# Intersection Types for Unboundedness Problems 

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## Our setting

Intersection types can be used as:

- an extension of simple types (mostly undecidable)
- a refinement of simple types (mostly decidable)
this talk


## Our setting

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Order: $\operatorname{ord}(0)=0, \operatorname{ord}(\alpha \rightarrow \beta)=\max (\operatorname{ord}(\alpha)+1, \operatorname{ord}(\beta))$
$\lambda$-terms:

- variables: $x^{\alpha}, y^{\beta}, \ldots$
- constants: $\mathrm{a}^{\alpha}, \mathrm{b}^{\beta}, \ldots-$ only for sorts of order $\leq 1$
- $\lambda$-abstraction: $\left(\lambda x^{\alpha} . K^{\beta}\right)^{\alpha \rightarrow \beta}$
- application: $\left(\mathrm{K}^{\alpha \rightarrow \beta} \mathrm{L}^{\alpha}\right)^{\beta}$ + coinduction

Every term has a particular sort.
We assume that all arguments of constants are already applied:
$a^{0 \rightarrow 0 \rightarrow 0} \mathrm{~K}^{0} \mathrm{~L}^{0}$ is allowed, but $\mathrm{a}^{0 \rightarrow 0 \rightarrow 0} \mathrm{~K}^{0}$ is not allowed

## Our setting - $\lambda Y$-calculus

$\lambda Y$-term is a finite representation of an infinite $\lambda$-term:

- In a $\lambda$ Y-term we may use a binder "Y"
- Meaning:
$\left(Y x^{\alpha} \cdot M^{\alpha}\right)^{\alpha}$ - this is the unique (infinite) $\lambda$-term such that

$$
Y x . M=M[Y x . M / x]
$$

## Example:

the $\lambda Y$-term: Yx.((גy.ay) x)
represents the $\lambda$-term: ((גy.ay) ((גy.ay) ((גy.ay) (( $\lambda y . a y) ~ . .)))$.

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- We may reduce each $M_{1}, \ldots, M_{k}$ to head- $\beta$-normal form, etc.
- The limit is called the Böhm tree of K .


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Then the Böhm tree is a tree built out of constants.

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Yx.((גy.ay) x) $=((\lambda y \cdot a y)((\lambda y \cdot a y)((\lambda y \cdot a y)((\lambda y \cdot a y) \ldots))))$

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\left(\text { a }\left(\left(\lambda y \cdot{ }^{\prime}{ }^{\prime}\right)((\lambda y \cdot a y)((\lambda y \cdot a y) \ldots))\right)\right)
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Example:
Yx.((גy.ay) $x)=((\lambda y \cdot a y)((\lambda y \cdot a y)((\lambda y \cdot a y)((\lambda y \cdot a y) \ldots))))$

$$
\left(a\left(a^{\nabla}\left(a^{\gamma} \ldots\right)\right)\right)
$$

## Our setting - Böhm trees

Example:
Yx.((גy.byy) x) = ((גy.byy) ((גy.byy) ((خy.byy) ((גy.byy) ...))))

$$
(b(b(b \ldots)(b \ldots))(b(b \ldots)(b \ldots))
$$



Equivalent formalisms - trees generated by:

- higher-order recursion schemes (HORSes)
- collapsible pushdown automata
- ordered tree-pushdown automata

Intersection types for $\lambda Y$-calculus - general setting
In the context of $\lambda Y$-calculus (recursion schemes), intersection types were used for:

- model checking -
this talk
- transformation of schemes
- pumping


## Plan

1) model checking for co-trivial tree automata (via intersection types)
2) transformation "words $\rightarrow$ trees" (via intersection types) + how to use it to solve unboundedness problems
3) unboundedness problems (directly via intersection types)

Motivation: from program verification to recursion schemes

## Example

| open( $x$, "foo") |
| :--- |
| $\mathrm{a}:=0$ |
| while $a<100$ do |
| $\quad$ read( $x$ ) |
| $a:=a+1$ |
| close $(x)$ |

is the file "foo"
accessed according to open,read*,close?

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## Example

Step 1: information about infinite data domains is approximated.

| open(x, "foo") |
| :--- |
| $\mathrm{a}:=0$ |
| while $\mathrm{a}<100$ do |
| read( x$)$ |
| $\mathrm{a}:=\mathrm{a}+1$ |
| close $(\mathrm{x})$ |

$$
\begin{array}{|l}
\hline \text { open(x, "foo") } \\
\text { while * do } \\
\text { read( } x \text { ) } \\
\text { close }(x) \\
\hline
\end{array}
$$

is the file "foo" accessed according to open,read ${ }^{*}$,close?

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## Example

Step 2: consider the tree of possible control flows.

| open(x, "foo") |
| :--- |
| while * do |
| $\operatorname{read}(x)$ |
| $\operatorname{close}(x)$ |


is the file "foo"
accessed according to open,read*,close?
is each path labelled by open,read*,close?

Motivation: from program verification to recursion schemes

## What about higher order programs?

```
let f(x,g)=
    if * then g(x)
    else f(x, fun h x -> h(x); h(x))
open(x)
f(x, read)
close(x)
```



- For programs without recursion, each path of the tree is a regular language.
- Programs with (higher-order) recursion can be approximated by recursion schemes


## Intersection types describing co-trivial ATA

We fix some alternating tree automaton:
$Q$ - set of states
$\Delta$ - set of transitions of the form $(q, a) \rightarrow\left(Q_{1}, \ldots, Q_{r}\right)$ where $r=\operatorname{arity}(a)$
$q_{0}$ - initial state (for the root of the tree)

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Run on a tree $t=$ labeling of nodes of $t$ by sets of states

- if a node $v$ is labeled by $S$, and its children by $S_{1}, \ldots, S_{r}$, then for every $q \in S$ there is a transition $(q, a) \rightarrow\left(Q_{1}, \ldots, Q_{r}\right)$ with $Q_{1} \subseteq S_{1}, \ldots, Q_{r} \subseteq S_{r}$

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- co-trivial accepting condition: only finitely many nodes are labeled by nonempty sets

Goal: given an automaton $A$ and a term $K$, decide whether $A$ accepts the Böhm tree of $K$.
We can achieve this goal using a type system of intersection types:
a type $\tau$ can be derived for $K \Leftrightarrow A$ accepts $B T(K)$
[Broadbent, Kobayashi - CSL 2013]

## Intersection types describing co-trivial ATA

Intersection types:

- describe behavior of the automaton
- refine simple types (sorts): for every sort $\alpha$ we have a set Types ${ }^{\alpha}$ of types refining sort $\alpha$
Type judgments:
$\Gamma \vdash \mathrm{K}: \tau$


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Types $^{0}=Q$
A term of sort o (a tree, or a term that generates a tree) has type $q$ (where $q \in Q$ ) if the tree can be accepted from state $q$

For each transition $(q, a) \rightarrow\left(Q_{1}, \ldots, Q_{r}\right)$ of $A$ we have a typing rule:
$\Gamma \vdash K_{i}: p$ for each $i \in\{1, \ldots, r\}$ and each $p \in Q_{i}$

$$
\Gamma \vdash a K_{1} \ldots K_{r}: q
$$

## Intersection types describing co-trivial ATA

Terms of order 1 describe fragments of trees:
Types ${ }^{0 \rightarrow o \rightarrow o}=P(Q) \times P(Q) \times Q$
such a type is of the form $Q_{x} \rightarrow Q_{y} \rightarrow q$
(it says that if the subtree given as the first
 argument is accepted from all states in $Q_{X}$, and the subtree given as the second argument is accepted from all states in $Q_{y}$, then the whole tree can be accepted from $q$ )

Remark: $Q_{X}$ has to be a set of states, not a single state, even if we consider nondeterministic automata instead of alternating automata, because $x$ can appear multiple times in $K$.

## Intersection types describing co-trivial ATA

In general:
Types ${ }^{\circ}=Q$
Types ${ }^{\alpha \rightarrow \beta}=P\left(\right.$ Types $\left.^{\alpha}\right) \times$ Types $^{\beta}$
Elements of Types ${ }^{\alpha \rightarrow \beta}$ are written as $\Psi \rightarrow \boldsymbol{\tau}$

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Types ${ }^{\alpha \rightarrow \beta}=P\left(\right.$ Types $\left.^{\alpha}\right) \times$ Types $^{\beta}$
Elements of Types ${ }^{\alpha \rightarrow \beta}$ are written as $\Psi \rightarrow \boldsymbol{\tau}$
Typing rules:
$\Gamma \vdash K_{i}: p$ for each $i \in\{1, \ldots, r\}$ and each $p \in Q_{i}$ $\Gamma \vdash a K_{1} \ldots K_{r}: q$

$$
\frac{\Gamma \vdash K: \Psi \rightarrow \tau \quad \Gamma \vdash L: \sigma \text { for each } \sigma \in \Psi}{\Gamma \vdash K L: \tau}
$$

$$
\begin{array}{r}
\tau \in \Gamma(x) \\
\Gamma \vdash x: \tau
\end{array}
$$

$$
\frac{\Gamma[x \rightarrow \Psi] \vdash K: \tau}{\Gamma \vdash \lambda x \cdot K: \Psi \rightarrow \tau}
$$

Intersection types describing co-trivial ATA
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$$
\begin{aligned}
& \tau \in \Gamma(x) \\
& \Gamma \vdash x: \tau \frac{\Gamma[x \rightarrow \Psi] \vdash K: \tau}{\Gamma \vdash \lambda x . K: \Psi \rightarrow \tau}
\end{aligned}
$$

$K$ may be infinite
Lemma: For a closed term $K$ of sort $o$, and for a state $q$,
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Lemma: For a closed term $K$ of sort $o$, and for a state $q$,
there is a finite derivation $\Leftrightarrow A$ accepts $B T(K)$ from state $q$ of $\varepsilon \vdash K: q$

Lemma 2: If we consider A with trivial accepting condition, instead of co-trivial (if we allow infinite runs of $A$ ), we have the equivalence
there is a derivation
(arbitrary - possibly infinite)
$\Longleftrightarrow A$ accepts $B T(K)$ from state $q$ of $\varepsilon \vdash K: q$

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Lemma: For a closed term $K$ of sort $o$, and for a state $q$,
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## Proof sketch:

1) If $M \rightarrow{ }_{\beta} N$, then $\Gamma \vdash M: \tau \Leftrightarrow \Gamma \vdash N: \tau$
2) For $K=B T(K)$ the lemma is trivial (only rules for a constant are used)
3) Both sides of the lemma talk only about finite prefixes of the term, so we can assume that K is finite. Then $K \rightarrow{ }_{\beta}^{*} B T(K)$.

Intersection types describing co-trivial ATA
Lemma: For a closed $\lambda$-term $K$ of sort $o$, and for a state $q$,
there is a finite derivation $\Leftrightarrow A$ accepts $B T(K)$ from state $q$ of $\varepsilon \vdash K: q$
$\underline{\text { Goal: }}$ given an automaton $A$ and a finite $\lambda Y$-term $K^{\prime}$, decide whether $A$ accepts $B T\left(K^{\prime}\right)$.

Intersection types describing co-trivial ATA
Lemma: For a closed $\lambda$-term $K$ of sort $o$, and for a state $q$,
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Goal: given an automaton $A$ and a finite $\lambda Y$-term $K^{\prime}$, decide whether $A$ accepts $B T\left(K^{\prime}\right)$.

- Recall that $K^{\prime}$ is a finite representation of an infinite $\lambda Y$-term $K$.
- Seeing $K^{\prime}$ we have to check whether a type judgment can be derived for $K$.
- I.e., seeing Yx.M, we have to check which type judgments can be derived for $M[M[M[M[M[\ldots] / x] / x] / x] / x]$.
- This is an easy fixpoint computation.


## Unboundedness - basic problem

Input: closed $\lambda Y$-term K of sort o (i.e. infinite $\lambda$-term represented in a finite way) Question: In the Böhm tree of K, are there (finite) branches with arbitrarily many symbols "a"?
( $\forall n \exists$ branch with $>n$ appearances of $a$ )

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Notice:
There may be no path with infinitely many „a".
Our property is not regular!!!
(regular properties can be checked e.g. by [Ong - LICS 2006])

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This is an instance of a more general problem, called diagonal problem or simultaneous unboundedness problem (SUP): Input: closed $\lambda$ Y-term K of sort o, set A of symbols Question: In the Böhm tree of K, are there (finite) branches with arbitrarily many appearances of every symbol from A?
( $\forall n \exists$ branch $\forall a \in A$ there are $>n$ appearances of $a$ on the branch)
This problem is decidable
[Hague, Kochems, Ong - POPL 2016],
[Clemente, P., Salvati, Walukiewicz - LICS 2016]

## Unboundedness - basic problem

Input: closed $\lambda$ Y-term K of sort 0 (i.e. infinite $\lambda$-term represented in a finite way)
Question 1: In the Böhm tree of K, are there finite branches with arbitrarily many symbols "a"?
( $\forall n \exists$ branch with $>n$ appearances of $a$ )
Solution - preparation:
We generalize the problem to nondeterministic terms
(aka nondeterministic recursion schemes).

- We add a new construct: $n d K^{\alpha} L^{\alpha}$
- We add reduction rules: nd $K L \rightarrow K$ and $n d K L \rightarrow L$
- Now there is no one unique Bohm tree Instead, we have a set of finite trees (normal forms) of a (closed, of sort 0 , potentially infinite) lambda-term $K$; we denote this set $\mathcal{L}(K)$


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- New question: are there trees in $\mathcal{L}(K)$ with arbitrarily many symbols "a"?
- Easy reduction from question 1 to the new question: replace every appearance of $a M N$ by $a$ ( $n d M N$ ); then $\mathcal{L}\left(K^{\prime}\right)$ is the set of branches $B T(K)$
- In particular all symbols in $K^{\prime}$ are of arity 0 and 1


## Unboundedness - basic problem

Input: nondeterministic closed $\lambda$ Y-term $K$ of sort o (symbols of arity 0 \& 1) Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"? How to solve it?
a term $K$ of order $m$, where $\xrightarrow{\text { step } 1}$ a term $K^{\prime}$ of order $m$ - 1 , where $\mathcal{L}(K)$ is a set of words written on branches
 in $\mathcal{L}\left(K^{\prime}\right)$ these words are written in leaves


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step 2 in $\mathcal{L}\left(K^{\prime}\right)$ these words are written in leaves
a term $K^{\prime \prime}$ of order $m-1$, where $\mathcal{L}\left(K^{\prime \prime}\right)$ has similar ${ }^{\star}$ words written on branches


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words written on branches

Repeat these steps until the order drops down to 0 , and solve the diagonal problem for a regular language.

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Input: nondeterministic closed $\lambda$ Y-term $K$ of sort o (symbols of arity 0 \& 1) Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"? a term $K^{\prime}$ of order $m-1$, where a term $K^{\prime \prime}$ of order $m-1, \quad$ step 2 in $\mathcal{L}\left(K^{\prime}\right)$ these words are where $\mathcal{L}\left(K^{\prime \prime}\right)$ has similar written in leaves

Example:

Idea:


1) Choose (nondeterministically) only one branch.
2) For every removed subtree with $a$, write a new $a$ just above.

## Unboundedness - basic problem

Input: nondeterministic closed $\lambda$ Y-term $K$ of sort o (symbols of arity 0 \& 1) Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"?
a term $K^{\prime \prime}$ of order $m-1, \quad$ step 2 in $\mathcal{L}\left(K^{\prime}\right)$ these words are where $\mathcal{L}\left(K^{\prime \prime}\right)$ has similar $\_$ words written on branches
a term $K^{\prime}$ of order $m-1$, where written in leaves

Example: $\quad a$

Idea:

1) Choose (nondeterministically) only one branch.
2) For every removed subtree with $a$, write a new $a$ just above.
3) The number of $a$ 's decreases at most logarithmically,
if the branch is chosen correctly (always go to the subtree with more $a^{\prime}$ s). We skip the details.

## Unboundedness - basic problem

Input: nondeterministic closed $\lambda$ Y-term $K$ of sort o (symbols of arity 0 \& 1) Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"? a term $K$ of order $m$, where step $1 \leadsto$ a term $K^{\prime}$ of order $m$ - 1 , where $\mathcal{L}(K)$ is a set of words written on branches in $\mathcal{L}\left(K^{\prime}\right)$ these words are written in leaves

[Asada, Kobayashi - ICALP 2016]

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Input: nondeterministic closed $\lambda$ Y-term $K$ of sort o (symbols of arity 0 \& 1) Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"? a term $K$ of order $m$, where step $1 \leadsto$ a term $K^{\prime}$ of order $m$ - 1 , where $\mathcal{L}(K)$ is a set of words written on branches in $\mathcal{L}\left(K^{\prime}\right)$ these words are written in leaves

$$
\left.\begin{array}{ll}
\text { Example: } & S \rightarrow A e c \\
& A x y \rightarrow a(A(b x)(d x)) \longrightarrow A \rightarrow \backsim A e \\
& A x y \rightarrow x
\end{array} \quad A \rightarrow a(\bullet A b)\right)
$$

Idea: 1) Observe that an argument of type o can be used at most once.

## Unboundedness - basic problem

Input: nondeterministic closed $\lambda Y$-term $K$ of sort o (symbols of arity 0 \& 1) Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"? a term $K$ of order $m$, where $\xrightarrow{\text { step } 1}$ a term $K^{\prime}$ of order $m$ - 1 , where $\mathcal{L}(K)$ is a set of words written on branches in $\mathcal{L}\left(K^{\prime}\right)$ these words are written in leaves

Example: $\begin{array}{ll}S \rightarrow A e c \\ A x y \rightarrow a(A(b x)(d x)) \longrightarrow \\ A x y \rightarrow x\end{array} \quad \begin{aligned} & S \rightarrow \backsim A e \\ & \\ & \\ & \\ & \\ & A \rightarrow \bullet a(\bullet A b)) \\ & A \rightarrow \bullet\end{aligned}$
Idea: 1) Observe that an argument of type o can be used at most once.
2) All arguments of type $o$ are dropped ( $\Rightarrow$ order decreases).
3) Every subterm $M N$ with $N$ of type $o$ can be replaced
a) either by $\cdot M N$ (when the argument is used in $M$ ),
b) or by $M$ (when the argument is ignored in $M$ ).

## Unboundedness - basic problem

Input: nondeterministic closed $\lambda \mathrm{Y}$-term $K$ of sort o (symbols of arity 0 \& 1)
Question: are there trees (paths) in $\mathcal{L}(K)$ with arb. many symbols "a"?
a term $K$ of order $m$, where step $1 \rightarrow$ a term $K^{\prime}$ of order $m-1$, where
$\mathcal{L}(K)$ is a set of words written on branches
in $\mathscr{L}\left(K^{\prime}\right)$ these words are written in leaves

Example: $S \rightarrow A e c \quad S \rightarrow \bullet A e$

$$
\left.\begin{array}{l}
A x y \rightarrow a(A(b x)(d x)) \longrightarrow \\
A x y \rightarrow x
\end{array}\right) A \rightarrow \begin{gathered}
A \rightarrow(\bullet A b)) \\
A \rightarrow \bullet
\end{gathered}
$$

Idea: 1) Observe that an argument of type $o$ can be used at most once.
2) All arguments of type $o$ are dropped ( $\Rightarrow$ order decreases).
3) Every subterm $M N$ with $N$ of type o can be replaced
a) either by $\bullet M N$ (when the argument is used in $M$ ),
b) or by $M$ (when the argument is ignored in $M$ ).
4) Additional work is required to choose correctly a) or b).

We use intersection types here.

## Type-guided transformation

Difficulty to overcome: given a nondeterministic closed $\lambda Y$-term $K$ of sort o, with symbols of arity $0 \& 1$ only, we want to say for every its subterm $M$ of order 0 whether $M$

- is "used in the generated tree", or (equivalently)
- is "responsible for creating the leaf of the generated tree"

We use intersection types to achieve this goal!

## Type-guided transformation

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Before we start:

- Notice that the considered property depends of the choice of the generated tree: maybe one tree uses $M$ to generate the leaf, and another tree does not.
- Thus, we first guess whether $M$ generates the leaf (nondeterministic choice), and then we make sure that the choice is respected.


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- Thus, we first guess whether $M$ generates the leaf (nondeterministic choice), and then we make sure that the choice is respected.

Let us first present the type system itself; then, we present the transformation.

## Type-guided transformation

For terms of sort o we need two types:

- this term is responsible for creating the leaf - denoted ( 1,0 );
- this term is not responsible for creating the leaf - denoted $(0,0)$.

Types ${ }^{0}=\{0,1\} \times\{0\}$

## Type-guided transformation

For terms of sort o we need two types:

- this term is responsible for creating the leaf - denoted (1,o);
- this term is not responsible for creating the leaf - denoted $(0,0)$.

Types $^{0}=\{0,1\} \times\{0\}$
Rules:

$$
\Gamma \vdash e:(1, o)
$$

$$
\frac{\Gamma \vdash K:(s, o)}{\Gamma \vdash a K:(s, o)}
$$

## Type-guided transformation

In general, for terms of sort $\alpha=\alpha_{1} \rightarrow \ldots \rightarrow \alpha_{k} \rightarrow 0$ :

- a type is of the form $\left(s, \Psi_{1} \rightarrow \ldots \rightarrow \Psi_{k} \rightarrow o\right)$, where $s \in\{0,1\}$, and $\Psi_{i} \subseteq$ Types $^{\alpha_{i}}$
- In other words: Types ${ }^{\alpha}=\{0,1\} \times P\left(\right.$ Types $\left.^{\alpha_{1}}\right) \times \ldots \times P\left(\right.$ Types $\left.^{\alpha_{1}}\right) \times\{o\}$ - $s$ says whether the term is responsible for creating the leaf
- $\Psi_{i}$ is the set of types needed for the $i$-th argument


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- $\Psi_{i}$ is the set of types needed for the $i$-th argument

Rules:

$$
\begin{array}{cc}
\frac{\Gamma \vdash e:(1, o)}{} & \frac{\Gamma \vdash K:(s, o)}{\Gamma \vdash a K:(s, o)} \\
\frac{\Gamma \vdash K: \tau}{\Gamma \vdash n d K L: \tau} & \frac{\Gamma \vdash L: \tau}{\Gamma \vdash n d K L: \tau}
\end{array}
$$

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- $s$ says whether the term is responsible for creating the leaf
- $\Psi_{i}$ is the set of types needed for the $i$-th argument

Rules:

$$
\begin{array}{lc}
\frac{\Gamma \vdash-(1, o)}{\Gamma \vdash e:(s, o)} \\
\frac{\Gamma \vdash K: \tau}{\Gamma \vdash a K:(s, o)} \\
\hline \Gamma \vdash n d K L: \tau & \frac{\Gamma \vdash L: \tau}{\Gamma \vdash n d K L: \tau} \\
\frac{\tau \in \Gamma(x)}{\Gamma \vdash x: \tau} &
\end{array}
$$

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Rules:

| $\overline{\Gamma \vdash e:(1, o)}$ | $\frac{\Gamma \vdash K:(s, o)}{\Gamma \vdash a K:(s, o)}$ |
| :--- | :---: |
| $\frac{\Gamma \vdash K: \tau}{\Gamma \vdash n d K L: \tau}$ | $\frac{\Gamma \vdash L: \tau}{\Gamma \vdash n d K L: \tau}$ |
| $\frac{\tau \in \Gamma(x)}{\Gamma \vdash x: \tau}$ | $\Gamma \vdash x \rightarrow \Psi] \vdash K:(s, \sigma)$ <br> $\Gamma \vdash \lambda x . K:\left(s^{\prime}, \Psi \rightarrow \sigma\right)$ <br> where $s^{\prime}=0, s=1$ if $\Psi$ contains a pair $(1, ?)$ <br> and $s^{\prime}=s$ otherwise |

## Type-guided transformation

Rules:

$$
\begin{aligned}
& \overline{\Gamma \vdash e:(1, o)} \\
& \frac{\Gamma \vdash K: \tau}{\Gamma \vdash n d K L: \tau} \\
& \frac{\tau \in \Gamma(x)}{\Gamma \vdash x: \tau}
\end{aligned}
$$

$$
\frac{\Gamma \vdash K:(s, o)}{\Gamma \vdash a K:(s, o)}
$$

$$
\frac{\Gamma \vdash L: \tau}{\Gamma \vdash n d K L: \tau}
$$

$$
\frac{\Gamma[x \rightarrow \Psi] \vdash K:(s, \sigma)}{\Gamma \vdash \lambda x \cdot K:\left(s^{\prime}, \Psi \rightarrow \sigma\right)}
$$

$$
\text { where } s^{\prime}=0, s=1 \text { if } \Psi \text { contains a pair }(1, ?)
$$

$$
\text { and } s^{\prime}=s \text { otherwise }
$$

$$
\frac{\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \quad \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \text { for each } i}{\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right)}
$$

## Type-guided transformation

It is not enough to derive types; we need to transform terms (basing on derived types)
We enrich type judgments:
$\Gamma \vdash M: \tau \Rightarrow N$
In environment $\Gamma$ the term $M$ can have type $\tau$ and then it should be transformed to term $N$.

## Type-guided transformation

Transformation:

$$
\begin{array}{cc}
\hline \Gamma \vdash e:(1, o) \Rightarrow e & \Gamma \vdash a K:(s, o) \Rightarrow \square a N \\
\frac{\Gamma \vdash K: \tau \Rightarrow N}{\Gamma \vdash n d K L: \tau \Rightarrow N} & \frac{\Gamma \vdash L: \tau \Rightarrow N}{\Gamma \vdash n d K L: \tau \Rightarrow N}
\end{array}
$$

Type-guided transformation
Transformation:

$$
\begin{array}{cc}
\hline \vdash e:(1, o) \Rightarrow e & \Gamma \vdash a K:(s, o) \Rightarrow \square a N \\
\frac{\Gamma \vdash K: \tau \Rightarrow N}{\Gamma \vdash n d K L: \tau \Rightarrow N} & \frac{\Gamma \vdash L: \tau \Rightarrow N}{\Gamma \vdash n d K L: \tau \Rightarrow N} \\
\frac{\tau \in \Gamma(x) \operatorname{ord}(x)=0}{\Gamma \vdash x: \tau \Rightarrow} & \frac{\tau \in \Gamma(x) \operatorname{ord}(x)>0}{\Gamma \vdash x: \tau \Rightarrow x_{\tau}}
\end{array}
$$

Arguments of order 0 disappear!

Type-guided transformation

## Transformation:

$$
\begin{array}{cc}
\Gamma \vdash e:(1,0) \Rightarrow e & \Gamma \vdash a K:(s, o) \Rightarrow \bullet a N \\
\frac{\Gamma \vdash K: \tau \Rightarrow N}{\Gamma \vdash n d K L: \tau \Rightarrow N} & \frac{\Gamma \vdash L: \tau \Rightarrow N}{\Gamma \vdash n d K L: \tau \Rightarrow N} \\
\frac{\tau \in \Gamma(x) \operatorname{ord}(x)=0}{\Gamma \vdash x: \tau \Rightarrow \bullet} & \frac{\tau \in \Gamma(x) \operatorname{ord}(x)>0}{\Gamma \vdash x: \tau \Rightarrow x_{\tau}}
\end{array}
$$

$$
\left.\frac{\Gamma[x \rightarrow \Psi] \vdash K:(s, \sigma) \Rightarrow N}{\Gamma \vdash \lambda x \cdot K:\left(s^{\prime}, \Psi \rightarrow \sigma\right) \Rightarrow N} \quad \operatorname{ord}(x)=0\right) \quad \begin{gathered}
\Gamma[x \rightarrow \Psi] \vdash K:(s, \sigma) \Rightarrow N \\
\text { where } \Psi=\left\{\tau_{1}, \ldots, \tau_{n}\right\} \text { and } s^{\prime}=0, s=1 \text { if } \quad \operatorname{ord}(x)>0 \\
\left.\Gamma \vdash \lambda x \cdot K:\left(s_{i}^{\prime}, \Psi \rightarrow \sigma\right) \Rightarrow \lambda x_{\tau_{i}} \cdot \cdots \cdot \lambda x_{\tau_{n}} \cdot N\right) \text { for some } i \text {, and } s^{\prime}=s \text { otherwise }
\end{gathered}
$$

Arguments of order 0 disappear!

Type-guided transformation
Transformation:

$$
\operatorname{ard}(x)>0
$$

$$
\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \Rightarrow N \quad \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \Rightarrow M_{i} \text { for each } i
$$

$$
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N M_{1} \ldots M_{n}
$$

Type-guided transformation

## Transformation:

$$
\operatorname{ard}(x)>0
$$

$$
\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \Rightarrow N \quad \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \Rightarrow M_{i} \text { for each } i
$$

$$
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N M_{1} \ldots M_{n}
$$

$$
s_{1}+\ldots+s_{n}=0, \operatorname{ord}(x)=0
$$

$$
\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \Rightarrow N \quad \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \Rightarrow M_{i} \text { for each } i
$$

$$
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N
$$

$$
s_{j}=1, \operatorname{ord}(x)=0
$$

$$
\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \Rightarrow N \quad \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \Rightarrow M_{i} \text { for each } i
$$

$$
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N M_{j}
$$

## Type-guided transformation

## Transformation:

$$
\operatorname{ord}(x)>0
$$

$$
\begin{array}{cc}
\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \Rightarrow N & \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \Rightarrow M_{i} \text { for each } i \\
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N M_{1} \ldots M_{n} \\
s_{1}+\ldots+s_{n}=0, & \operatorname{ord}(x)=0 \\
\Gamma \vdash K:\left(s_{K},\left\{\left(s_{1}, \sigma_{1}\right), \ldots,\left(s_{n}, \sigma_{n}\right)\right\} \rightarrow \sigma\right) \Rightarrow N & \Gamma \vdash L:\left(s_{i}, \sigma_{i}\right) \Rightarrow M_{i} \text { for each } i
\end{array}
$$

$$
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N
$$

$$
s_{j}=1, \operatorname{ord}(x)=0
$$

$$
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$$

$$
\Gamma \vdash K L:\left(s_{K}+s_{1}+\ldots+s_{n}, \sigma\right) \Rightarrow N M_{j}
$$

$M_{1}, \ldots, M_{n}$ are all terms such that $\Gamma \vdash K: \tau \Rightarrow M_{i}$

$$
\Gamma \vdash K: \tau \Rightarrow n d M_{1}\left(\ldots\left(n d M_{n-1} M_{n}\right) \ldots\right)
$$

## We have seen so far:

- A type system describing behavior of a (co-trivial) alternating tree automaton
- A type system that helps in transforming path-generating lambda-terms to tree-generating lambda-terms of order lower by one.
$\rightarrow$ This allows to solve the unboundedness problem
Next:
- A type system that solves the unboundedness problem directly.


## Unboundedness directly via intersection types - idea



- Böhm tree of K

path $P$ in Böhm tree
derivation for K approximating the number of , $\mathrm{a}^{2}$ on P
single letter: [P. - ITRS 2016] multiple letters: [P. - FSTTCS 2017]

Property to describe (unboundedness): In the Böhm tree of K, are there finite paths with arbitrarily many symbols "a"?

## Unboundedness directly via intersection types - idea


derivation for K approximating the number of „a" on $P$

Easy to say using intersection types:

- which „a" of K will appear in the Böhm tree


## Unboundedness directly via intersection types - idea



- Böhm tree of $K$

path $P$ in Böhm tree derivation for K
approximating the $\triangleleft$ number of „a" on $P$

Quite easy to say using intersection types:

- which „a" of K will appear on P in the Böhm tree


## Unboundedness directly via intersection types - idea


path $P$ in Böhm tree approximating the $\longleftarrow$ number of „a" on P

Quite easy to say using intersection types:

- which „a" of K will appear on P in the Böhm tree

Difficulty:

- single „a" of K may result in many „a" on P $\left(\lambda y \cdot y\left(y b^{0}\right)\right) \cdot a^{0 \rightarrow 0}$

Idea of solution:

- detect (and count) places where variable containing „a" is duplicated


## Intersection types

Solution: type derivations are labeled by flags and markers.
Intersection types refining sort o:

$$
\mathcal{T}^{\mathrm{o}}=\{(\mathrm{F}, \mathrm{M}, \mathrm{o})\}
$$

flags used in the derivation
markers used in the derivation
(for each order m we have flags of order m, and a marker of order m)

## Intersection types

Solution: type derivations are labeled by flags and markers.
Intersection types refining sort $\alpha=\alpha_{1} \rightarrow \ldots \rightarrow \alpha_{k} \rightarrow 0$ :

$$
\mathcal{T} \alpha=\left\{\left(F, M, T_{1} \rightarrow \ldots \rightarrow T_{k} \rightarrow 0\right)\right\}
$$

flags used in the derivation

$$
\text { sets of types refining } \alpha_{1}, \ldots, \alpha_{k}
$$

markers used in the derivation
(for each order m we have flags of order m, and a marker of order m)

Only finite derivations!
No weakening! (every type for an argument have to be used)
For every sort there are only finitely many types refining it!

Flags \& markers
one marker of order 0 (= end of path) flags of order 1 (= „a" on the path)

Flags \& markers
one marker of order 0 (= end of path) flags of order 1 (= „a" on the path)


Flags \& markers
one marker of order 0
flags of order 1
the type system ensures that a variable with marker is used exactly once!

number of order-1 flags unchanged!

Flags \& markers
one marker of order 0 flags of order 1
one marker of order 1

number of order-1 flags unchanged!

## Flags \& markers

one marker of order 0
flags of order 1
one marker of order 1
flags of order 2 - places on the path to order-1 marker having a descendant with order-1 flag

number of order-1 flags unchanged!

## Flags \& markers

one marker of order 0
flags of order 1
one marker of order 1
flags of order 2 - places on the path to order-1 marker having a descendant with order-1 flag
for some location of order-1 marker

number of order-1 flags unchanged!

Flags \& markers


## Flags \& markers



We put all the flags \& markers in derivations for K.
The number of order-n flags approximates the number of „a" on some path in the Böhm tree of K .
there exist derivations for K with arbitrarily many order-n flags
in the Böhm tree of $K$ there exist paths with arbitrarily many „a"
easy to decide

Intersection types
Intersection types refining sort $\alpha=\alpha_{1} \rightarrow \ldots \rightarrow \alpha_{k} \rightarrow 0$ :

$$
\mathcal{T}^{\alpha}=\left\{\left(\mathrm{F}, \mathrm{M}, \mathrm{~T}_{1} \rightarrow \ldots \rightarrow \mathrm{~T}_{\mathrm{k}} \rightarrow 0\right)\right\}
$$

flags used in the derivation

$$
\text { sets of types refining } \alpha_{1}, \ldots, \alpha_{k}
$$

markers used in the derivation
4
(for each order $m$ we have flags of order $m$, and a marker of order m)
Type judgments: $\Gamma \stackrel{ }{ }^{\complement} K: \tau$, where $c$ is the number of flag of order $n$

- Only finite derivations!
- No weakening! (every type for an argument have to be used)
- Some types are idemponent (when no marker is present) - can be used arbitrarily many times
- Some types are not idempotent (when a marker is present) - can be used only once
- But every kind of marker can be placed only in one place.
- In effect, for every sort there are only finitely many types refining it!


## Advantages of the approach via intersection types:

- Better complexity
- We can obtain a reflection property:

Given a lambda-term K (closed, of sort o), we can compute a lambda-term $K^{\prime}$ such that $B T\left(K^{\prime}\right)$ is an enriched version of $B T(K)$ namely, for every node $v$ of $\mathrm{BT}\left(\mathrm{K}^{\prime}\right)$ we have an additional bit saying whether there are finite paths with arbitrarily many symbols "a" starting in $v$.

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- Consequence: We can decide the WMSO+U logic on those Bohm trees - given a sentence $\phi$ of WMSO+U, and a lambda-term K (closed, of sort o), we can decide whether $\phi$ holds in BT(K). [P. - STACS 2018]


## WMSO+U

## MSO+U logic (introduced by Bojańczyk in 2004)

MSO+U extends MSO by the following „U" quantifier:

## UX. $\phi(\mathrm{X})$

$\phi(X)$ holds for sets of arbitrarily large size

$$
\forall n \in \mathbb{N} \exists X(n<|X|<\infty \wedge \phi(X))
$$

This construction may be nested inside other quantifiers, and $\phi$ may have free variables other than X .

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$$

This construction may be nested inside other quantifiers, and $\phi$ may have free variables other than X .

We consider Weak MSO+U (quantification over finite sets only):

$$
\exists X \rightarrow \exists_{\mathrm{fin}} X
$$

e.g. we can express that there exist paths with arbitrarily many „a"

Thank you!

