Population protocols - example

Deaf Black Ninjas in the Dark (Javier Esparza)

* deaf black ninjas meet at a Zen garden
in the dark - they must decide by majority
to attack or not (no attack if tie)

* how can they conduct to vote?

* ninjas wander randomly, interacting when they bump into each other

* they store their current estimation of the final outcome: attack (for) / don't attack (against)

additionaly they are rested or tired (easy to get convinced to other's point of view)

* initially all ninjas are rested (estimation = vote)

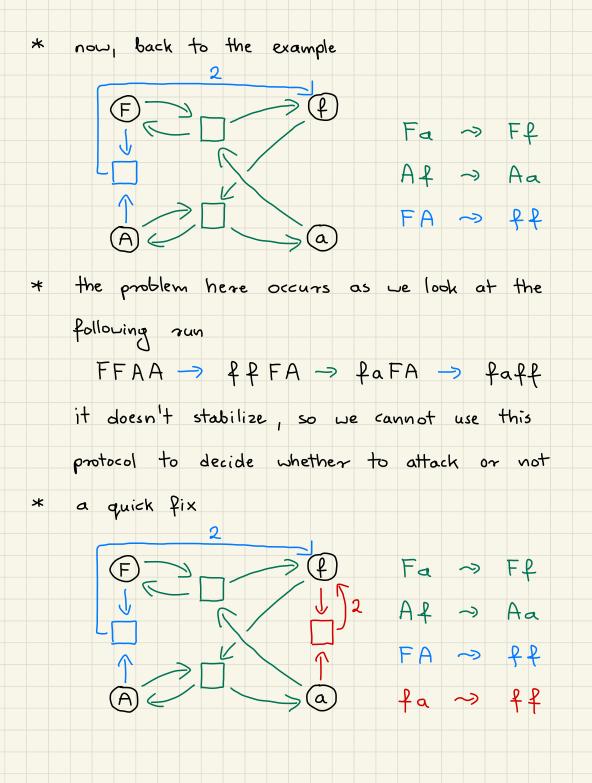
* goal of voting protocol: eventually all ninjas
reach the same estimation (corresponding)

we need to decide the outcome of each possible meeting (for any too types of ninjus) * let us model this situation using a binary Petri net with the set of places rested { For tired { against first, consider the following meeting outcomes F A A A A Fa ~> Ff Af -> Aa FA ~> ff in other words, each rested ninja convinces tired ninjas they meet to their point of view, while two rested ninjas: one for, one against, become tired and for the attack however, there is a problem ...

Some theory recap - binary Petri nets $T \in P$ $T = \{A, F\}$ set of places set of all places used in the initial marking Final outcome function $0: P \rightarrow \{0,1\}$ $A, a \rightarrow 0$ F, f ~ 1 Configurations INP - the number of tokens at each place $M^{T} = d M \in M^{P} : \forall P \in P \setminus I M(P) = 0$ set of initial configurations Runs $M_0 \rightarrow M_1 \rightarrow M_2 \rightarrow ...$ infinite $O(M) = \begin{cases} b & \text{if } \forall p \in P & M(p) > 0 \Rightarrow O(p) = b \\ L & \text{otherwise} \end{cases}$ final outcome of a net with configuration M

Fair runs YM>M' di: Mi = M] is infinite => di: Mi=M, Mi+1=M'] is infinite YM'. di: Mi > M'} is infinite ⇒ li: Mi = M'} is infinite Run stabilizes to b if Jk Visk O(Mi) = b. Protocol computes a predicate up: IN = > 40,1] if every fair run stabilizes to $\phi(M_0)$. Protocol is well-specified if it computes some predicate. Alternative approach - probabilistic semantics Protocol computes of if Y MOENI a nun

starting at Mo stabilizes to $\varphi(M_0)$ with probability 1



One can check that the protocol on the previous page works, however, it still has some disadvantages. For instance, the simulations show that - if the number of ninjas is chosen uniformly at random between 10 and 15, and we allow the simulation to run for at most 500 steps, then the protocol does not reach a consensus in about 25% of the mus on average, such a problem happens only for the case in which the initial number of A-ninjas is slightly above the number of F-ninjas (then we reach a situation were we have one A-ninja and all the other ninjas are f-ninja: A turns f to a, but f reverse it ...),

- for the initial configuration of 8 A-ninjas and 7 F-ninjas reaching the consensus takes on average 9072494 steps, which means that dawn arrives long before consensus. Thus, the question arises of how to improve this protocol? since ties are the source of all problems, ve should deal with them explicitly * consider having a third option for each ninja's outcome expectation being a tie T now, when two active ninjas meet, only one of them becomes passive, and both

change their expectations in the natural way * still, passive ninjas adopt the expectation of active ninjas

* formally, we consider the following meeting outcomes FA -> Tt ∀LEdf,a,t} FT → Ff F7 → Et AT > Aa $A \lambda \rightarrow A a$ $T \downarrow \rightarrow T t$ TT -> Tt and set O(T) = O(t) = 0 (tie = no attack) notice that the last transition: Td -> Tt is useful only in the case of a tie, for instance, we need to be able to go through the following run FA fff -> TTfff -> ... -> Ttttt for such a protocol, in simulations with up to 15 ninjas, consensus never takes more than 170 steps

2. Prove that all semi-linear predicates can be computed by population protocols.