omega)}$). This, in turn, implies that if $w \in W^{1,p}(B_R)$ solves the Dirichlet problem

$$\begin{cases} \operatorname{div} a(Dw) = \mu & \text{in } B_R \\ w = u & \text{on } \partial B_R, \end{cases}$$

then $w = u$ (this is standard, just test by $u - w$ as shown below). Therefore, by approximation we can reduce to the case $\mu \in L^1$, as explained, for instance, in [1,2]. In turn, this allows us to easily perform the scaling arguments used in [30,

Lemma 4.1]. In turn, this allows us to reduce to the case $B_R \equiv B_1$ and $|\mu|(B_1) \leq 1$, and to prove that

$$\int_{B_1} |Du - Dv|^q dy \leq c(n, p, v, q). \tag{2.16}$$

Next, notice that $p_M \leq p$ if and only if $p \leq n$, and this case has been proved in [30, Lemma 4.1]. The proof in the case $p > n$ is actually simpler, as μ belong to the dual $W^{-1,p'}$ (with dual norm depending on $|\mu|(B_1)$), and we provide a sketch here by actually showing that (2.16) holds for $q = p$. By testing (2.12) with $u - v$ (recall that $p > n$ implies that $u - w \in L^\infty$) we easily get, via Morrey’s embedding theorem and using $|\mu|(B_1) \leq 1$, that

$$\|Du - Dv\|_{L^p}^p \leq c \|u - v\|_{L^\infty} |\mu|(B_1) \leq c \|Du - Dv\|_{L^p},$$

so that (2.16) with $q = p$ follows via Young’s inequality. \square

Next, we collect a number of purely technical lemmas that will be useful later. From now on, u and v denote the functions appearing in Lemmas 2.4–2.5.

Lemma 2.6. *Assume that*

$$\left[\frac{|\mu|(B_R)}{R^{n-1}} \right]^{1/(p-1)} \leq \lambda \quad \text{and} \quad \int_{B_R} (|Du| + s) dy \leq \lambda$$

for some $\lambda \geq 0$. Then

$$\sup_{B_{R/2}} |Dv| + s \leq c_2 \lambda \quad \text{holds with } c_2 \equiv c_2(n, p, v, L).$$

Proof. By using (2.6) and (2.14) we have

$$\sup_{B_{R/2}} |Dv| + s \leq c_l \int_{B_R} |Dv - Du| dy + c_l \int_{B_R} (|Du| + s) dy \leq 2c_l c_1 \lambda. \tag{2.17}$$

\square

Lemma 2.7. *Let $\delta, \theta \in (0, 1]$ and $\lambda \geq 0$. Suppose that*

$$\left[\frac{|\mu|(B_R)}{R^{n-1}} \right]^{1/(p-1)} \leq \frac{\delta^n}{c_1} \theta \lambda \quad \text{and} \quad \int_{B_R} (|Du| + s) dy \leq \lambda,$$

where $c_1 \equiv c_1(n, p, v)$ is as in Lemma 2.5. Then the following lower bound holds:

$$\int_{\delta B_R} (|Du| + s) dy - \theta \lambda \leq \int_{\delta B_R} (|Dv| + s) dy. \tag{2.18}$$

Proof. Use of (2.14) yields

$$\begin{aligned} \int_{\delta B_R} |Du| dy &\leq \int_{\delta B_R} |Du - Dv| dy + \int_{\delta B_R} |Dv| dy \\ &\leq \delta^{-n} \int_{B_R} |Du - Dv| dy + \int_{\delta B_R} |Dv| dy \\ &\leq \theta \lambda + \int_{\delta B_R} |Dv| dy. \end{aligned} \tag{2.18}$$

\square

3. Proof of Theorem 1.3

In the following, given a ball $B \subset \Omega$, we define the excess functional

$$E(Du, B) := \int_B |Du - (Du)_B| \, dy.$$

An elementary property of this functional is given by the following:

$$\int_B |Du - (Du)_B| \, dy \leq 2 \int_B |Du - \gamma| \, dy \quad \text{for every } \gamma \in \mathbb{R}^n. \quad (3.1)$$

Finally, given a map $g : A \rightarrow \mathbb{R}^n$, we define its oscillation on A as

$$\text{osc}_A g := \sup_{x, y \in A} |g(x) - g(y)|.$$

The proof of Theorem 1.3 begins with a preliminary lemma which will also play an important role in the proof of Theorem 1.5 in the next section. Given $\delta_1 \in (0, 1/2)$, we consider a ball $B(x, 2r) \subset \Omega$ and the shrinking balls

$$B_i := B(x, r_i), \quad r_i = \delta_1^i r, \quad (3.2)$$

whenever $i \geq 0$ is an integer. The related comparison solutions $v_i \in u + W_0^{1,p}(B_i)$ are as in (2.10), that is,

$$\begin{cases} \operatorname{div} a(Dv_i) = 0 & \text{in } B_i \\ v_i = u & \text{on } \partial B_i. \end{cases} \quad (3.3)$$

Then we have

Lemma 3.1. *Assume that, for $i \geq 1$,*

$$\int_{B_{i-1}} (|Du| + s) \, dy \leq \lambda \quad \text{and} \quad \int_{B_i} (|Du| + s) \, dy \leq \lambda \quad (3.4)$$

hold for a number $\lambda > 0$ satisfying

$$\left[\frac{|\mu|(B_i)}{r_i^{n-1}} \right]^{1/(p-1)} + \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]^{1/(p-1)} \leq \lambda, \quad (3.5)$$

together with

$$\frac{\lambda}{H} \leq |Dv_{i-1}| \leq H\lambda \quad \text{in } B_i \quad \text{and} \quad \frac{\lambda}{H} \leq |Dv_i| \leq H\lambda \quad \text{in } B_{i+1} \quad (3.6)$$

for some constant $H \geq 1$. Then there exists a constant $c_H \equiv c_H(n, p, \nu, L, \delta_1, H)$ such that the following inequality holds:

$$\int_{B_{i+1}} |Du - Dv_i| \, dy \leq c_H \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]. \quad (3.7)$$

Proof. We fix parameters γ and ξ as

$$\gamma := \frac{1}{4(n+1)(p+2)}, \quad \xi = 1 + 2\gamma, \tag{3.8}$$

and introduce $\bar{v}_i = v_i/\lambda$ and $\bar{v}_{i-1} = v_{i-1}/\lambda$. In the case in which (3.7) does not trivialize (that is the left-hand side is not zero) by (3.6) it will be sufficient to prove that

$$\int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \leq c \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right] \tag{3.9}$$

holds for a constant $c \equiv c(n, p, \nu, L, \delta_1, H)$. To this aim, applying Hölder’s inequality and keeping (2.2) in mind, yields, for any $\alpha > 0$,

$$\begin{aligned} & \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \\ & \leq c \int_{B_i} \left[\lambda^{2-p} \frac{|V(Du) - V(Dv_i)|^2}{(\alpha + |u - v_i|)^\xi} \right]^{1/2} \\ & \quad \times \left[|D\bar{v}_i|^{(p-2)(1+2\gamma)} (\alpha + |u - v_i|)^\xi \right]^{1/2} \, dy \\ & \leq c \left(\lambda^{2-p} \int_{B_i} \frac{|V(Du) - V(Dv_i)|^2}{(\alpha + |u - v_i|)^\xi} \, dy \right)^{1/2} \\ & \quad \times \left(\int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} (\alpha + |u - v_i|)^\xi \, dy \right)^{1/2} \\ & \leq c \left(\lambda^{2-p} \frac{|\mu|(B_i)}{r_i^n} \alpha^{1-\xi} \right)^{1/2} \left(\int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} (\alpha + |u - v_i|)^\xi \, dy \right)^{1/2}. \end{aligned} \tag{3.10}$$

Above, c depends only on n, p, ν , because we have applied (2.11). As we are still free to choose α , we fix it as

$$\alpha := \left[\left(\int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} \, dy \right)^{-1} \int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} |u - v_i|^\xi \, dy \right]^{1/\xi}.$$

We may assume $\alpha > 0$, since (3.6) would imply that (3.7) is trivial. Moreover, α is finite, since in its definition the first integral is positive by (3.6), and, by (3.8), the second one is easily seen to be finite by Hölder’s inequality and Sobolev embedding, as both u and v_i belong to $W^{1,p}(B_i)$. Now, (3.10) gives

$$\begin{aligned} & \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \\ & \leq c \left(\lambda^{2-p} \frac{|\mu|(B_i)}{r_i^n} \alpha^{1-\xi} \right)^{1/2} \alpha^{\xi/2} \left(\int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} \, dy \right)^{1/2}. \end{aligned} \tag{3.11}$$

To estimate the last integral, note that

$$\begin{aligned}
 \int_{B_i} |Dv_i - Dv_{i-1}|^q \, dy &\leq c \int_{B_i} |Du - Dv_i|^q \, dy + c \int_{B_i} |Du - Dv_{i-1}|^q \, dy \\
 &\leq c \left[\frac{|\mu|(B_i)}{r_i^{n-1}} \right]^{q/(p-1)} + c\delta_1^{-n} \int_{B_{i-1}} |Du - Dv_{i-1}|^q \, dy \\
 &\leq c \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]^{q/(p-1)} \tag{3.12}
 \end{aligned}$$

holds for all $1 \leq q \leq (p - 1)(1 + 2\gamma) < p_M$, where $c \equiv c(n, p, \nu, \delta_1)$; here we have used (2.14) and kept (3.8) in mind. It then follows, by using (3.5) in (3.12), together with (3.6), that

$$\begin{aligned}
 \int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} \, dy &\leq c \int_{B_i} |D\bar{v}_i - D\bar{v}_{i-1}|^{(p-2)(1+2\gamma)} \, dy \\
 &\quad + c \int_{B_i} |D\bar{v}_{i-1}|^{(p-2)(1+2\gamma)} \, dy \leq c(n, p, \nu, L, H).
 \end{aligned}$$

Using the last inequality in (3.11) then gives

$$\begin{aligned}
 \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy &\leq c \left(\lambda^{2-p} \frac{|\mu|(B_i)}{r_i^n} \alpha \right)^{1/2} \\
 &\leq \varepsilon \frac{\alpha}{r_i} + \tilde{c}(\varepsilon) \lambda^{2-p} \left[\frac{|\mu|(B_i)}{r_i^{n-1}} \right]. \tag{3.13}
 \end{aligned}$$

Notice that we have applied Young’s inequality in the last estimate and, with $\varepsilon \in (0, 1)$, the constant is $\tilde{c}(\varepsilon) \equiv \tilde{c}(n, p, \nu, L, \delta_1, H, \varepsilon)$.

We start the estimation of α . We first apply (3.6) to estimate

$$\int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} \, dy \geq \delta_1^n \int_{B_{i+1}} |D\bar{v}_i|^{(p-2)(1+2\gamma)} \, dy \geq \frac{1}{c}, \tag{3.14}$$

with $c \equiv c(n, p, \nu, L, \delta_1, H) > 1$. Therefore we obtain

$$\alpha^\xi \leq c \int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} |u - v_i|^\xi \, dy, \tag{3.15}$$

again for a constant $c \equiv c(n, p, \nu, L, \delta_1, H)$. In turn,

$$\begin{aligned}
 &\int_{B_i} |D\bar{v}_i|^{(p-2)(1+2\gamma)} |u - v_i|^\xi \, dy \\
 &\leq c \int_{B_i} |D\bar{v}_{i-1}|^{(p-2)(1+2\gamma)} |u - v_i|^\xi \, dy \\
 &\quad + c \int_{B_i} |D\bar{v}_{i-1} - D\bar{v}_i|^{(p-2)(1+2\gamma)} |u - v_i|^\xi \, dy \\
 &=: I_1 + I_2. \tag{3.16}
 \end{aligned}$$

To estimate I_2 , we use (3.12) and hence deduce by Hölder’s inequality, Sobolev embedding and (2.14) that

$$\begin{aligned}
 I_2 &\leq c\lambda^{(2-p)(1+2\gamma)} \left[\int_{B_i} |Dv_{i-1} - Dv_i|^{(p-1)(1+2\gamma)} \, dy \right]^{(p-2)/(p-1)} \\
 &\quad \times \left[\int_{B_i} |u - v_i|^{\xi(p-1)} \, dy \right]^{1/(p-1)} \\
 &\leq c\lambda^{(2-p)(1+2\gamma)} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]^{(1+2\gamma)(p-2)/(p-1)} \\
 &\quad \times r_i^\xi \left[\int_{B_i} |Du - Dv_i|^{p-1} \, dy \right]^{\xi/(p-1)} \\
 &\leq cr_i^\xi \lambda^{(2-p)(1+2\gamma)} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]^{[\xi+(1+2\gamma)(p-2)]/(p-1)}.
 \end{aligned}$$

The constant c depends on n, p, ν and δ_1 ; here we have again used (3.8), which ensures that $(p - 1)(1 + 2\gamma) < p_M$ and that $\xi \leq n/(n - 1)$. By definitions of γ and ξ in (3.8) it readily follows that

$$I_2^{1/\xi} \leq cr_i \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right], \tag{3.17}$$

with $c \equiv c(n, p, \nu, \delta_1)$. Furthermore, appealing to (3.6) repeatedly, the term I_1 is first estimated by Sobolev embedding as

$$\begin{aligned}
 I_1 &\leq cr_i^\xi \left[\int_{B_i} |Du - Dv_i| \, dy \right]^\xi \\
 &\leq cr_i^\xi \left[\int_{B_i} |D\bar{v}_{i-1}|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \right]^\xi,
 \end{aligned}$$

and therefore, with $c \equiv c(n, p, H)$, we have

$$I_1^{1/\xi} \leq cr_i \int_{B_i} |D\bar{v}_{i-1}|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy. \tag{3.18}$$

By using the triangle inequality we further deduce

$$\begin{aligned}
 \int_{B_i} |D\bar{v}_{i-1}|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy &\leq c \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \\
 &\quad + c\lambda^{-(p-2)(1+\gamma)} \int_{B_i} |Dv_i - Dv_{i-1}|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy.
 \end{aligned}$$

The last integral can be estimated similarly to the case of I_2 , that is, by making use of (2.14) and (3.12); indeed

$$\begin{aligned} & \int_{B_i} |Dv_i - Dv_{i-1}|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \\ & \leq \left(\int_{B_i} |Dv_i - Dv_{i-1}|^{(p-1)(1+\gamma)} \, dy \right)^{(p-2)/(p-1)} \\ & \quad \times \left(\int_{B_i} |Du - Dv_i|^{p-1} \, dy \right)^{1/(p-1)} \leq c \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]^{1+\gamma(p-2)/(p-1)}. \end{aligned}$$

Combining the last two inequalities and using (3.5) to estimate

$$\lambda^{-(p-2)(1+\gamma)} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]^{1+\gamma(p-2)/(p-1)} \leq \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right],$$

we obtain

$$\begin{aligned} & \int_{B_i} |D\bar{v}_{i-1}|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \\ & \leq c \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy + c\lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]. \end{aligned}$$

Recalling (3.18) we thus end up with

$$I_1^{1/\xi} \leq cr_i \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy + cr_i \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right].$$

The last estimate with (3.17), and eventually with (3.15)–(3.16), gives

$$\begin{aligned} \alpha & \leq c \left(I_1^{1/\xi} + I_2^{1/\xi} \right) \\ & \leq cr_i \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy + cr_i \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right], \end{aligned}$$

for $c \equiv c(n, p, \nu, L, \delta_1, H)$. Inserting the last inequality into (3.13) and choosing $\varepsilon \equiv \varepsilon(n, p, \nu, L, \delta_1, H) = 1/(2c)$, we obtain

$$\begin{aligned} & \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy \\ & \leq \frac{1}{2} \int_{B_i} |D\bar{v}_i|^{(p-2)(1+\gamma)} |Du - Dv_i| \, dy + c\lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right], \end{aligned}$$

again with $c \equiv c(n, p, \nu, L, \delta_1, H)$, from which (3.9), and therefore (3.7), follows. Notice that by (3.8) the quantity we are reabsorbing here is finite. \square

The rest of the proof of Theorem 1.3 proceeds in four steps.

Step 1: Main characters in the proof. Let $x \in \Omega$ be a Lebesgue point of Du and let $B(x, 2r) \subset \Omega$ be a ball; in the following all the balls considered will be centered at x . We start by taking a positive number λ such that

$$\lambda := H_1 \int_{B_r} (|Du| + s) \, dy + H_2 \left(\int_0^{2r} \frac{|\mu|(B_\varrho)}{\varrho^{n-1}} \frac{d\varrho}{\varrho} \right)^{1/(p-1)}, \tag{3.19}$$

and fix the constants $H_1, H_2 \geq 1$ in a few lines (see (3.26) below), in a way that makes them dependent only on n, p, ν, L ; clearly, we may assume without loss of generality that $\lambda > 0$. In the end we shall simply prove that

$$|Du(x)| \leq \lambda \tag{3.20}$$

and, due to the fact that the ball $B(x, 2r) \subset \Omega$ is arbitrary, we shall conclude with (1.2) by taking $c := 2^{p-2} \max\{H_1, H_2\}^{p-1}$ (and changing the radius r a bit).

We begin by defining the number

$$\delta_1 := \left(\frac{1}{10^8 c_0} \right)^{1/\beta} \left(\frac{1}{10^8 c_h c_2^2} \right)^{1/\beta}, \tag{3.21}$$

where constants c_0, β, c_h and c_2 appear in Theorems 2.1–2.2 and in Lemma 2.6. It follows that δ_1 depends only on n, p, ν, L . With such a choice of δ_1 we consider the balls in (3.2) and the related comparison solutions in (3.3). Moreover, with δ_1 given in (3.21), we determine the new constant

$$c_3 := c_H(n, p, \nu, L, \delta_1, H) \quad \text{with} \quad H := 10^4 c_2 \tag{3.22}$$

according to Lemma 3.1. In this way we ultimately have that c_3 depends only on n, p, ν, L . We also define the composite quantity

$$C_i := \sum_{j=i-2}^i \int_{B_j} (|Du| + s) \, dy + \delta_1^{-n} E(Du, B_i) \tag{3.23}$$

for every integer $i \geq 2$. We meanwhile record the following inclusions, which hold for every $i \geq 0$:

$$\delta_1 B_i = B_{i+1} \subset \left(\frac{1}{10^8 c_h c_2^2} \right)^{1/\beta} B_i \subset (1/4) B_i \subset B_i. \tag{3.24}$$

Next, we take k as the smallest integer satisfying

$$8c_h (2\delta_1)^{k\beta} \leq \frac{\delta_1^n}{10^8 c_2^2} \quad \text{and} \quad k \geq 3. \tag{3.25}$$

In this way k depends only upon n, p, ν, L . We finally set

$$H_1 := 10^8 c_2 \delta_1^{-3n} \quad \text{and} \quad H_2 := 10^8 c_1 c_2 c_3 \delta_1^{-(k+3)n}, \tag{3.26}$$

where $c_1 \equiv c_1(n, p, v)$ has been fixed in Lemma 2.5. Notice that the choice of H_1 also implies

$$C_i \leq 5\delta_1^{-3n} \int_{B_0} (|Du| + s) \, dy \leq \frac{\lambda}{10^7 c_2} \tag{3.27}$$

for $i = 2, 3$, together with

$$s \leq \frac{\lambda}{10^7 c_2}. \tag{3.28}$$

Now, observe that

$$\begin{aligned} \int_0^{2r} \frac{|\mu|(B_\varrho)}{\varrho^{n-1}} \frac{d\varrho}{\varrho} &= \sum_{i=0}^{\infty} \int_{r_{i+1}}^{r_i} \frac{|\mu|(B_\varrho)}{\varrho^{n-1}} \frac{d\varrho}{\varrho} + \int_r^{2r} \frac{|\mu|(B_\varrho)}{\varrho^{n-1}} \frac{d\varrho}{\varrho} \\ &\geq \sum_{i=0}^{\infty} \frac{|\mu|(B_{i+1})}{r_i^{n-1}} \int_{r_{i+1}}^{r_i} \frac{d\varrho}{\varrho} + \frac{|\mu|(B_0)}{(2r)^{n-1}} \int_r^{2r} \frac{d\varrho}{\varrho} \\ &= \delta_1^{n-1} \log\left(\frac{1}{\delta_1}\right) \sum_{i=0}^{\infty} \frac{|\mu|(B_{i+1})}{r_{i+1}^{n-1}} + \frac{\log 2}{2^{n-1}} \left[\frac{|\mu|(B_0)}{r_0^{n-1}} \right] \\ &\geq \delta_1^n \sum_{i=0}^{\infty} \frac{|\mu|(B_i)}{r_i^{n-1}}. \end{aligned} \tag{3.29}$$

Therefore, by (3.19) and the choice in (3.26) it follows that

$$10^8 c_1 c_2 c_3 \delta_1^{-4n} \left[\sum_{i=0}^{\infty} \frac{|\mu|(B_i)}{r_i^{n-1}} \right]^{1/(p-1)} \leq \lambda \tag{3.30}$$

and

$$\left[\frac{|\mu|(B_i)}{r_i^{n-1}} \right]^{1/(p-1)} \leq \frac{\delta_1^{(k+2)n}}{10^8 c_1 c_2} \lambda \leq \lambda \quad \text{for every } i \geq 0. \tag{3.31}$$

Of course we are using constants like 10^8 to emphasize the fact that in certain places in the proof, what it matters is to take very large or very small quantities.

Step 2: The exit time index. Starting from (3.27), let us show that without loss of generality we may assume there exists an “exit time” index $i_e \geq 3$, such that

$$C_{i_e} \leq \frac{\lambda}{100}, \quad C_j > \frac{\lambda}{100} \quad \text{for every } j > i_e. \tag{3.32}$$

Indeed, on the contrary, we would have $C_{j_i} \leq \lambda/100$, for every $i \in \mathbb{N}$, for an increasing subsequence $\{j_i\}$, and then, as x is a Lebesgue point of Du , obviously

$$|Du(x)| \leq \lim_{i \rightarrow \infty} \int_{B_{j_i}} (|Du| + s) \, dy \leq \frac{\lambda}{100},$$

and the proof would be finished.

Step 3: Basic properties of the comparison functions. Here, we record a few basic properties of the functions $\{v_i\}$.

Lemma 3.2. *Assume that for a certain index $i \geq 0$ the following inequality holds:*

$$\int_{B_i} (|Du| + s) \, dy \leq \lambda, \tag{3.33}$$

where $\lambda > 0$ is defined in (3.19). Then

$$|Dv_i| + s \leq c_2\lambda \quad \text{in } B_i/2 \tag{3.34}$$

is satisfied with $c_2 \equiv c_2(n, p, \nu, L)$ appearing in Lemma 2.6. Moreover, if in addition it holds that $i \geq i_e - 2$, then we also have

$$\frac{\lambda}{10^4 c_2} \leq |Dv_i| \quad \text{in } B_{i+1}. \tag{3.35}$$

Proof. The estimate (3.34) is a consequence of Lemma 2.6 applied with $B_R \equiv B_i$, thanks to (3.33) and (3.31). It remains to prove (3.35), and for this we want to apply Lemma 2.3. We start with

$$\frac{\lambda}{200} \leq \sum_{j=i-2+k}^{i+k} \int_{B_j} (|Dv_i| + s) \, dy, \tag{3.36}$$

where $k \equiv k(n, p, \nu, L)$ has been defined in (3.25). By (3.31) we apply Lemma 2.7 three times, with the choice $B_R \equiv B_i$, $\delta \in \{\delta_1^k, \delta_1^{k-1}, \delta_1^{k-2}\}$ and $\theta = \delta_1/(10^8 c_2)$. Summing up the inequalities resulting from the application of (2.17) yields

$$\sum_{j=i-2+k}^{i+k} \int_{B_j} (|Du| + s) \, dy - \frac{\lambda}{10^7 c_2} \leq \sum_{j=i-2+k}^{i+k} \int_{B_j} (|Dv_i| + s) \, dy.$$

The definition of C_i in (3.23), in turn, gives

$$C_{i+k} - \delta_1^{-n} E(Du, B_{i+k}) - \frac{\lambda}{10^7 c_2} \leq \sum_{j=i-2+k}^{i+k} \int_{B_j} (|Dv_i| + s) \, dy.$$

As $i \geq i_e - 2$ and $k \geq 3$, we have $C_{i+k} \geq \lambda/100$ by (3.32); using this fact in the inequality appearing in the latest display leads to

$$\frac{\lambda}{100} - \delta_1^{-n} E(Du, B_{i+k}) - \frac{\lambda}{10^7 c_2} \leq \sum_{j=i-2+k}^{i+k} \int_{B_j} (|Dv_i| + s) \, dy. \tag{3.37}$$

To proceed in the estimation of the excess term we note that

$$\int_{B_{i+k}} |Du - Dv_i| \, dy \leq \frac{|B_i|}{|B_{i+k}|} \int_{B_i} |Du - Dv_i| \, dy \leq c_1 \delta_1^{-kn} \left[\frac{|\mu|(B_i)}{r_i^{n-1}} \right]^{1/(p-1)},$$

where we have used (2.14) with $q = 1$. Using (3.32) again provides us

$$\int_{B_{i+k}} |Du - Dv_i| \, dy \leq \frac{\delta_1^n}{10^8 c_2} \lambda. \tag{3.38}$$

On the other hand, Theorem 2.2 (applied to v_i on B_i , choosing $B_R \equiv B_i/2$ in (2.7)), estimate (3.34), and finally (3.25), give

$$2\text{osc}_{B_{i+k}} Dv_i \leq 2c_h c_2 (2\delta_1)^{k\beta} \lambda \leq \frac{\delta_1^n}{10^8 c_2} \lambda,$$

so that, thanks to (3.1) and (3.38), we can estimate

$$\begin{aligned} E(Du, B_{i+k}) &\leq 2 \int_{B_{i+k}} |Du - (Dv_i)_{B_{i+k}}| dy \\ &\leq 2E(Dv_i, B_{i+k}) + 2 \int_{B_{i+k}} |Du - Dv_i| dy \\ &\leq 2\text{osc}_{B_{i+k}} Dv_i + \frac{\delta_1^n \lambda}{10^8 c_2} \\ &\leq \frac{\delta_1^n \lambda}{10^7 c_2}. \end{aligned}$$

Inserting the last estimate into (3.37) yields (3.36). In turn, (3.36) implies that there exists an index $j \in \{i - 2 + k, i - 1 + k, i + k\}$ such that

$$\frac{\lambda}{200} \leq 3 \int_{B_j} (|Dv_i| + s) dy = 3 \int_{\delta_1^{j-i} B_i} (|Dv_i| + s) dy.$$

This inequality allows us to apply Lemma 2.3 with parameters $B \equiv B_i$, $\sigma = \delta_1$, $m = j - i \geq 1$ (recall that $k \geq 3$ and observe that (3.34) is in force) and $\Gamma = 600c_2$ (keep (3.21) in mind to check (2.9)), and therefore we conclude with

$$\frac{\lambda}{2400c_2} \leq |Dv_i| + s \quad \text{in } B_{i+1} = \delta_1 B_i,$$

which, together with (3.28), implies (3.35). \square

Step 4: Final iteration and conclusion. First, a lemma.

Lemma 3.3. *Let (3.4) hold for a certain number $i \geq i_e - 1$. Then*

$$E(Du, B_{i+2}) \leq \frac{1}{4} E(Du, B_{i+1}) + c_4 \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]$$

holds for a constant c_4 depending only on n, p, v, L , which is given by $c_4 = 4\delta_1^{-n} c_3$, and, in turn, $c_3 \equiv c_3(n, p, v, L)$ is the constant appearing in (3.22).

Proof. Let us first prove that

$$\int_{B_{i+1}} |Du - Dv_i| dy \leq c_3 \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right] \tag{3.39}$$

holds, and for this we want to apply Lemma 3.1. To this aim, we repeatedly apply Lemma 3.2 to both v_i and v_{i-1} ; notice that, since we are assuming $i \geq i_e - 1$, we obviously have $i - 1 \geq i_e - 2$. In conclusion, Lemma 3.2 gives

$$\frac{\lambda}{10^4 c_2} \leq |Dv_{i-1}| \leq c_2 \lambda \quad \text{in } B_i \quad \text{and} \quad \frac{\lambda}{10^4 c_2} \leq |Dv_i| \leq c_2 \lambda \quad \text{in } B_{i+1}.$$

Therefore assumptions (3.6) are satisfied with $H \equiv 10^4 c_2$, while (3.5) holds by (3.32), and hence (3.39) follows by Lemma 3.1.

Next, by using estimate (2.5) applied on v_i and recalling the choice of δ_1 in (3.21), we obtain

$$E(Dv_i, B_{i+2}) \leq \frac{E(Dv_i, B_{i+1})}{2^6}.$$

This last inequality, (3.39) and (3.1) give

$$\begin{aligned} E(Du, B_{i+2}) &\leq 2 \int_{B_{i+2}} |Du - (Dv_i)_{B_{i+2}}| \, dy \\ &\leq 2E(Dv_i, B_{i+2}) + 2 \int_{B_{i+2}} |Du - Dv_i| \, dy \\ &\leq \frac{E(Dv_i, B_{i+1})}{2^5} + 2\delta_1^{-n} \int_{B_{i+1}} |Du - Dv_i| \, dy \\ &\leq \frac{E(Du, B_{i+1})}{2^4} + 4\delta_1^{-n} \int_{B_{i+1}} |Du - Dv_i| \, dy \\ &\leq \frac{E(Du, B_{i+1})}{2^4} + c_4 \lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]. \end{aligned}$$

□

To proceed with the proof of Theorem 1.3, denote in short

$$A_i := E(Du, B_i) \quad \text{and} \quad a_i = |(Du)_{B_i}|.$$

By the definition in (3.23) and (3.32) we have

$$s + \sum_{j=i_e-2}^{i_e} a_j + \delta_1^{-n} A_{i_e} \leq C_{i_e} \leq \frac{\lambda}{100}. \tag{3.40}$$

We now prove, by induction, that

$$s + a_j + A_j \leq \lambda \tag{3.41}$$

holds whenever $j \geq i_e$. Indeed, by (3.40), the case $j = i_e$ of the previous inequality holds. Then, assume by induction that (3.41) holds whenever $j \in \{i_e, \dots, i\}$. This, also taking (3.40) into account and recalling that the definition in (3.23) allows us to control the averages of $|Du|$ on the three balls B_{i_e-2}, B_{i_e-1} and B_{i_e} , implies that

$$\int_{B_j} (|Du| + s) \, dy \leq \lambda \quad \text{for } j \in \{i_e - 2, \dots, i\}.$$

We can thus apply Lemma 3.3, thereby getting

$$A_{j+2} \leq \frac{1}{4}A_{j+1} + c_4\lambda^{2-p} \left[\frac{|\mu|(B_{j-1})}{r_{j-1}^{n-1}} \right] \tag{3.42}$$

for all $j \in \{i_e - 1, \dots, i - 1\}$. It immediately follows, by (3.41) inductively assumed for $i_e \leq j \leq i$ and (3.30), that

$$A_{i+1} \leq \frac{\lambda}{4} + c_4\lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right] \leq \frac{\lambda}{4} + \frac{\lambda}{10^3} \leq \frac{\lambda}{3}. \tag{3.43}$$

Furthermore, summing up (3.42) for $j \in \{i_e - 1, i_e, \dots, i - 1\}$ leads to

$$\sum_{j=i_e}^{i+1} A_j \leq A_{i_e} + \frac{1}{4} \sum_{j=i_e}^i A_j + c_4\lambda^{2-p} \sum_{j=0}^{\infty} \left[\frac{|\mu|(B_j)}{r_j^{n-1}} \right], \tag{3.44}$$

in turn yielding

$$\sum_{j=i_e}^{i+1} A_j \leq 2A_{i_e} + 2c_4\lambda^{2-p} \sum_{j=0}^{\infty} \left[\frac{|\mu|(B_j)}{r_j^{n-1}} \right]. \tag{3.45}$$

On the other hand, notice that

$$\begin{aligned} a_{i+1} - a_{i_e} &= \sum_{j=i_e}^i (a_{j+1} - a_j) \\ &\leq \sum_{j=i_e}^i \int_{B_{j+1}} |Du - (Du)_{B_j}| \, dy \\ &= \sum_{j=i_e}^i \frac{|B_j|}{|B_{j+1}|} E(Du, B_j), \end{aligned}$$

and therefore (3.45) and eventually (3.30) give

$$a_{i+1} \leq a_{i_e} + 2\delta_1^{-n} A_{i_e} + 2\delta_1^{-n} c_4\lambda^{2-p} \sum_{j=0}^{\infty} \left[\frac{|\mu|(B_j)}{r_j^{n-1}} \right] \leq 2C_{i_e} + \frac{\lambda}{10^3}.$$

By (3.40) the previous estimate yields $a_{i+1} \leq \lambda/3$. This inequality together with (3.28) and (3.43) allows us to finally verify the induction step, that is $s + a_{i+1} + A_{i+1} \leq \lambda$. Therefore (3.41) holds for every $i \geq i_e$. Estimate (3.20) finally follows since x is Lebesgue point of Du and therefore

$$|Du(x)| = \lim_{i \rightarrow \infty} a_i \leq \lambda.$$

4. Proof of Theorem 1.5

By (1.10) and Corollary 1.4 we may assume that $Du \in L^\infty_{loc}(\Omega, \mathbb{R}^n)$.

In the rest of the Section we select open subsets $\Omega' \Subset \Omega'' \Subset \Omega$, and prove that Du is continuous in Ω' . Due to arbitrariness of the choice of the open subsets this is sufficient to prove Theorem 1.5. From now on, we denote

$$\lambda := \|Du\|_{L^\infty(\Omega'')} + s. \tag{4.1}$$

We recall that we may assume that $\mu(\cdot)$ is defined on the whole of \mathbb{R}^n by eventually setting μ to be zero outside of Ω . In the following we shall also set $d := \text{dist}(\Omega', \partial\Omega'') > 0$. As a preliminary, we prove the VMO-regularity of Du .

Proposition 4.1. *Under the assumptions of Theorem 1.5, Du is locally VMO-regular in Ω . In particular, for every $\varepsilon \in (0, 1)$, there exists a positive radius $r_\varepsilon \equiv r_\varepsilon(n, p, \nu, L, \lambda, \mu(\cdot), \varepsilon) < d$ such that*

$$\int_{B(x, \varrho)} |Du - (Du)_{B(x, \varrho)}| \, dy < \lambda \varepsilon \tag{4.2}$$

holds whenever $\varrho \in (0, r_\varepsilon]$ and $x \in \Omega'$.

Proof. Let us set, for $\varepsilon \in (0, 1)$, as in the statement,

$$\delta_1 := \left(\frac{\varepsilon}{10^8 c_0} \right)^{1/\beta} \left(\frac{\varepsilon^2}{10^8 c_h c_2^2} \right)^{1/\beta}, \tag{4.3}$$

where c_0, c_h, c_2 and β are the constants introduced in Theorems 2.1–2.2 and Lemma 2.6; they all depend only on n, p, ν, L and so the same dependence is inherited by δ_1 . We then look at Lemma 3.1 and determine the constant

$$c_5 := c_H(n, p, \nu, L, \delta_1, H) \quad \text{with} \quad H = \frac{10^3 c_2}{\varepsilon}. \tag{4.4}$$

This ultimately yields $c_5 \equiv c_5(n, p, \nu, L, \varepsilon)$. Accordingly, we choose a positive radius $R \equiv R(n, p, \nu, L, \lambda, \mu(\cdot), \varepsilon) < d$ such that

$$\sup_{0 < \varrho \leq R} \sup_{y \in \Omega'} \left[\frac{|\mu|(B(y, \varrho))}{\varrho^{n-1}} \right]^{1/(p-1)} \leq \frac{\delta_1^{3n} \lambda \varepsilon}{10^8 c_1 c_5}, \tag{4.5}$$

which, again, is possible by (1.10). Finally, we fix $x \in \Omega'$ and define the chain of shrinking intrinsic balls

$$B_i \equiv B(x, r_i), \quad r_i = \delta_1^i r, \quad \text{where } r \in (\delta_1 R, R], \tag{4.6}$$

for every integer $i \geq 0$, and define the related comparison solutions $v_i \in u + W_0^{1,p}(B_i)$ as in (3.3). Notice now that, thanks to (4.1), $B_i \subset \Omega'$ holds for every $i \in \mathbb{N}$, and therefore

$$\int_{B_i} (|Du| + s) \, dy \leq \lambda \quad \text{for every integer } i \geq 0. \tag{4.7}$$

We shall prove that

$$E(Du, B_{i+2}) < \lambda\varepsilon \quad \text{for every } i \in \mathbb{N} \cap [1, \infty). \tag{4.8}$$

Let us single out an index $i \geq 1$ and let us distinguish two cases; the first is when

$$\int_{B_{i+2}} |Du| \, dy < \frac{\lambda\varepsilon}{50},$$

so that we trivially have $E(Du, B_{i+2}) < \lambda\varepsilon/25$ and (4.8) follows. The other case is fixed in the next lemma, so that (4.8) eventually follows via (4.1) and (4.5). \square

Lemma 4.2. *Assume that*

$$\int_{B_{i+2}} |Du| \, dy \geq \frac{\lambda\varepsilon}{50}. \tag{4.9}$$

Then it holds that

$$E(Du, B_{i+2}) \leq \frac{\varepsilon}{2^4} E(Du, B_{i+1}) + 4c_5\delta_1^{-n}\lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]. \tag{4.10}$$

Proof. As a preliminary, we establish the validity of

$$\int_{B_{i+1}} |Du - Dv_i| \, dy \leq c_5\lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right], \tag{4.11}$$

for $c_5 \equiv c_5(n, p, \nu, L, \varepsilon)$ as determined in (4.4). We use Lemma 3.1; as (3.4) and (3.5) are satisfied by (4.7) and (4.5), respectively, it remains to show that (3.6) is satisfied for the choice of H made above, that is, $H = 10^3c_2/\varepsilon$. Specifically, we show that

$$\begin{cases} \frac{\lambda\varepsilon}{10^3c_2} \leq |Dv_{i-1}| \leq c_2\lambda & \text{in } B_i \\ \frac{\lambda\varepsilon}{10^3c_2} \leq |Dv_i| \leq c_2\lambda & \text{in } B_{i+1} \end{cases} \tag{4.12}$$

hold. By (4.5) and Lemma 2.7, applied to v_{i-1} and with $B \equiv B_{i-1}$, $\delta = \delta_1^3$ and $\theta = \varepsilon/100$, we gain

$$\int_{B_{i+2}} (|Du| + s) \, dy - \frac{\lambda\varepsilon}{100} \leq \int_{B_{i+2}} (|Dv_{i-1}| + s) \, dy,$$

and therefore (4.9) allows us to conclude with

$$\int_{B_{i+2}} (|Dv_{i-1}| + s) \, dy \geq \frac{\lambda\varepsilon}{100}.$$

Observe that by Lemma 2.6 we have $|Dv_{i-1}(x)| + s \leq c_2\lambda$ whenever $x \in B_{i-1}/2$, and in particular whenever $x \in B_i$. Keeping (4.3) in mind, we are now ready to apply the density Lemma 2.3, choosing $B \equiv B_{i-1}$, $\sigma = \delta_1$, $m = 3$ and $\Gamma = 100c_2/\varepsilon$. In this way the assertion about v_{i-1} in (4.12) is proved. Arguing in a completely

similar way for v_i , and replacing B_{i-1} by B_i , we also obtain the assertions in (4.12) concerning v_i . Now, using Lemma 3.1 we gain (4.11).

Proceeding with the proof, by using estimate (2.5) applied to v_i and recalling the choice of δ_1 in (4.3), we obtain

$$E(Dv_i, B_{i+2}) \leq \frac{\varepsilon}{2^6} E(Dv_i, B_{i+1}).$$

In turn, by using this inequality, together with (4.11) and (3.1), we get (4.10):

$$\begin{aligned} E(Du, B_{i+2}) &\leq 2 \int_{B_{i+2}} |Du - (Dv_i)_{B_{i+2}}| \, dy \\ &\leq 2E(Dv_i, B_{i+2}) + 2 \int_{B_{i+2}} |Du - Dv_i| \, dy \\ &\leq \frac{\varepsilon}{2^5} E(Dv_i, B_{i+1}) + 2\delta_1^{-n} \int_{B_{i+1}} |Du - Dv_i| \, dy \\ &\leq \frac{\varepsilon}{2^4} E(Du, B_{i+1}) + 4\delta_1^{-n} \int_{B_{i+1}} |Du - Dv_i| \, dy \\ &\leq \frac{\varepsilon}{2^4} E(Du, B_{i+1}) + 4c_5\delta_1^{-n}\lambda^{2-p} \left[\frac{|\mu|(B_{i-1})}{r_{i-1}^{n-1}} \right]. \end{aligned}$$

□

To conclude the proof of Proposition 4.1, since all the estimates above are uniform with respect to the choice of $x \in \Omega'$ and of the initial radius $r \in (\delta_1 R, R]$ chosen to build the chain in (4.6), we obtain (4.2) with $r_\varepsilon = \delta_1^3 R$. Indeed, let $\varrho \leq \delta_1^3 R$; this means there exists an integer $m \geq 3$ such that $\delta_1^{m+1} R < \varrho \leq \delta_1^m R$. Therefore we have $\varrho = \delta_1^m r$ for some $r \in (\delta_1 R, R]$ and (4.2) follows from (4.8). The proof is complete. □

Proof of Theorem 1.5. We prove the continuity of Du by showing that it is the (local) uniform limit of a net of continuous maps. More precisely, we consider the family of maps, indexed in ϱ , defined by

$$x \rightarrow (Du)_{B(x,\varrho)} \quad \text{for } 0 < \varrho \leq d := \text{dist}(\Omega', \partial\Omega''),$$

which are obviously continuous. We shall then prove that, for every $\varepsilon > 0$, there exists a radius $r_\varepsilon \leq d/2$, independent of the point $x \in \Omega'$ considered, such that

$$|(Du)_{B(x,\varrho)} - (Du)_{B(x,\rho)}| \leq \lambda\varepsilon \quad \text{for every choice of } \varrho, \rho \in (0, r_\varepsilon]. \quad (4.13)$$

The rest of the proof is dedicated to showing that (4.13) holds. A point worth stressing here, and that makes things different from Section 3, is that (4.13) will prove to be valid for every $x \in \Omega'$, not only for Lebesgue points of Du . Therefore, all the inequalities will be derived by considering a fixed point $x \in \Omega'$, but will be uniform to this choice.

With $\varepsilon > 0$ being fixed in (4.13), we shall keep the choice of the constants δ_1 and c_5 made in (4.3) and (4.4), respectively. Next, we take a positive radius $R \leq d/2$ such that (4.5) holds, together with

$$\sup_y \left[\int_0^{2R} \frac{|\mu|(B(y, \varrho))}{\varrho^{n-1}} \frac{d\varrho}{\varrho} \right]^{1/(p-1)} \leq \frac{\delta_1^{4n} \lambda \varepsilon}{10^8 c_1 c_5} \tag{4.14}$$

and

$$\sup_{0 < \varrho \leq R} \sup_{y \in \Omega'} E(Du, B(y, \varrho)) \leq \frac{\delta_1^{4n} \lambda \varepsilon}{10^8}. \tag{4.15}$$

A computation similar to the one in (3.29) and (4.14) gives

$$\left[\sum_{i=0}^{\infty} \frac{|\mu|(B_i)}{r_i^{n-1}} \right]^{1/(p-1)} \leq \frac{\delta_1^{3n} \lambda \varepsilon}{10^8 c_1 c_5}. \tag{4.16}$$

We shall eventually show that the radius $r_\varepsilon \equiv \delta_1^3 R$, determined via the smallness conditions (4.14)–(4.15), will work as r_ε in (4.13). With R just determined through (4.14)–(4.15), we consider the balls $\{B_i\}$ similarly to (4.6), that is, $B_i \equiv B(x, r_i)$ and $r_i = \delta_1^i R$. Finally, the functions $v_i \in u + W_0^{1,p}(B_i)$ are accordingly defined exactly as in (3.3). We shall now prove that

$$|(Du)_{B_h} - (Du)_{B_k}| \leq \frac{\lambda \varepsilon}{12} \quad \text{holds whenever } 3 \leq k \leq h. \tag{4.17}$$

For this we consider the set \mathcal{L} defined by

$$\mathcal{L} := \left\{ i \in \mathbb{N} : \int_{B_i} |Du| \, dy < \frac{\lambda \varepsilon}{50} \right\},$$

and, accordingly, we then define the set

$$\mathcal{C}_i^m = \{j \in \mathbb{N} : i \leq j \leq i + m, i \in \mathcal{L}, i + m + 1 \in \mathcal{L}, j \notin \mathcal{L} \text{ if } j > i\}$$

and call it *maximal iteration chain* of length m , starting at i . In other words, we have $\mathcal{C}_i^m = \{i, \dots, i + m\}$ and each element of \mathcal{C}_i^m but i lies outside of \mathcal{L} ; \mathcal{C}_i^m is maximal in the sense that there cannot be another set of the same type properly containing it. Obviously, such sets do not exist when $\mathcal{L} = \mathbb{N}$. In the same way we define $\mathcal{C}_i^\infty = \{j \in \mathbb{N} : i \leq j < \infty, i \in \mathcal{L}, j \notin \mathcal{L} \text{ if } j > i\}$ as the *infinite maximal chain* starting at i . Notice that, in every case, the smallest element of such a chain always belongs to \mathcal{L} , being then the only one of the chain to have such a property. Moreover, we define $i_e := \min \mathcal{L}$. Note that we set $i_e = \infty$ if $\mathcal{L} = \emptyset$. We are now ready for the proof of (4.17); for this we need to distinguish three cases. We shall, of course, assume $3 \leq k < h$, because otherwise (4.17) trivializes.

Case 1. $k < h \leq i_e$. This, in particular, applies when $i_e = \infty$, that is, when \mathcal{L} is empty. Now, if $h - 1 > k$, then we can apply Lemma 4.2 repeatedly, and this yields

$$E(Du, B_{i+1}) \leq \frac{1}{2} E(Du, B_i) + 4c_5 \delta_1^{-n} \lambda^{2-p} \left[\frac{|\mu|(B_{i-2})}{r_{i-2}^{n-1}} \right] \tag{4.18}$$

for every $i \in \{k, \dots, h - 2\}$. Summing up the previous inequalities, and making elementary manipulations—see (3.44)–(3.45)—we have

$$\sum_{i=k}^{h-1} E(Du, B_i) \leq 2E(Du, B_k) + 8c_5\delta_1^{-n}\lambda^{2-p} \sum_{i=0}^{\infty} \left[\frac{|\mu|(B_i)}{r_i^{n-1}} \right].$$

Then, using (4.15)–(4.16) yields

$$\sum_{i=k}^{h-1} E(Du, B_i) \leq \frac{\delta_1^{2n}\lambda\varepsilon}{50}.$$

The previous inequality follows in any case as, when $h - 1 = k$, it is a direct consequence of (4.15). In turn, (4.17) follows since

$$\begin{aligned} |(Du)_{B_h} - (Du)_{B_k}| &\leq \sum_{i=k}^{h-1} |(Du)_{B_{i+1}} - (Du)_{B_i}| \\ &\leq \sum_{i=k}^{h-1} \int_{B_{i+1}} |Du - (Du)_{B_i}| \, dy \quad (4.19) \\ &\leq \sum_{i=k}^{h-1} \frac{|B_i|}{|B_{i+1}|} E(Du, B_i) \\ &= \delta_1^{-n} \sum_{i=k}^{h-1} E(Du, B_i) \\ &\leq \frac{\lambda\varepsilon}{50}. \quad (4.20) \end{aligned}$$

Case 2. $i_e \leq k < h$. Let us prove that in this case we have

$$|(Du)_{B_h}| \leq \frac{\lambda\varepsilon}{25} \quad \text{and} \quad |(Du)_{B_k}| \leq \frac{\lambda\varepsilon}{25}. \quad (4.21)$$

We prove the former inequality in (4.21), the proof of the latter being the same. If $h \in \mathcal{L}$, the first inequality in (4.21) follows immediately from the definition of \mathcal{L} . On the other hand, if $h \notin \mathcal{L}$, then, as $h \geq i_e$, it is possible to consider the maximal iteration chain $C_{i_h}^{m_h}$ such that $h \in C_{i_h}^{m_h}$. Note that $h > i_h$ as $h \notin \mathcal{L} \ni i_h$. Then, iterating Lemma 4.2 as done after (4.18)—that is, replacing k by i_h —we gain the analogue of (4.20), that is $|(Du)_{B_h} - (Du)_{B_{i_h}}| \leq \lambda\varepsilon/50$. In turn, using that $|(Du)_{B_{i_h}}| \leq \lambda\varepsilon/50$ as $i_h \in \mathcal{L}$, we again obtain the first inequality in (4.21) and, in any case, (4.21) follows. Estimating as

$$|(Du)_{B_h} - (Du)_{B_k}| \leq |(Du)_{B_h}| + |(Du)_{B_k}| \leq \frac{\lambda\varepsilon}{25} + \frac{\lambda\varepsilon}{25} \leq \frac{\lambda\varepsilon}{12} \quad (4.22)$$

we have that (4.17) holds in the second case, too.

Case 3. $k < i_e < h$. Here we prove that (4.21) still holds and then we conclude as in Step 2. Indeed, the first inequality in (4.21) follows as in Case 2. As for the second estimate in (4.21), let us remark that, as $i_e \in \mathcal{L}$, we have that

$$|(Du)_{B_{i_e}}| \leq \frac{\lambda\varepsilon}{50}. \tag{4.23}$$

On the other hand, we can argue exactly as in Case 1, that is, this time replacing h by i_e , thereby obtaining $|(Du)_{B_{i_e}} - (Du)_{B_k}| \leq \lambda\varepsilon/50$ that together with (4.23) gives the second inequality in (4.21). In turn, (4.17) follows in this case as in (4.22).

We are now ready to show (4.13), thereby concluding the proof. As already mentioned, we take $r_\varepsilon = \delta_1^3 R$, and then fix $0 < \rho < \varrho \leq r_\varepsilon$. This means that there exist two integers, $3 \leq k \leq h$, such that

$$\delta_1^{k+1} R < \varrho \leq \delta_1^k R \quad \text{and} \quad \delta_1^{h+1} R < \rho \leq \delta_1^h R. \tag{4.24}$$

Applying (4.15) we get

$$\begin{aligned} |(Du)_{B(x,\varrho)} - (Du)_{B_{k+1}}| &\leq \int_{B_{k+1}} |Du - (Du)_{B(x,\varrho)}| \, dy \\ &\leq \frac{|B(x,\varrho)|}{|B_{k+1}|} \int_{B(x,\varrho)} |Du - (Du)_{B(x,\varrho)}| \, dy \\ &\leq \delta_1^{-n} E(Du, B(x,\varrho)) \\ &\leq \frac{\lambda\varepsilon}{10}, \end{aligned}$$

and in the same way

$$|(Du)_{B(x,\rho)} - (Du)_{B_{h+1}}| \leq \frac{\lambda\varepsilon}{10}.$$

Using the last two inequalities together with (4.17) establishes (4.13).

Proof of Corollary 1.6. The proof follows by the arguments in [12, Theorem 1.3] and related references; it indeed follows that if $\mu \in L(n, 1)$ holds locally in Ω , then (1.10) is satisfied.

By carefully inspecting the proof of Proposition 4.1 we gain the following:

Theorem 4.3. *Let $u \in W^{1,p}(\Omega)$ be a weak solution to the equation (1.7) under the assumptions of Theorem 1.3. If $\mathbf{I}_1^{|\mu|}(x, R)$ is locally bounded in Ω for some $R > 0$ and if*

$$\lim_{R \rightarrow 0} \frac{|\mu|(B(x, R))}{R^{n-1}} = 0 \quad \text{locally uniformly in } \Omega \text{ w.r.t. } x,$$

then Du is locally VMO-regular in Ω .

5. General Measure Data Problems and Extensions

Theorems 1.1 and 1.3 have been stated for classical energy distributional solutions, that is, $u \in W^{1,p}(\Omega)$. They nevertheless hold for solutions to measure data problems, which in turn do not always belong to $W^{1,p}$. More precisely, Theorems 1.1 and 1.3 extend to the so-called SOLA (Solution Obtained as Limits of Approximations), which are solutions to the Dirichlet problems of the type

$$\begin{cases} -\operatorname{div} a(Du) = \mu & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (5.1)$$

obtained as limits of solutions u_k of similar problems, where this time $\mu \equiv \mu_k$ is a smooth function, typically obtained by a convolution. Here, however, we will not recall the whole construction, which is rather long and available in several papers. The original approach was introduced by BOCCARDO and GALLOUET [1,2], to which we refer the reader for the basic results and definitions (including that of SOLA), together with [7], while for applications of (1.2) in this setting we refer to [30, Section 4] and [9, Section 5]. We confine ourselves to reporting the main outcome, that is,

Theorem 5.1. *Let $u \in W^{1,p-1}(\Omega)$ be a SOLA to (5.1), under the assumptions of (1.8), with μ being a Borel measure with finite total mass and $\Omega \subset \mathbb{R}^n$ being a Lipschitz domain. Then there exists a constant c , depending only on n, p, ν, L such that the pointwise estimate (1.9) holds whenever $B(x, R) \subseteq \Omega$ and $x \in \Omega$ is a Lebesgue point of Du .*

We recall that SOLA are not known, in general, to be unique, but can be under a few additional assumptions (for instance $p = 2$, or when $\mu \in L^1(\Omega)$). We refer to [15,24] for more results concerning the solvability of measure data problems.

We finally remark that Theorem 1.3 extends to more general equations with coefficients of the type

$$-\operatorname{div} a(x, Du) = \mu,$$

where the main assumption on the x -dependence is that the partial map

$$x \mapsto \frac{a(x, z)}{(|z|^2 + s^2)^{(p-1)/2}}$$

is Dini-continuous, uniformly with respect to $z \in \mathbb{R}^n$. This will be shown in a forthcoming paper.

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