# Higher-Order Nonemptiness Step by Step 

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Higher-Order = we consider higher-order recursion schemes

Nonemptiness = we solve the acceptance problem for alternating reachability automata (= language nonemptiness)

Step by Step = we give a new method, working in multiple simple steps

## Higher-order recursion schemes - what is this?

## Definition

Higher-order recursion schemes $=$ a generalization of context-free grammars, where nonterminals can take arguments. We use them to generate trees.

Equivalent definition: simply-typed lambda-calculus + recursion
In other words:

- programs with recursion
- higher-order functions (i.e., functions taking other functions as parameters)
- every function/parameter has a fixed type
- no data values, only functions


## Higher-order recursion schemes - example

Ranked alphabet: (rank = number of children) $a$ of rank $2, b$ of rank $1, c$ of rank 0

Nonterminals:
$S$ (starting), $A, D$

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D(D b) c \rightarrow D b(D b c) \rightarrow b(b(D b c))
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## Types

Ranked alphabet: (rank = number of children) $a$ of rank 2, $b$ of rank 1, $c$ of rank 0

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Every nonterminal (every argument) has assigned some type, for example:

- o - a tree
- $o \rightarrow O$ - a function that takes a tree, and produces a tree
- $o \rightarrow(o \rightarrow o) \rightarrow o$ - a function that takes a tree and a function of type $o \rightarrow o$, and produces a tree


## Order of a type

$$
\begin{aligned}
& \operatorname{ord}(o)=0 \\
& \operatorname{ord}\left(\alpha_{1} \rightarrow \ldots \rightarrow \alpha_{k} \rightarrow o\right)=1+\max \left(\operatorname{ord}\left(\alpha_{1}\right), \ldots, \operatorname{ord}\left(\alpha_{k}\right)\right)
\end{aligned}
$$

For example:

- $\operatorname{ord}(o)=0$,
- $\operatorname{ord}(o \rightarrow o)=\operatorname{ord}(o \rightarrow o \rightarrow o)=1$,
- $\operatorname{ord}(o \rightarrow(o \rightarrow o) \rightarrow o)=2$

Order of a recursion scheme
= maximal order of (a type of) its nonterminal

## Model-checking for recursion schemes

General goal: verifying properties of trees generated by schemes
Why? Recursion schemes are decidable models (abstractions) of programs using higher-order recursion

## Model-checking for recursion schemes

Input: alternating tree automaton (ATA) $\mathcal{A}$, recursion scheme $\mathcal{G}$ Qestion: does $\mathcal{A}$ accept the tree generated by $\mathcal{G}$ ?

Theorem [Ong 2006]
This problem is decidable for parity ATA (i.e., for MSO).

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This problem is decidable for parity ATA (i.e., for MSO).
Several proofs, using:

- game semantics
- collapsible pushdown automata
- intersection types
- Krivine machines
and several extensions.
Some proofs only for reachability ATA.
We show another, very simple algorithm for reachability ATA.


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Complexity:

- n-EXPTIME-complete for recursion schemes of order n,
- FTP: linear in the size of $\mathcal{G}$, when size of $\mathcal{A}$ and maximal arity of types in $\mathcal{G}$ are fixed,
- the same for parity ATA and for reachability ATA
- (algorithms based on intersection types perform relatively well in practice)

Our algorithm achieves the same complexity.

## Preprocessing

We consider an (appropriately defined) product of $\mathcal{G}$ and $\mathcal{A}$.
It is a recursion scheme generating a tree labeled by:
$\wedge$ (AND),
v (OR),
with T (empty AND), $\perp$ (empty OR) as special cases
We ask about alternating reachability.


## General idea

We replace the recursion scheme $\mathcal{G}_{n}$ of order $n$ by an equivalent recursion scheme $\mathcal{G}_{n-1}$ of order $n-1$. Size grows exponentially.

$$
\mathcal{G}_{n} \longrightarrow \mathcal{G}_{n-1} \longrightarrow \mathcal{G}_{n-2} \longrightarrow \cdots \longrightarrow \mathcal{G}_{1} \longrightarrow \mathcal{G}_{0}
$$

For recursion schemes of order 0 the problem becomes trivial.

## Transformation

Consider an application KL , where L is of order 0 (generates a tree). When is the tree generated by KL accepting?

- When $\mathrm{K} \perp$ is accepting (i.e., K is accepting without using the argument)
- When both KT and $L$ are accepting



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- When $K \perp$ is accepting (i.e., K is accepting without using the argument)
- When both KT and $L$ are accepting

We change KL into $\vee(K \perp)(\wedge(K T) L)$


## Complete example (order 1)

order-0 argument

$$
\begin{array}{ll}
X \rightarrow Y Z^{\prime} \\
Y X \rightarrow V T X \\
Z \rightarrow T
\end{array} \quad \begin{aligned}
& X \rightarrow V Y_{0}\left(\wedge Y_{1} Z\right) \\
& Y_{0} \rightarrow V T \perp \quad Y_{1} \rightarrow V T T \\
& Z \rightarrow T
\end{aligned}
$$

( $k$ order- 0 arguments $\Rightarrow 2^{k}$ variants of the nonterminal)

## Complete example (order 2)

$$
\begin{array}{ll}
\begin{array}{l}
\mathrm{X} \rightarrow \mathrm{ZY} \\
\mathrm{Yx} \rightarrow \mathrm{~V} \mathrm{TX} \\
\mathrm{Zy} \rightarrow \mathrm{y} \\
\underbrace{\mathrm{y} \mathrm{~T}}_{\text {order-0 arguments }})
\end{array} \quad \begin{array}{l}
\mathrm{X} \rightarrow \mathrm{Z} \mathrm{Y}_{0} \mathrm{Y}_{1} \\
\mathrm{Y}_{0} \rightarrow \mathrm{VT} \perp \\
\mathrm{Z} y_{0} y_{1} \rightarrow \vee y_{0}\left(\wedge y_{1}\left(\vee y_{0}\left(\wedge y_{1} \mathrm{~T}\right)\right)\right)
\end{array} \\
\mathrm{Y}_{1} \rightarrow \mathrm{VTT}
\end{array}
$$

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$$
\begin{array}{ll}
\mathrm{X} \rightarrow \mathrm{ZY} \\
\mathrm{Yx} \rightarrow \mathrm{VTx} \\
\mathrm{Zy} \rightarrow \mathrm{~V} \\
\underbrace{\mathrm{yT} \mathrm{~T}}_{\text {order-0 arguments }}
\end{array} \quad \begin{aligned}
& \mathrm{X} \rightarrow \mathrm{ZY} \mathrm{Y}_{0} \mathrm{Y}_{1} \\
& \mathrm{Y}_{0} \rightarrow \vee \mathrm{~V} \perp \\
& \mathrm{Z} y_{0} y_{1} \rightarrow \mathrm{~V} y_{0}\left(\wedge y_{1}\left(\vee y_{0}\left(\wedge y_{1} \mathrm{~T}\right)\right)\right)
\end{aligned}
$$

- easy to generalize
- easy (syntactical) correctness proof
- verified in Coq


## Conclusion

- We consider the model-checking problem for recursion schemes + reachability ATA
- We propose a new, simpler method algorithm solving this problem: we repeatedly reduce the order of a recursion scheme by one, increasing its size exponentially
- We obtain optimal complexity
- Future work: extend this method to parity ATA / to the diagonal problem (SUP)

Thank you!

