

Reconfiguration and graph structure

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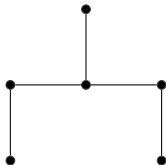
- Reconfiguration – what & why
- Bounded pathwidth: PSPACE-hard
- Claw-free: P

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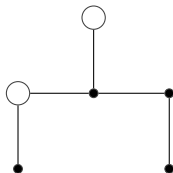
Reconfiguration – an example

Token sliding



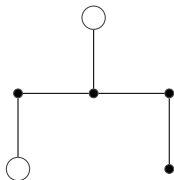
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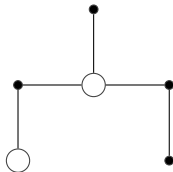
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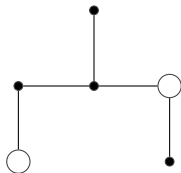
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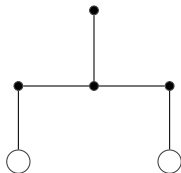
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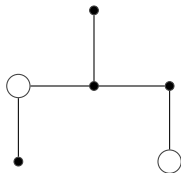
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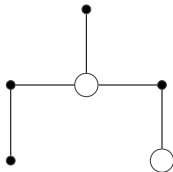
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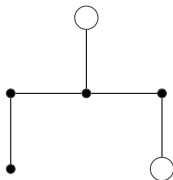
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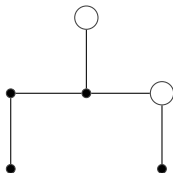
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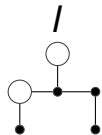
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Reconfiguration – an example

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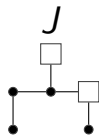




TOKEN SLIDING REACH.

Input: G, I, J

Question: $I \leftrightarrow_{\text{TS}} J?$



a TS-sequence
 I_0, \dots, I_m with
 $I_0 = I$ and $I_m = J$

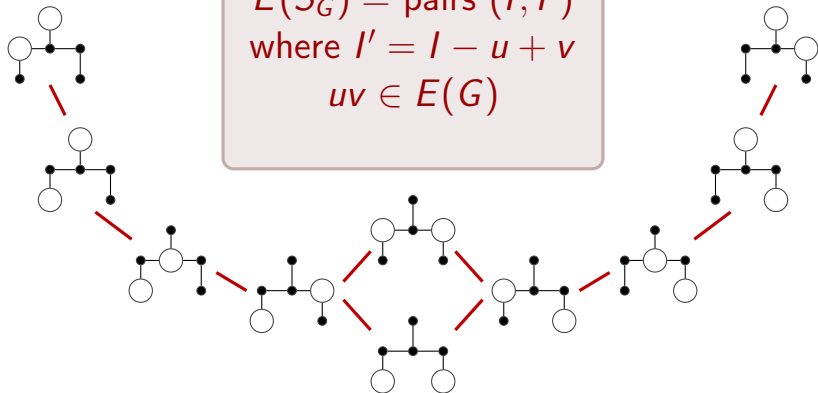


$V(S_G) = \text{solutions}$
 $= \text{independent sets}$
 $\text{of size } k$



Solution graph

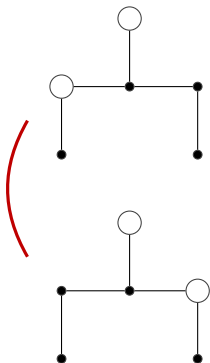
$E(S_G) = \text{pairs } (I, I')$
where $I' = I - u + v$
 $uv \in E(G)$



Independent Set – TS, TJ and TAR

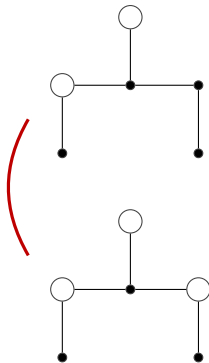
Token Jumping

$$I' = I - u + v \text{ for } \underline{\text{any}} \ u, v$$



Token Addition & Removal

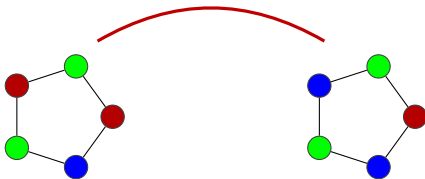
$$I' = I \pm v \text{ and } |I| \geq k$$



k -Recoloring

$k = 3$

$V = k$ -colorings, $E =$ switching one color



Reconfiguration – why

- Explore the solution space
- Practical problems(?) and puzzles
- Unexpected, nontrivial results

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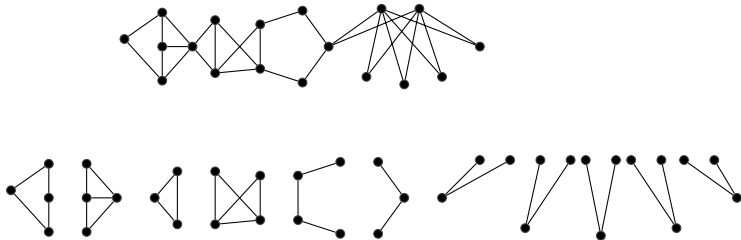
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- Practical problems(?) and puzzles
- Unexpected, nontrivial results

Theorem [Cereceda, van den Heuvel, Johnson 2011]

3-recoloring is P.

Pathwidth

$$p = 3$$



Take a sequence of graphs on $\leq p + 1$ vertices.
Glue any vertices from two consecutive graphs.

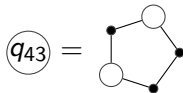
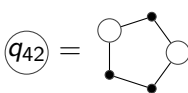
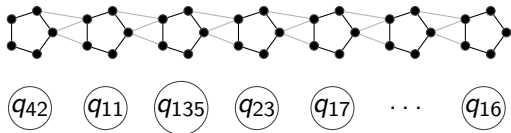
- $\text{pathwidth} \leq p \implies \text{treewidth} \leq p$
- pathwidth is treewidth without branching/merging steps.
- MAX INDEPENDENT SET, k -COLORING, ...
are P in bounded pathwidth.
- so is counting solutions, extensions to solutions, ...

Pathwidth

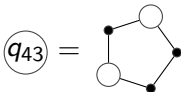
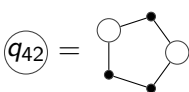
Why we thought reconfiguration is P?

- MAX INDEPENDENT SET, k -COLORING, ... are P in bounded pathwidth.
- so is counting solutions, extensions to solutions, ...
- TOKEN JUMPING, k -RECOLORING is P in trees.
- TOKEN JUMPING has a dynamic algorithm in cographs.

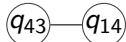
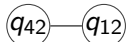
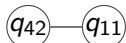
Why is reconfiguration hard?



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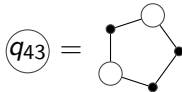
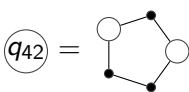


Rules:

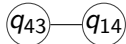
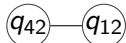
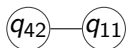


...

Why is reconfiguration hard?



Rules:



...

If we can construct enough states and any set of rules,
we can simulate a Turing Machine's tape.

String Rewriting Systems

A *string rewriting system* is a pair (Σ, R)

Σ – alphabet

$R \subseteq \Sigma^* \times \Sigma^*$ – set of rules

Apply a rule (α, β) to a word u by replacing a subword α by β .

$u \rightsquigarrow_R v$: = u can be transformed into v by applying rules.

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Word problem

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WORD PROBLEM for (Σ, R)

Input: $u, v \in \Sigma^*$

Question: $u \rightsquigarrow_R v$?

Theorem [Post 1947]

There is a SRS whose word problem is undecidable.

Also known as semi-Thue systems, finitely presented monoids, unrestricted grammars.

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symmetric SRS $:= (\alpha, \beta) \in R \iff (\beta, \alpha) \in R$

balanced SRS $:= |\alpha| = |\beta|$ for all $(\alpha, \beta) \in R$

2-balanced SRS $:= |\alpha| = |\beta| = 2$ for all $(\alpha, \beta) \in R$

balanced \implies word problem can be solved in polynomial space.

a variant of Post's theorem

There is a 2-balanced symmetric SRS whose word problem is PSPACE-complete.

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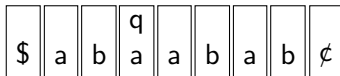
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a Turing Machine is an SRS

| | | | | | | | | |
|----|---|---|---|---|---|---|---|---|
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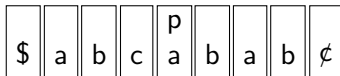
a Turing Machine is an SRS

$$\delta(q, a) = (p, c, \rightarrow)$$



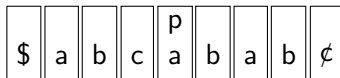
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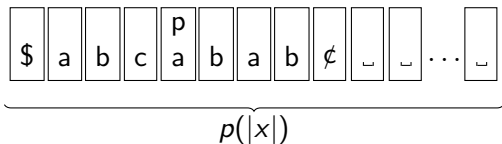
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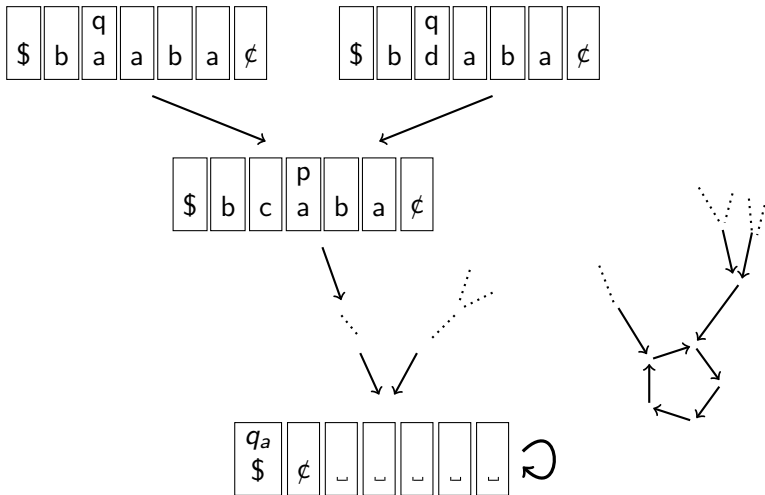
$$\left(\begin{array}{|c|} \hline q \\ \hline a \\ \hline \end{array}, \begin{array}{|c|} \hline \\ \hline c \\ \hline \end{array}, \begin{array}{|c|} \hline p \\ \hline a \\ \hline \end{array} \right) \in R$$

a PSPACE Turing Machine is a balanced SRS

$$\delta(q, a) = (p, c, \rightarrow)$$



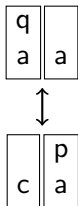
a deterministic Turing Machine is a symmetric SRS



Simplifying the system further

Lemma

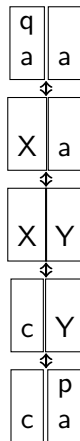
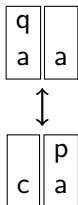
There is a 2-balanced symmetric SRS (Σ, R) whose word problem is PSPACE-complete.



Simplifying the system further

Lemma

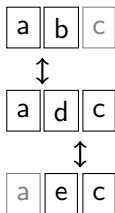
There is a 2-balanced symmetric SRS (Σ, R) such that for all $\{a_1 a_2, b_1 b_2\} \in R$ either $a_1 = b_1$ or $a_2 = b_2$ whose word problem is PSPACE-complete.



Simplifying the system even further

Lemma

There is a 2-balanced symmetric SRS (Σ, R) such that for all $\{a_1 a_2, b_1 b_2\} \in R$ either $a_1 = b_1$ or $a_2 = b_2$ whose word problem is PSPACE-complete.



Let $H = (\Sigma, R)$ where $R \subseteq \Sigma \times \Sigma$ is a relation between symbols.
 H -word := consecutive symbols are related = directed walk in H

H -WORD RECONFIGURATION

Input: $u, v \in \Sigma^n$ – two H -words of equal length

Question: Is there a sequence of H -words between u and v such that consecutive H -words differ in only one symbol?

H-WORD RECONFIGURATION is hard

Let $(\{a, b, c, \dots\}, \{\{a_1 b_1, a_1, c_1\}, \dots\})$ be our SRS.

Let $\Sigma =$

pair symbols: $ab, ac, \dots, \sqcup a, \sqcup b, \dots$

special symbols: $\$, \phi, x_1, \dots$



Allow:



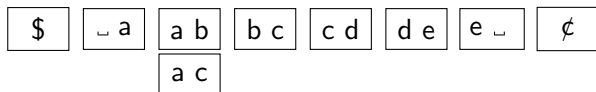
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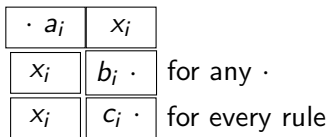
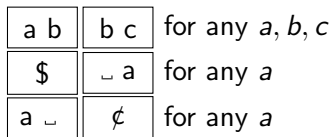
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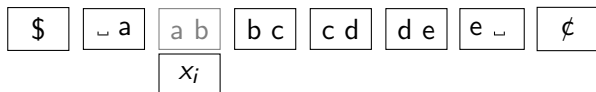
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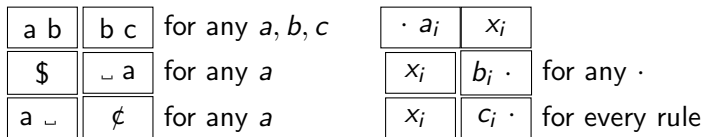
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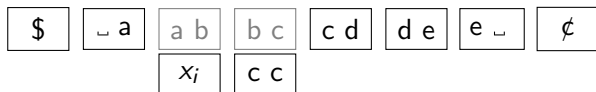
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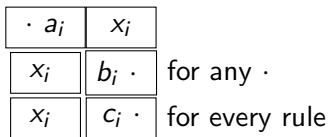
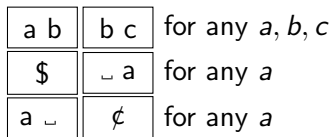
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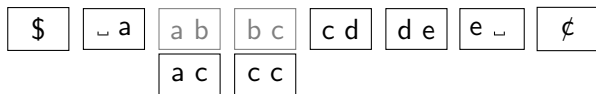
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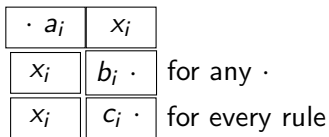
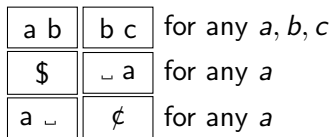
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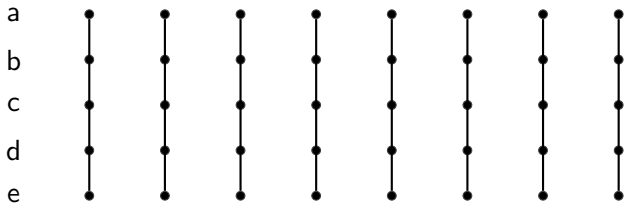
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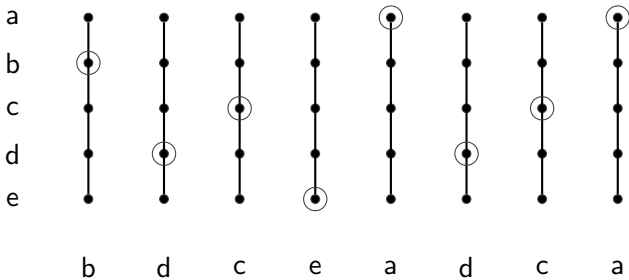
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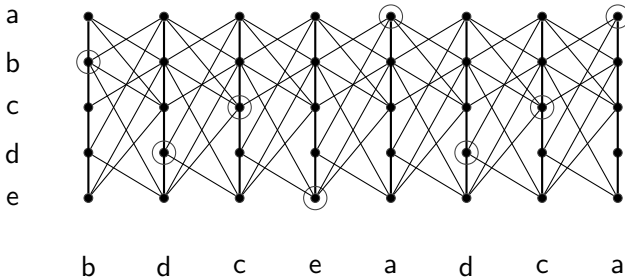
Token Sliding and Jumping



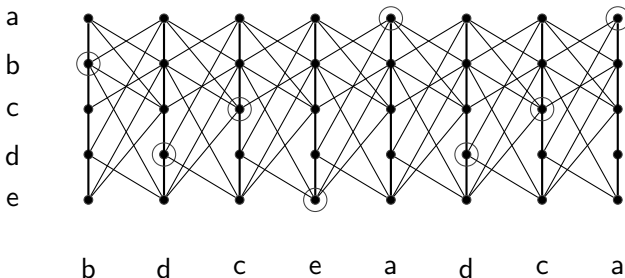
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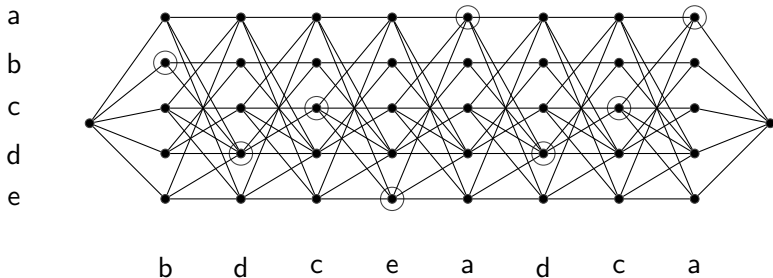


Token Sliding and Jumping



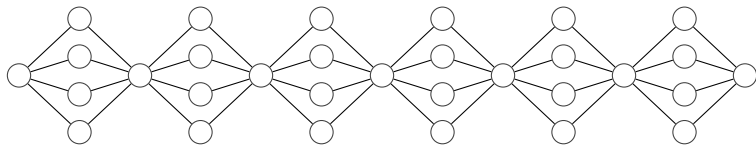
There is a p such that **TOKEN SLIDING** and **TOKEN JUMPING** are PSPACE-complete on graphs of pathwidth $\leq p$.

Shortest Path

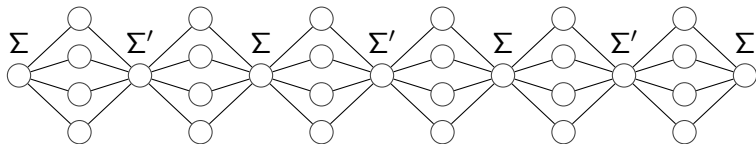


There is a p such that SHORTEST PATH RECONFIGURATION is PSPACE-complete on graphs of pathwidth $\leq p$.

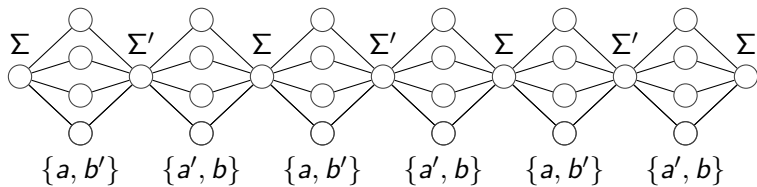
Let $H = (\Sigma, R)$, let Σ' be a copy of Σ .



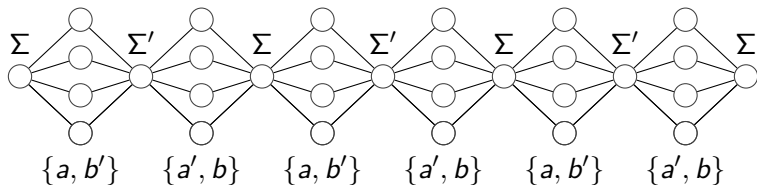
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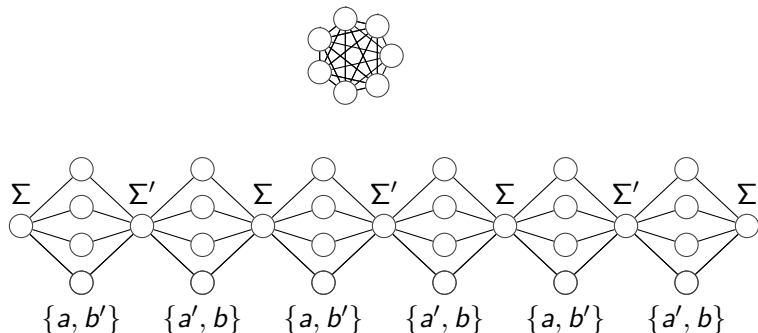


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There are integers k, p such that k -LIST-RECOLORING is PSPACE-complete on chains of p -onions.

Just add a k -clique, give it a fixed coloring, replace lists with edges.



There are integers k, p such that k -RECOLORING is PSPACE-complete on graphs of pathwidth $\leq p$.

- Many reconfiguration problems are PSPACE-complete.
- But not all. Clique reconfiguration is trivial:
all cliques can be listed in $\mathcal{O}(2^p n)$ time in treewidth $\leq p$.
- Is connectivity hard?
- Parameterized hardness – what parameter?

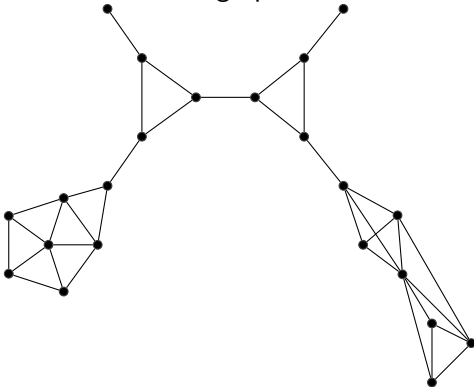
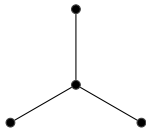
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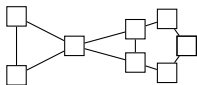
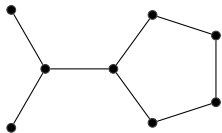
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Claw-free graphs

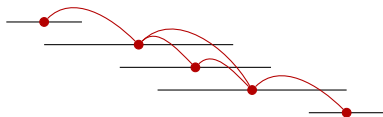
Claw-free := no claw as an induced subgraph.



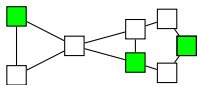
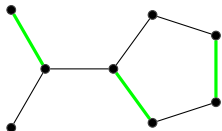
Line graphs



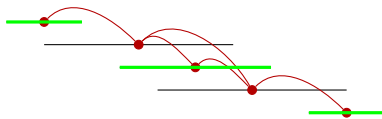
Proper interval graphs



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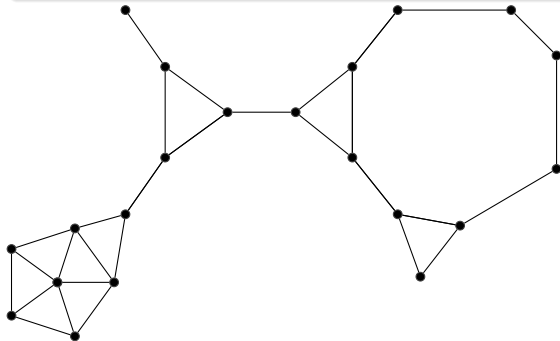


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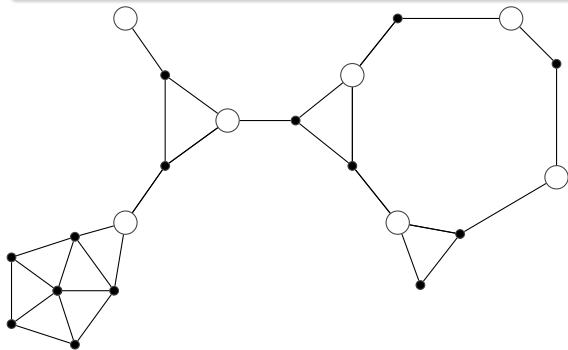
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Let I, J be independent sets in a connected claw-free G .
If $G[I \Delta J]$ contains no cycles, then $I \leftrightarrow_{\text{TS}} J$.



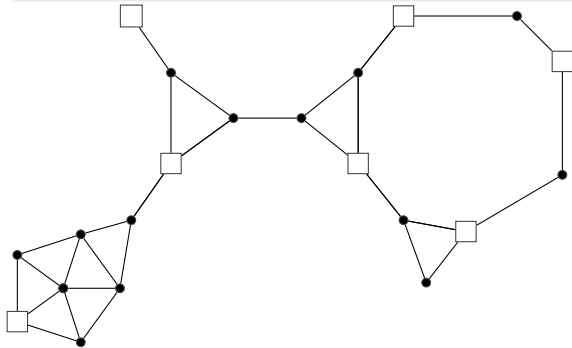
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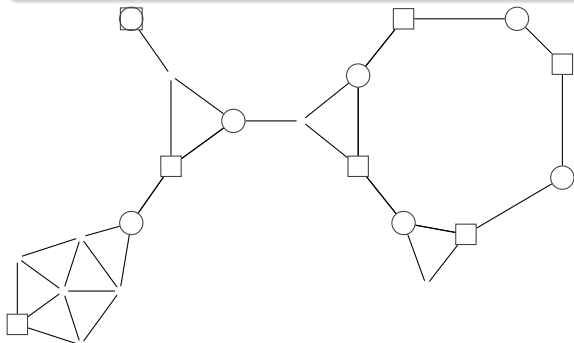
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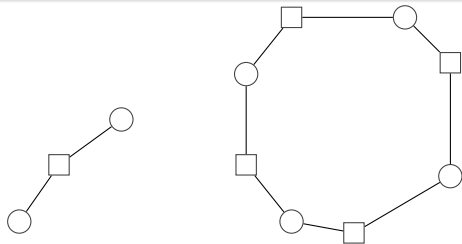
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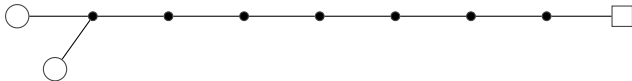
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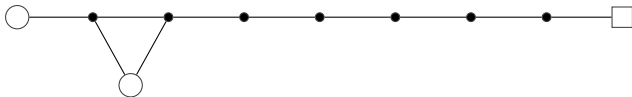
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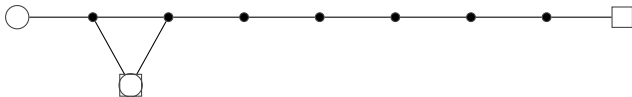
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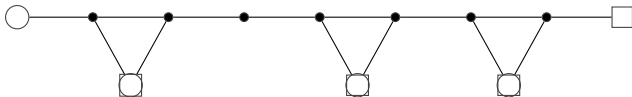
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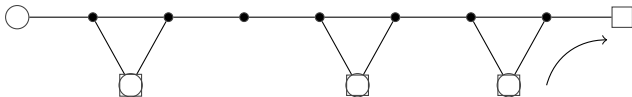
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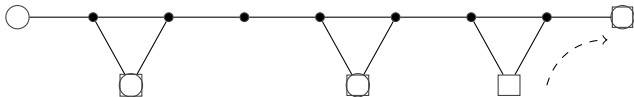
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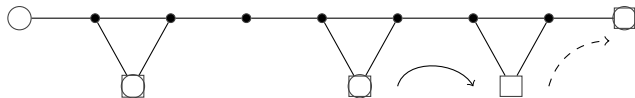
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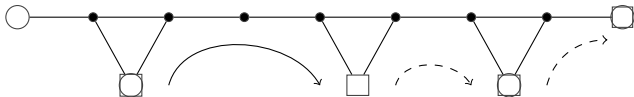
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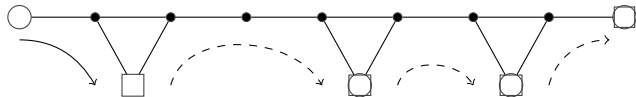
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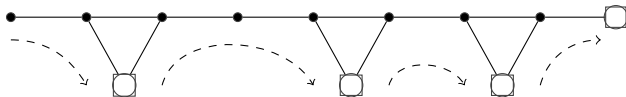
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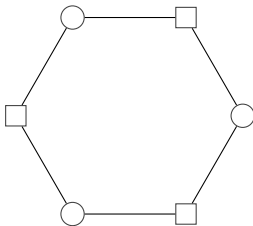
The symmetric difference between I and $I - u + v$ has no cycles!

Corollary

In a connected graph G , $I \leftrightarrow_{\text{TS}} J$ if and only if $I \leftrightarrow_{\text{TJ}} J$.

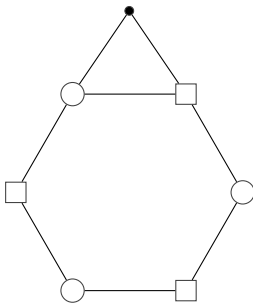
Breaking cycles

NO instance – can't move any token.



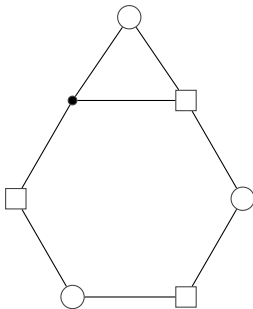
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YES instance – we can break the cycle.



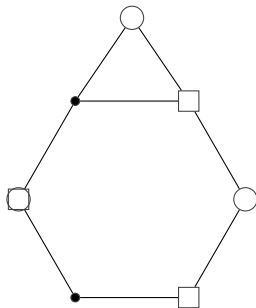
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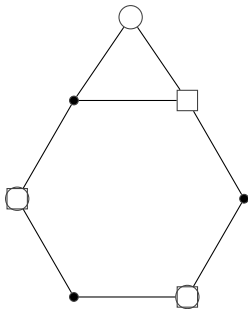
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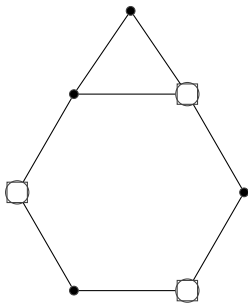
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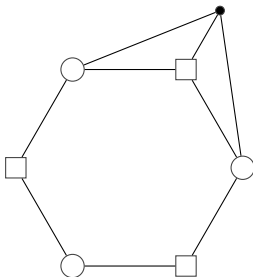
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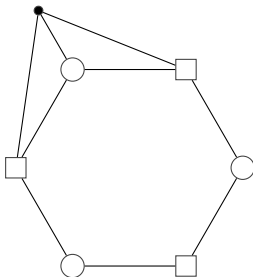
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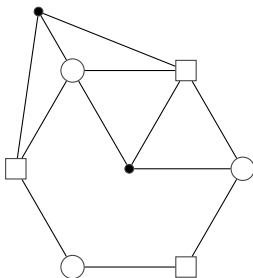
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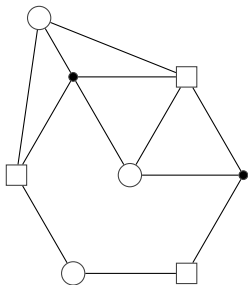
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Internal and external

$\square \cap C$ – target vertices on the cycle.

Internal vertex := has exactly 2 neighbors in $\square \cap C$.

Breaking vertex := has exactly 1 neighbor in $\square \cap C$.

External vertex := has exactly 0 neighbors in $\square \cap C$.

$V = \text{internal} \uplus \text{breaking} \uplus \text{external} \uplus (\square \cap C)$

Observation

In any token sliding sequence, a move is the first to break the cycle iff it is the first to move a token to a breaking vertex.

There are no edges between external and internal vertices!

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S ends with an internal-to-breaking move.

Any move before that is internal-to-internal or external-to-external.

External moves are completely independent from internal moves.

Only one move is needed to make the last vertex free.

So we can forget all moves of the other type.

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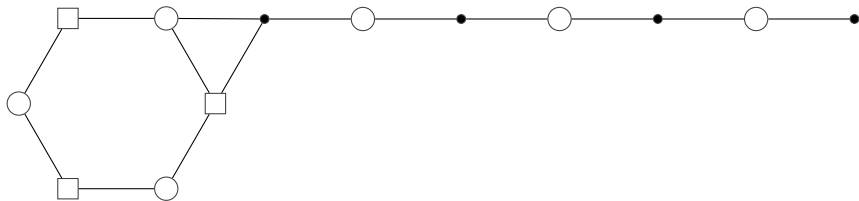
Resolving all cycles

Let S be a shortest sequence breaking the cycle.
 S has only external moves or only internal moves.

Then I can be reconfigured to $I\Delta C$.
So if each is breakable, then we can 'turn' them one by one.

Thus it's enough to ask for each cycle independently: is it externally or internally breakable?

External case



External case

A cycle is externally resolvable iff there is an alternating path as above.

Warning: finding such a path is not easy! [Minty 1980]

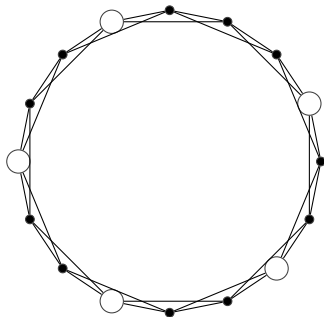
Internal case

Example

$$V = \{1, \dots, nk + 1\}$$

edges go $\pm 1, \dots, \pm(k - 1)$

$$n = 5, k = 3$$



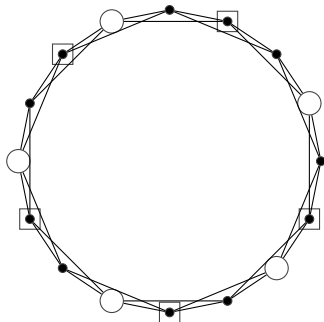
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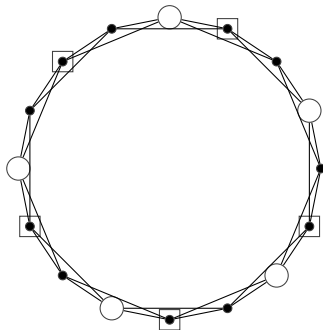
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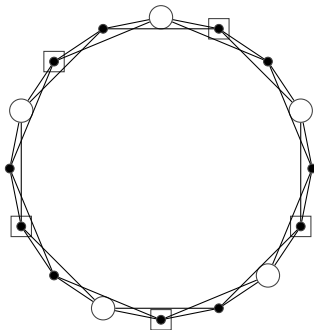
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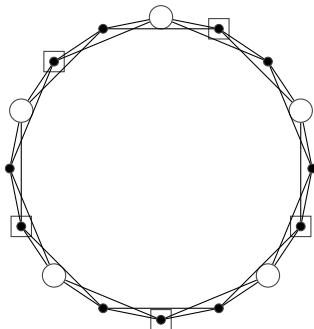
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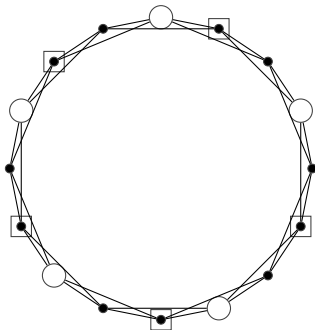
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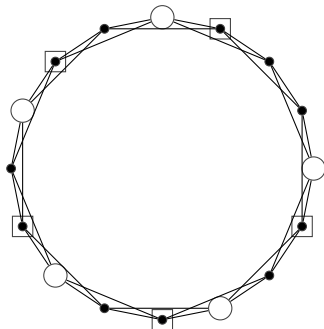
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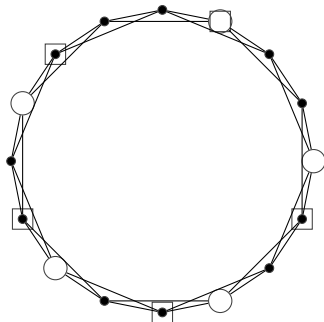
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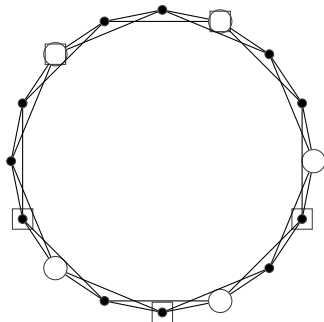
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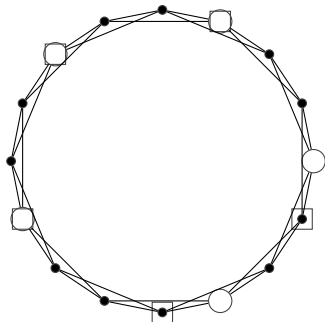
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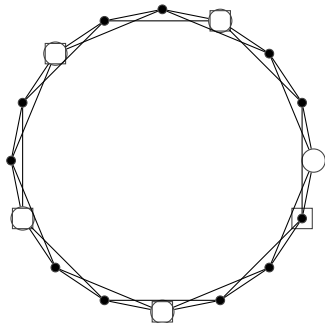
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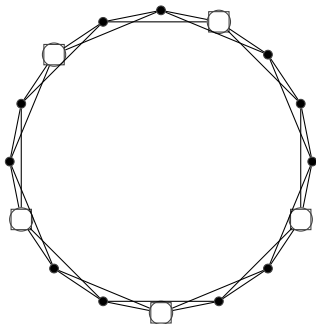
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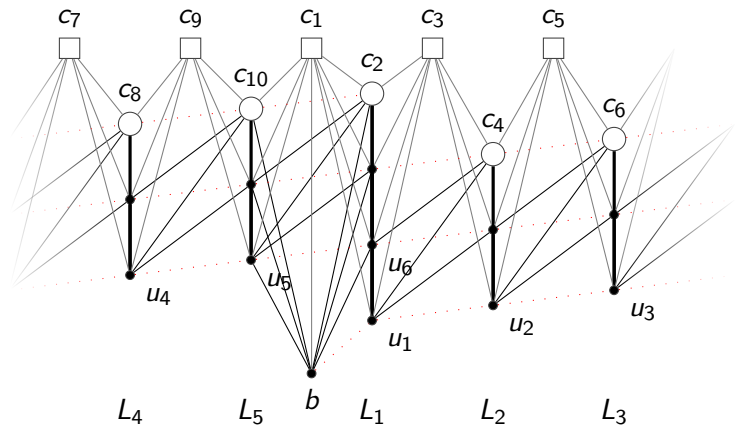
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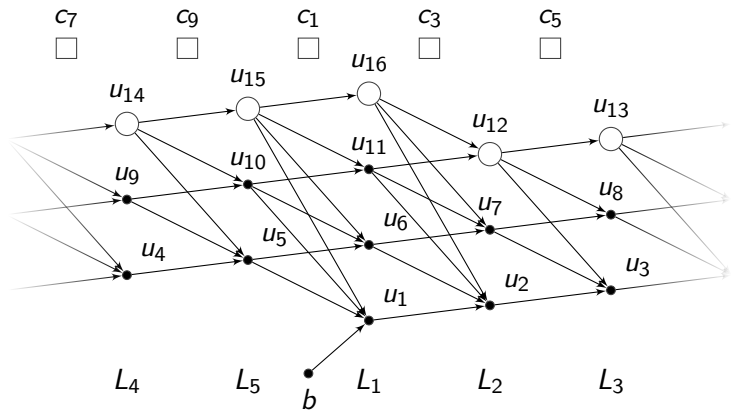
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Thank you!
Questions?