

Regular tree languages in low levels of Wadge Hierarchy*

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Abstract

In this article we provide effective characterisations of regular languages of infinite trees that belong to the low levels of Wadge Hierarchy. More precisely we prove decidability for each of the finite levels of the hierarchy; for the class of the Boolean combinations of open sets $\text{BC}(\Sigma_1^0)$ (i.e. the union of the first ω levels); and for the Borel class Δ_2^0 (i.e. for the union of the first ω_1 levels).

This is an extended version of [BP12] and contains a correction of a proof from [FM14].

1 Introduction

The space of all infinite trees over a finite alphabet is equivalent to the Cantor space. Therefore, it makes sense to ask if a language of infinite trees — in our setting, we are interested in regular ones — is for instance open, Borel, or of specific descriptive set theoretical complexity. As witnessed by a number of conjectures and results [Sku93, Mur08b, FMM16, SW16, CMS17], topologically defined classes, often have natural automata counterparts. For instance, in the case of ω -words, the structure of parity *deterministic* automata (defined in terms of Wagner hierarchy) are strictly connected to Wadge Hierarchy, see [Wag79]. In the case of regular tree languages that are Borel, there is a strong connection between the *Borel rank* and priorities used by *weak alternating automata* (see [DM07] and [CMS17]).

Algorithms that determine if a regular language belongs to a subclass \mathcal{L} of regular languages are known as *effective characterisation*. Typically, an effective characterisation

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comes with a structural description of automata (or algebras) that recognise languages from \mathcal{L} . The seminal example is Schützenberger’s Theorem [Sch65], which says that a regular language is star-free if and only if it is recognised by an aperiodic semigroup. For other examples about finite words, see the survey [PZ15], which discusses effective characterisations for the low levels of the quantifier alternation hierarchy. For examples on ω -words, including topologically motivated ones, see [PP04]. For examples on finite trees, see e.g. [BW08] or a survey [Boj10].

Most of the known effective characterisations speak about languages of words (finite or infinite) or finite trees. The case of regular languages of infinite trees seems to be much more difficult, mainly because of the inherent non-determinism needed to recognise these languages [Blu11, BS13]. Thus, the known examples of effective characterisations are usually limited either to simple classes of sets (e.g. open sets [KW02, Wal02a]) or to restricted classes of languages given as the input (e.g. recognised by deterministic automata [Mur08a]).

In this work we focus on the very low levels of Borel Hierarchy: the class $\text{BC}(\Sigma_1^0)$ of Boolean combinations of open sets; and the self-dual class Δ_2^0 at the second level of the hierarchy. We use algebraic methods for infinite trees, i.e. our characterisations are defined by equations which must be satisfied by the syntactic algebra of a language.

This paper continues a line of work aimed at understanding the algebraic theory of regular languages of infinite trees [Blu11, BS13, BI09]. The obtained results show that even simple algebras (i.e. not strong enough to distinguish all regular languages or not *complete*, see Subsection 15.1) can be adequate for characterising classes of languages that are sufficiently simple. This opens the possibility that a bit more complex algebraic structure (but a priori not complete) might be enough for the successive levels of Borel Hierarchy, like Δ_3^0 .

Related work First, a series of works [NW05, NW03, Mur08b, FMM16] provide effective characterisations for almost all natural classes when the input is restricted to deterministic automata or their dualised variant — the so-called game automata. These results are based on the *pattern method* saying that the language recognised by a deterministic automaton is complex if and only if the automaton itself contains a *complex pattern*. Unfortunately, there is no known method how to extend these methods to languages involving non-determinism.

Recently, certain new techniques have been developed that show how to deal with non-determinism of regular languages of infinite trees. The first result of this kind is the reduction of the general Rabin-Mostowski index problem to a certain boundedness problem for cost automata [CL08]. Unfortunately, the latter problem is not known to be decidable. However, the game approach used in the above reduction turned out to work for the lowest indices [CKLV13]. By adopting these techniques, the authors of [SW16] provided a characterisation of Borel sets among languages recognisable by Büchi automata. A similar approach used in [CMS17] provided an effective characterisation of the Borel class Π_2^0 among all regular tree languages. An effective (but not algebraic) characterisation of the class Δ_2^0 follows directly from that result, however it does not solve the more difficult

case of $\text{BC}(\Sigma_1^0)$.

The paper is based on the conference papers [BP12] and [FM14], see Conclusions for a discussion on relations between the new paper and the original ones.

Structure The paper is structured as follows. In Section 2 we recall some basic notions about words and trees and we set the notation used throughout the article. In Section 3 we recall all the topological notions that are used in this work. Section 4 provides a precise overview of the results of the paper, based on the previously introduced topological notions. In Section 5 we describe a topological game that will be used to obtain effective characterisations of the levels of Wadge Hierarchy up to ω . In Section 6 we introduce the infinite variant of this game, aimed at characterising the class Δ_2^0 . In Section 7 we start to climb up Wadge Hierarchy and we prove decidability of each of the first ω levels of it (i.e. all the finite levels). In Section 8 we present the algebraic structure used in this paper to represent regular languages of infinite trees. In Section 9 we state Theorem 9.1 characterising the class $\text{BC}(\Sigma_1^0)$ in terms of equations defined in the syntactic algebra. The proof of this theorem is spread across Sections 10, 11, 12 and 13. Finally, in Section 14 we state and prove Theorem 14.1 that uses the algebraic tools from Theorem 9.1 to characterise the Borel class Δ_2^0 .

2 Basic notions

In this section we recall some basic notions about words and trees, that constitute the general framework of this paper.

If f is a function, by $\text{dom}(f)$ we denote the domain of f . We denote by ω the first infinite ordinal and by ω_1 the first uncountable ordinal.

Consider a non-empty set A . We call A an *alphabet* if A is finite. Let A^n be the space of the functions of the form $s: \{0, \dots, n-1\} \rightarrow A$. Such a function can be represented as a word $s = (s(0), \dots, s(n-1)) = s_0 \dots s_{n-1}$ over A . If $s = s_0 s_1 \dots s_{n-1}$ then we say that n is the *length* of s , and we denote it by $lt(s)$. The empty word is denoted by ϵ , i.e. $lt(\epsilon) = 0$ and $A^0 = \{\epsilon\}$. By $A^{\leq n}$ we denote the set of words over A of length at most n , i.e. $A^{\leq n} \stackrel{\text{def}}{=} A^0 \cup A^1 \cup \dots \cup A^n$. We denote by A^* the set of all the finite words over A : $A^* \stackrel{\text{def}}{=} \bigcup_{n \in \omega} A^n$. By A^ω we denote the set of infinite words over the alphabet A , formally the elements of this space are functions of the form $\alpha: \omega \rightarrow A$. Such a function can be represented as an infinite sequence $(\alpha(0), \alpha(1), \alpha(2), \dots) = \alpha_0 \alpha_1 \alpha_2 \dots$. Finally, we set $A^{\leq \omega} \stackrel{\text{def}}{=} A^* \cup A^\omega$.

If $\alpha \in A^{\leq \omega}$ and $n \in \omega$, we define $\alpha \upharpoonright n \stackrel{\text{def}}{=} \alpha_0 \alpha_1 \dots \alpha_{n-1} \in A^n$ (if α is finite this definition makes sense only if $n \leq lt(\alpha)$). We say that $s \in A^*$ is a *prefix* of $\alpha \in A^{\leq \omega}$ if $s = \alpha \upharpoonright n$ for some n ; in symbols $s \preceq \alpha$. We write $s \prec \alpha$ if $s \preceq \alpha$ but $s \neq \alpha$. The *concatenation* of $s, t \in A^*$, where $s = s_0 \dots s_{n-1}$ and $t = t_0 \dots t_{m-1}$, is the word $s \hat{\ } t = st = s_0 \dots s_{n-1} t_0 \dots t_{m-1}$. We can also consider the concatenation $s \hat{\ } \alpha$ of a finite word s and an infinite word α defined in the obvious way: $s \hat{\ } \alpha = s_0 s_1 s_2 \dots s_{lt(s)-1} \alpha_0 \alpha_1 \dots$.

Now let us generalise these notions to trees. In this article, we focus on trees with binary branching, where the two *directions* are *left* L and *right* R . A *partial tree* over an alphabet A is a partial function $t: \{\mathsf{L}, \mathsf{R}\}^* \rightarrow A$ with a non-empty prefix-closed domain $\text{dom}(t)$ (i.e. if $s \in \text{dom}(t)$ and $s' \preceq s$ then $s' \in \text{dom}(t)$). A node $u \in \text{dom}(t)$ is either an *internal node* (i.e. both $u \hat{\mathsf{L}}$ and $u \hat{\mathsf{R}}$ belong to $\text{dom}(t)$), a *unary node* (i.e. exactly one of $u \hat{\mathsf{L}}$ and $u \hat{\mathsf{R}}$ belongs to $\text{dom}(t)$), or a *leaf* (i.e. none of $u \hat{\mathsf{L}}$ and $u \hat{\mathsf{R}}$ belongs to $\text{dom}(t)$). For the sake of readability, we write $u \in t$ to denote that $u \in \text{dom}(t)$ is a node of t . The empty sequence ϵ belongs to every partial tree and it is called the *root* of a tree. A *branch* of a partial tree t is a word π such that $\pi \upharpoonright n \in t$ for any $n \leq \text{lt}(\pi)$ if π is finite (resp. for any $n \in \omega$ if π is infinite). An infinite branch of a partial tree t is called a *path* of t . A node u is *on a branch* (finite or infinite) π if it is a prefix of π , i.e. if $u \preceq \pi$. A partial tree t is *finite* if its domain $\text{dom}(t)$ is finite. A *tree* is a partial tree t with $\text{dom}(t) = \{\mathsf{L}, \mathsf{R}\}^*$ (i.e. a *complete tree*). The set of all trees over an alphabet A is denoted Tr_A , that is $\text{Tr}_A \stackrel{\text{def}}{=} \{t \mid t: \{\mathsf{L}, \mathsf{R}\}^* \rightarrow A\}$.

If p and t are partial trees, we say that p is a *prefix* of t , and we denote it by $p \subseteq t$, if $\text{dom}(p) \subseteq \text{dom}(t)$ and $p(u) = t(u)$ for any $u \in \text{dom}(p)$. We write $p \subset t$ if $p \subseteq t$ but $p \neq t$. Finally, if t is a partial tree and u is a node of t , by $t.u$ we indicate the partial tree t *truncated* in u : for any w such that $uw \in \text{dom}(t)$, we have $t.u(w) = t(uw)$.

A subset $L \subseteq \text{Tr}_A$ is a *tree language*. *Regular* tree languages are the ones recognised by parity non-deterministic automata or, equivalently, definable in Monadic Second-order Logic (for this equivalence see for example [GTW02]).

3 Descriptive Set Theory

In this section we recall the topological notions coming from Descriptive Set Theory that we will use throughout the article. We do not aim for completeness, for more details we refer the reader to [Kec95]. In the first subsection we define Polish spaces, that are the main objects studied in Descriptive Set Theory. In the remaining section we introduce the main hierarchies usually considered for Polish spaces, i.e. Borel, Difference, and Wadge Hierarchies.

3.1 Polish Spaces

We denote a topological space by (X, τ) , where X is a non-empty set and τ is a family of subsets of X called *open sets*. If τ is understood from the context we write just X and suppress τ from the notation. We say that X is a *Polish space* if τ is completely metrizable (i.e. there exists a complete metric on X that generates τ) and separable (i.e. there exists a countable dense subset of X).

If a space X is known from the context and $A \subseteq X$ then by $A^c \stackrel{\text{def}}{=} X \setminus A$ we denote the complement of A in X . Similarly, if Γ is a family of subsets of X then $\Gamma^c \stackrel{\text{def}}{=} \{A^c \mid A \in \Gamma\}$.

Consider a non-empty at most countable set B . The space of infinite words B^ω over B

can be endowed with the topology generated by the basic open sets of the form:

$$N_s = \{\alpha \in B^\omega \mid s \prec \alpha\},$$

with $s \in B^*$. This topology is called the *prefix topology*. When $B = \{0, 1\}$, we obtain the *Cantor space*, denoted by 2^ω . When $B = \omega$, we obtain the *Baire space*, denoted by ω^ω . Every space of the form B^ω with the prefix topology is Polish. It is easy to check that the prefix topology is completely metrizable: the metric $d(\alpha, \beta) = 2^{-n}$, where n is the minimum index such that $\alpha(n) \neq \beta(n)$, is complete and it generates the prefix topology. Moreover, if we fix a symbol $c \in B$, the set

$$D = \{s \hat{\ } ccc \dots \mid s \in B^*\}$$

is countable (since B^* is countable) and dense, so B^ω is separable. In particular, the Cantor space and the Baire space are Polish spaces.

The prefix topology can easily be generalised to trees: in this case we can endow Tr_A with the topology whose basic open sets are of the form:

$$N_p = \{t \in \text{Tr}_A \mid p \subset t\},$$

with p being a finite partial tree. Every N_p is actually a clopen (i.e. both open and closed). Again, we call this topology the *prefix topology* and we denote it by τ_{pref} . The topology τ_{pref} is generated by several metrics. The usual metric considered to generate τ_{pref} is $d_{\text{pref}}(t_1, t_2) = 2^{-n}$ where n is the minimum length of a node u such that $t_1(u) \neq t_2(u)$. Each open ball of d_{pref} is a basic clopen set N_p for a certain finite partial tree p .

Notice that the metric d_{pref} satisfies the following strengthening of the triangle inequality:

$$d_{\text{pref}}(x, z) \leq \max(d_{\text{pref}}(x, y), d_{\text{pref}}(y, z)).$$

Such a metric is called an *ultrametric*, see [Kec95, Exercise 2.2]. This property makes d_{pref} too rigid for our way of choosing optimal witnesses (see Definition 11.11 of optimal strategy trees). Therefore, we will also consider a different metric, denoted by λ and called the *discounted distance*. This metric also generates τ_{pref} but has less intuitive family of open balls. Fix some enumeration u_0, u_1, \dots of all the nodes in $\{\mathbb{L}, \mathbb{R}\}^*$. Given two trees t_1 and t_2 , for any node u , define $\text{dist}(t_1(u), t_2(u)) = 0$ if $t_1(u) = t_2(u)$, 1 in the other case. Let

$$\lambda(t_1, t_2) \stackrel{\text{def}}{=} \sum_{n \geq 0} \frac{1}{2^n} \text{dist}(t_1(u_n), t_2(u_n)).$$

Fact 3.1. *Regardless of the enumeration (u_0, u_1, \dots) , the prefix and discounted distances yield the same topology.*

Proof. It is enough to observe that τ_{pref} is exactly the product topology obtained by starting from the discrete topology and the discounted distance is exactly the product metric. \square

Fact 3.2. *Tr_A with the topology τ_{pref} is a Polish space homeomorphic to the Cantor space 2^ω .*

Proof. The proof is a standard encoding of one compact product space into another. One can also use a characterisation of the Cantor space, see [Kec95, Theorem 7.4, page 35]. \square

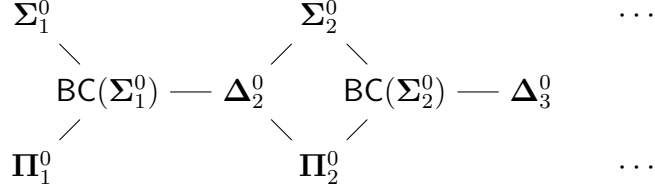


Figure 1: The first levels of Borel Hierarchy.

3.2 Borel Hierarchy

Let (X, τ) be a topological space. Recall that ω_1 is the first uncountable ordinal. We define, by a transfinite recursion on $1 \leq \xi < \omega_1$, the following classes:

$$\begin{aligned}
\Sigma_1^0(X) &\stackrel{\text{def}}{=} \{A \subseteq X \mid A \text{ is open}\}; \\
\Pi_\xi^0(X) &\stackrel{\text{def}}{=} \{A^c \subseteq X \mid A \in \Sigma_\xi^0(X)\} = (\Sigma_\xi^0(X))^c; \\
\Sigma_\xi^0(X) &\stackrel{\text{def}}{=} \left\{ \bigcup_n A_n \mid A_n \in \Pi_{\xi_n}^0(X), 1 \leq \xi_n < \xi, n \in \omega \right\}.
\end{aligned}$$

Moreover, for $1 \leq \xi < \omega_1$, we define the intersection of the two classes $\Delta_\xi^0(X) \stackrel{\text{def}}{=} \Sigma_\xi^0(X) \cap \Pi_\xi^0(X)$.

Fact 3.3. *For each $1 \leq \xi < \omega_1$, the classes $\Sigma_\xi^0(X)$ and $\Pi_\xi^0(X)$ are closed under finite unions and finite intersections. The class $\Delta_\xi^0(X)$ is also closed under complement and therefore forms a Boolean algebra.*

The smallest Boolean algebra containing all the sets from $\Sigma_\xi^0(X)$ is denoted $\text{BC}(\Sigma_\xi^0)(X)$. The above fact implies that $\text{BC}(\Sigma_\xi^0)(X) \subseteq \Delta_{\xi+1}^0(X)$. For uncountable Polish spaces the inclusion is strict, this fact follows from [Kec95, Exercise 22.26(iii)].

The *Borel sets* of X are:

$$\mathcal{B}(X) = \bigcup_{\xi \in \omega_1} \Sigma_\xi^0(X) = \bigcup_{\xi \in \omega_1} \Pi_\xi^0(X) = \bigcup_{\xi \in \omega_1} \Delta_\xi^0(X).$$

When the space X is clear from the context, we omit it and write just Σ_ξ^0 , Π_ξ^0 , etc. . .

Fact 3.4 ([Kec95, Theorem 22.4]). *Let (X, τ) be an uncountable Polish space. Then Borel Hierarchy of X does not collapse i.e. every class Σ_ξ^0 is properly contained in $\Sigma_{\xi+1}^0$.*

For the rest of the article we will focus on the first two levels of Borel Hierarchy, as depicted in Figure 1.

3.3 Difference Hierarchy

Borel Hierarchy is refined by the so-called *Difference Hierarchy*, see [Kec95, Section 22.E]. First notice that every ordinal θ can be uniquely written as $\lambda + n$, where λ is 0 or a limit ordinal and $n \in \omega$. We say that the *parity* of θ is *even* (resp. *odd*) if n is even (resp. odd).

Definition 3.5. *Let X be a topological space, Γ a family of subsets of X , and $\theta < \omega_1$ a countable ordinal. A set $A \subseteq X$ is called a θ -difference of Γ sets if and only if there exists a θ -indexed sequence of sets $(A_\eta)_{\eta < \theta} \subseteq \Gamma$ that is non-decreasing (i.e. $A_\eta \subseteq A_{\eta'}$ if $\eta \leq \eta'$) and:*

$$x \in A \iff \text{the minimum } \eta < \theta \text{ such that } x \in A_\eta, \\ \text{has parity opposite to that of } \theta.$$

The family of all θ -differences of Γ sets is denoted $\mathcal{D}_\theta(\Gamma)$. In particular, for each $\xi < \omega_1$ the class $\mathcal{D}_\theta(\Sigma_\xi^0)(X)$ is the family of all θ -differences of sets from the Borel class $\Sigma_\xi^0(X)$.

Notice that for a natural number n , $A \in \mathcal{D}_n(\Sigma_\xi^0)$ if and only if it can be written as follows (see Figure 2):

$$A = A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{n-1} \setminus A_{n-2}) \quad \text{if } n \text{ is odd,} \quad (1)$$

$$A = (A_1 \setminus A_0) \cup \dots \cup (A_{n-1} \setminus A_{n-2}) \quad \text{if } n \text{ is even,} \quad (2)$$

with A_0, \dots, A_{n-1} belonging to Σ_ξ^0 .

The following theorem shows that Difference Hierarchy over Σ_ξ^0 saturates the successive class $\Delta_{\xi+1}^0$.

Theorem 3.6 (Hausdorff, Kuratowski, see [Kec95, Theorem 22.27, page 176]). *In Polish spaces and for any $1 \leq \xi < \omega_1$ we have that*

$$\Delta_{\xi+1}^0 = \bigcup_{1 \leq \theta < \omega_1} \mathcal{D}_\theta(\Sigma_\xi^0).$$

Similarly, the first ω levels of the hierarchy coincide with the class $\text{BC}(\Sigma_\xi^0)$:

Theorem 3.7 ([Kec95, Exercise 22.30, page 177]). *In Polish spaces and for any $1 \leq \xi < \omega_1$ we have that*

$$\text{BC}(\Sigma_\xi^0) = \bigcup_{1 \leq \theta < \omega} \mathcal{D}_\theta(\Sigma_\xi^0).$$

3.4 Continuous reductions

In this section we introduce the notion of continuous reductions that will allow us to compare the topological complexity of sets.

Definition 3.8. *Let X, Y be two topological spaces. We say that a set $A \subseteq X$ continuously reduces to $B \subseteq Y$ if there is a continuous function $f: X \rightarrow Y$ such that the pre-image $f^{-1}(B) = \{x \in X \mid f(x) \in B\}$ is equal to A (i.e. $x \in A \Leftrightarrow f(x) \in B$ for every $x \in X$).*

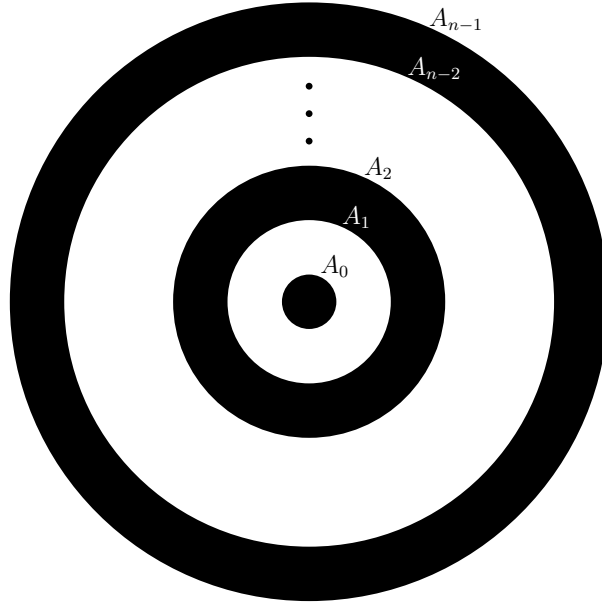


Figure 2: A set $A = A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{n-1} \setminus A_{n-2})$ (A is the union of the black parts) with $A_0 \subseteq A_1 \subseteq A_2 \subseteq \dots \subseteq A_{n-2} \subseteq A_{n-1}$ and $A_i \in \Sigma_\xi^0$ for every i .

The following proposition shows that continuous reductions preserve the topological classes defined above.

Proposition 3.9. *Let Γ be a level of Borel Hierarchy or of Difference Hierarchy. Then Γ is closed under continuous preimages: if B is a subset of a topological space Y such that $B \in \Gamma(Y)$ and $f: X \rightarrow Y$ is a continuous function from a topological space X to Y , then $f^{-1}(B) \in \Gamma(X)$.*

3.5 Wadge Hierarchy

We are now in the position to define Wadge Hierarchy of a general topological space. Later in the article we will focus on the specific case of Wadge Hierarchy of the Cantor space 2^ω .

Definition 3.10. *Let X and Y be two topological spaces and let $A \subseteq X$ and $B \subseteq Y$. We say that A is Wadge reducible to B , and we denote it by $A \leq_W B$, if there exists a continuous reduction of A to B . We say that A is Wadge equivalent to B , in symbols $A \equiv_W B$, if $A \leq_W B$ and $B \leq_W A$. Finally, we write $A <_W B$ if $A \leq_W B$ and $B \not\leq_W A$ does not hold.*

Fact 3.11. \leq_W is an equivalence relation.

The relation \leq_W induces a partial order between the \equiv_W -classes, called *Wadge degrees*, of subsets of topological spaces. If we fix a space X and we restrict the ordering induced

by \leq_W to the sets of X , we obtain *Wadge Hierarchy* of X . If A is a subset of X , then by $[A]_W$ we denote its Wadge degree:

$$[A]_W = \{B \subseteq X \mid B \equiv_W A\}.$$

Even though Wadge Hierarchy can be defined for any topological space, its shape for a generic space can be very complicated (for example Wadge Hierarchy of many non zero-dimensional topological spaces, including the space of real numbers, is very complicated: see for instance [RS14] and [RSS15]). Also, the good properties of the hierarchy (like its width or well-foundedness) depend on the determinacy of related games. Therefore, in our work we will restrict our attention to the order \leq_W restricted to the first levels of Borel Hierarchy of the Cantor space 2^ω . We refer the reader to [AC13] for a description of the structure of Wadge Hierarchy for 2^ω .

Theorem 3.12 (Wadge’s Lemma, see [Kec95, Theorem 21.14, page 156]). *For any $A, B \in \mathcal{B}(2^\omega)$ it holds that*

$$A \leq_W B \quad \text{or} \quad B^c \leq_W A.$$

Theorem 3.13 (Wadge, Martin, Monk, see [Kec95, Theorem 21.15, page 158]). *The ordering \leq_W among the Borel sets of 2^ω is well-founded.*

Definition 3.14. *A set which is Wadge reducible to its complement is called self-dual, otherwise it is called non self-dual.*

Example 3.15. *It is easy to check that every clopen set of 2^ω is self-dual.*

Since the notion of self-duality is invariant under \equiv_W we can speak of self-dual and non self-dual Wadge degrees. If $[A]_W$ is a non self-dual Wadge degree then we say that the pair $\{[A]_W, [A^c]_W\}$ is a *non self-dual pair*.

Corollary 3.16. *The anti-chains in the Wadge degrees have length at most 2 and are of the form*

$$\{[A]_W, [A^c]_W\},$$

with A non self-dual.

Notice that technically every Wadge degree does not contain the elements contained in the previous degrees of the hierarchy. For example, the Wadge degree $[C]_W$, where C is a clopen set different from 2^ω and \emptyset , contains all the clopen sets except the whole space 2^ω and the empty set \emptyset . This is obvious, since any Wadge degree is an equivalence class of the relation \equiv_W . We define the *Wadge class* of a set as the union of its Wadge degree with all its predecessors in the hierarchy. For example the Wadge class Δ_1^0 is obtained by taking the union of the Wadge degree $\Delta_1^0 \setminus \{\emptyset, 2^\omega\}$ with its predecessors $\{\emptyset\}$ and $\{2^\omega\}$. It is clear that the two hierarchies, the one of Wadge degrees and the one of Wadge classes, are isomorphic as orders, so we can treat both the hierarchies in the same way. In the pictures of this section we show the hierarchy of the Wadge classes, because they are more intuitive and easier to describe.

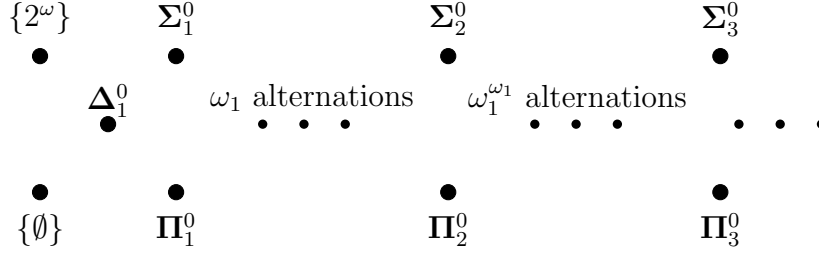


Figure 3: An initial fragment of Wadge Hierarchy inside Borel Hierarchy of 2^ω .

Theorem 3.17 (See [AC13]). *In the Cantor space, $[2^\omega]_W = \{2^\omega\}$ and $[\emptyset]_W = \{\emptyset\}$ are the two minimal Wadge degrees and they clearly form a non self-dual pair. Then we have the Wadge degree formed by any clopen set different from 2^ω and \emptyset and this is a self-dual Wadge degree. The hierarchy continues with a constant alternation of a non self-dual pair and one self-dual Wadge degree. All the limit levels of Wadge Hierarchy consist of a non self-dual pair. Certain specific Wadge classes coincide with the levels of Borel Hierarchy.*

Hence, Wadge Hierarchy of the Cantor space has the shape as depicted in Figure 4.

Now we can assign an ordinal to any level of the hierarchy. This ordinal is the *Wadge rank* of a Wadge degree (or of the corresponding Wadge class). The two bottom Wadge degrees $\{\emptyset\}$ and $\{2^\omega\}$ have Wadge rank 0, the Wadge degree $\Delta_1^0 \setminus \{\emptyset, 2^\omega\}$ has Wadge rank 1 (so it has the Wadge class Δ_1^0), and so on.

Among the non self-dual Wadge classes we find the classes Σ_n^0 and Π_n^0 . The classes Σ_1^0 and Π_1^0 are immediately after the Wadge class Δ_1^0 , so their Wadge rank is 2. Then, between the non self-dual pair

$$\{\Sigma_n^0, \Pi_n^0\}$$

and the successive

$$\{\Sigma_{n+1}^0, \Pi_{n+1}^0\}$$

there are $\omega_1^{\omega_1}$ ^{ω_1 times} Wadge classes. In particular, there are ω_1 Wadge classes between the pair $\{\Sigma_1^0, \Pi_1^0\}$ and $\{\Sigma_2^0, \Pi_2^0\}$. Hence, the Wadge rank of the Wadge classes Σ_2^0 and Π_2^0 is ω_1 , while the Borel class Δ_2^0 contains ω_1 different levels of Wadge Hierarchy.

Now we focus on the segment that we will study in this article, that is the initial segment from the beginning of the hierarchy until the Wadge classes Σ_2^0 and Π_2^0 . Using this notion we can express a characterisation of the first ω_1 levels of Wadge Hierarchy in 2^ω in terms of Difference Hierarchy.

Theorem 3.18 (See [AC13]). *For every $m \geq 1$ every class $\mathcal{D}_\theta(\Sigma_m^0)$ corresponds to a Wadge class of a non self-dual pair. For $m = 1$ these are essentially all Wadge classes: there is no non self-dual Wadge class between $\mathcal{D}_\theta(\Sigma_1^0)$ and $\mathcal{D}_{\theta+1}(\Sigma_1^0)$. Therefore, Figure 4 depicts the first ω_1 levels of Wadge Hierarchy.*

Hence, in the Cantor space Difference Hierarchy is an important tool to understand Wadge Hierarchy, especially in the initial part up to Σ_2^0 . Beyond that level, Difference Hierarchy becomes much coarser (i.e. it skips a lot of Wadge degrees).

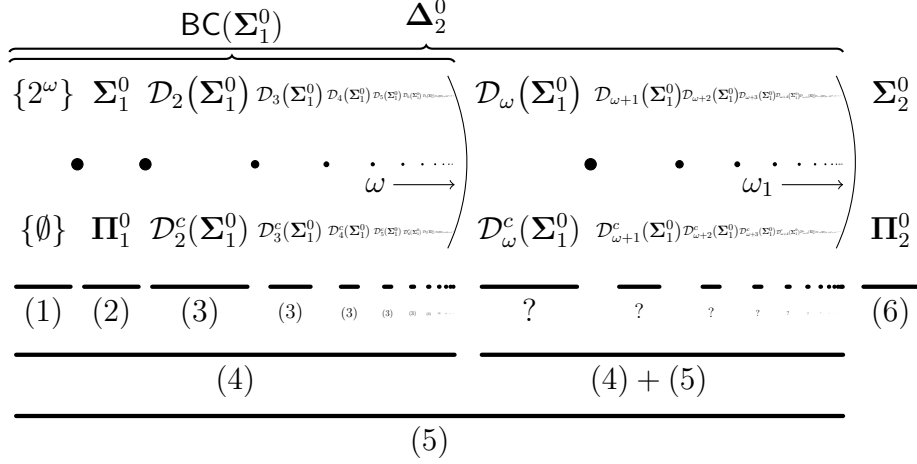


Figure 4: The first $\omega_1 + 1$ levels of Wadge Hierarchy for infinite trees; together with their decidability results. The self-dual classes are depicted by \bullet , they are formed by the intersection of the two consecutive non self-dual classes.

4 Contribution of this article

Consider a class Γ of languages (e.g. the class of open sets Σ_1^0). Then, an *effective characterisation* of Γ is an algorithm for the following decision problem:

Problem 4.1 (Effective Characterisation of Γ). *Given a representation of a regular language L , decide if $L \in \Gamma$.*

As explained in Introduction, there are multiple results providing effective characterisations for various classes of languages. In this article we focus on the classes of Wadge Hierarchy inside Δ_2^0 , see Figure 4. Notice that since regular languages are effectively closed under complement, an effective characterisation of Γ provides at the same time an effective characterisation of Γ^c and $\Gamma \cap \Gamma^c$. Thus, we will focus on non self-dual classes on one *side* of the hierarchy. Since Tr_A is homeomorphic to 2^ω (see Fact 3.2) all the results from Section 3 apply, and Wadge Hierarchy over Tr_A introduces the following classes of sets:

1. The class $\{\text{Tr}_A\}$. A language L belongs to $\{\text{Tr}_A\}$ if and only if $L = \text{Tr}_A$, thus solving the effective characterisation for that class boils down to checking universality of L , which reduces to non-emptiness of the complement of L [Rab69].
2. The class of open sets Σ_1^0 . That characterisation follows from [KW02, Wal02a].
3. The classes of Difference Hierarchy $\mathcal{D}_n(\Sigma_1^0)$ for $2 \leq n < \omega$. These classes are characterised in this paper, see Theorem 5.9.
4. The class $\text{BC}(\Sigma_1^0) = \bigcup_{n < \omega} \mathcal{D}_n(\Sigma_1^0)$ of Boolean combinations of open sets. This is the main contribution of this paper, see Theorem 9.1.

5. The self-dual class $\Delta_2^0 = \bigcup_{\xi < \omega_1} \mathcal{D}_\xi(\Sigma_1^0)$ of Borel Hierarchy. This result was claimed in [FM14], however the arguments there contain a flow, see discussion in Section 14. In this paper we provide a complete argument, see Theorem 14.1.
6. The class Σ_2^0 from the second level of Borel Hierarchy. This class seems to be out of reach of the algebras considered in this paper, see Subsection 15.1. However, an effective characterisation for that class exists, see [CMS17].

What remains open is how to characterise the specific classes $\mathcal{D}_\xi(\Sigma_1^0)$ for $\omega \leq \xi < \omega_1$. Notice that there are only countably many regular languages and therefore there must exist $\xi_0 < \omega_1$ such that no regular language belongs to $\mathcal{D}_\xi(\Sigma_1^0)$ for $\xi \geq \xi_0$. However, the value of ξ_0 is not known. Duparc and Murlak [DM07] have proved that there exist regular languages in any Wadge degree with Wadge rank less than ω^ω (i.e. $\xi_0 \geq \omega^\omega$). We do not know if $\xi_0 = \omega^\omega$, even if this is a quite reasonable conjecture.

5 The game for finite Wadge ranks

In this section we define a game that we will use in this article to obtain results of decidability of Wadge degrees with Wadge ranks up to ω (i.e. the classes $\mathcal{D}_n(\Sigma_1^0)$ for $n < \omega$). This game is played by two players, named Alternator and Constrainer and it is a finite duration game. In this article we work on the space Tr_A , but *a priori* this game can be defined in any topological space and the characterization that it gives holds in general. Yet, in the case of regular languages of trees, it is possible to decide which player wins the game. This fact will be crucial to state the results about decidability.

Let us describe the game. Let X be a topological space, $U_0 \subseteq X$ open and non-empty, and let X_1, \dots, X_n be arbitrary subsets of X . We define the game

$$\mathcal{H}_{U_0}(X_1, \dots, X_n)$$

played by Constrainer (choosing open subsets of X) and Alternator (choosing points of X). The game will last for n rounds, a round i for $1, \dots, n$ of the game is played as follows:

1. Alternator chooses a point $x_i \in U_{i-1} \cap X_i$. If there is no such point x_i , the game is interrupted and Constrainer wins immediately.
2. Constrainer chooses an open set $U_i \subseteq U_{i-1}$ that contains x_i and the next round is played.

If Alternator manages to survive n rounds then he wins, otherwise Constrainer wins.

A special variant of the game, when $U_0 = X$ is the whole space, is denoted as simply $\mathcal{H}(X_1, \dots, X_n)$. Now we prove some properties of this game.

Let (X, τ) be a topological space, $U \subseteq X$ open non-empty, and let X_1, \dots, X_n be subsets of X . Consider the game $\mathcal{H}_U(X_1, \dots, X_n)$. In this framework we can represent a position of a play through a tuple

$$\langle U_0, x_1, U_1, x_2, U_2, \dots, x_i, U_i \rangle,$$

where $x_1, \dots, x_i \in X$ and $U_0, U_1, \dots, U_i \in \tau$ with $U_0 = U$. A *strategy for Constrainer* in the game $\mathcal{H}_U(X_1, \dots, X_n)$ is a function

$$\sigma: X^{\leq n} \rightarrow \tau.$$

If s is a word belonging to $X^{\leq n}$ compatible with the game \mathcal{H} and with σ , then $\sigma(s)$ is the open set played by Constrainer in the position

$$\langle s_0, \sigma(s_0), s_1, \sigma(s_0s_1), \dots, s_{\text{lt}(s)-1}, \sigma(s) \rangle.$$

If s does not represent a position compatible with the game \mathcal{H} and with σ (for example because the second letter of s is not an element of X_2 or it is not an element of $\sigma(s_0)$), then we put $\sigma(s) = \emptyset$ by convention. As usual, a strategy σ for Constrainer is *winning* if Constrainer wins every play where he follows σ . In a specular way we could define strategies for Alternator, but we will not use them in this article. Since the duration of the game is finite, it is determined, as expressed by the following fact.

Fact 5.1. *The game $\mathcal{H}_U(X_1, \dots, X_n)$ is positionally determined: there are two positional strategies (σ_C for Constrainer and σ_A for Alternator) defined in all the positions of the game, such that each position of the game is either:*

- *winning for Constrainer and σ_C is winning from that position,*
- *winning for Alternator and σ_A is winning from that position.*

The first property we prove is Refinement Lemma, that states that if the sets X_1, \dots, X_n are split into finitely many parts each and Alternator wins $\mathcal{H}(X_1, \dots, X_n)$ then he can win for some choice of parts of X_1, \dots, X_n .

Lemma 5.2 (Refinement Lemma). *Let X_1, \dots, X_n be subsets of a topological space X . For $i \in \{1, \dots, n\}$, let \mathcal{Y}_i a finite family of sets partitioning X_i . For any non-empty open $U \subseteq X$, if Alternator wins*

$$\mathcal{H}_U(X_1, \dots, X_n)$$

then there exist $Y_1 \in \mathcal{Y}_1, \dots, Y_n \in \mathcal{Y}_n$ such that Alternator wins

$$\mathcal{H}_U(Y_1, \dots, Y_n).$$

Proof. We prove the theorem by induction on n . The induction base is immediate, because Alternator always wins when $n = 0$ and he wins when $n = 1$ if and only if $X_1 \neq \emptyset$. Now prove the induction step. Consider the first move by Alternator, where he chooses a point $x \in U$. This point necessarily belongs to some $Y_1 \in \mathcal{Y}_1$. For $i \in \omega$, let U_i be the open ball around x of radius $\frac{1}{i}$. By the definition of the game, we know that Alternator wins

$$\mathcal{H}_{U_i}(X_1, \dots, X_n)$$

for every i . By the inductive assumption, we know that for every i there exist $Y_2^{(i)} \in \mathcal{Y}_2, \dots, Y_n^{(i)} \in \mathcal{Y}_n$ such that Alternator wins

$$H_{U_i}(Y_2^{(i)}, \dots, Y_n^{(i)}).$$

By Pigeon-hole Principle, there must be some Y_2, \dots, Y_n such that

$$(Y_2, \dots, Y_n) = (Y_2^{(i)}, \dots, Y_n^{(i)})$$

holds for infinitely many i . Since the game $\mathcal{H}_V(Y_2, \dots, Y_n)$ grows more difficult for Alternator as the open set V becomes smaller, and since every open set V that contains x contains some U_i , we conclude that Alternator wins

$$\mathcal{H}_V(Y_2, \dots, Y_n)$$

for every V that contains x . By viewing V as a response of Constrainer to Alternator's move $x \in Y_1$, we conclude that Alternator wins the game

$$\mathcal{H}_U(Y_1, \dots, Y_n).$$

The proof is complete. □

Now let Y be a subset of our topological space X and consider a particular case of the game where the sets X_1, \dots, X_n alternate between Y and its complement, i.e. we consider $\mathcal{H}(X_1, \dots, X_n)$ where X_i is Y if i is odd, Y^c otherwise. We denote by $\mathcal{H}^{\epsilon, \neq}(Y, n)$ that game and by $\mathcal{H}_U^{\epsilon, \neq}(Y, n)$ the variant relativised to a non-empty open set $U \subseteq X$.

Example 5.3. *Consider the game where the topological space X is the space of real numbers \mathbb{R} and $Y = \mathbb{Q}$, i.e. the rational numbers. Then for every n , Alternator wins the game $\mathcal{H}^{\epsilon, \neq}(Y, n)$.*

Remark 5.4. *Notice that if Alternator wants to survive in $\mathcal{H}^{\epsilon, \neq}(Y, n)$ as long as possible, he has to avoid to play points in the interior¹ of Y and the interior of Y^c . For example, if at the first round Alternator plays x belonging to the interior of Y then Constrainer can play (a subset of) the interior of Y and Alternator loses because he cannot go outside Y any more.*

Example 5.5. *In the real numbers \mathbb{R} , let Y be the complement of $\{\frac{1}{n} \in \mathbb{R} \mid n \in \omega\}$. Alternator wins $\mathcal{H}^{\epsilon, \neq}(Y, 3)$. Indeed, in the first round Alternator can play $0 \in Y$. In the second round, Alternator plays $\frac{1}{n} \notin Y$ for some large n depending on Constrainer's move. In the third round, Alternator plays $\frac{1}{n} + \epsilon \in Y$, for some small ϵ depending on Constrainer's move. Moreover, Constrainer wins (Y, n) for $n \geq 4$.*

Remark 5.6. *Let σ_1 and σ_2 be two strategies for Constrainer such that $\sigma_1(s) \subseteq \sigma_2(s)$ for any finite word $s \in X^{\leq n}$. If σ_2 is winning for Constrainer then σ_1 is winning for Constrainer too.*

¹Recall that the interior of a set Y is the union of all open sets contained in Y .

Lemma 5.7. *Choose some basis B for the topology of the topological space X . If Constrainer has a winning strategy in $\mathcal{H}^{\varepsilon, \neq}(Y, n)$ then he has a winning strategy which uses only basic open sets from B .*

Proof. Using Axiom of Choice AC we can define a function f that to every pair (U, x) , where U is an open set and $x \in U$, assigns a basic open set $V \in B$ such that $x \in V$ and $V \subseteq U$. Let σ be a winning strategy for Constrainer. We can define another winning strategy $\bar{\sigma}$ that takes sets always from B : given a finite word s of length i , we define $\bar{\sigma}(s) = f(\sigma(s), s_i)$. Since σ was winning for Constrainer, by Remark 5.6 also $\bar{\sigma}$ is winning. \square

Corollary 5.8. *When considering strategies of Constrainer in $\mathcal{H}^{\varepsilon, \neq}(Y, n)$ we can assume that each open set U_i played by him is a basic open set, i.e. $U_{i+1} = N_p$ for a finite prefix p of the currently played tree t_i . The condition that $U_{i+2} \subseteq U_{i+1}$ boils down to the assumption that $p_{i+2} \supseteq p_{i+1}$.*

Now we are ready to give a characterization of $\mathcal{D}_n(\Sigma_1^0)$ sets in terms of the game \mathcal{H} .

Theorem 5.9. *Let X be a topological space and let $Y \subseteq X$. The following conditions are equivalent:*

1. Y belongs to $\mathcal{D}_n(\Sigma_1^0)$.
2. Constrainer has a winning strategy in $\mathcal{H}^{\varepsilon, \neq}(Y, n + 1)$.

Proof. We have to prove both directions separately.

Implication 1 \Rightarrow 2. Suppose that n is odd and let

$$Y = A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{n-1} \setminus A_{n-2}), \quad (3)$$

where $A_0 \subseteq A_1 \subseteq A_2 \subseteq \dots \subseteq A_{n-2} \subseteq A_{n-1}$ and every A_i is open for $0 \leq i \leq n - 1$. Then, a winning strategy for Constrainer in $\mathcal{H}^{\varepsilon, \neq}(Y, n)$ is to play A_{n-1} as the first move, A_{n-2} as the second move, and so on. Equation (3) implies that this is a valid strategy of Constrainer. The n th move will be A_0 , and since $A_0 \subseteq Y$, at that point Alternator loses at the $(n+1)$ th round. The case of n even is completely dual, in that case $A_0 \subseteq Y^c$.

Implication 2 \Rightarrow 1. Suppose that n is odd, the opposite case can be solved by an entirely dual argument. Our aim is to present Y as in (3). For $i = 0, 1, 2, \dots$ define sets

$$\begin{aligned} A_i &\stackrel{\text{def}}{=} \bigcup \{U \mid \text{Constrainer wins } \mathcal{H}_U^{\varepsilon, \neq}(Y, i + 1)\} && \text{for odd } i \\ A_i &\stackrel{\text{def}}{=} \bigcup \{U \mid \text{Constrainer wins } \mathcal{H}_U^{\varepsilon, \neq}(Y^c, i + 1)\} && \text{for even } i \end{aligned}$$

where the unions range over open sets $U \subseteq X$. Notice that if Constrainer wins $\mathcal{H}_U^{\varepsilon, \neq}(Y, i)$ then he also wins $\mathcal{H}_U^{\varepsilon, \neq}(Y^c, i + 1)$ by the same strategy, just playing U in the first round. Therefore, the family (A_i) is increasing. By the definition, all the sets A_i are open. Clearly, the assumption that Constrainer has a winning strategy in $\mathcal{H}^{\varepsilon, \neq}(Y, n + 1)$ implies that A_n is the whole space. Thus, it is enough to inductively prove the following claim.

Claim 5.10. For $i = 0, 1, \dots$ the following holds

$$\begin{aligned} Y \cap A_i &= A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{i-1} \setminus A_{i-2}) && \text{for odd } i \\ Y^c \cap A_i &= (A_1 \setminus A_0) \cup (A_3 \setminus A_2) \cup \dots \cup (A_{i-1} \setminus A_{i-2}) && \text{for even } i \end{aligned}$$

Notice that by the definition $A_0 \subseteq Y$ — whenever there exists $x \in U \cap Y^c$ then Alternator wins $\mathcal{H}_U^{\varepsilon, \neq}(Y^c, 1)$ by playing x . Therefore, the above claim holds for $i = 0$ as $Y^c \cap A_0 = \emptyset$.

Assume that Claim 5.10 holds for $i-1$ and consider the two cases for i .

The case of odd i . In that case we need to prove that $Y \cap A_i$ is of the form from (3). Consider a point $x \in A_i$. First consider the case that $x \in A_{i-1}$. Then by the inductive assumption $x \in Y$ if and only if

$$x \notin (A_1 \setminus A_0) \cup (A_3 \setminus A_2) \cup \dots \cup (A_{i-2} \setminus A_{i-3})$$

what is equivalent to the disjunction of $x \in (A_{i-1} \setminus A_{i-2})$ or

$$x \in A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{i-3} \setminus A_{i-4}).$$

Thus, $x \in Y$ if and only if

$$x \in A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{i-1} \setminus A_{i-2}).$$

Thus, the statement of Claim 5.10 holds in that case.

Now assume that $x \notin A_{i-1}$. We will prove that in that case $x \notin Y$. Assume contrarily that $x \in Y$. Since $x \in A_i$, there exists an open set U such that $x \in U \subseteq A_i$ and Constrainer wins $\mathcal{H}_U^{\varepsilon, \neq}(Y, i+1)$. Consider the first round of $\mathcal{H}_U^{\varepsilon, \neq}(Y, i+1)$ in which Alternator plays x and a winning strategy of Constrainer replies with $V \ni x$. This means that Constrainer has a winning strategy in $\mathcal{H}_V^{\varepsilon, \neq}(Y^c, i)$ and therefore by the definition $x \in V \subseteq A_{i-1}$, a contradiction.

The case of even i . This case is entirely dual: we take $x \in A_i$ and consider the case that $x \in A_{i-1}$. Then the following conditions are equivalent:

$$\begin{aligned} &x \notin Y \\ &x \notin A_0 \cup (A_2 \setminus A_1) \cup \dots \cup (A_{i-2} \setminus A_{i-3}) \\ &x \in (A_1 \setminus A_0) \cup (A_3 \setminus A_2) \cup \dots \cup (A_{i-3} \setminus A_{i-4}) \text{ or } x \in (A_{i-1} \setminus A_{i-2}) \\ &x \in (A_1 \setminus A_0) \cup (A_3 \setminus A_2) \cup \dots \cup (A_{i-1} \setminus A_{i-2}) \end{aligned}$$

and therefore Claim 5.10 holds in that case. If $x \notin A_{i-1}$ then we need to prove that $x \in Y$. Since $x \in A_i$, we know that $x \in U \subseteq A_i$ with Constrainer winning $\mathcal{H}_U^{\varepsilon, \neq}(Y^c, i+1)$ for some open U . Assume contrarily that $x \notin Y$ and as before we see a contradiction, as x is a valid move of Alternator in $\mathcal{H}_U^{\varepsilon, \neq}(Y^c, i+1)$ and therefore $x \in A_{i-1}$. \square

Corollary 5.11. *The following conditions are equivalent for a set Y :*

1. Y belongs to $\bigcup_{n \in \omega} \mathcal{D}_n(\Sigma_1^0) = \text{BC}(\Sigma_1^0)$.
2. Constrainer wins the game $\mathcal{H}^{\varepsilon, \neq}(Y, n)$ for all but finitely many n .

Proof. It follows from Theorem 5.9. □

6 The infinite variant of the game

We denote by $\mathcal{H}^\infty(L)$ the infinite variant of $\mathcal{H}^{\varepsilon, \neq}(L, n)$: $\mathcal{H}^\infty(L)$ is the infinite duration game played the same way as $\mathcal{H}^{\varepsilon, \neq}(L, n)$ but the winning condition for Alternator is that he has to survive for infinitely many turns. By $\mathcal{H}_U^\infty(L)$ we denote the relativised game.

Remark 6.1. *The game $\mathcal{H}^\infty(L)$ is determined: every play where Constrainer wins is finite. Therefore, the winning condition for Constrainer is an open condition, while the winning condition for Alternator is a closed condition, both in the space $(\text{Tr}_A \times \tau)^*$, where the sets Tr_A and τ are taken with the discrete topology. Hence, the game is determined by Gale-Stewart Theorem.*

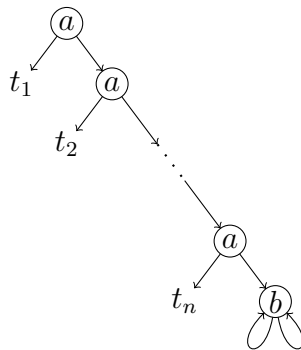
Remark 6.2. *In the same fashion as in the case of the finite game, without loss of generality we can assume that Constrainer in his strategies uses only basic open sets represented by prefixes of the played trees, see Corollary 5.8.*

The following fact follows directly from the definition of the two variants of the game.

Fact 6.3. *If Alternator wins $\mathcal{H}^\infty(L)$ then he wins $\mathcal{H}^{\varepsilon, \neq}(L, n)$ for any n .*

Proposition 6.4. *The converse to Fact 6.3 is not true, even for regular tree languages L .*

Proof. We have to exhibit a counterexample. To do that it is convenient to work with an alphabet with three different symbols, so let A be the alphabet $\{a, b, c\}$. For the sake of this example, assume that if t_1, \dots, t_n are trees, by $[t_1, \dots, t_n]$ we denote the tree



Now let L be the language of all the trees of the form $[t_1, \dots, t_n]$ where for every $i \in \{1, \dots, n\}$ the tree t_i is

1. either a tree with every node labelled by a ,
2. or a tree that contains only finitely many letters different than c , i.e. a tree for which there exists a finite prefix p of t_i such that $t_i(u) = c$ for any node $u \notin p$.

If t_i respects the first condition we say that t_i is a *first case tree*, if it respects the second condition we say it is a *second case tree*. We first prove that Alternator wins $\mathcal{H}^{\varepsilon, \neq}(L, n)$ for any n . Fix a natural number n , we provide a winning strategy for Alternator for the game $\mathcal{H}^{\varepsilon, \neq}(L, 2n)$. We define the following sets of trees:

- For $i \in \{1, \dots, n\}$ let L_i be the set of trees $[t_1, \dots, t_n]$ such that the trees t_1, \dots, t_{i-1} are second case trees and the trees t_i, \dots, t_n are first case trees. It is clear that $L_i \subseteq L$ for any i .
- We define L'_i as L_i except that the tree t_i contains both a and b nodes, but no c nodes. Obviously L'_i is disjoint from L .

Every prefix of a tree in L_i can be completed into a tree in L'_i and every prefix of a tree in L'_i can be completed into a tree in L_{i+1} . It follows that Alternator wins the game

$$\mathcal{H}(L_1, L'_1, L_2, L'_2, \dots, L_n, L'_n)$$

and therefore also Alternator wins $\mathcal{H}^{\varepsilon, \neq}(L, 2n)$.

Now we move to a proof that Alternator loses $\mathcal{H}^\infty(L)$. Consider the tree played by Alternator in the first round. Since this tree belongs to L , it must be of the form $[t_1, \dots, t_n]$ with t_1, \dots, t_n either first case trees or second case trees. Let p_1 be a finite prefix of this tree which contains the node \mathfrak{r}^n . Constrainer uses a strategy, which preserves the following properties:

1. All prefixes played by Constrainer extend the prefix p_1 . Consequently, all the trees played by Alternator are of the form $[s_1, \dots, s_n]$. Indeed, the prefix p_1 guarantees that the played trees t satisfy $t(\mathfrak{r}^n) = b$ and $t(\mathfrak{r}^k) = a$ for $k < n$. Hence, all the modifications done by Alternator are relative to the trees t_1, \dots, t_n and therefore for $k \in \{1, \dots, n\}$ it is meaningful to talk about the k th coordinate of the tree played by Alternator in a round which refers to the tree s_k .
2. Suppose that Alternator plays a tree $[s_1, \dots, s_n]$ in some round i . Let p_i be a finite prefix of this tree such that for every coordinate $k \in \{1, \dots, n\}$ we have:
 - If s_k is a second case tree then p_i contains a prefix of s_k such that under that prefix every node is labelled by c .
 - If s_k contains some b then p_i contains some b in the subtree s_k .

In the next round Constrainer chooses p_i . Consequently, if i, j are rounds with $i < j$ and $k \in \{1, \dots, n\}$ then

- If the k th coordinate of Alternator's tree in round i is a second case tree then also the k th coordinate of Alternator's tree in round j has to be a second case tree.
- If the k th coordinate of Alternator's tree in round i contains a b then also the k th coordinate of Alternator's tree in round j contains a b .

So, in an odd-numbered round, Alternator's tree belongs to the language and therefore all the coordinates with a b are second case trees. In an even-numbered round, Alternator's tree is outside the language. Therefore, when going from an odd-numbered round to the next even-numbered round, Alternator must change some coordinate from a first case tree without b to a tree with b . It follows that the number coordinates with b increases in each even-numbered round. Since this can happen at most n times, Alternator must lose after at most $2n$ rounds.

The proof is complete. □

Now we can give a non-effective characterisation of the class Δ_2^0 for topological spaces that are completely metrizable (for the levels $\mathcal{D}_n(\Sigma_1^0)$ we gave a characterisation that holds in general for any topological space, but here we are forced to require complete metrizability).

Proposition 6.5. *Let X be a completely metrizable topological space and let Y be a subset of X . Then the following conditions are equivalent:*

1. *Constrainer wins $\mathcal{H}^\infty(Y)$.*
2. *$Y \in \Delta_2^0(X)$.*

Proof. The proof is very similar to the analysis of other games of this kind, for instance Banach–Mazur game, see [Kec95, Section 8.H].

Implication 1 \Rightarrow 2. Assume that Constrainer has a winning strategy σ in $\mathcal{H}^\infty(Y)$. By Remark 6.2 we can assume that σ plays only basic open sets.

Notice that σ (seen as a tree) is well-founded because the strategy is winning and therefore it admits no infinite play. We will prove by induction on the structure of σ that if $\langle U_0, x_1, U_1, \dots, U_{i-1} \rangle$ is a position compatible with σ then $Y \cap U_{i-1} \in \Delta_2^0$. Consider such a position $P = \langle U_0, x_1, U_1, \dots, U_{i-1} \rangle$ and assume that the thesis holds for all the positions extending that one. If the position P is instantly winning for Constrainer (i.e. Alternator cannot play a single round from P) then, depending on parity of i , either $U_{i-1} \subseteq Y^c$ or $U_{i-1} \subseteq Y$. In both cases the inductive thesis holds. Now assume that P is not instantly winning for Constrainer. By the symmetry lets assume that i is odd, i.e. Alternator is forced to play $x_i \in U_{i-1} \cap Y$. Let $(B_x)_{x \in U_{i-1} \cap Y}$ be the indexed family of basic open sets B_x played by σ as a response to Alternator playing x . By the inductive assumption we know that for each $x \in U_{i-1} \cap Y$ we have $Y \cap B_x \in \Delta_2^0$.

By the definition of the family B_x we know that

$$Y \cap U_{i-1} = \bigcup_{x \in U_{i-1} \cap Y} (B_x \cap Y),$$

where the union is in fact countable since there is only countably many basic open sets in X . As every set taken in the union is Σ_2^0 (in fact Δ_2^0) we know that $Y \cap U_{i-1}$ is Σ_2^0 . Dually

$$Y^c \cap U_{i-1} = \left(U_{i-1} \setminus \bigcup_{x \in U_{i-1} \cap Y} B_x \right) \cup \bigcup_{x \in U_{i-1} \cap Y} (B_x \cap Y^c),$$

which again is a Σ_2^0 presentation of $Y^c \cap U_{i-1}$.

Thus, the above induction implies that $Y \cap U_0 = Y \cap X = Y$ is Δ_2^0 .

Implication 2 \Rightarrow 1. We need to prove that if $Y \in \Delta_2^0$ then Constrainer wins $\mathcal{H}^\infty(Y)$. Indeed, if Y is in Δ_2^0 we can write Y and its complement as

$$Y = \bigcap_{j \in \omega} A_j \quad \text{and} \quad Y^c = \bigcap_{j \in \omega} B_j,$$

where all the sets A_i and B_i are open. Now we can describe a winning strategy for Constrainer in $\mathcal{H}^\infty(Y)$. Suppose $i = 1, 2, \dots$ is the round we are playing and i is odd (resp. i is even). Let $j = \lfloor \frac{i-1}{2} \rfloor$. Assume that U_{i-1} is the open set that was played last ($U_0 = X$) and let x_i be the point played by Alternator in the current round. By the definition of the game, if i is odd then $x_i \in Y$ and otherwise $x_i \in Y^c$. Let Constrainer play U_i such that $\overline{U_i} \subseteq U_{i-1}$; $U_i \subseteq A_j$ (resp. $U_i \subseteq B_j$); and the diameter of U_i is smaller than 2^{-i} . Such a set exists because $x_i \in U_{i-1} \cap A_j$ (resp. $x_i \in U_{i-1} \cap B_j$).

Clearly it is a valid strategy of Constrainer. Consider an infinite play consistent with this strategy. Since X is Polish and the sets U_i are of decreasing diameter with $\overline{U_i} \subseteq U_{i-1}$, there must exist $x \in \bigcap_{n \in \omega} U_n$. But by the construction of U_i , such x must belong to both $\bigcap_{j \in \omega} A_j = Y$ and $\bigcap_{j \in \omega} B_j = Y^c$, a contradiction. Thus, each play consistent with the above strategy is finite and therefore winning for Constrainer. \square

Corollary 6.6. *Let X be a completely metrizable topological space and Y be a subset of X . Then $Y \in \Delta_2^0 \setminus \text{BC}(\Sigma_1^0)$ if and only if Alternator wins $\mathcal{H}^{\varepsilon, \neq}(Y, n)$ for any n but he loses $\mathcal{H}^\infty(Y)$.*

7 Decidability of finite levels of Wadge Hierarchy

In this section we prove that, given a natural number n , it is decidable if a regular language L is an n -difference of open sets (i.e. belongs to $\mathcal{D}_n(\Sigma_1^0)$). To obtain that, we use the game $\mathcal{H}^{\varepsilon, \neq}(Y, n)$ in the topological space Tr_A . Recall that without of generality (see Corollary 5.8) we can assume that Constrainer plays finite prefixes of the trees played by Alternator, and Alternator has to extend the finite prefixes played by Constrainer.

Example 7.1. Consider the language

$$L = \{t \in \text{Tr}_A \mid \text{infinitely many } a \text{ appear in } t\}.$$

L is regular and it is easy to check that Alternator can win the game $\mathcal{H}^{\varepsilon, \notin}(L, n)$ for every $n \in \omega$. This is because every finite prefix can be extended to a tree with finitely many a or to a tree with infinitely many a . So L is not a Boolean combination of open sets (it is known, indeed, that L is a Π_2^0 set but it is not a Σ_2^0 set).

Lemma 7.2. Given regular tree languages L_1, \dots, L_n , one can decide who wins the game $\mathcal{H}(L_1, \dots, L_n)$. In particular, given L and n , one can decide who wins $\mathcal{H}^{\varepsilon, \notin}(L, n)$.

Proof. We prove the statement for two regular languages L_1, L_2 . It is easy to generalise to n regular languages. The sentences “Alternator wins the game $\mathcal{H}(L_1, L_2)$ ” and “Constrainer wins the game $\mathcal{H}(L_1, L_2)$ ” can be effectively formalized in monadic second-order logic on the complete binary tree. For instance the sentence

“Alternator wins the game $\mathcal{H}(L_1, L_2)$ ”

is:

there exists a tree $t_1 \in L_1$ such that for any finite prefix p of T_1
there exists a tree $t_2 \in L_2$ that extends p .

In similar way we can write the sentence that says that Constrainer wins for $n > 2$. □

So we obtain:

Corollary 7.3. It is decidable, given a regular tree language L and $n \in \omega$, whether L is an n -difference of open sets.

Proof. It directly follows from Theorem 5.9 and Lemma 7.2. □

Hence, since Wadge degrees with Wadge ranks below ω are formed by Boolean combinations of the levels of Difference Hierarchy, we easily obtain:

Theorem 7.4. Given a regular language L and a Wadge degree $[A]_W$ with Wadge rank less than ω , it is decidable if L belongs to $[A]_W$.

Now our next goal is decidability of the class $\bigcup_{n \in \omega} \mathcal{D}_n(\Sigma_1^0) = \text{BC}(\Sigma_1^0)$. Notice that Corollary 7.3 gives us a semi-algorithm for deciding if a regular language is in $\bigcup_{n \in \omega} \mathcal{D}_n(\Sigma_1^0)$. Indeed, for $n = 1, 2, \dots$ we can use Corollary 7.3 to decide if $L \in \mathcal{D}_n(\Sigma_1^0)$. If for some n it is the fact then $L \in \bigcup_{n \in \omega} \mathcal{D}_n(\Sigma_1^0)$ and the algorithm terminates. Otherwise the algorithm does not terminate. In Sections 8, 9, 10, 11, 12, and 13 we will develop tools and provide an algorithm that always terminates and solves the above decision problem.

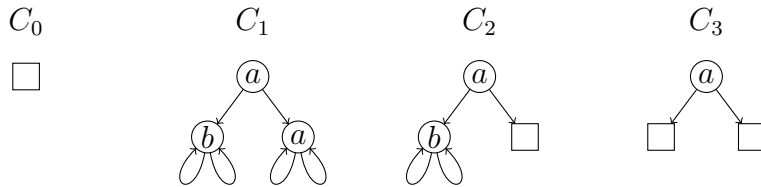
8 The algebra on trees

The algebraic approach we define in this section is based on the so-called *Myhill-Nerode equivalence* that allows to distinguish trees based on their behaviour when put into certain *contexts*.

Definition 8.1. A multicontext over an alphabet A is a partial tree t over $A \sqcup \{\square\}$ where $\square \notin A$ such that: t does not contain any unary nodes and a node of t is a leaf if and only if it is labelled \square . A port of a multicontext C is any node of t that is labelled \square (i.e. any leaf of t).

The number of ports is called the *arity* of the multicontext. *A priori* a multicontext may have infinitely many ports and in that case the arity is ∞ . A multicontext with exactly one port is called a *context*. Given a multicontext C and a valuation η which maps ports of C to trees in Tr_A , we write $C[\eta]$ for the tree obtained by replacing each port u by the tree $\eta(u)$. The tree $C[\eta]$ is said to *extend* the multicontext C . If L is a set of trees and C is a multicontext then by $C[L]$ we denote the set of trees obtained by plugging trees of L in the ports of C in all the possible ways. The set of all trees extending a multicontext C is denoted by $C[*]$. If C is a multicontext, possibly with infinitely many ports, and t is a tree, we denote by $C[t]$ the tree obtained by putting t in every port of C .

Example 8.2. The multicontext C_0 consists of only one node — the root. It is called the trivial context and denoted \square . C_1 is a tree, it has no ports, and $C_1[*]$ is $\{C_1\}$. The multicontext C_2 is a context and if we complete C_2 with a tree we obtain a tree where the root label is a and the left subtree of the root is labelled with only letters b . Finally, C_3 is a finite multicontext and $C_3[*] = \{t \mid t(\epsilon) = a\}$.



Now we focus on contexts, i.e. multicontexts with exactly one port. We write Cntx_A for the set of all non-trivial contexts over A . Given two contexts C, D we write $C \cdot D$ for the context obtained by replacing the port of C with D . Moreover, if $C \neq \square$ (i.e. C is not trivial) then we write C^∞ for the infinite tree

$$C \cdot C \cdot C \cdot C \dots$$

Remark 8.3. It is easy to verify that \cdot is associative, therefore $(\text{Cntx}_A \sqcup \{\square\}, \cdot)$ is an infinite monoid, with the trivial context \square as the neutral element.

Now we define the two Myhill-Nerode equivalence relations: one for trees and one for contexts. These equivalence relations depend on a fixed language $L \subseteq \text{Tr}_A$.

Definition 8.4. In the Myhill-Nerode equivalence for trees, we say that two trees t and t' are L -equivalent if

$$C[t] \in L \iff C[t'] \in L \quad \text{for every multicontext } C.$$

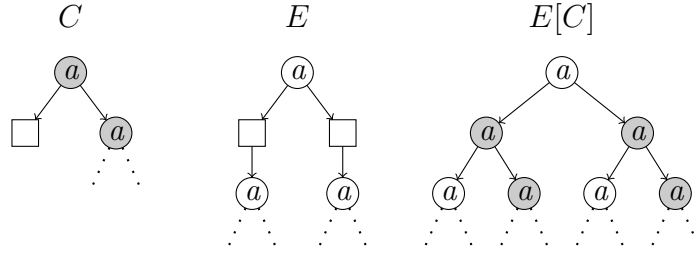
Example 8.5. Consider the language $L = \{t \in \text{Tr}_A \mid t(\epsilon) = a\}$. In this case we have just two equivalence classes that are L and the complement L^c . The context that establishes if a tree belongs to L or L^c is the trivial context \square .

To give a similar definition for contexts, we use a variant of multicontexts where the ports can be substituted by contexts and not trees.

Definition 8.6. A context environment over an alphabet A is a partial tree labelled by $A \sqcup \{\square\}$ such that: t has no leaves and a node of t is unary if and only if it is labelled \square . A port of a context environment is any node of t that is labelled \square (i.e. any unary node of t).

Given a context environment E and a non-trivial context C , we write $E[C]$ for the tree obtained by substituting C for every port of E .

Example 8.7. C is a context, E is a context environment and $E[C]$ is a tree.



Definition 8.8. We define two non-trivial contexts C and C' to be L -equivalent if

$$E[C] \in L \iff E[C'] \in L \quad \text{for every context environment } E.$$

We denote by H_L the set of the equivalence classes of trees with respect to L , the elements of H_L are called *tree types*. Similarly we denote by V_L the set of the equivalence classes of non-trivial contexts with respect to L , the elements of V_L are called *context types*. By 1_L we denote an artificial context type that does not belong to V_L and corresponds to the trivial context \square .

Definition 8.9. We define the syntactic morphism of L , denoted by α_L , as the two-sorted function

$$\alpha_L: (\text{Tr}_A, \text{Cntx}_A) \rightarrow (H_L, V_L),$$

that maps a tree $t \in \text{Tr}_A$ into its L -equivalence class $\alpha_L(t) \in H_L$ (analogously for $C \in \text{Cntx}_A$ we have $\alpha_L(C) \in V_L$).

The following fact follows from standard methods of constructing algebra from automata, see for instance [BI09] where algebras with structure richer than here are used.

Fact 8.10. *If L is a regular language then both H_L and V_L are finite. Moreover, given a parity non-deterministic automaton \mathcal{A} recognising L , one can compute in EXPTIME a syntactic algebra (H_L, V_L) for L where both H_L and V_L have at most exponentially many elements in the number of states of \mathcal{A} .*

Remark 8.11. *Finiteness of H_L and V_L is necessary but not sufficient for regularity, for instance both H_L and V_L are finite for any language defined in MSO+U (see [Boj04]).*

As expressed by the following lemma, the natural operations on contexts and trees respect the L -equivalence. Therefore the lemma implies that α_L imposes a two-sorted algebraic structure on (H_L, V_L) .

Lemma 8.12. *The following operations respect L -equivalence.*

1. *For every multicontext D , the operation $t \rightarrow D[t]$.*
2. *For every context environment E , the operation $C \rightarrow E[C]$.*
3. *The composition of contexts $(C_1, C_2) \rightarrow C_1 \cdot C_2$.*
4. *Substituting a tree in the port of a context $(C, t) \rightarrow C \cdot t$.*
5. *Infinite iteration of a non-trivial context $C \rightarrow C^\infty$.*
6. *For every symbol $c \in A$, the operations $t \mapsto c(t, \square)$ and $t \mapsto c(\square, t)$, that produce new contexts with roots labelled c and t plugged as one of the subtrees under the root.*

Proof. We prove all the six items.

Items 1 and 2 These items follow directly from the definition of L -equivalence.

Item 3 Let C_1, C_2, D_1, D_2 be contexts such that C_1 is L -equivalent with D_1 and C_2 is L -equivalent with D_2 . Let E be some context environment, we prove:

$$E[C_1 \cdot C_2] \in L \Leftrightarrow E[D_1 \cdot D_2] \in L.$$

We construct from E, C_1 and E, D_2 respectively two new context environments E_C and E_D such that

$$E_C[C_2] = E[C_1 \cdot C_2] \text{ and } E_D[D_1] = E[D_1 \cdot D_2].$$

Using the L -equivalence, we have:

$$\begin{aligned} E_D[C_1] \in L &\Leftrightarrow E_D[D_1] \in L \\ E_C[C_2] \in L &\Leftrightarrow E_C[D_2] \in L \end{aligned}$$

Note that by the definition of E_C and E_D we have $E_C[D_2] = E_D[C_1]$. It follows that

$$E[C_1 \cdot C_2] \in L \Leftrightarrow E[D_1 \cdot D_2] \in L.$$

Indeed

$$E[C_1 \cdot C_2] \in L \Leftrightarrow E_C[C_2] \in L \Leftrightarrow E_C[D_2] \in L \Leftrightarrow E_D[C_1] \in L \Leftrightarrow E_D[D_1] \in L.$$

Therefore, $C_1 \cdot C_2$ and $D_1 \cdot D_2$ are L -equivalent.

Item 4 Let C, C' be L -equivalent contexts and t, t' be L -equivalent trees. We want to prove that $C[t]$ and $C'[t']$ are two L -equivalent trees. Let D be a generic multicontext. We prove that

$$D[C[t]] \in L \Leftrightarrow D[C'[t']] \in L.$$

Let D' be a multicontext such that $D'[t] = D[C[t]]$ and E a context environment such that $E[C'] = D[C'[t']]$. Using the L -equivalence we have:

$$\begin{aligned} D'[t] \in L &\Leftrightarrow D'[t'] \in L \\ E[C] \in L &\Leftrightarrow E[C'] \in L \end{aligned}$$

By definition of E, D' we have $D'[t'] = E[C]$. It follows that

$$D[C[t]] \in L \Leftrightarrow D[C'[t']] \in L.$$

Therefore, $C[t]$ and $C'[t']$ are L -equivalent.

Item 5 Let C, C' be L -equivalent non-trivial contexts. We want to prove that C^∞ and C'^∞ are two L -equivalent trees. Let D be some multicontext, we prove that

$$D[C^\infty] \in L \Leftrightarrow D[C'^\infty] \in L.$$

Consider a context environment E constructed from D by replacing each port of D with an infinite chain of ports. Using L -equivalence of C and C' we get:

$$E[C] \in L \Leftrightarrow E[C'] \in L$$

By definition of E we have $E[C] = D[C^\infty]$ and $E[C'] = D[C'^\infty]$. It follows that

$$D[C^\infty] \in L \Leftrightarrow D[C'^\infty] \in L.$$

Therefore, C^∞ and C'^∞ are L -equivalent.

Item 6 We only do the proof for $t \mapsto c(t, \square)$, the other operations is handled symmetrically. Let t, t' be L -equivalent trees. Let E be some context environment, we prove that

$$E[c(t, \square)] \in L \Leftrightarrow E[c(t', \square)] \in L.$$

By inserting c into the ports of E we construct a multicontext C such that for all trees s , $C[s] = E[c(s, \square)]$. Using L -equivalence of t and t' we get:

$$C[t] \in L \Leftrightarrow C[t'] \in L$$

Therefore, $c(t, \square)$ and $c(t', \square)$ are L -equivalent.

The proof is complete. \square

Corollary 8.13. *The syntactic morphism α_L introduces the following algebraic structure on (H_L, V_L) :*

- composition of context types $V_L \ni u, v \mapsto u \cdot v \in V_L$,
- action of V_L on H_L i.e. $V_L \times H_L \ni (u, h) \mapsto u \cdot h \in H_L$,
- infinite composition $V_L \ni u \mapsto u^\infty \in H_L$,
- creation of contexts $H_L \ni h \mapsto c(\square, h), c(h, \square) \in V_L$ for $c \in A$.

Moreover, (V_L, \cdot) is a semigroup acting over H_L via \cdot , $(V_L \sqcup \{1_L\}, \cdot)$ is a monoid, and (H_L, V_L) satisfy the axioms of a Wilke algebra [Wil93].

The following fact follows from a general algebraic considerations, see [Idz12, Lemma 24 on page 42]; it can also be proved directly, by minimality of the syntactic algebra.

Fact 8.14. *The syntactic algebra (H_L, V_L) is faithful with respect to V_L : consider two elements $v, v' \in V_L$ and assume that for all $h \in H_L$ we have $vh = v'h$ and for all $u \in V_L$ we have $(vu)^\infty = (v'u)^\infty$; then $v = v'$.*

The next fact is considered folklore, see for instance [PP04, Proposition 1.11 in Annex A on page 442].

Fact 8.15. *Given any finite semigroup V , there is a number \sharp_V (denoted just \sharp if V is known from the context) such that for each element v of V the element v^\sharp is an idempotent, i.e. $v^\sharp = v^\sharp v^\sharp$.*

8.1 Quotients

Similarly as in the case of finite words, the syntactic algebra induces a natural notion of a quotient of a language: given a multicontext D with n holes and a language K of trees, by $D^{-1}(K)$ we denote the set of tuples (t_1, \dots, t_n) such that the valuation η mapping the i th port of D into t_i satisfies

$$D[\eta] \in K.$$

Notice that if D is a context then $D^{-1}(K)$ is a set of trees.

If L is a language recognised by a homomorphism α_L then the fact whether $D[t] \in L$ depends only on $\alpha_L(D) \in V_L \sqcup \{1_L\}$ and $\alpha_L(t) \in H_L$. Therefore, it makes sense to write $v^{-1}(L)$ for $v \in V_L \sqcup \{1_L\}$. Also in that case $v^{-1}(L)$ is a language recognised by the homomorphism α_L . Directly from the definition we get that

$$(vu)^{-1}(L) = u^{-1}(v^{-1}(L)). \quad (4)$$

8.2 The game on types

Now we want to extend the definition of the game \mathcal{H} to sets of contexts. Recall that contexts are defined as a special case of partial trees, with an additional port label that appears in exactly one leaf. Hence, there is a natural notion of product topology on contexts and therefore we can talk about open sets of contexts. This yields the definition of a game $\mathcal{V}(K_1, \dots, K_n)$ for a sequence K_1, \dots, K_n of context languages (i.e. subsets of $\text{Cntx}_A \sqcup \{\square\}$), which is played by Alternator and Constrainer. The game is played in n rounds. Round $i = 1$ is special: Alternator chooses a context $C_1 \in K_1$. Let u be the port of the context C_1 . This port will stay fixed for the rest of the game; all contexts produced by Alternator will have their port in the node u . Next, Constrainer chooses a finite prefix D_1 of C_1 , which has one of its leaves in the node u .

A subsequent round $i \in \{2, \dots, n\}$ is played as follows. Let D_{i-1} be the finite partial tree over $A \sqcup \{\square\}$ chosen by Constrainer in the previous round with a leaf in the node u .

- Alternator provides a context C_i , which extends D_{i-1} , belongs to K_i , and has its port in the node u . If there is no such context, the game is interrupted and Constrainer wins immediately.
- Constrainer chooses a finite prefix D_i of C_i and which has a leaf in the node u .

If Alternator manages to survive n rounds then he wins. Recall that by the definition of the syntactic morphism, a tree type $h \in H_L$ is actually equal to the set of trees $\alpha_L^{-1}(h)$, similarly for a context type $v \in V_L$. Therefore, it makes sense to talk about the games $\mathcal{H}(h_1, \dots, h_n)$, and $\mathcal{V}(v_1, \dots, v_n)$ for sequences of types. Using these games we define the following sets of sequences of types:

Definition 8.16. *We define two sets:*

$$\begin{aligned} \mathcal{H}_L &= \{(h_1, \dots, h_n) \in (H_L)^* \mid \text{Alternator wins } \mathcal{H}(h_1, \dots, h_n)\}, \\ \mathcal{V}_L &= \{(v_1, \dots, v_n) \in (V_L)^* \mid \text{Alternator wins } \mathcal{V}(v_1, \dots, v_n)\}. \end{aligned}$$

A comment on notation is in order here. The sets \mathcal{H}_L and \mathcal{V}_L contain words, over alphabets H_L and V_L , respectively. Usually when dealing with words, one omits the brackets and commas and writes abc instead of (a, b, c) . When the alphabet is V_L this leads to ambiguity, since the expression vwu can be interpreted as a word with a single letter obtained by multiplying the three context types v, w and u , or a three-letter word over the

alphabet V_L . These two interpretations should not be confused, so we write $(v_1 \dots, v_n)$ for n -letter words over the alphabet V_L . For the sake of uniformity, we also write (h_1, \dots, h_n) for n -letter words over the alphabet H_L , although there is no risk of ambiguity here.

It turns out that the sets of words \mathcal{H}_L and \mathcal{V}_L have specific structure. We say that a word u is a *subword* of w if u can be obtained from w by removing some letters. It is clear from the definitions of the games \mathcal{H} and \mathcal{V} that both sets \mathcal{H}_L and \mathcal{V}_L are closed under removing letters. Therefore, Higman's Lemma implies that both these sets are regular.

Lemma 8.17 (Higman's Lemma, see [Hig52]). *The set of finite words A^* over a finite alphabet A with the subword ordering is a well-quasi order: there is no infinite antichain nor an infinite descending chain.*

Corollary 8.18. *If $L \subseteq A^*$ is closed under removing letters then L is regular.*

Proof. Consider $L \subseteq A^*$ that is closed under removing letters. Then L forms a downward-closed set with respect to the subword relation. Thus, Higman's Lemma implies that there exists a finite set of words w_1, \dots, w_N such that w does not belong to L if and only if one of w_1, \dots, w_N is a subword of w . Such a condition is a regular condition. \square

Proposition 8.19. *Both \mathcal{H}_L and \mathcal{V}_L are regular languages of finite words.*

Proof. Both languages are closed under removing letters and therefore Corollary 8.18 applies. \square

The above fact is amusing, but useless, because it does not say how to compute automata for \mathcal{H}_L and \mathcal{V}_L as a function of a representation of the language L .

Lemma 8.20. *The following properties hold:*

1. $(h_1, \dots, h_n) \in \mathcal{H}_L$ implies $(C[h_1], \dots, C[h_n]) \in \mathcal{H}_L$.
2. $(v_1, \dots, v_n) \in \mathcal{V}_L$ implies $(E[v_1], \dots, E[v_n]) \in \mathcal{H}_L$.
3. $(v_1, \dots, v_n), (w_1, \dots, w_n) \in \mathcal{V}_L$ implies $(v_1 w_1, \dots, v_n w_n) \in \mathcal{V}_L$.
4. $(v_1, \dots, v_n) \in \mathcal{V}_L, (h_1, \dots, h_n) \in \mathcal{H}_L$ implies $(v_1 h_1, \dots, v_n h_n) \in \mathcal{H}_L$.
5. $(v_1, \dots, v_n) \in \mathcal{V}_L$ implies $(v_1^\infty, \dots, v_n^\infty) \in \mathcal{H}_L$.
6. $(h_1, \dots, h_n) \in \mathcal{H}_L$ implies $(c[\square, h_1], \dots, c[\square, h_n]) \in \mathcal{V}_L$.
7. $(h_1, \dots, h_n) \in \mathcal{H}_L$ implies $(c[h_1, \square], \dots, c[h_n, \square]) \in \mathcal{V}_L$.

Proof. All properties are proved by composing strategies, we prove the first one. All other properties are proved similarly. Assume that $(h_1, \dots, h_n) \in \mathcal{H}_L$, and consider some multicontext C (possibly with infinitely many ports). For all i let L_i be the set of trees that are Alternator's first move in some winning strategy for $\mathcal{H}(h_i, \dots, h_n)$. Note that since $(h_1, \dots, h_n) \in \mathcal{H}_L$, L_i is non-empty for all i .

Claim 8.21. *For all $i \leq n$, for all trees t obtained by plugging trees of L_i in the ports of C , Alternator has a winning strategy in $\mathcal{H}(C[h_i], \dots, C[h_n])$ such that the tree chosen in round 1 is t .*

Proof. We proceed by induction on i . For $i = n$ this is obvious. Assume the result holds for i and we prove it for $i - 1$. Let p be a prefix of t , for all subtree s plugged into a port of C , p yields some (possibly empty) prefix p_s of s . Since $s \in L_{i-1}$, p_s can be completed into a tree $s' \in L_i$. It follows that p can be completed into t' obtained by plugging trees of L_i in the ports of C . By induction hypothesis, Alternator has winning strategy in $\mathcal{H}(C[h_i], \dots, C[h_n])$ such the tree chosen in round 1 is t' . Finally we conclude that Alternator has winning strategy in $\mathcal{H}(C[h_{i-1}], \dots, C[h_n])$ such the tree chosen in round 1 is t . \square

Lemma 8.20 follows directly from the above claim. \square

Definition 8.22. *We define the alternation of a finite word to be its length, after iteratively eliminating letters that are identical to their predecessors. We say that a set of words has unbounded alternation if it contains words with arbitrarily large alternation. In the other case we say that a set has bounded alternation. A word is alternating if every two consecutive letters are distinct.*

For example the alternation of *abaabbb* is 4. The notion of *alternation* gives us another characterization of the class $\mathbf{BC}(\Sigma_1^0)$.

Lemma 8.23. *For a regular language L of infinite trees, the following conditions are equivalent:*

1. *Alternator wins the game $\mathcal{H}^{\infty, \neq}(L, n)$ for any n .*
2. *The set \mathcal{H}_L has unbounded alternation.*

Proof. We have to prove both the implications.

- 1 \Rightarrow 2. We show that if Alternator wins the game $\mathcal{H}^{\infty, \neq}(L, n)$, then \mathcal{H}_L contains a word of length n where every two consecutive letters are different. Suppose that Alternator wins $\mathcal{H}^{\infty, \neq}(L, n)$. Both L and L^c can be partitioned into tree types. By Lemma 5.2, Alternator wins $\mathcal{H}(h_1, \dots, h_n)$ for some sequence of types, such that h_i is included in L or its complement, depending on the parity of i . In particular, the consecutive types are different.
- 2 \Rightarrow 1. Suppose that \mathcal{H}_L has unbounded alternation. It is easy to check that \mathcal{H}_L is closed under removing letters, so there must be some $g, h \in H_L$ such that \mathcal{H}_L contains all the words

$$(g, h), (g, h, g, h), (g, h, g, h, g, h), \dots$$

Since g and h are different elements of the syntactic algebra, it follows that there must be some multicontext C such that the tree type $C[g]$ is contained in L , while the

tree type $C[h]$ is disjoint with L . By the first item of Lemma 8.20, we can conclude that \mathcal{H}_L contains all the words

$$(C[g], C[h]), (C[g], C[h], C[g], C[h]), (C[g], C[h], C[g], C[h], C[g], C[h]), \dots$$

It follows that Alternator can alternate arbitrarily long between the language L and its complement.

The proof is complete. \square

Lemma 8.24. *If \mathcal{V}_L has unbounded alternation then so does \mathcal{H}_L .*

Proof. Assume that \mathcal{V}_L has unbounded alternation. Take $n > 0$, we will find a sequence in \mathcal{H}_L of alternation at least n . Let $N \stackrel{\text{def}}{=} 2 \cdot n \cdot |V_L|^2$ and let (v_1, \dots, v_N) be an alternating sequence in \mathcal{V}_L of alternation N — such a sequence exists by the assumption and the fact that the language \mathcal{V}_L is closed under removing letters. By Pigeon-hole Principle, there exist two types $v \neq v' \in V_L$ such that the word $(v, v')^n$ can be obtained from (v_1, \dots, v_N) by removing letters. Thus, $(v, v')^n \in \mathcal{V}_L$. By the fact that $v \neq v'$ and Fact 8.14 we know that one of the following two cases holds.

The first case is that there exists $h \in H_L$ such that $vh \neq v'h$. Clearly $(h, h, \dots, h) \in \mathcal{H}_L$. By Item 4 from Lemma 8.20 we know that in that case $(vh, v'h, vh, v'h, \dots, v'h) \in \mathcal{H}_L$ but as $vh \neq v'h$ the alternation of that sequence is at least n .

The second case is that there exists $u \in V_L$ such that $(vu)^\infty \neq (v'u)^\infty$. Similarly as before, Items 3 and 5 of Lemma 8.20 imply that both the sequences $(vu, v'u, \dots, v'u)$ and $((vu)^\infty, (v'u)^\infty)^n$ belong to \mathcal{V}_L and \mathcal{H}_L respectively. As $(vu)^\infty \neq (v'u)^\infty$, the alternation of that element of \mathcal{H}_L is at least n and the proof is concluded. \square

9 Effective characterisation of $\text{BC}(\Sigma_1^0)$

In this section we state the crucial result of the paper, providing an effective characterisation of the class of regular tree languages in $\text{BC}(\Sigma_1^0)$.

Theorem 9.1. *For a regular language L of infinite trees, the following conditions are equivalent.*

1. L is a Boolean combination of open sets, i.e. $L \in \text{BC}(\Sigma_1^0)$.
2. Constrainer wins the game $\mathcal{H}^{\epsilon, \neq}(L, n)$ for all but finitely many n .
3. The set \mathcal{H}_L has bounded alternation.
4. The following identities are satisfied in the algebra (H_L, V_L) :

$$u^\#uw^\# = u^\#vw^\# = u^\#wv^\# \quad \text{if } (u, v, w) \in \mathcal{V}_L \text{ or } (w, v, u) \in \mathcal{V}_L \quad (5)$$

$$(u_2w_2^\#v)^\#u_1w_1^\infty = (u_2w_2^\#v)^\infty \quad \text{if } v \in V_L \text{ and } (u_1, u_2), (w_1, w_2) \in \mathcal{V}_L \quad (6)$$

Proof. We have already proved the implications $1 \Leftrightarrow 2 \Leftrightarrow 3$ respectively in Lemma 8.23 and Corollary 5.11. It remains to prove $3 \Leftrightarrow 4$. The direction $3 \Rightarrow 4$ is not hard and we prove it in the next section, whereas the direction $4 \Rightarrow 3$ forms the technical core of the paper. \square

Corollary 9.2. *The problem whether a regular language L belongs to $\text{BC}(\Sigma_1^0)$ is EXPTIME-complete, when the language L is given as a parity non-deterministic automaton \mathcal{A} recognising L .*

Proof. Given a representation of L , one can compute the algebra (H_L, V_L) in EXPTIME, see Fact 8.10. Then, verifying the equations from condition 4 of Theorem 9.1 can be done in time polynomial in the size of the algebra (which is exponential in the number of states of the given automaton for L).

Hardness follows immediately from EXPTIME hardness of the universality problem for non-deterministic automata over finite trees [Sei89], see [Wal02b, Theorem 4.1, page 8] for a generic reduction of problems about complexity of infinite tree languages to universality of finite tree languages. \square

10 The implication $3 \Rightarrow 4$

In this section we prove the implication $3 \Rightarrow 4$ of Theorem 9.1.

Proposition 10.1. *If the set \mathcal{H}_L has bounded alternation then the identities (5) and (6) of Theorem 9.1 are satisfied.*

We prove the contrapositive: if one of the identities (5) or (6) is violated then \mathcal{H}_L has unbounded alternation.

The case when (5) is violated. The assumption that (5) is violated says that there are $u, v, w \in V_L$ such that

$$(u, v, w) \in \mathcal{V}_L \quad \text{or} \quad (w, v, u) \in \mathcal{V}_L,$$

but the three context types $u^\sharp u w^\sharp$, $u^\sharp v w^\sharp$, and $u^\sharp w w^\sharp$ are not all equal. If the three context types are not equal then the second one must be different from either the first one or the third one. We only do the proof for the case when $(u, v, w) \in \mathcal{V}_L$ and when $u^\sharp u w^\sharp \neq u^\sharp v w^\sharp$; the other cases are entirely dual. For $n \geq 0$ and $i \in \{1, \dots, n\}$, define

$$\vec{w}_{(i,n)} \stackrel{\text{def}}{=} \left(\overbrace{u, u, \dots, u}^{2(n-i)+1}, v, \overbrace{w, w, \dots, w}^{2(i-1)} \right) \in (V_L)^{2n}.$$

This word is obtained from (u, v, w) by duplicating some letters, and therefore it belongs to \mathcal{V}_L . For a given n , consider the words

$$\vec{w}_{(1,n)}, \dots, \vec{w}_{(n,n)} \in \mathcal{V}_L.$$

These are n words of length $2n$. Let us multiply all these words coordinate-wise, yielding a word \vec{w}_n , also of length $2n$, which is depicted in the following picture:

$$\begin{array}{cccccccccc}
& & & & \text{letter } 2i-1 & & \text{letter } 2i & & & \\
& & & & \swarrow & & \swarrow & & & \\
\vec{w}_{(1,n)} = & u & u & u & u & u & u & u & u & v \\
\vec{w}_{(2,n)} = & u & u & u & u & u & u & v & w & w \\
\vec{w}_{(3,n)} = & u & u & u & u & v & w & w & w & w \\
\vec{w}_{(4,n)} = & u & u & u & v & w & w & w & w & w \\
\vec{w}_{(5,n)} = & u & v & w & w & w & w & w & w & w \\
& & & & \nwarrow & & \nwarrow & & & \\
& & & & u^{n-i+1}w^{i-1} & & u^{n-i}vw^{i-1} & & &
\end{array}$$

As \vec{w}_n is obtained by a coordinate-wise multiplication of the rows of the above matrix, and all these rows belong to \mathcal{V}_L , Lemma 8.20 implies that also $\vec{w}_n \in \mathcal{V}_L$.

Recall that \sharp is a number dependant on V_L such that for every $z \in V_L$ we know that z^\sharp is an idempotent. Choose some k , and take $n = k \cdot \sharp + 1$, and $i \in \{\sharp + 1, 2\sharp + 1, \dots, (k-1) \cdot \sharp + 1\}$. Consider the letters $2i-1$ and $2i$ in the word \vec{w}_n , which are

$$u^{n-i+1}w^{i-1} = u^\sharp u w^\sharp \quad u^{n-i}v w^{i-1} = u^\sharp v w^\sharp.$$

By the assumption, these letters are different, and therefore the word \vec{w} has alternation at least k . Because k was chosen arbitrarily, it follows that \mathcal{V}_L has unbounded alternation. Lemma 8.24 implies that in that case also \mathcal{H}_L has unbounded alternation.

The case when (6) is violated. The assumption that (6) is violated says that \mathcal{V}_L contains pairs (u_1, u_2) and (w_1, w_2) such that for some $v \in V_L$,

$$e^\infty \neq e u_1 w_1^\infty \quad \text{for } e \stackrel{\text{def}}{=} (u_2 w_2^\sharp v)^\sharp.$$

Let $h_1 = e^\infty$ and $h_2 = e u_1 w_1^\infty$, by the above assumption we know that $h_1 \neq h_2$. It turns out that a violation of Equation (6) has even stronger consequences than a violation of Equation (5), as expressed by the following claim.

Claim 10.2. *If Equation (6) is violated then Alternator wins $\mathcal{H}^\infty(h_1, h_2, h_1, \dots)$.*

The above claim implies in particular that for every n the sequence

$$(h_1, h_2)^n$$

belongs to \mathcal{H}_L , and thus \mathcal{H}_L has unbounded alternation.

Proof. Let C_{u_1}, C_{u_2} be contexts of types u_1, u_2 that witness that $(u_1, u_2), (w_1, w_2) \in \mathcal{V}$ i.e. they are contexts played by Alternator in the first rounds of the respective games. Let C_{u_2}, C_{w_2} , and C_v be any three contexts of types u_2, w_2 , and v respectively. Let $C_e \stackrel{\text{def}}{=} (C_{u_2} C_{w_2}^\sharp C_v)^\sharp$. The type of the context C_e is e .

The strategy of Alternator starts with the tree $t_1 = (C_e)^\infty$. We will demonstrate how it works for the first three rounds of the game, the rest is analogous.

Consider a prefix p_1 of the tree t_1 that is fixed by Constrainer. It must be the case that p_1 is a prefix of $(C_e)^{n_1}$ for some n_1 . Thus, Alternator can now provide the tree

$$t_2 = (C_e)^{n_1} \cdot C_{u_1} \cdot C_{w_1}^\infty.$$

Now Constrainer chooses a prefix p_2 of the above tree, in fact p_2 is a prefix of $(C_e)^{n_1} \cdot C_{u_1} \cdot C_{w_1}^{\sharp n_2}$ for some n_2 . Thus, by the assumptions on C_{u_1} and C_{u_2} , Alternator is able to provide a tree of the form

$$t_2 = (C_e)^{n_1} \cdot (D_{u_2} \cdot D_{w_2}^{\sharp n_2} \cdot C_v) \cdot (C_e)^\infty,$$

where the contexts D_{u_2} and D_{w_2} depend on the prefix p_2 and have types u_2 and w_2 respectively. Now we proceed inductively as before, because any prefix p_3 of t_2 must be a prefix of $(C_e)^{n_1} \cdot (D_{u_2} \cdot D_{w_2}^{\sharp n_2} \cdot C_v) \cdot (C_e)^{n_3}$.

Notice that by the choice of e , the type of the context $D_{u_2} \cdot D_{w_2}^{\sharp n_2} \cdot C_v$ is e . Therefore, the trees t_i for odd i have type $e^\infty = h_1$ and the trees t_i for even i have type $eu_1w_1^\infty = h_2$. \square

Since (H_L, V_L) is a syntactic algebra, every two distinct types $h_1 \neq h_2$ can be distinguished with respect to the language, see Definition 8.4. Thus, by using the above strategy under some fixed multicontext C , we obtain the following corollary.

Corollary 10.3. *If Equation (6) is violated then Alternator wins $\mathcal{H}^\infty(L)$.*

11 The implication $4 \Rightarrow 3$ — case distinction

We now move to the implication $4 \Rightarrow 3$ of Theorem 9.1, which is the most involved part of the article. To prove it, we need to introduce a crucial concept witnessing large alternation of the set \mathcal{H}_L . The objects witnessing that will be called *strategy trees* and *locally optimal strategy trees*. Using these objects we will split the proof of that implication into two separate cases. We deal with these cases in the following two sections of the paper.

11.1 Strategy trees

First, a *type-labelled tree* is a tree such that the nodes are labelled with tree types, i.e. it is a tree over the alphabet H_L .

Definition 11.1. *If t is a tree over the alphabet A , the type-labelled tree induced by t is the type-labelled tree σ where the label of a node u is the tree type of the subtree $t.u$, i.e. $\sigma(u) = \alpha_L(t.u)$. In particular $\sigma(\epsilon) = \alpha_L(t)$.*

Definition 11.2. *Let σ be a type-labelled tree and let t be a tree over A . We say that σ is locally consistent with t if for every node $u \in \{\mathbf{L}, \mathbf{R}\}^*$, whose label in t is a , we have that $\sigma(u)$ is the type obtained by applying the letter a to the pair of types $\sigma(u_{\mathbf{L}})$ and $\sigma(u_{\mathbf{R}})$, that is*

$$\sigma(u) = a(\sigma(u_{\mathbf{L}}), \square) \cdot \sigma(u_{\mathbf{R}}). \quad (7)$$

In other words, if we take a tree t_1 inside $\sigma(u_{\mathbf{L}})$ and a tree t_2 inside $\sigma(u_{\mathbf{R}})$ and we plug these two trees as the left and the right children of a , then the type of the result is $\sigma(u)$.

Remark 11.3. *The type-labelled tree induced by t is locally consistent with t .*

Example 11.4. *Consider the language*

$$L = \{t \in \text{Tr}_A \mid t \text{ contains at least one } b\}$$

over the alphabet $A = \{a, b\}$. H_L contains two tree types that (treated as sets of trees) are L and L^c . Now consider a type-labelled tree σ where every node is labelled with L . It is easy to check that σ is locally consistent with every tree $t \in \text{Tr}_A$, even with the tree that contains only letters a .

Fact 11.5. *The set of pairs*

$$\{(t, \sigma) \in \text{Tr}_A \times \text{Tr}_{H_L} \mid \sigma \text{ is locally consistent with } t\}$$

is closed in the product topology.

Proof. As Condition (7) speaks about finitely many values of σ and t , it corresponds to a clopen set of pairs. A type-labelled tree σ is locally consistent with a tree t if they obey the local consistency conditions from (7) in all the vertices. Thus, the above defined set of pairs is an intersection of a family of clopen sets. \square

Lemma 11.6. *Let $(t_n)_{n \in \mathbb{N}}$ be a sequence of trees that converges to t_* and let $(\sigma_n)_{n \in \mathbb{N}}$ be a sequence of type-labelled trees that converges to σ_* . If σ_n is locally consistent with t_n for every n then σ_* is locally consistent with t_* .*

Proof. Follows directly from Fact 11.5. \square

Now we are ready to define strategy trees, a key concept of this paper.

Definition 11.7. *A strategy tree is a tuple $\sigma = (t, \sigma_1, \dots, \sigma_n)$ where:*

1. *t is a tree over A , called the support of σ .*
2. *σ_1 is the type-labelled tree induced by t .*
3. *The type-labelled trees $\sigma_2, \dots, \sigma_n$ are locally consistent with t .*
4. *For each node u of t , the sequence $(\sigma_2(u), \dots, \sigma_n(u))$ belongs to \mathcal{H}_L .*

Notice that the fourth condition of Definition 11.7 does not mention the type-labelled tree σ_1 . By the definition, σ can be interpreted as a single tree over the alphabet $A \times H_L^n$.

Intuitively speaking, a strategy tree represents a special kind of strategy for Alternator. In the first round, Alternator plays the support t of σ . However, Alternator also declares all the types that will appear in the nodes of t as the game progresses. More specifically, he declares that for every node u of t and round $k \in \{2, \dots, n\}$, he has a strategy so that for the tree played in the round k , the subtree in the node u has type $\sigma_k(u)$.

Alternations. The number n is called the *duration* of a strategy tree $\sigma = (t, \sigma_1, \dots, \sigma_n)$. We define the *root sequence* of a strategy tree to be the sequence of root labels of $\sigma_1, \dots, \sigma_n$. If the duration is n , the root sequence is in H_L^n . We define the *root alternation* of a strategy tree σ to be the alternation of its root sequence. We define the *limit alternation* of σ to be the maximal number ℓ such that infinitely many subtrees of σ have root alternation at least ℓ . This means that if the limit alternation of σ is ℓ then there exist infinitely many nodes u such that their root sequence (i.e. the root sequence of the strategy tree obtained by truncating σ in the node u) has alternation at least ℓ .

Context zones. A *context zone* is a set X of nodes for which there exists a node u , called the *root* of X , and a node y , called the *port* of X , such that $u \prec y$ and X contains the nodes that are in the subtree of u , but not in the subtree of y :

$$X = \{x \in \{\mathsf{L}, \mathsf{R}\}^* \mid u \preceq x \wedge y \not\preceq x\}.$$

We say that context zones X_1, \dots, X_n are *consecutive* if for each $i \in \{1, \dots, n-1\}$, the port of X_i is the root of X_{i+1} . The union of consecutive context zones is a context zone.

Consider a tree t , a type-labelled tree σ , and a context zone X . X can be seen as a context inside t taking into account the types of the subtrees of t as declared in σ . This is achieved by defining a value $\text{val}(t, \sigma, X) \in V_L$. The definition of $\text{val}(t, \sigma, X)$ is inductive on the number of nodes v in X such that $v \preceq y$, where y is the port of X . If there is only one such node then the port y of X is a child of its root u . Let a be the label of u in t and $v \in X$ be the other child of u . We set $\text{val}(t, \sigma, X)$ as $a(\square, \sigma(v))$ if v is the right child and $a(\sigma(v), \square)$ if v is the left child. Otherwise, let u be the root of X , y its port and z the child of u such that $z \preceq y$. Let X_1 be the context zone with root u and port z and X_2 the context zone of root z and port y . We define

$$\text{val}(t, \sigma, X) \stackrel{\text{def}}{=} \text{val}(t, \sigma, X_1) \cdot \text{val}(t, \sigma, X_2).$$

Figure 5 illustrates an example of a tree and a context zone with

$$\text{val}(t, \sigma, X) = b(\square, h_1) \cdot c(h_2, \square) \in V_L.$$

In other words, $\text{val}(t, \sigma, X)$ is the value of the context $C \stackrel{\text{def}}{=} t \upharpoonright X$ when we assume that the subtrees of t aside of the branch leading to the port of C have types as declared by σ .

Now assume that $\sigma = (t, \sigma_1, \dots, \sigma_n)$ is a strategy tree. Let X be a context zone of σ (we can see σ as a single tree). For a round $i \in \{1, \dots, n\}$, we define the type

$$\text{val}(\sigma, X, i) \stackrel{\text{def}}{=} \text{val}(t, \sigma_i, X) \in V_L.$$

Fact 11.8. *Let $\sigma = (t, \sigma_1, \dots, \sigma_n)$ be a strategy tree and X be a context zone. Then*

$$(\text{val}(\sigma, X, 1), \dots, \text{val}(\sigma, X, n)) \in \mathcal{V}_L.$$

Proof. This is by construction and Items 3, 6 and 7 of Lemma 8.20. □

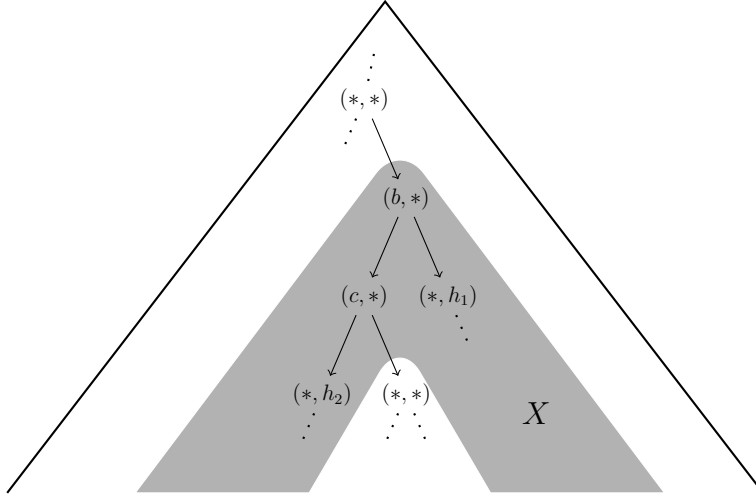


Figure 5: An illustration to the value $\text{val}(t, \sigma, X)$. The gray area is the set X , a label (a, h) of a node u represents the values of $t(u) = a$ and $\sigma(u) = h$ respectively. The symbol $*$ indicates values that are irrelevant for the value of the set X .

11.2 Existence of strategy trees

We will now prove that whenever Alternator has a strategy in \mathcal{H} then this fact is witnessed by a strategy tree. This fact is expressed by the following two lemmas. For inductive reasons these lemmas are parametrised by a finite multicontext C . The games $\mathcal{H}_C(h_1, \dots, h_n)$ and $\mathcal{V}_C(h_1, \dots, h_n)$ are defined as the games $\mathcal{H}_U(h_1, \dots, h_n)$ and $\mathcal{V}_U(h_1, \dots, h_n)$ respectively, where U is the open set of all trees (resp. contexts) that can be obtained from C , i.e. $C[*]$.

Lemma 11.9. *Let C be a finite multicontext for strategy trees. Consider a sequence of valuations η_1, \dots, η_n that map ports of C to H_L . If*

$$(\eta_1(u), \dots, \eta_n(u)) \in \mathcal{H}_L$$

for every port u , then Alternator wins the game

$$\mathcal{H}_C(C[\eta_1], \dots, C[\eta_n]).$$

Proof. For every port u of C , Alternator has a winning strategy for the game

$$\mathcal{H}(\eta_1(u), \dots, \eta_n(u)).$$

We describe a winning strategy for Alternator in $\mathcal{H}_C(C[\eta_1], \dots, C[\eta_n])$. Alternator starts with a tree obtained by plugging the initial tree from his winning strategy in the game $\mathcal{H}(\eta_1(u), \dots, \eta_n(u))$ in every port u of C . Then every prefix of this tree yields a prefix for each subtree plugged into a port of C and Alternator can then use his strategies for the game $\mathcal{H}(\eta_1(u), \dots, \eta_n(u))$ to answer. \square

Lemma 11.10. *For a sequence $(h_1, \dots, h_n) \in H_L^*$ and a finite multicontext C the following conditions are equivalent:*

1. *Alternator wins $\mathcal{H}_C(h_1, \dots, h_n)$.*
2. *There is a strategy tree whose support extends C , with root sequence (h_1, \dots, h_n) .*

Proof. We prove the lemma by induction on n . The base case when $n = 0$ or $n = 1$, is trivial. We do the induction step. Let us begin with the easier implication from 2 to 1. Suppose that

$$\sigma \equiv (t, \sigma_1, \dots, \sigma_n)$$

is a strategy tree as in item 2. Alternator's strategy is as follows. In the first round, he plays the tree t , which has type h_1 . Suppose Constrainer chooses a prefix D of t . Consider the valuations η_2, \dots, η_n that map ports of D to H_L with $\eta_i(u) = \sigma_i(u)$ for any port u . For every $i \in \{2, \dots, n\}$, the root label of σ_i is the same as $D[\eta_i]$, because σ_i is locally consistent with t and D is a prefix of t . By Lemma 11.9, Alternator wins the game

$$\mathcal{H}_D(D[\eta_2], \dots, D[\eta_n]).$$

This shows that for every choice of D , Alternator has a winning strategy in the remaining part of the game.

Now we move to the more difficult implication from 1 to 2.

Suppose that Alternator wins $\mathcal{H}_C(h_1, \dots, h_n)$. Let t be the tree of type h_1 that Alternator plays in the first round. This tree has prefix C . Also, for every finite prefix D of t , Alternator wins $\mathcal{H}_D(h_2, \dots, h_n)$. By the induction assumption, for every finite prefix D of t , there is a strategy tree

$$\sigma_D = (t_D, \sigma_{D_2}, \dots, \sigma_{D_n})$$

such that t_D has prefix D , and the root sequence of σ_D is (h_2, \dots, h_n) .

A sequence of finite multicontexts $(D_i)_{i \in \omega}$ is said to converge to t if all of the multicontexts are prefixes of t , and for every $j \in \omega$, only finitely many multicontexts have some port at depth at most j . By compactness, there is an infinite sequence of finite multicontexts $(D_i)_{i \in \omega}$ which converges to the tree t and such that all of the sequences

$$(t_{D_i})_{i \in \omega} \quad (\sigma_{D_i 2})_{i \in \omega} \quad \dots \quad (\sigma_{D_i n})_{i \in \omega}$$

are convergent. Let the limits of these sequences be

$$t_* \quad \sigma_{*2} \quad \dots \quad \sigma_{*n}.$$

Because the sequence $(D_i)_{i \in \omega}$ converges to t , it follows that $t_* = t$. For each D , the type trees

$$(\sigma_{D 2}, \dots, \sigma_{D n})$$

are locally consistent with t_D . Therefore, by Lemma 11.6 it follows that the limits $\sigma_{*2}, \dots, \sigma_{*n}$ are locally consistent with t . Finally, define σ_{*1} to be the unique type tree that is globally consistent with t . We have just proved that

$$(\sigma_{*1}, \dots, \sigma_{*n})$$

is a strategy tree. Because root values are preserved under limits, the root value of this strategy tree is the desired (h_1, \dots, h_n) . \square

11.3 Locally optimal strategy trees

To make the structure of a strategy tree more rigid, we will introduce a notion of a *locally optimal strategy tree*. In such a strategy tree, whenever $\sigma_i(u) \neq \sigma_{i+1}(u)$, there is some concrete reason for that fact.

Definition 11.11. Consider a strategy tree $(t, \sigma_1, \dots, \sigma_n)$ and let $v \in V_L \sqcup \{1_L\}$. The strategy tree is called *locally optimal* for v if for every $i \in \{2, \dots, n\}$ and for every type-labelled tree σ' , if σ' is locally consistent with t and $v \cdot \sigma'(\epsilon) = v \cdot \sigma_i(\epsilon)$, then

$$\lambda(\sigma_{i-1}, \sigma_i) \leq \lambda(\sigma_{i-1}, \sigma'),$$

where λ is the discounted distance.

If σ is optimal for the context type 1_L of the trivial context \square then we just say that σ is *locally optimal*.

Fact 11.12. If σ is locally optimal for $u \cdot v$ then σ is locally optimal for v as well.

Lemma 11.13. Consider a strategy tree σ with root sequence (h_1, \dots, h_n) . Let $v \in V_L \sqcup \{1_L\}$ be a context type. Then there exists a locally optimal strategy tree σ' for v with root sequence (h'_1, \dots, h'_n) such that

$$v \cdot (h_1, \dots, h_n) = v \cdot (h'_1, \dots, h'_n). \quad (8)$$

Proof. Take a strategy tree $\sigma = (t, \sigma_1, \dots, \sigma_n)$. Consider the set Σ_2 of type-labelled trees σ'_2 that are:

- locally consistent with t ,
- if h (resp. h') is the root value of σ_2 (resp. σ'_2) then $v \cdot h = v \cdot h'$.

Fact 11.5 implies that Σ_2 is a closed set. As a closed subset of the compact space of all trees, Σ_2 is compact. It follows that some elements of Σ_2 minimise the discounted distance with respect to σ_1 . We choose such an element as the new σ_2 and we iterate this mechanism to build a locally optimal strategy tree $\bar{\sigma}$. This tree satisfies condition (8). If $v \neq 1_L$ then the root sequence of the new strategy tree might be different than the original root sequence. However, if $v = 1_L$ then the root sequence is not modified. \square

Corollary 11.14. *If $(h_1, h_2, \dots, h_n) \in \mathcal{H}_L$ then there exists a locally optimal strategy tree σ with root sequence (h_1, \dots, h_n) .*

Using the above properties, without loss of generality we can restrict our attention to locally optimal strategy trees. One of the direct consequences of working with such strategy trees is expressed by the following lemma.

Lemma 11.15. *If σ is a locally optimal strategy tree, $u \preceq y$ two nodes of σ then for all $i = 1, \dots, n$ we have*

$$\sigma_i(y) \neq \sigma_{i+1}(y) \Rightarrow \sigma_i(u) \neq \sigma_{i+1}(u).$$

Proof. Assume that $\sigma_i(y) \neq \sigma_{i+1}(y)$ and $\sigma_i(u) = \sigma_{i+1}(u)$. We show that this contradicts local optimality. Consider the type-labelled tree σ'_{i+1} defined as follows:

- for every z such that $u \preceq z$, $\sigma'_{i+1}(z) = \sigma_i(z)$,
- for all other nodes z , $\sigma'_{i+1}(z) = \sigma_{i+1}(z)$.

By the construction, σ'_{i+1} is locally consistent with t (this is by the definition for all nodes $z \neq u$, and because $\sigma_i(u) = \sigma_{i+1}(u)$). Note that by the definition, for all nodes z :

$$\text{dist}(\sigma_i(z), \sigma'_{i+1}(z)) \leq \text{dist}(\sigma_i(z), \sigma_{i+1}(z))$$

Moreover, $\text{dist}(\sigma_i(y), \sigma'_{i+1}(y)) = 0$ and $\text{dist}(\sigma_i(y), \sigma_{i+1}(y)) = 1$. Combining all this we obtain:

- $\lambda(\sigma_i, \sigma'_{i+1}) < \lambda(\sigma_i, \sigma_{i+1})$.
- $\text{val}(\sigma'_{i+1}) = \text{val}(\sigma_{i+1})$.

This contradicts local optimality of σ . □

Corollary 11.16. *If σ is a locally optimal strategy tree and $u \preceq y$ are two nodes of σ then the root alternation of $\sigma.u$ is not smaller than the root alternation of $\sigma.y$.*

11.4 Case distinction

We can now split the proof of the implication $4 \Rightarrow 3$ of Theorem 9.1 into two subcases, as discussed below. Then we will treat these cases separately, as expressed by Propositions 11.17 and 11.18.

Assume for the sake of contradiction that Condition 3 of Theorem 9.1 is violated, what means that \mathcal{H}_L has unbounded alternation. Thus, by Corollary 11.14 we know that the root alternation of the set of all locally optimal strategy trees for L (denoted Σ_L) is unbounded. Now consider the following two dual subcases:

- (C1) Σ_L has unbounded root alternation and there exists a subset $\Sigma' \subseteq \Sigma_L$ that has unbounded root alternation but bounded limit alternation.

(C2) Σ_L has unbounded root alternation and every subset $\Sigma' \subseteq \Sigma_L$ with unbounded root alternation has also unbounded limit alternation.

The following two propositions consider these cases separately:

Proposition 11.17. *Assuming (C1), Equation (5) is violated.*

Proposition 11.18. *Assuming (C2), Equation (6) is violated.*

The proofs of these propositions are given in Sections 12 and 13. Notice that since either (C1) or (C2) must hold, both these propositions complete the proof of the implication $4 \Rightarrow 3$ of Theorem 9.1.

Roughly speaking, Case (C1) corresponds to the situation in which high alternation of \mathcal{H}_L is achieved by modifications in the strategy trees that are spread inside their structure. On the opposite, Case (C2) corresponds to the situation in which the high alternation occurs on some infinite branch of the considered strategy trees.

12 Case (C1) — limit alternation is bounded

In this section we assume that $\Sigma' \subseteq \Sigma_L$ is a set of locally optimal strategy trees such that the root alternation of Σ' is unbounded but the limit alternation of Σ' is bounded. Under that assumption we prove that Equation (5) is violated. We do this in two steps, using a new object called *strategy matrix* as an intermediary. Strategy matrices represent special strategies for Alternator in the game on tree types. In our first step, we show that if the root alternation of Σ' is unbounded but the limit alternation of Σ' is bounded then there exist special strategy matrices of arbitrarily large size. Finally we show that the existence of sufficiently large special strategy matrices violates Equation (5).

Definition 12.1. *A strategy matrix is a rectangular matrix with entries from V_L such that every row belongs to \mathcal{V}_L . The value of a column of a strategy matrix is the value in V_L obtained by multiplying the entries in that column in V_L in the top-to-bottom order.*

Definition 12.2. *A strategy matrix M is called parity alternating if for some $n \in \omega$ it has $2n$ columns and n rows, and one of the following conditions holds (see Figure 6):*

- a) *For every $i \in \{1, \dots, n\}$,*
 - *Columns $2i - 1$ and $2i$ have the same entries in all rows except for row i .*
 - *The values of columns $2i - 1$ and $2i$ are different.*
- b) *Condition a) holds when the order of columns is reversed.*

If the case a) holds then the matrix is called top-down and if the case b) holds then it is called bottom-up. The set of parity alternating matrices with n rows and $2n$ columns is denoted by \mathbb{P}_n .

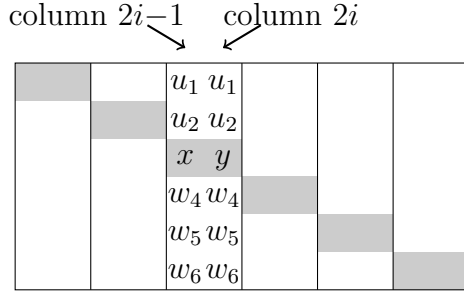


Figure 6: A matrix in \mathbb{P}_6 .

Figure 6 depicts a top-down parity alternating strategy matrix in \mathbb{P}_6 . The picture presents columns $2i - 1$ and $2i$ for $i = 3$, the entries of these columns agree everywhere except the third row, where the values x and y are distinct. The differences in all the other pairs of columns are indicated by gray rectangles, their values are not written down for the sake of clarity. It is important that the definition of a parity alternating strategy matrix requires the total values of the respective columns to differ, not only the entries in gray rectangles.

12.1 Constructing strategy matrices

As we have already said, we want to prove that under our assumptions we can build arbitrary large strategy matrices: the goal that we aim now, is to prove that if Σ' has unbounded root alternation and bounded limit alternation, then \mathbb{P}_n is non-empty for every $n \in \omega$.

Fix some arbitrary $n \in \omega$. We want to construct a strategy matrix $M \in \mathbb{P}_n$. Let ℓ be the maximal limit alternation among the strategy trees in Σ' . Choose a strategy tree $\sigma \in \Sigma'$ with root alternation at least $\ell \cdot 2^{n^2}$ and let m be the duration of σ , i.e. $\sigma = (t, \sigma_1, \dots, \sigma_m)$.

During the proof we will use a known combinatorial fact that we recall now.

Theorem 12.3 (Erdős-Szekeres Theorem, see [ES35]). *For given $r, s \in \mathbb{N}$, any sequence of length at least $(r-1)(s-1)+1$ contains a monotonically increasing subsequence of length r or a monotonically decreasing subsequence of length s .*

Lemma 12.4. *There are consecutive contexts zones X_1, \dots, X_n in σ and a sequence of rounds $i_1, \dots, i_n \in \{1, \dots, m-1\}$ such that the sequence of rounds is either strictly increasing or strictly decreasing, and*

$$\text{val}(\sigma, i_j, X_j) \neq \text{val}(\sigma, i_j+1, X_j) \quad \text{for every } j \in \{1, \dots, n\}$$

Proof. For a round $i \in \{1, \dots, m-1\}$, define:

$$\text{change}_i(\sigma) = \{x \in \{\mathbb{L}, \mathbb{R}\}^* \mid \sigma_i(x) \neq \sigma_{i+1}(x)\}.$$

Now we prove three different claims. Once these claims are proved, we easily finish the proof of the lemma.

Claim 1 Let X be a context zone, and let π be an infinite path that passes through the root of X , but not through the port. Then

$$\pi \subseteq \text{change}_i(\sigma) \implies \text{val}(\sigma, i, X) \neq \text{val}(\sigma, i+1, X)$$

holds for every round $i \in \{1, \dots, m-1\}$.

Proof of Claim 1. This is by local optimality of σ . Assume that $\pi \subseteq \text{change}_i(\sigma)$ and $\text{val}(\sigma, i, X) = \text{val}(\sigma, i+1, X)$ for some round i . We construct a type-labelled tree σ'_{i+1} that is closer to σ_i than σ_{i+1} regarding the discounted distance λ and with the same root value as σ_{i+1} , contradicting local optimality.

Consider the type-labelled tree σ'_{i+1} defined as follows:

- For nodes $x \in X$ $\sigma'_{i+1}(x) = \sigma_i(x)$. Hence, for $x \in X$

$$\text{dist}(\sigma_i(x), \sigma'_{i+1}(x)) = 0 \leq \text{dist}(\sigma_i(x), \sigma_{i+1}(x))$$

- For other nodes y we define $\sigma'_{i+1}(y) = \sigma_{i+1}(y)$. Hence

$$\text{dist}(\sigma_i(y), \sigma'_{i+1}(y)) = \text{dist}(\sigma_i(y), \sigma_{i+1}(y)).$$

Because $\pi \subseteq \text{change}_i(\sigma)$, there exists at least one node $x \in X$ such that s

$$\text{dist}(\sigma_i(x), \sigma_{i+1}(x)) = 1.$$

It follows that:

$$\lambda(\sigma_i, \sigma'_{i+1}) < \lambda(\sigma_i, \sigma_{i+1})$$

Moreover since $\text{val}(\sigma, i, X) = \text{val}(\sigma, i+1, X)$, we have $\sigma'_{i+1}(\epsilon) = \sigma_{i+1}(\epsilon)$. This contradicts local optimality of σ .

The proof of Claim 1 is complete. \square

Claim 2 There is a set Π of at least 2^{n^2} distinct infinite paths, and a function $\text{when} : \Pi \rightarrow \{1, \dots, m-1\}$ such that for every $\pi \in \Pi$

$$\pi \subseteq \text{change}_{\text{when}(\pi)}(\sigma).$$

Proof of Claim 2. By consistency of a strategy tree, every node in $\text{change}_j(\sigma)$ has at least one child in $\text{change}_j(\sigma)$. Therefore, each of the non-empty sets $\text{change}_j(\sigma)$ contains at least one infinite path. By the assumption on the root alternation there are at least $\ell \cdot 2^{n^2}$ rounds j where $\text{change}_j(\sigma)$ is non-empty. By the assumption on limit alternation, an infinite path can be contained in sets $\text{change}_j(\sigma)$ for at most ℓ different values of j . This proves the statement of Claim 2. \square

Claim 3 Let Π be a set of 2^k distinct infinite paths in a binary tree. There exist consecutive context zones X_1, \dots, X_k and paths $\pi_1, \dots, \pi_k \in \Pi$ such that for every $i \in \{1, \dots, k\}$, the path π_i passes through the ports of the context zones X_1, \dots, X_{i-1} , but not through the port of X_i .

Proof of Claim 3. The proof is by induction on k . The induction base of $k = 1$ is obvious.

Now assume that the thesis holds for k and consider a set Π of 2^{k+1} paths. Let u be the deepest node in the tree that belongs to all paths of Π (u exists since the root belongs to all paths of Π). Let Π_L (respectively, Π_R) be those paths in Π that pass through the left child of u (respectively, the right child of u). One of the sets Π_L or Π_R must have at least half of the paths, i.e. at least 2^k paths. By symmetry, assume that Π_L has at least 2^k paths and let y be the left child of u . We apply the induction hypothesis to Π_L and obtain paths $\pi_2, \dots, \pi_{k+1} \in \Pi_L$ and consecutive context zones X_2, \dots, X_{k+1} such that for every $i \in \{2, \dots, k+1\}$, path π_i passes through the ports of contexts X_2, \dots, X_{i-1} , but not through the port of X_i .

We slightly modify X_2 by setting y as its root. Note that this does not affect the properties of the paths $\pi_2, \dots, \pi_{k+1} \in \Pi_L$. Now, we define X_1 as the context zone with the root u and the root of X_2 as the port. Let π_1 be some arbitrary path in Π_R . By the definition, X_1, \dots, X_{k+1} are consecutive context zones. Moreover, the paths π_2, \dots, π_{k+1} are paths of Π_L and therefore pass through y , i.e. the port of X_L . Finally, by the definition π_1 passes through the right child of u and therefore not through the port of X_1 . The proof of the third claim is complete. \square

Now we can easily complete the proof of Lemma 12.4. Let Π and the function **when** be as defined in Claim 2. Apply Claim 3 to Π , yielding a sequence of paths, $\tau_1, \dots, \tau_{n^2}$, and a sequence of context zones, Y_1, \dots, Y_{n^2} , such that for every $i \in \{1, \dots, n^2\}$, the path τ_i passes through the ports of context zones Y_1, \dots, Y_{i-1} , but not through the port of Y_i . Consider the sequence

$$\text{when}(\tau_1), \dots, \text{when}(\tau_{n^2}) \in \{1, \dots, m-1\}.$$

By Erdős-Szekeres Theorem, we can find a sequence of indexes

$$j_1 < \dots < j_n \in \{1, \dots, n^2\}$$

such that the sequence

$$\text{when}(\tau_{j_1}), \dots, \text{when}(\tau_{j_n})$$

is either increasing or decreasing. For $i \in \{1, \dots, n\}$, define π_i to be τ_{j_i} and X_i to be the union of the context zones

$$Y_{j_i} \cup \dots \cup Y_{j_{i+1}-1}.$$

By the construction, we know that the path π_i passes through the ports of the context zones X_1, \dots, X_{i-1} , but not through the port of the context zone X_i . By Claim 1 we know that

$$\text{val}(\sigma, \text{when}(\pi_i), X_i) \neq \text{val}(\sigma, \text{when}(\pi_i) + 1, X_i).$$

Therefore, our proof is complete if we define i_1, \dots, i_n to be

$$\text{when}(\pi_1), \dots, \text{when}(\pi_n).$$

This concludes the proof of Lemma 12.4. \square

Definition 12.5. Let M be a matrix and consider a row j and a column i of M which is not the first column. We define a new column, denoted by

$$\text{almostcopy}_i^{\neq j}(M),$$

as follows: $\text{almostcopy}_i^{\neq j}(M)$ is equal to column i of M in all rows except for row j , where it is equal to column $i - 1$ of M .

Definition 12.6. Let σ be a strategy tree of duration m and let X_1, \dots, X_n be consecutive context zones. We define a matrix with n rows and m columns as follows (for $i = 1, \dots, m$ and $j = 1, \dots, n$):

$$\text{matrix}(\sigma, X_1, \dots, X_n) [i, j] \stackrel{\text{def}}{=} \text{val}(\sigma, i, X_j).$$

Note that it follows from Fact 11.8 that every row of $\text{matrix}(\sigma, X_1, \dots, X_n)$ belongs to \mathcal{V}_L and therefore it is a strategy matrix.

Lemma 12.7. Let N be a strategy matrix defined by

$$N = \text{matrix}(\sigma, X_1, \dots, X_n),$$

for some locally optimal strategy tree σ and consecutive context zones X_1, \dots, X_n . Let j be a row and i a column, which is not the first column. If columns i and $i - 1$ in N have different entries in row j then the value of the column

$$\text{almostcopy}_i^{\neq j}(N)$$

is different from the value of column i in N .

Proof. This is a consequence of local optimality of σ . The proof is the same as Claim 2 in the proof of Lemma 12.4. \square

Now we are ready to prove the first intermediary step: constructing a matrix in \mathbb{P}_n .

Proposition 12.8. Under our assumptions about the strategy tree σ we can construct a matrix $M \in \mathbb{P}_n$.

Proof. Let X_1, \dots, X_n and i_1, \dots, i_n be as in Lemma 12.4. Consider the strategy matrix $N = \text{matrix}(\sigma, X_1, \dots, X_n)$.

By Lemma 12.4 we know that for every $j \in \{1, \dots, n\}$ the entries in row j are different in columns i_j and $i_j + 1$.

Suppose first that the sequence i_1, \dots, i_n is strictly increasing. Define a new matrix M , which has n rows and $2n$ columns as follows.

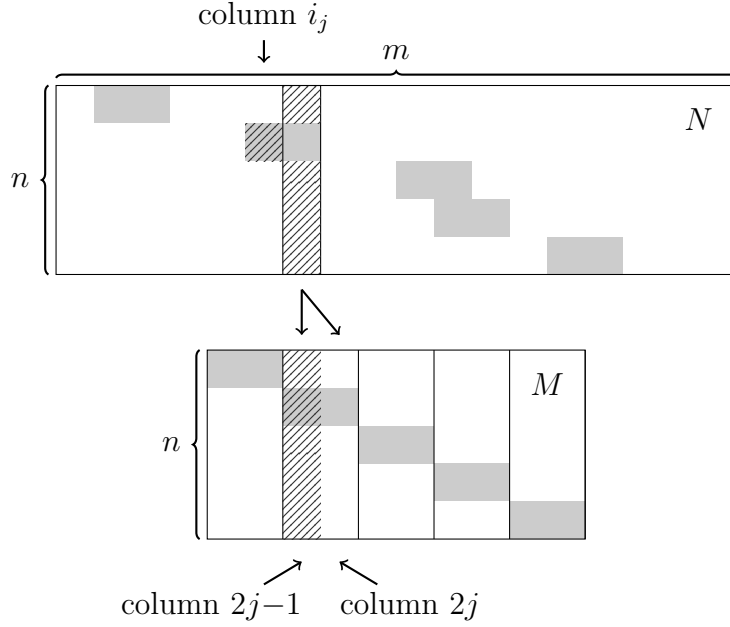


Figure 7: Construction of the matrix M from N . Column $2j - 1$ of M equals almostcopy of column $i_j + 1$ of N (i.e. the dashed part), while column $2j$ just equals column $i_j + 1$ of N .

- For $j \in \{1, \dots, n\}$, column $2j - 1$ of M is almostcopy $_{i_j+1}^{\neq j}(N)$.
- For $j \in \{1, \dots, n\}$, column $2j$ of M is column $i_j + 1$ of N .

Figure 7 depicts the process of constructing the matrix M . Gray regions in the matrix N indicate pairs of distinct values in a row j of the consecutive columns i_j and $i_j + 1$. We assume that the sequence i_j is strictly increasing (the other case leads to a bottom-up parity alternating strategy matrix).

Now we show that $M \in \mathbb{P}_n$. The dimensions of the matrix M are correct: it has n rows and $2n$ columns. We now show that M is a strategy matrix, which means that each row belongs to \mathcal{V}_L . For $j \in \{1, \dots, n\}$, let us see how row j of M

$$M[j, 1], \dots, M[j, 2n]$$

depends on row j of N

$$N[j, 1], \dots, N[j, m].$$

By reading the definition of M , we see that the dependency is

- When $k \neq j$, then $M[j, 2k - 1] = M[j, 2k] = N[j, i_k + 1]$.
- When $k = j$, then $M[j, 2k - 1] = N[j, i_k]$ and $M[j, 2k] = N[j, i_k + 1]$.

It follows that row j of M is obtained from row j of N by eliminating some letters and duplicating some other letters. Since \mathcal{V}_L is closed under eliminating and duplicating letters, and since N was a strategy matrix, it follows that also M is a strategy matrix.

By Lemma 12.7, for every $j \in \{1, \dots, n\}$, the values of columns $2j - 1$ and $2j$ in M are different. By the construction, columns $2j - 1$ and $2j$ in M have the same entries, except for row j . So M is parity alternating.

When the sequence i_1, \dots, i_n is strictly decreasing, the matrix M is defined like for a strictly increasing sequence, except that the columns of M are filled in not from left to right, but from right to left. Formally speaking:

- For $j \in \{1, \dots, n\}$, column $2(n - j + 1) - 1$ of M is almostcopy $_{i_j+1}^{\neq j}(N)$.
- For $j \in \{1, \dots, n\}$, column $2(n - j + 1)$ of M is column $i_j + 1$ of N .

The proof that M belongs to \mathbb{P}_n is the same as above. □

12.2 From strategy matrices to violation of (5)

So now we can do the second intermediary step. Let us assume that \mathbb{P}_n is non-empty for any n . By the symmetry we can assume that for every n there exists a top-down parity alternating matrix of size n (the other case is handled symmetrically): under this assumption we prove that Equation (5) is violated. To do that, we need to start from a parity alternating matrix of a large size, and by consecutive simplifications, construct a small matrix from the violation can be easily extracted.

Take a strategy matrix M . Our aim is define a matrix obtained form M by *merging* two consecutive rows i and $i + 1$ of M . Let

$$(v_{1,1}, \dots, v_{1,n}), \dots, (v_{k,1}, \dots, v_{k,n}) \in V_L^n.$$

be the rows in M . The merge operation removes rows

$$(v_{i,1}, \dots, v_{i,n}) \quad \text{and} \quad (v_{(i+1),1}, \dots, v_{(i+1),n})$$

and replaces them by the row

$$(v_{i,1} \cdot v_{(i+1),1}, \dots, v_{i,n} \cdot v_{(i+1),n}),$$

which is the product of the two removed rows in the monoid V_L^n . Clearly, the result of the merging operation is also a strategy matrix with the same values of all the columns.

Now we define four *safe rules*, i.e. rules that preserve parity alternating strategy matrices.

Lemma 12.9. *For every $M \in \mathbb{P}_n$ that is top-down and $i \in \{1, \dots, n\}$, applying the following rules yields a parity alternating strategy matrix in \mathbb{P}_{n-1} :*

- remove columns $2i - 1$ and $2i$ and then merge row i with $i+1$;

- remove columns $2i - 1$ and $2i$ and then merge row $i-1$ with i ;
- remove the first two columns and remove the first row;
- remove the last two columns and remove the last row.

The same holds for a bottom-up parity alternating matrices but then we count the columns in the reversed order.

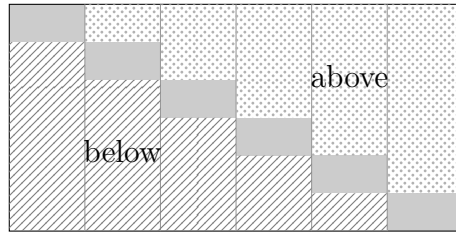
Proof. Immediate by the definition of the rules. □

Notice that $ux \neq uy$ implies that $x \neq y$, but $uvx \neq uvy$ does not imply that $ux \neq uy$, therefore we cannot safely remove columns $2i - 1$ and $2i$ and remove row i except for $i = 1$ or $i = n$.

Consider a parity alternating strategy matrix $M \in \mathbb{P}_n$ and two indices $i \in \{1, \dots, n\}$ and $j \in \{1, \dots, 2n\}$. We say that the entry $M[i, j]$ is *above diagonal* (resp. *below diagonal*) if:

- if M is top-down then $2i$ must be smaller than j (resp. $2i$ must be greater than $j + 1$),
- if M is bottom-up parity alternating then $2(n - i)$ must be greater than $j - 1$ (resp. $2(n - i)$ must be smaller than $j - 2$).

The following picture depicts the regions above and below the diagonal of a top-down parity alternating matrix in \mathbb{P}_6 .



Definition 12.10. A parity alternating strategy matrix M is upper (resp. lower) idempotent if there exists an idempotent $e \in V_L$ such that every entry above (resp. below) the diagonal of M equals e . M is called just idempotent if it is both upper and lower idempotent (possibly with two distinct idempotents $e, e' \in V_L$).

Fact 12.11. The safe rules preserve the fact that a given parity alternating matrix is upper (resp. lower) idempotent.

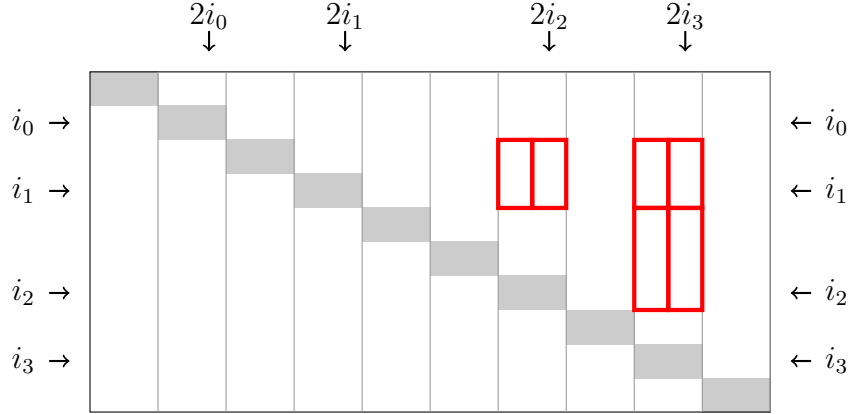
Lemma 12.12. For each $m \in \mathbb{N}$ there is some $n \in \mathbb{N}$ such that for any matrix in \mathbb{P}_n there is a sequence of safe rules that yields a matrix $N \in \mathbb{P}_m$ that is upper (resp. lower) idempotent.

Proof. By the symmetry we will only deal with the upper idempotent case. The proof uses Ramsey Theorem for hypergraphs with edges of size 3. This theorem says that for every $m \in \mathbb{N}$ there exists a number $f(m)$ such that for any complete hypergraph with edges coloured over V_L , there exists a complete sub-hypergraph of size m in which all edges share the same colour. We choose $n = f(m + 1)$.

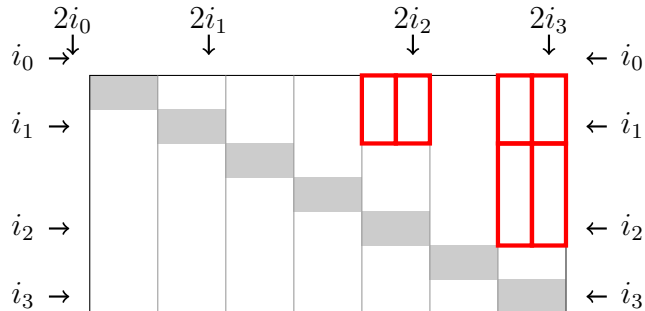
Fix a matrix $M \in \mathbb{P}_n$. Again by the symmetry we assume that M is a top-down parity alternating matrix. Consider the hypergraph where the nodes are $\{1, \dots, n\}$ and an edge $\{i < j < k\}$ is coloured by the value obtained by multiplying, in the monoid V_L , the entries that appear in rows $i + 1, \dots, j$ of column $2k$. By the choice of n , we can apply Ramsey Theorem to this colouring and get a subset of size $m + 1$:

$$I = \{i_0 < i_1 < \dots < i_m\} \subseteq \{1, \dots, n\}$$

such that all the hyperedges on I have the same colour, say $e \in V_L$. This colour must be an idempotent, i.e. it must satisfy $e = ee$. This situation is illustrated below, with a matrix in \mathbb{P}_{10} . The multiplication in V_L of the entries in the regions marked by red rectangles always gives the idempotent e . The regions come in pairs, for columns $2i_\ell$ and $2i_\ell - 1$ but as the matrix is parity alternating, the entries in these columns agree (except row i_ℓ).



Now we apply a sequence of safe rules. First, we remove the first i_0 rows and first $2i_0$ columns. Then we remove the last $n - i_m$ rows and last $2(n - i_m)$ columns. We assume that the indices of rows and columns are shifted accordingly to the operations we perform; i.e. now $i_\ell \stackrel{\text{def}}{=} i_\ell - i_0$ for $\ell = 0, \dots, m$. After these operations, the matrix gets the following shape.



Now, for $\ell = 1, 2, \dots, m$ we remove columns $2i_{\ell-1} + 1, \dots, 2i_{\ell} - 2$ and merge rows $i_{\ell-1} + 1, \dots, i_{\ell}$ into one row (with value e in columns $2i_{\ell+1}, \dots, 2i_m$). This way, we get the following matrix, which is upper idempotent.



□

Corollary 12.13. *For each $m \in \mathbb{N}$ there is some $n \in \mathbb{N}$ such that for any matrix in \mathbb{P}_n there is a sequence of safe rules that yields a matrix $N \in \mathbb{P}_m$ that is idempotent.*

Proof. Since the safe rules preserve the fact that a matrix is upper (resp. lower) idempotent, we can apply Lemma 12.12 twice, once to get an upper idempotent matrix and then to make it also lower idempotent. □

Fact 12.14. *If M is an idempotent parity alternating matrix, the operation that removes columns $2i$ and $2i - 1$ and removes row i preserves the fact that the matrix is idempotent parity alternating.*

Proof. If $i = 1$ or $i = n$ then the above operation is safe. For $1 < i < n$ we use the fact that the matrix is idempotent, so the values of columns $2i - 1$ and $2i$ depend only on the unique entry in that column which is neither above nor below the diagonal. The following picture depicts an idempotent parity alternating matrix in \mathbb{P}_6 where the upper idempotent is u and the lower idempotent is w . Removing row 4 and columns 7 and 8 of that matrix preserves the fact that the matrix is idempotent parity alternating.

x_1	y_1	u	u	u	u	u	u	u	u	u	u
w	w	x_2	y_2	u	u	u	u	u	u	u	u
w	w	w	w	x_3	y_3	u	u	u	u	u	u
w	w	w	w	w	w	x_4	y_4	u	u	u	u
w	w	w	w	w	w	w	w	x_5	y_5	u	u
w	w	w	w	w	w	w	w	w	w	x_6	y_6

□

Lemma 12.15. *If \mathbb{P}_n is non-empty for arbitrarily big n then there are $u, w, x, y \in V_L$ such that u and w are idempotents and \mathbb{P}_4 contains the matrix*

x	y	u	u	u	u	u	u
w	w	x	y	u	u	u	u
w	w	w	w	x	y	u	u
w	w	w	w	w	w	x	y

Proof. By the hypothesis, we can apply Corollary 12.13 for $m = 4 * |V_L|^2$. Let N be the resulting matrix. Each row of that matrix is of the form $w \cdots w \cdot x_i \cdot y_i \cdot u \cdots u$. Thus, there exists a pair (x, y) that appears as (x_i, y_i) in at least 4 rows. Using Fact 12.14 we can remove all the remaining rows (and the corresponding pairs of columns) from N and the result has the above form. \square

We can conclude the proof of Proposition 11.17 by showing that under our assumptions Equation (5) is violated.

Let M be the matrix described in Lemma 12.15. Let $\{u_1, \dots, u_8\}$ be the values of all the columns in M . The matrix is in \mathbb{P}_4 so $u_3 \neq u_4$. Because u and w are idempotent,

$$u_3 = uxww = uxw = uuxw = u_5$$

For the same reason, $u_4 = u_6$. This is depicted in the picture below

x	y	u	u	u	u	u	u
w	w	x	y	u	u	u	u
w	w	w	w	x	y	u	u
w	w	w	w	w	w	x	y
		↑	↑	↑	↑		
		u_3	u_4	u_3	u_4		

Since u_3 and u_4 are different, at least one of them is different than uw . Without loss of generality suppose that $u_3 \neq uw$. Because each row of the matrix belongs to \mathcal{V}_L and \mathcal{V}_L is closed under removing letters, it follows that

$$(w, x, u) \in \mathcal{V}_L.$$

This means that we have a violation of Equation (5), which requires that

$$uw = u^\omega \cdot u \cdot w^\omega = u^\omega \cdot x \cdot w^\omega = u_3.$$

This concludes the proof of Proposition 11.17.

13 Case (C2) — limit alternation is unbounded

In this section we assume that Σ_L has unbounded root alternation and every subset $\Sigma' \subseteq \Sigma_L$ with unbounded root alternation has also unbounded limit alternation. Under that assumption we need to prove that Equation (6) is violated.

We start by defining a notion of a *strategy graph* that represents very specific strategies of Alternation in the game on types. We then show that the above assumptions imply that the strategy graph needs to be *recursive* — roughly speaking it contains complicated connected components. Then we finish the proof of Proposition 11.18 by showing that recursivity of the strategy graph gives rise to a violation of Equation (6).

13.1 Strategy graph

Given a language L , the *strategy graph of L* (denoted G_L) is defined as follows. The set of nodes of G_L is $(V_L \sqcup \{1_L\}) \times H_L$. There is an edge from a node (v, h) to a node (v', h') if there exist:

$$(u_1, u_2), (w_1, w_2) \in \mathcal{V}_L, z \in V_L \sqcup \{1_L\}$$

such that

$$h = vu_1w_1^\infty \quad \text{and} \quad v' = vu_2w_2^\sharp z.$$

Notice that the above definition does not invoke h' (the value of h' matters for a successive edge from (v', h')).

The following lemma provides a less explicit definition of edges in G_L .

Lemma 13.1. *There exists an edge from (v, h) to (v', h') in G_L if and only if the following condition is satisfied:*

There exists a tree $t \in \text{Tr}_A$ such that $v \cdot \alpha_L(t) = h$ and there exists an infinite path π of t such that if D is a finite prefix of t then D can be completed into a context C' with the port located on π such that $v \cdot \alpha_L(C') \cdot z = v'$ for some $z \in V_L \sqcup \{1_L\}$.

Proof. First assume that there exists an edge from (v, h) to (v', h') in G_L with $(u_1, u_2), (w_1, w_2), z$ witnessing that. Let C_u, C_w, C_z be contexts of types u_1, w_1, z respectively. Take $t \stackrel{\text{def}}{=} C_u \cdot C_w^\infty$. In that case $v \cdot \alpha_L(t) = h$ and let π be the infinite path that contains all the ports of the contexts $C_u \cdot C_w^k$ for $k = 0, 1, \dots$

Consider a finite prefix D of t . Let D' be an extension of D that is also finite, contains exactly one port, and D' is a prefix of $C_u \cdot C_w^{(\sharp \cdot k)}$ for some k .

By the definition, D' can be written as

$$D = D_0 \cdot D_1 \cdot \dots \cdot D_{\sharp \cdot k},$$

where $D_0, \dots, D_{\sharp \cdot k}$ are finite prefixes of contexts (i.e. each of them has exactly one port); and moreover D_0 is a prefix of C_u and all $D_1, \dots, D_{\sharp \cdot k}$ are prefixes of C_w . By the assumption that $(u_1, u_2), (w_1, w_2) \in \mathcal{V}_L$ we know that we can extend all $D_0, D_1, \dots, D_{\sharp \cdot k}$ into contexts $C_0, C_1, \dots, C_{\sharp \cdot k}$ such that $\alpha_L(C_0) = u_2$ and $\alpha_L(C_i) = w_2$ for $i = 1, \dots, \sharp \cdot k$. Take $C' = C_0 \cdot C_1 \cdot \dots \cdot C_{\sharp \cdot k}$. Clearly the port of C' is located on π . Notice that

$$\alpha_L(C') = u_2 \cdot w_2^{\sharp \cdot k} = u_2 \cdot w_2^\sharp.$$

Therefore, $v \cdot \alpha_L(C') \cdot z = v'$ by the assumption that there is an edge from (v, h) to (v', h') .

Now consider the more involved direction: we assume that $(v, h), (v', h')$ satisfy the condition from Lemma 13.1 and we need to prove that there is an edge between them in G_L . This will be achieved by the Ramsey theorem. Consider a triple of nodes $x \prec y \prec \delta$ on π . Let $d = |\delta|$ be the depth of δ and let D_d be the finite prefix of t up to the depth d (i.e. D_d is t restricted to the subset $\{L, R\}^{\leq d}$ of its domain). Let us fix C' given from the assumption in Lemma 13.1.

Let u_1, u_2, w_1, w_2 be the α_L -types of the context zones:

- u_1 (resp. u_2) the type of the context zone rooted in ϵ with the port in x of t (resp. of C');
- w_1 (resp. w_2) the type of the context zone rooted in x with the port in y of t (resp. of C').

Let z be the type given by the assumption for C' .

Define $f(x, y, \delta)$ as the quintuple $(u_1, u_2, w_1, w_2, z) \in V_L^5$. Apply the Ramsey theorem for triples to f to get an infinite set X of nodes on π . We know that for all the triples from X the function f is constantly equal a fixed quintuple $(u_1, u_2, w_1, w_2, z) \in V_L^5$. It is easy to see that $\alpha_L(t) = u_1 \cdot w_1^\infty$. Thus, $h = vu_1w_1^\infty$. Similarly, the Ramsey theorem guarantees that $w_2 \cdot w_2 = w_2$ and therefore $v' = vu_2w_2^\#z$. Moreover, for fixed $x \prec y$ from X there are infinitely many $\delta \in X$ and therefore we know that (u_1, u_2) and (w_1, w_2) are both elements of \mathcal{V}_L . Thus, we have proved that there is an edge from (v, h) to (v', h') in G_L . \square

Lemma 13.2. *The strategy graph G_L is transitive.*

Proof. Consider an edge between (v, h) and (v', h') witnessed by (u_1, u_2) , (w_1, w_2) , and z ; and an edge between (v', h') and (v'', h'') witnessed by (u'_1, u'_2) , (w'_1, w'_2) , z' . Then $h = vu_1w_1^\infty$ and $v'' = vu_2w_2^\#(zu'_2(w'_2)^\#z')$. It means that there is an edge between (v, h) and (v'', h'') with $(u_1, u_2), (w_1, w_2) \in \mathcal{V}_L$, and $z'' \stackrel{\text{def}}{=} zu'_2(w'_2)^\#z'$. \square

Definition 13.3 (*Recursive strategy graphs*). *We say that a strategy graph G_L is recursive if there exists a strongly connected component of G_L that contains two nodes (v, h) , (v', h') with $h \neq h'$.*

Lemma 13.4. *If the strategy graph G_L is recursive then Equation (6) is violated.*

Proof. Assume contrarily that G_L is recursive but Equation (6) holds. Consider a pair of nodes (v, h) and (v', h') with $h \neq h'$ that witness recursivity of G_L . By Lemma 13.2 there must exist edges in G_L from (v, h) to (v', h') and back. Let (u_1, u_2) , (w_1, w_2) , z ; and (u'_1, u'_2) , (w'_1, w'_2) , z' witness the existence of these edges respectively.

Apply Equation (6) to obtain that:

$$\begin{aligned} (u_2(w_2)^\# zu'_2(w'_2)^\#z')^\# u_1(w_1)^\infty &= (u_2(w_2)^\# zu'_2(w'_2)^\#z')^\infty \\ (u'_2(w'_2)^\# z'u_2(w_2)^\#z)^\# u'_1(w'_1)^\infty &= (u'_2(w'_2)^\# z'u_2(w_2)^\#z)^\infty \end{aligned}$$

Let $W = u_2(w_2)^\#z$ and $W' = u'_2(w'_2)^\#z'$. Then by the assumptions on the edges between (v, h) and (v', h') we get that $vW = v'$ and $v'W' = v$. Moreover, the above equations get the form

$$\begin{aligned} (WW')^\# u_1(w_1)^\infty &= (WW')^\infty \\ (W'W)^\# u_2(w_2)^\infty &= (W'W)^\infty \end{aligned}$$

And therefore by using the values of h , h' and multiplying these equations by v and v' respectively we get:

$$\begin{aligned} h &= v \cdot u_1(w_1)^\infty = v \cdot (WW')^\# u_1(w_1)^\infty = v \cdot (WW')^\infty \\ h' &= v' \cdot u'_1(w'_1)^\infty = v' \cdot (W'W)^\# u'_1(w'_1)^\infty = v' \cdot (W'W)^\infty \end{aligned}$$

Now since $h = v \cdot (WW')^\infty = vW \cdot (W'W)^\infty = v' \cdot (W'W)^\infty = h'$ we obtain the contradiction as we assumed that $h \neq h'$. \square

13.2 Constructing a path in G_L

We will now use the assumption that (C2) holds to construct an infinite path in G_L such that every two consecutive nodes on that path (v, h) , (v', h') satisfy $h \neq h'$. Since G_L is finite, such an infinite path witnesses that some strongly connected components of G_L contains such two nodes and therefore G_L is recursive. By Lemma 13.4 it means a violation of Equation (6) and the proof of Proposition 11.18 is finished.

The construction of the path will be inductive, preserving an invariant that the last node constructed on the path is *alternating*: a node (v, h) in G_L is *alternating* if $v \cdot \mathcal{H}_L$ contains words that begin with h and have arbitrarily high alternation.

Lemma 13.5. *G_L contains at least one alternating node.*

Proof. This is because \mathcal{H}_L has unbounded alternation. Therefore, by Pigeon-hole Principle there exists some $h \in H_L$ such that \mathcal{H}_L contains words that begin with h that have arbitrarily high alternation. By the definition, this means that the node $(1_L, h)$ is alternating in G_L . \square

The inductive step of the construction will be based on the following lemma.

Lemma 13.6. *If (v, h) is an alternating node of G_L and (C2) holds then there exists an edge in G_L from (v, h) to (v', h') such that $h \neq h'$ and (v', h') is also alternating.*

The rest of the section is devoted to a proof of Lemma 13.6. Let $\Sigma_{(v,h)}$ be the set of all strategy trees σ (with root sequences of the form (h_1, \dots, h_n)) such that:

- σ is locally optimal for v (see Definition 11.11),
- $v \cdot h_1 = h$,
- the sequence (vh_1, \dots, vh_n) is alternating (i.e. every two consecutive values in the sequence are distinct, see Definition 8.22).

Fact 13.7. *The set $\Sigma_{(v,h)}$ is a subset of Σ_L that has unbounded root alternation and by (C2) also unbounded limit alternation.*

Proof. Fact 11.12 implies that all strategy trees in $\Sigma_{(v,h)}$ belong also to Σ_L . By the fact that (v, h) is alternating and by Lemma 11.13 we know that $\Sigma_{(v,h)}$ has unbounded root alternation. Therefore, (C2) guarantees that $\Sigma_{(v,h)}$ has also unbounded limit alternation. \square

Now observe that for each $g, g' \in H_L$ either $(g, g')^k \in \mathcal{H}_L$ for all $k \in \omega$, or there exists a unique $k_{g,g'} \in \omega$ such that $(g, g')^{k_{g,g'}} \in \mathcal{H}_L$ but $(g, g')^{1+k_{g,g'}} \notin \mathcal{H}_L$. Since the set H_L is finite, there exists a number K that is greater than all the defined numbers $k_{g,g'}$. Thus, the following fact holds.

Fact 13.8. *If for some pair $g, g' \in H_L$ we have $(g, g')^K \in \mathcal{H}_L$ then $(g, g')^k \in \mathcal{H}_L$ for all $k \in \omega$.*

Let $\ell \stackrel{\text{def}}{=} |H_L|^2 \cdot K$ and let $\sigma = (t, \sigma_1, \dots, \sigma_n)$ be a strategy tree in $\Sigma_{(v,h)}$ that has limit alternation greater than ℓ .

We will now construct a path π in t on which the high limit alternation of σ is located. Let Z be the set of nodes z of t such that the root alternation of $\sigma.z$ is greater than ℓ . By Corollary 11.16 we know that Z is prefix closed and by the fact that the limit alternation of σ is greater than ℓ we know that Z is infinite. Therefore, by König lemma we know that Z contains an infinite path π .

Lemma 13.9. *There exists an infinite set $X \subseteq \pi$ and two sequences $(h_1, \dots, h_n) \in H_L^*$ and $(v_1, \dots, v_n) \in V_L^*$ such that for all nodes $x \in X$:*

- $(\sigma_1(x), \dots, \sigma_n(x)) = (h_1, \dots, h_n),$
- $(\text{val}(\sigma, X, 1), \dots, \text{val}(\sigma, X, n)) = (v_1, \dots, v_n),$ where X is the context zone with the root in ϵ and port in x .

Moreover, $(h_1, \dots, h_n) \in \mathcal{H}_L$ and $(v_1, \dots, v_n) \in \mathcal{V}_L$.

Proof. The choice of X and the sequences $(h_1, \dots, h_n) \in H_L^*$, $(v_1, \dots, v_n) \in V_L^*$ is just by Pigeon-hole Principle. By the definition of a strategy tree we know that $(h_1, \dots, h_n) \in \mathcal{H}_L$. By Fact 11.8 we know that also $(v_1, \dots, v_n) \in \mathcal{V}_L$. \square

Since the alternation of (h_1, \dots, h_n) is greater than $\ell = |H_L|^2 \cdot K$, we know that there exists a pair $g \neq g' \in H_L$ and a set of indices $I \subseteq \{1, \dots, n-1\}$ such that $|I| \geq K$ and for all $i \in I$ we have $h_i = g$ and $h_{i+1} = g'$. Fix as i_0 the minimal element of I . By closure of \mathcal{H}_L under subwords, we know that $(g, g')^K \in \mathcal{H}_L$. By Fact 13.8 it implies that

$$(g, g')^k \in \mathcal{H}_L \quad \text{for all } k \in \omega. \quad (9)$$

Let $u = v_{i_0}$ and $u' = v_{i_0+1}$ where i_0 is the minimal element of I . We will finish the proof by showing the following three lemmas.

Lemma 13.10. *The values $vu'g$ and $vu'g'$ are distinct.*

Proof. Recall that $g = h_{i_0}$ and $g' = h_{i_0+1}$. Assume that the value $vu'g$ is equal to $vu'g'$. Consider a strategy tree σ' that equals σ except for the subtree $\sigma'_{i_0+1}.x$ where x is the \preceq -minimal element of X . Over that subtree, let σ'_{i_0+1} be equal to σ_{i_0} . Let (h'_1, \dots, h'_n) be the root sequence of σ' . We know that $v \cdot (h'_1, \dots, h'_n) = (h_1, \dots, h_n)$ and $\text{dist}(\sigma_{i_0}, \sigma'_{i_0+1})$ is strictly smaller than $\text{dist}(\sigma_{i_0}, \sigma_{i_0+1})$, what contradicts local minimality of σ for v . \square

Lemma 13.11. *The nodes $(vu', vu'g)$ and $(vu', vu'g')$ are both alternating in G_L .*

Proof. By (9) and Fact 8.20 we know that $(vu'g, vu'g')^k \in \mathcal{H}_L$ for all $k \in \omega$. Moreover, Lemma 13.10 says that $vu'g \neq vu'g'$. \square

Now it remains to prove the following lemma.

Lemma 13.12. *There exist edges in G_L from (v, h) to both $(vu', vu'g)$ and $(vu', vu'g')$.*

Proof. Since the existence of an edge from (v, h) to (v', h') does not depend on h' , it is enough to show an edge from (v, h) to $(vu', vu'g)$. This will be done using Lemma 13.1. Let σ' be the strategy tree obtained from σ by removing the first i_0 rounds: $\sigma' = (t, \sigma_{i_0+1}, \sigma_{i_0+2}, \dots, \sigma_n)$ (i_0 is the minimal element of I).

Consider the tree t from the strategy tree σ and the path π . By the definition of σ we know that $v \cdot \alpha_L(t) = h$. Let D be a finite prefix of t . The strategy tree σ' witnesses that D can be extended into a context C' with a port located on π such that that $\alpha_L(C') = v_{i_0+1} = u'$. Therefore $v \cdot \alpha_L(C') \cdot 1_{V_L} = vu'$.

This way we have proved the property in Lemma 13.1 and therefore there must be an edge in G_L from (v, h) to $(vu', vu'g)$. \square

Thus, Lemma 13.10 implies that at least one of the nodes $(vu', vu'g)$ and $(vu', vu'g')$ has the second coordinate distinct than h , Lemma 13.11 implies that this node is alternating, and Lemma 13.12 implies that G_L contains an edge from (v, h) to that node. Thus, the proof of Lemma 13.6 is concluded.

14 Effective characterisation of Δ_2^0

This final section is devoted to the effective characterisation of the Borel class Δ_2^0 (that corresponds to the union of the first ω_1 Wadge degrees). Decidability of the class Δ_2^0 can be actually obtained as a direct corollary of [CMS17]: in this work the authors proved that it is decidable if a regular tree language is in the Borel class Π_2^0 ; since regular languages are closed under complement and $\Delta_2^0 = \Pi_2^0 \cap \Sigma_2^0$ we automatically obtain that it is decidable if a regular tree language is in Δ_2^0 . However, here we show that the algebraic approach developed in the previous sections covers the case of the Borel class Δ_2^0 as well. What we will prove is the following:

Theorem 14.1. *A regular tree language L belongs to the class Δ_2^0 if and only if its syntactic algebra satisfies Equation (6) from Theorem 9.1.*

This theorem is the main result of [FM14]; unfortunately the proof provided there is wrong:

- Proposition 4 in [FM14] cites Lemma G.2 from [BP12] in a wrong way. The logical claim in Proposition F.2 is of the form: if there is a set Σ of unbounded root alternation then there is a set Σ' of unbounded limit alternation². Lemma G.2 says that if Proposition F.2 is violated then the strategy graph is recursive. Logically, it takes the form: if there is a set Σ of unbounded root alternation but no set Σ' has unbounded limit alternation then the graph is recursive. The way Proposition 4 summarises that statement is: if there exists a set Σ of unbounded limit alternation then the strategy graph is recursive. This statement does not follow from [BP12].
- The proof of Theorem 1 in [FM14] in the implication (2) \Rightarrow (1), shows how to construct, given an infinite strategy tree s^∞ , a family of strategy trees of unbounded limit alternation. The first step of the proof is to construct a family \mathcal{G} of strategy trees of finite duration but unbounded root alternation. Then, an invalid application of a compactness argument (to find the set X) shows that \mathcal{G} has in fact unbounded limit alternation. Such a set X doesn't need to exist, it can be the case that the limit alternation of s is 2 but for each pair $k < k' \leq j$ there are infinitely many nodes n in s such that $\sigma_k(n) \neq \sigma_{k'}(n)$ — it is enough that the nodes for distinct values k, k' lie on distinct infinite branches.

Additionally, if it was the case that every set of strategy trees of unbounded root alternation has unbounded limit alternation; Proposition F.1 would hold always, nevertheless of the assumption of Identity (2).

The proof we provide here follows the logical structure of [FM14], with the following differences:

- Instead of the wrong reference used in Proposition 4 of [FM14] we show recursivity of G_L using a new Lemma 13.12 that characterises existence of edges in G_L .
- Instead of the statement about existence of the set X from the proof of Theorem 1 in [FM14] we provide here a direct construction (Lemma 14.9) showing that a winning strategy of Alternator in $\mathcal{H}^\infty(L)$ must take a specific structure that fits the characterisation from Lemma 14.9.

As observed in [FM14], the techniques used to characterise $\text{BC}(\Sigma_1^0)$ provide a big part of a proof of Theorem 14.1. First, Proposition 6.5 says that L is Δ_2^0 if and only if Constrainer wins $\mathcal{H}^\infty(L)$. Corollary 10.3 says that if Equation (6) is violated then Alternator wins $\mathcal{H}^\infty(L)$. Thus, the “only if” part of Theorem 14.1 follows.

On the other hand, Lemma 13.4 says that if the strategy graph G_L is recursive then Equation (6) is violated. It means that the only remaining statement to prove Theorem 14.1 is expressed by the following proposition.

²Unbounded limit alternation implies unbounded root alternation.

Proposition 14.2. *If Alternator wins $\mathcal{H}^\infty(L)$ then the strategy graph G_L is recursive.*

The rest of this section is devoted to a proof of the above proposition. During the proof we will inductively construct an infinite path $(v_n, h_n)_{n \in \omega}$ in the strategy graph such that the sequence h_n alternates between L and L^c . The invariant of our construction is expressed by the following definition, using the notions of quotients from Subsection 8.1.

Definition 14.3. *Consider a node (v, h) of the strategy graph G_L . We say that (v, h) is prolongable if there exists a winning strategy σ of Alternator in $\mathcal{H}^\infty(v^{-1}(L))$ or in $\mathcal{H}^\infty(v^{-1}(L)^c)$ such that if t is the tree played by σ in the first round then $v \cdot \alpha_L(t) = h$.*

Lets fix a strategy σ of Alternator in $\mathcal{H}^\infty(L)$ and let t_0 be the tree played by σ in the first round. Let $v_0 = 1_L$ and $h_0 = \alpha_L(t_0)$. Directly from the definition we know that (v_0, h_0) is prolongable. Therefore, to prove Proposition 14.2 it is enough to prove the following inductive lemma.

Lemma 14.4. *If (v, h) is prolongable then there exists a node (v', h') in the strategy graph G_L such that $h' \neq h$, (v', h') is prolongable, and there is an edge from (v, h) to (v', h') .*

Lets fix a node (v, h) that is prolongable, as witnessed by a strategy σ and a tree t . By the symmetry we can assume that σ is winning in $\mathcal{H}^\infty(v^{-1}(L)^c)$. We will now analyse the structure of the strategy σ in such a way to extract a witness of an edge in G_L as characterised by Lemma 13.1. For that we need to find an infinite path π of t . This will be achieved by finding a sequence of *essential nodes* in t .

For $d > 0$ a *d-prefix* of a tree t is the prefix $p \stackrel{\text{def}}{=} t \upharpoonright \{\mathsf{L}, \mathsf{R}\}^{<d}$, i.e. the prefix of t containing all the nodes at depths smaller than d . For instance, the 1-prefix of t consists of the root of t only.

Definition 14.5. *Consider a node $u \in \{\mathsf{L}, \mathsf{R}\}^d$ for $d > 0$. Let p be the d -prefix of t . We say that u is essential if there exists a context C of a type $w \in V_L$, such that the port of C is in u ; C extends p ; and we have $(vw)^{-1}(L) \notin \Delta_2^0$.*

The last condition implies that Alternator has a winning strategy in³ $\mathcal{H}^\infty((vw)^{-1}(L))$. Let t' be a tree played by one of such winning strategies of Alternator and let $g = \alpha_L(t')$. Using the above notions we say that u is (w, g) -essential.

Fact 14.6. *If C is a context then the function $t \mapsto C[t]$ is continuous. Therefore, if $w^{-1}(K) \notin \Delta_2^0$ then also $K \notin \Delta_2^0$. In particular, using (4) we obtain that for $v, w \in V_L \sqcup \{1_L\}$ if $(vw)^{-1}(L) \notin \Delta_2^0$ then also $v^{-1}(L) \notin \Delta_2^0$. It means that if $\epsilon \prec u \preceq u'$ and u' is essential then also u is essential.*

The crucial step towards the proof of Lemma 14.4 is expressed by the following claim.

Claim 14.7. *Using the above notions, there are infinitely many essential nodes in t .*

³We have assumed that σ is winning in $\mathcal{H}^\infty(v^{-1}(L)^c)$ and therefore we have no complement here; in the dual case σ is winning in $\mathcal{H}^\infty(v^{-1}(L))$ and here we consider a winning strategy in $\mathcal{H}^\infty((vw)^{-1}(L)^c)$.

A proof of this claim is given in Subsection 14.1. Now we show how the claim implies Lemma 14.4. Since there are infinitely many essential nodes, and a prefix of an essential node is also essential (see Fact 14.6), there exists a path π such that for all $\epsilon \prec u \prec \pi$ the node u is essential. Notice that each of these nodes u comes with at least one pair $(w_u, g_u) \in V_L \times H_L$ such that u is (w_u, g_u) -essential, see Definition 14.5. Let (w, g) be a pair that equals (w_u, g_u) for infinitely many u . Let $v' = vw$ and $h' = vwg$. By the choice of h and h' we know that $h \subseteq L^c$ and $h' \subseteq L$ and therefore $h' \neq h$. Also, directly from the definition of a (w, g) -essential node we know that the node (v', h') is prolongable.

Therefore, to conclude Lemma 14.4 it is enough to show that G_L contains an edge from (v, h) to (v', h') . For that we will check the condition from Lemma 13.12. Consider a finite prefix D of t . There must exist an essential node $u \prec \pi$ such that $u \in \{\mathsf{L}, \mathsf{R}\}^d$ for some $d > 0$; $(w_u, g_u) = (w, g)$; and D is a prefix of the d -prefix of t . Since u is essential, D can be completed into a context C with the port located in u , such that $\alpha_L(C) = w$. Thus, $v \cdot \alpha_L(C) \cdot 1_L = v \cdot w = v'$. This fulfils the requirements of Lemma 13.12 and therefore G_L contains an edge from (v, h) to (v', h') .

14.1 Proof of Claim 14.7

Consider a number $d > 0$ and let p be the d -prefix of t . We will find an essential node $u \in \{\mathsf{L}, \mathsf{R}\}^d$. Let D be the multicontext obtained from p by making all the nodes in $\{\mathsf{L}, \mathsf{R}\}^d$ ports; let u_1, \dots, u_N be the list of these ports ($N = 2^d$); and $U \stackrel{\text{def}}{=} D[*]$ be the basic open set defined by p . Finally, put

$$M \stackrel{\text{def}}{=} D^{-1}(v^{-1}(L)) \subseteq \text{Tr}_A^N.$$

Remark 14.8. *The fact whether $(t_1, \dots, t_N) \in M$ depends only on the tuple of types $(\alpha_L(t_1), \dots, \alpha_L(t_N))$.*

Since (v, h) is prolongable and U is a valid response of Constrainer to Alternator playing t in $\mathcal{H}^\infty(v^{-1}(L)^c)$, we know that Alternator has a winning strategy in $\mathcal{H}_U^\infty(v^{-1}(L))$. This game is equivalent to the game $\mathcal{H}^\infty(M)$ played in the topological space Tr_A^N . Therefore, by Proposition 6.5 we know that $M \notin \Delta_2^0$.

Lemma 14.9. *Using the above notation, if $M \subseteq \text{Tr}_A^N$ is not Δ_2^0 then there exists a port u_i of D and trees $t_1, \dots, t_{i-1}, t_{i+1}, \dots, t_N$ such that for the context*

$$C \stackrel{\text{def}}{=} D[t_1, \dots, t_{i-1}, \square, t_{i+1}, \dots, t_N],$$

we have $C^{-1}(v^{-1}(L)) \notin \Delta_2^0$.

Notice that if we put $w = \alpha_L(C)$ then the last condition in the above lemma says that $(vw)^{-1}(L) \notin \Delta_2^0$ and therefore the context C witnesses that u_i is essential. Thus, to conclude Claim 14.7 it is enough to show the above lemma.

Notice that the set $C^{-1}(v^{-1}(L))$ from Lemma 14.9 can be equivalently defined as

$$\{t \in \text{Tr}_A \mid (t_1, \dots, t_{i-1}, t, t_{i+1}, \dots, t_N) \in M\}.$$

We will call sets of that form *sections* of M . Due to Remark 14.8, taking $h_j = \alpha_L(t_j)$ for $j = 1, \dots, N$, $j \neq i$, we can equivalently define the above section as

$$(h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N) \stackrel{\text{def}}{=} \{t \in \text{Tr}_A \mid h_1 \times \dots \times h_{i-1} \times \{t\} \times h_{i+1} \times \dots \times h_N \subseteq M\}. \quad (10)$$

Thus, Lemma 14.9 can be equivalently stated as.

Lemma 14.10. *If $M \notin \Delta_2^0$ then there exists a section of M that is not Δ_2^0 .*

In general such a property does not hold, however it holds for M due to the fact that M has only finitely many distinct sections, see Remark 14.8.

Notice that the notation from (10) naturally extends to formulae with more than one \square . Such sets are called *multisections*. The number of holes in a multisection is called its *dimension*, i.e. a multisection of dimension n is a subset Tr_A^n . There is one multisection of the maximal dimension N : $(\square, \dots, \square) = M$.

Claim 14.11. *Each multisection can be obtained from sections by taking finite unions, finite intersections, and products.*

Proof. The proof will be inductive on the dimension of the given multisection. For the sake of simplicity of notation we even consider multisections of dimension zero, i.e. expressions of the form (h_1, \dots, h_N) with no holes. Formally such an expression is either the empty set, or a set containing the empty tuple $()$ (depending on whether $h_1 \times \dots \times h_N \subseteq M$ or not).

A multisection of dimension 1 is just a section, so the claim follows. Consider a multisection of the form (this form is generic up to rearranging the coordinates):

$$N = (\square, \square, \dots, \square, h_{i+1}, h_{i+2}, \dots, h_N).$$

We will prove that N can be represented as in Claim 14.11.

Consider a tuple h_1, \dots, h_{i-1} . If $(h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N)$ is empty then let us put $S(h_1, \dots, h_{i-1}) = \emptyset$ and otherwise let $S(h_1, \dots, h_{i-1})$ be

$$\bigcap_{h_i \subseteq (h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N)} (\square, \dots, \square, h_i, \dots, h_N) \times (h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N).$$

Now consider the set K defined as

$$\bigcup_{h_1, \dots, h_{i-1}} S(h_1, \dots, h_{i-1}).$$

By the inductive assumption the set K can be obtained from sections by finite unions, finite intersections, and products. It remains to prove that $K = N$.

First consider a tuple of types (g_1, g_2, \dots, g_i) such that

$$g_1 \times \dots \times g_i \subseteq N. \quad (11)$$

We will show that this product is contained in $S(g_1, \dots, g_{i-1})$. First, by (11) we know that $g_i \subseteq (g_1, \dots, g_{i-1}, \square, h_{i+1}, \dots, h_N)$ and therefore the later set is not empty. Consider any value $h_i \subseteq (g_1, \dots, g_{i-1}, \square, h_{i+1}, \dots, h_N)$. By the assumption about the considered values h_i we know that $g_1 \times \dots \times g_{i-1} \subseteq (\square, \dots, \square, h_i, \dots, h_N)$. Therefore, $g_1 \times \dots \times g_i$ is contained in the product $(\square, \dots, \square, h_i, \dots, h_N) \times (h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N)$.

Now consider the other implication: take a tuple of types (g_1, g_2, \dots, g_i) such that

$$g_1 \times \dots \times g_i \subseteq S(h_1, \dots, h_{i-1}), \quad (12)$$

for some choice of types h_1, \dots, h_{i-1} . It means that there must exist a type h_i contained in $(h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N)$, because the later set cannot be empty. Therefore, $g_i \subseteq (h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N)$ and it means that g_i is among the values h_i over which we take the intersection. Thus

$$g_1 \times \dots \times g_i \subseteq (\square, \dots, \square, g_i, \dots, h_N) \times (h_1, \dots, h_{i-1}, \square, h_{i+1}, \dots, h_N).$$

In particular $g_1 \times \dots \times g_{i-1} \subseteq (\square, \dots, \square, g_i, \dots, h_N)$ what implies that

$$g_1 \times \dots \times g_i \subseteq N.$$

This concludes the proof that $N = K$ and thus the claim is proved. \square

Proof of Lemma 14.10. Assume contrarily that all the sections of M are Δ_2^0 . By Claim 14.11 the multisection $(\square, \dots, \square) = M$ can be obtained from the sections of M using finite unions, finite intersections, and products. As all these operations preserve Δ_2^0 sets, the set M is also Δ_2^0 . This contradicts the assumption. \square

15 Conclusions

This paper utilises the syntactic algebra of a given regular language L to understand the topological complexity of L . The main result (Theorem 9.1) says that the language is $\text{BC}(\Sigma_1^0)$ if and only if its syntactic algebra satisfies Identities (5) and (6).

The first equation speaks about the *branching* structure of alternations between the language and the complement. The combinatorial background of this equation is represented by the three claims from Subsection 12.1, which show that one can alternate using distinct infinite branches of a given tree.

The second equation is focused on alternations that continue along a single branch, see Lemma 13.12 for the explicit form of such an alternation.

As observed by Facchini and Michalewski [FM14], languages outside the class Δ_2^0 should admit the second kind of alternation. Although the original paper contained certain mistakes, the claim is correct (Theorem 14.1): a regular language is Δ_2^0 if and only if its syntactic algebra satisfies Identity (6).

15.1 Limitations

In general there is no proper algebraic framework for analysing all regular languages of infinite trees. The available algebras are either too weak [BI09, BS13], too strong [Boj10], or not closed under homomorphic images (i.e. contain a hidden existential quantifier) [Blu11]. Therefore, effective characterisations based on algebraic approach are limited either to certain subclasses of languages as the input; or to simple classes that are being characterised.

In this paper the input is not restricted (i.e. the characterisation works for all regular languages as the input); but the characterised classes are low in Borel hierarchy. It is not surprising, as the structure of the considered algebras is quite weak, as expressed by the following remark.

Remark 15.1. *For every non-trivial language $L_0 \subseteq \text{Tr}_A$ the syntactic algebra of the language*

$$\{t \in \text{Tr}_A \mid \forall u \exists v \succeq u. t|v \in L_0\}$$

is the same, with both H and V being two-element sets.

Notice that if $L_0 = \{t \in \text{Tr}_{\{a,b\}} \mid t(\epsilon) = a\}$ then the above language belongs to $\mathbf{\Pi}_2^0$, while for $L_0 = \{t \in \text{Tr}_{\{a,b,c\}} \mid \text{if } t(\epsilon) = c \text{ then } t \text{ contains a branch with infinitely many } a\}$ the above language is non-Borel (Σ_1^1 -complete). This shows that the structure of the considered algebras is not strong enough to distinguish the complexity of languages right above the class $\mathbf{\Delta}_2^0$. To climb higher in Borel Hierarchy one should consider some class of algebras with richer structure; unfortunately there is no natural candidate for such a class at the moment. The known characterisations of classes higher in the hierarchy⁴ [SW16, CMS17] are based directly on games instead of using algebras.

15.2 Comparison with original papers

Comparing to the original work [BP12], this work provides more detailed and polished proofs, more pictures, and certain minor glitches corrected. Moreover, the newly added Lemma 13.12 provides an explicit characterisation of the edges in the strategy graph G_L .

As discussed in Section 14, the logical structure of [FM14] is not sound. In this work we repair the gap by providing a direct proof of existence of certain edges in the strategy graph G_L . For that, we introduce a new concept of an *essential node* (see Definition 14.5) and a combinatorial lemma about sections of matrices, see Lemma 14.10.

15.3 Further work

There are still natural classes of languages within $\mathbf{\Delta}_2^0$ that await characterisations.

⁴There are other characterisations where the input is restricted to languages with limited use of non-determinism, see [Mur08b, FMM16].

Equations for finite levels. In this work we remark that the finite levels of Difference hierarchy can be characterised using sentences of MSO. It remains open whether these finite levels correspond to equations (or their ordered variants) in the syntactic algebra of the language.

Bounds for infinite levels. In [DM07] it has been proved that if L_1 and L_2 are regular tree languages with Wadge rank α_1 and α_2 respectively, then we can build regular languages $L_1 \oplus L_2$ and $L_1 \otimes \omega$ with Wadge rank $\alpha_1 + \alpha_2$ and $\alpha_1 \times \omega$ respectively. Hence, every Wadge degree with Wadge rank below ω^ω is inhabited by regular languages. In particular, there are examples of regular tree languages in $\Delta_2^0 \setminus \text{BC}(\Sigma_1^0)$. However, as Wadge Hierarchy over Σ_1^0 has length ω_1 and there are only countably many regular languages, there must exist a bound on the levels of Wadge Hierarchy occupied by regular languages. The ordinal ω^ω is a natural candidate for the upper bound, as all the examples of the regular languages inside Δ_2^0 exhaust exactly the first ω^ω levels of Wadge Hierarchy.

Characterisations of transfinite levels. Not only we don't know how many transfinite levels of Difference Hierarchy are occupied, but there is no effective characterisation of any transfinite level known. Thus, one can ask for instance how to verify if the Wadge degree η of a regular tree language verifies $\omega \leq \eta < \omega \cdot 2$.

Higher in the hierarchy. The operations of the algebras used in this paper seem to be suited exactly to the classes up to Δ_2^0 . However, one might imagine enriching their algebraic structure just a bit in such a way to cover one more level of Borel Hierarchy. This motivates the following problem.

Problem 15.2. *Is there a natural algebraic structure extending the algebras given in this paper which allow an equational characterisation of the Borel class Δ_3^0 .*

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