

The Probabilistic Rabin Tree Theorem

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Theorem

We can compute the probability that a random infinite tree belongs to a given regular language L .

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given by, e.g.

- an MSO formula
- a nondeterministic parity automaton

full binary tree,
each label chosen
independently in random

- the result is an algebraic number
- can be computed in 3-EXPTIME
- can be compared with a given rational q in 2-EXPSPACE

Context

Decidable

- some results for ω -words (probability always rational)
- infinite trees: the probability exists (not clear because regular languages of infinite trees need not to be Borel)
[Gogacz, Michalewski, Mio, Skrzypczak 2017]
- determ. top-down parity autom.
[Chen, Dräger, Kiefer 2012]
- game automata
[Michalewski, Mio 2015]
- weak MSO
[Niwiński, Przybyłko, Skrzypczak 2020]

Undecidable

- nonemptiness for probabilistic automata (exists a finite word accepted with probability >0.5)
- value-1 for probabilistic automata (exists a sequence of finite words where acceptance probability tends to 1)
- exists a ω -word accepted by a probabilistic Büchi automaton with probability >0 .

Open

- Satisfiability of PCTL*

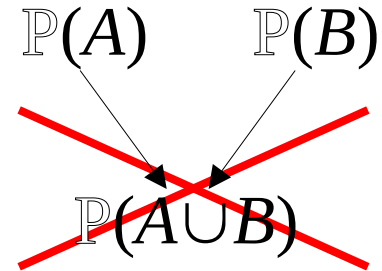
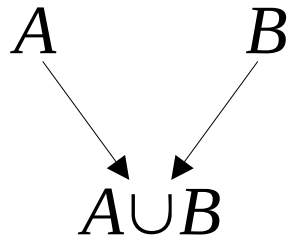
Two worlds

Languages \longrightarrow Probabilities

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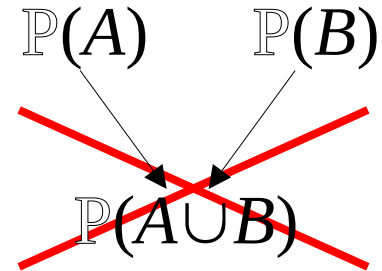
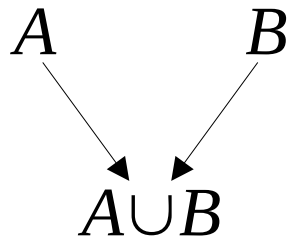
Key difficulty:



Two worlds

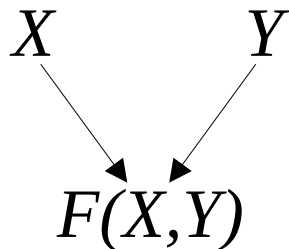
Languages \longrightarrow Probabilities

Key difficulty:

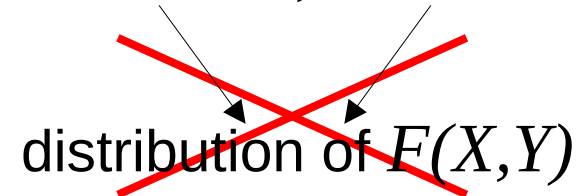


Another aspect:

(random variables)



distribution of X , distribution of Y



distribution of $X \times Y$

distribution of $F(X, Y)$



Step 1

~~Nondeterministic automata~~ → μ -calculus / powersets

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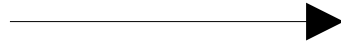
~~Nondeterministic automata~~ \longrightarrow μ -calculus / powersets

$$\mu x_1. \nu x_2. \mu x_3. \nu x_4 \dots \mu x_{d-1}. \nu x_d. \delta(x_1, x_2, \dots, x_d)$$

Still not good – a function of many variables!

Step 2

$$\delta(\tau_1, \tau_2, \dots, \tau_d)$$



$$\bar{\tau} = (\tau_1, \tau_2, \dots, \tau_d)$$
$$\Delta(\bar{\tau})$$

Not so nice – we need \vee, \wedge to interact
between coordinates!
e.g. $\mu x. F(x \vee y)$

Step 3

$$\cancel{\mu x. F(x \vee y)} \longrightarrow F \uparrow (y)$$

Intuition behind $\mu x. F(x \vee y)$ (but not precise meaning):
least fixed point of F above y

We define: $F \uparrow (y) =$ least fixed point of F above y

Unary μ -calculus

Syntax: $H, F_1;F_2, F\uparrow, F\downarrow$ (defines a one-argument function $V \rightarrow V$)

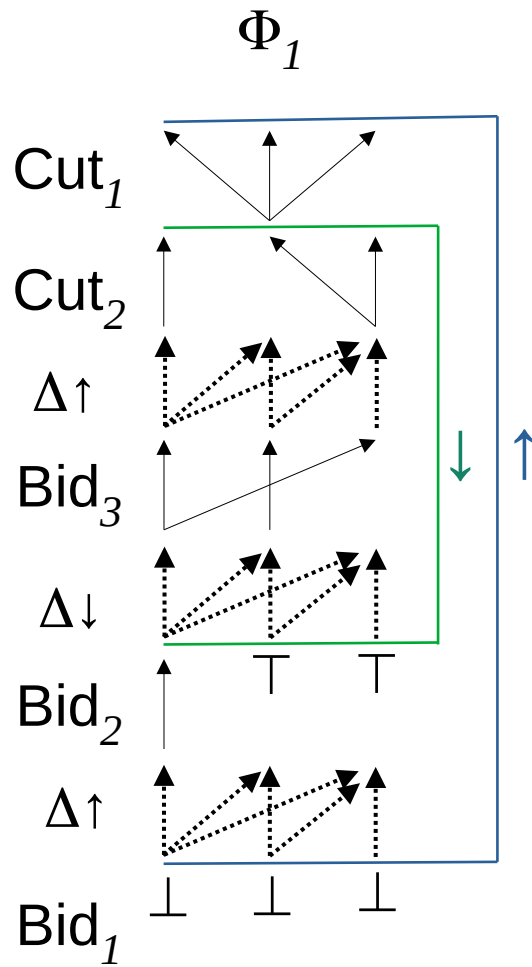
composition

fixed base functions

$F\downarrow(y)$ = greatest fixed point of F below y

$F\uparrow(y)$ = least fixed point of F above y

Unary μ -calculus – the formula

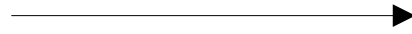


What has to be shown?

- 1) all fixpoints in Φ_1 exist
- 2) Φ_1 computes $\mu x_1. \nu x_2. \dots \mu x_{d-1}. \nu x_d. \delta(x_1, \dots, x_d)$
- 3) all intermediate sets used while computing Φ_1 are measurable
- 4) the same computation can be done on distributions

Last step

Sets



Distributions

$$\tau : \text{trees} \rightarrow \mathcal{P}(Q \times \{1, \dots, d\})$$

$$\hat{\tau} : \mathbb{D}(\mathcal{P}(Q \times \{1, \dots, d\}))$$

$$\hat{\tau}(R) = \mathbb{P}(\{t \mid \tau(t) = R\})$$

Φ_1 can be expressed in first-order logic over reals – decidable by Tarski (the formula is of exponential size)

Conclusions

- We shown how to compute the probability that a random infinite tree belongs to a given regular language.
- We introduced unary μ -calculus, which works well for orders without \vee and \wedge (e.g. probability distributions)

Thank you