

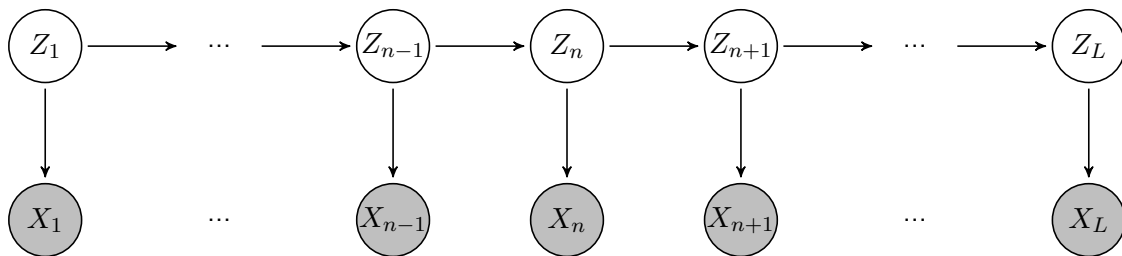


Statistical Data Analysis 2

Exercises # 3

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Problem 1: HMMs and EM: Expected Hidden Log Likelihood



Consider the HMM represented by the above graph, where X_n are observed variables and Z_n are latent variables. The Z_n are K -dimensional binary random vectors satisfying $\sum_{k=1}^K z_{nk} = 1$ and $z_{nk} \in \{0, 1\}$. The parameters of the HMM are $\theta = \{\pi, A, E\}$. The *initial state probabilities* are given by

$$P(Z_1 = z_1) = \prod_{k=1}^K \pi_k^{z_{1k}},$$

where $\sum_k \pi_k = 1$. For the *transition probabilities* with $A = (a_{jk}) \in \mathbb{R}^{K \times K}$ with $0 \leq a_{jk} \leq 1$ and $\sum_k a_{jk} = 1$ we have

$$P(Z_n = z_n \mid Z_{n-1} = z_{n-1}, A) = \prod_{k=1}^K \prod_{j=1}^K a_{jk}^{z_{n-1,j} z_{nk}}.$$

The *emission probabilities* $P(X_n = x_n \mid Z_n = z_n, E)$ obey a probability distribution parametrized by E , specified later. Given a set of successive observations x_1, \dots, x_L , the EM algorithm can be used to approximate maximum likelihood estimators of all the parameters θ .

Let $E(\ell_{hid}(\theta))$ shortly denote $E_{Z|X, \theta}(\ell_{hid}(\theta))$, i.e., the expectation is computed with respect to the posterior probability $P(Z_1, \dots, Z_L \mid X_1, \dots, X_L, \theta)$. Write down the factorization for the joint probability distribution $P(X, Z)$ of the HMM and derive that the expected hidden log likelihood $E(\ell_{hid}(\theta))$ can be written as

$$E(\ell_{hid}(\theta)) = \left(\sum_{n=1}^L \sum_{k=1}^K E(z_{nk}) \log(P(X_n = x_n \mid Z_n = e_k, E)) \right) + \left(\sum_{l=1}^K E(z_{1l}) \log(\pi_l) \right) + \sum_{n=2}^L \sum_{k=1}^K \sum_{j=1}^K E(z_{n-1,j} z_{nk}) \log(a_{jk}),$$

where e_k is the unit vector with the k th entry equal to 1.

Problem 2: HMMs and EM: The E-Step

Consider the Hidden Markov model defined above. Show that $E(z_{nk}) = P(Z_n = e_k | X_1 = x_1, \dots, X_L = x_L, \theta)$ and $E(z_{n-1,j}z_{nk}) = P(Z_{n-1} = e_j, Z_n = e_k | X_1 = x_1, \dots, X_L = x_L, \theta)$ by exploiting the binary character of Z_n .

Problem 3: HMMs and EM: The M-Step

Consider the Hidden Markov model defined above. In the M-step, maximizing $E(\ell_{hid}(\theta))$ with respect to π and A (while assuming that $E(z_{nk})$ and $E(z_{n-1,j}z_{nk})$ are constant) we get

$$\pi_k = \frac{E(z_{1k})}{\sum_{k=1}^K E(z_{1k})} \quad \text{and} \quad a_{jk} = \frac{\sum_{n=2}^L E(z_{n-1,j}z_{nk})}{\sum_{n=2}^L \sum_{l=1}^K E(z_{n-1,j}z_{nl})}.$$

Show that if any elements of the parameters π or A are initially set to zero, then those elements will remain zero in all subsequent updates of the EM algorithm.

Hint: Given that the posterior probability is

$$P(Z_1, \dots, Z_L | X_1, \dots, X_L, \theta) = \frac{\left(\prod_{n=1}^L P(X_n | Z_n) \right) P(Z_1) \prod_{n=2}^L P(Z_n | Z_{n-1})}{C},$$

(where C is a normalization constant), derive expressions for $P(Z_1 | X_1, \dots, X_L, \theta)$ and $P(Z_{u-1}, Z_u | X_1, \dots, X_L, \theta)$.

Problem 4: HMMs and EM: Multinomial Emission Probabilities

Consider the Hidden Markov model defined above. If the emission probabilities $E = (p_{jk})$ are *multinomial*, i.e.

$$f_{X_n|Z_n}(x_n | Z_n = z_n) = \prod_{j=1}^m \prod_{k=1}^K p_{jk}^{x_{nj}z_{nk}}$$

with parameters $p_{jk} \in [0, 1]$, show that the maximization step yields

$$p_{jk} = \frac{\sum_{n=1}^L E(z_{nk})x_{nj}}{\sum_{n=1}^L E(z_{nk})}.$$

Problem 5: Modelling the duration of hidden Markov processes

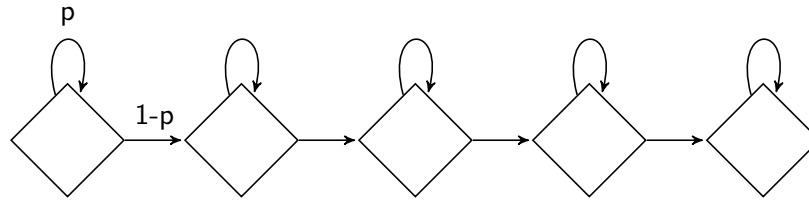
Consider again the hidden Markov model encoded by the graph of Problem 1. Assume that $P(Z_{i+1} = \xi | Z_i = \xi) = p$ for a fixed state ξ of the hidden variable. Thus, after entering the state ξ there is a probability of $1 - p$ of leaving it.

(a) Show that the probability of staying in state ξ for l time steps is given by

$$P(Z_i = \xi, Z_{i+1} = \xi, \dots, Z_{i+l-1} = \xi, Z_{i+l} \neq \xi) = (1 - p)p^{l-1}.$$

This exponentially decaying distribution on lengths (l) is called *geometric distribution*.

- (b) Geometric distribution on lengths can be inappropriate in some applications, where the distribution of lengths is important and significantly different from geometric. A way to circumvent this issue is to model the state ξ with an array of $N \in \mathbb{L}$ identical states in which the transition probabilities are as in the following figure:



Show that for any given path of length l through the model the probability of all its transitions is given by $p^{l-N}(1-p)^L$. Moreover, show that the total probability summed over all possible paths is

$$P(l) = \binom{l-1}{N-1} p^{l-N} (1-p)^L.$$