

# Behavioural differential equations: an introduction

Joost Winter

Centrum Wiskunde & Informatica, Leiden University  
Part the NWO project 'CoRE' (Coinductive Calculi of Regular Expressions)

ICT Open, October 23, 2012

This talk will be about:

1. Finite, nondeterministic, stream and weighted automata (seen as coalgebras)

This talk will be about:

1. Finite, nondeterministic, stream and weighted automata (seen as coalgebras)
2. Presenting work developed by Brzozowski, Rutten, Bonsangue, Silva, and many others. . .

This talk will be about:

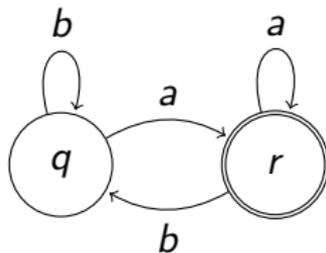
1. Finite, nondeterministic, stream and weighted automata (seen as coalgebras)
2. Presenting work developed by Brzozowski, Rutten, Bonsangue, Silva, and many others. . .
3. . . and if time allows even some of my own research.

This talk will be about:

1. Finite, nondeterministic, stream and weighted automata (seen as coalgebras)
2. Presenting work developed by Brzozowski, Rutten, Bonsangue, Silva, and many others. . .
3. . . and if time allows even some of my own research.
4. (Almost) no category theory.

# A fresh look at automata

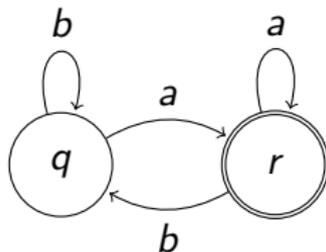
An *automaton* is a triple  $(Q, o, \delta)$



$$Q = \{q, r\}$$

# A fresh look at automata

An *automaton* is a triple  $(Q, o, \delta)$



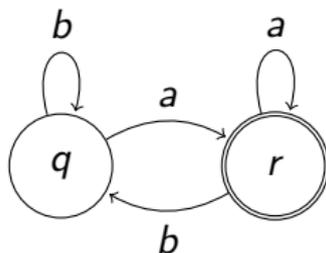
$$Q = \{q, r\}$$

We represent  $o$  and  $\delta$  with a system of *behavioural differential equations*:

$$\begin{array}{lll} o(q) = 0 & q_a = r & q_b = q \\ o(r) = 1 & r_a = r & r_b = q \end{array}$$

- ▶  $q_a$ : shorthand for  $\delta(q, a)$ .
- ▶ Called the *a-derivative* of  $q$ ...
- ▶ ... has some properties similar to the familiar derivative from calculus!

# Word derivatives

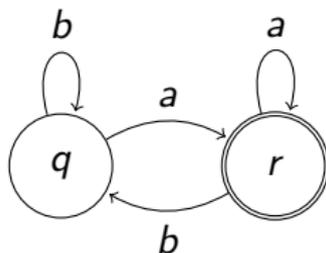


We can extend the notion of derivatives from alphabet symbols to words inductively (1 denotes the empty word):

$$q_1 = q$$

$$q_{a \cdot w} = (q_a)_w$$

# Word derivatives



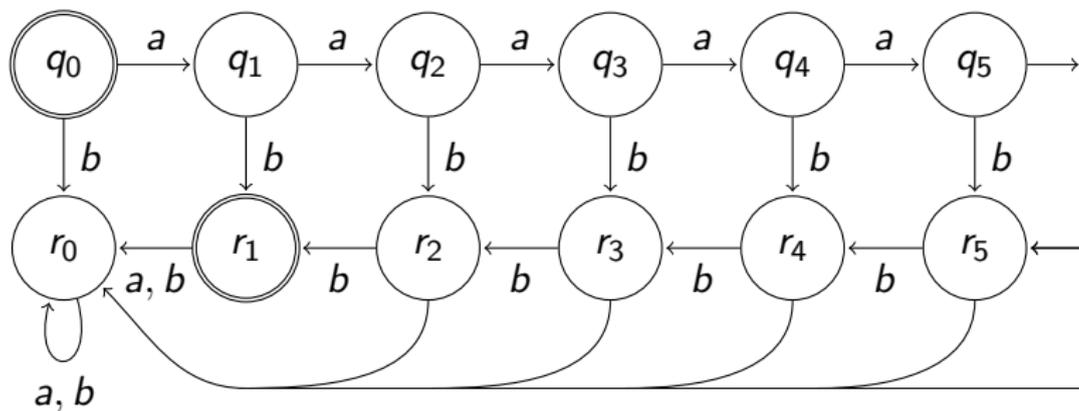
We can extend the notion of derivatives from alphabet symbols to words inductively (1 denotes the empty word):

$$q_1 = q$$
$$q_{a \cdot w} = (q_a)_w$$

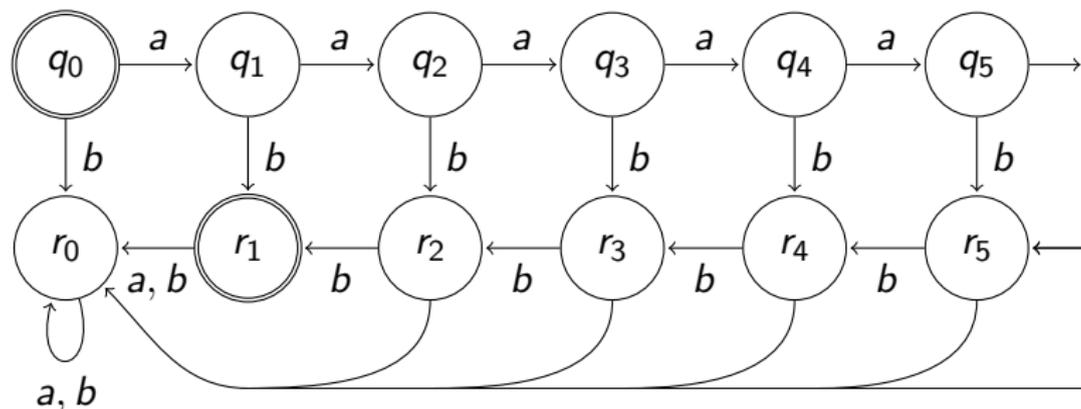
In the above automaton, we have e.g.

$$q_{abb} = q$$

# An infinite automaton...



# An infinite automaton...



Corresponding system of b.d.e.'s:

$$\begin{array}{lll} o(q_i) = 0 & (q_i)_a = q_{i+1} & (q_i)_b = r_i \\ o(r_0) = 0 & (r_0)_a = r_0 & (r_0)_b = r_0 \\ o(r_1) = 1 & (r_1)_a = r_0 & (r_1)_b = r_0 \\ o(r_{k+2}) = 0 & (r_{k+2})_a = r_0 & (r_{k+2})_b = r_{k+1} \end{array}$$

# A very large automaton

Consider the automaton  $(\mathcal{L}, o, \delta)$ :

- ▶  $\mathcal{L} = \mathcal{P}(\mathcal{P}(A^*))$ , the set of all languages over  $A$
- ▶  $o(L)$  is 1 if  $1 \in L$ , and 0 otherwise
- ▶  $L_a = \{w \mid aw \in L\}$  for all alphabet symbols  $a$

# A very large automaton

Consider the automaton  $(\mathcal{L}, o, \delta)$ :

- ▶  $\mathcal{L} = \mathcal{P}(\mathcal{P}(A^*))$ , the set of all languages over  $A$
- ▶  $o(L)$  is 1 if  $1 \in L$ , and 0 otherwise
- ▶  $L_a = \{w \mid aw \in L\}$  for all alphabet symbols  $a$

## Proposition

*For every automaton  $(Q, o', \delta')$ , there is exactly one mapping  $\llbracket \cdot \rrbracket : Q \rightarrow \mathcal{L}$ , such that*

1.  $o'(q) = o(\llbracket q \rrbracket)$  for all states  $q$ , and
2.  $\llbracket q_a \rrbracket = \llbracket q \rrbracket_a$  for all states  $q$  and alphabet symbols  $a$ .

# A very large automaton

Consider the automaton  $(\mathcal{L}, o, \delta)$ :

- ▶  $\mathcal{L} = \mathcal{P}(\mathcal{P}(A^*))$ , the set of all languages over  $A$
- ▶  $o(L)$  is 1 if  $1 \in L$ , and 0 otherwise
- ▶  $L_a = \{w \mid aw \in L\}$  for all alphabet symbols  $a$

## Proposition

*For every automaton  $(Q, o', \delta')$ , there is exactly one mapping  $\llbracket \cdot \rrbracket : Q \rightarrow \mathcal{L}$ , such that*

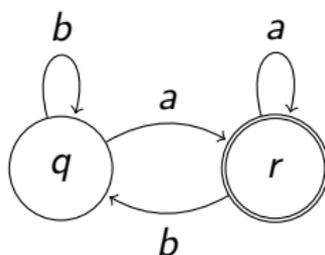
1.  $o'(q) = o(\llbracket q \rrbracket)$  for all states  $q$ , and
2.  $\llbracket q_a \rrbracket = \llbracket q \rrbracket_a$  for all states  $q$  and alphabet symbols  $a$ .

In other words:  $\mathcal{L}$  is a *final automaton* or *final coalgebra*.

# This is not a categorical diagram (1)

$$\begin{array}{ccc} Q & \xrightarrow{\quad \llbracket \quad \rrbracket \quad} & \mathcal{L} \\ \downarrow (o', \delta') & & \downarrow (o, \delta) \\ \mathbb{B} \times Q^A & \xrightarrow{\quad \text{id} \times \llbracket \quad \rrbracket^A \quad} & \mathbb{B} \times \mathcal{L}^A \end{array}$$

# The final homomorphism



$\llbracket \cdot \rrbracket$  assigns to states the language accepted by those states:

$$\llbracket q \rrbracket = \{w \mid w \text{ ends in } a\}$$

$$\llbracket r \rrbracket = \{w \mid w \text{ ends in } a \text{ or is empty}\}$$

# Bisimulation (1)

A bisimulation between two automata with state spaces  $Q_0$  and  $Q_1 \dots$

# Bisimulation (1)

A bisimulation between two automata with state spaces  $Q_0$  and  $Q_1 \dots$

$\dots$  is a relation  $R \subset Q_0 \times Q_1$  such that, whenever  $(q, r) \in R$ :

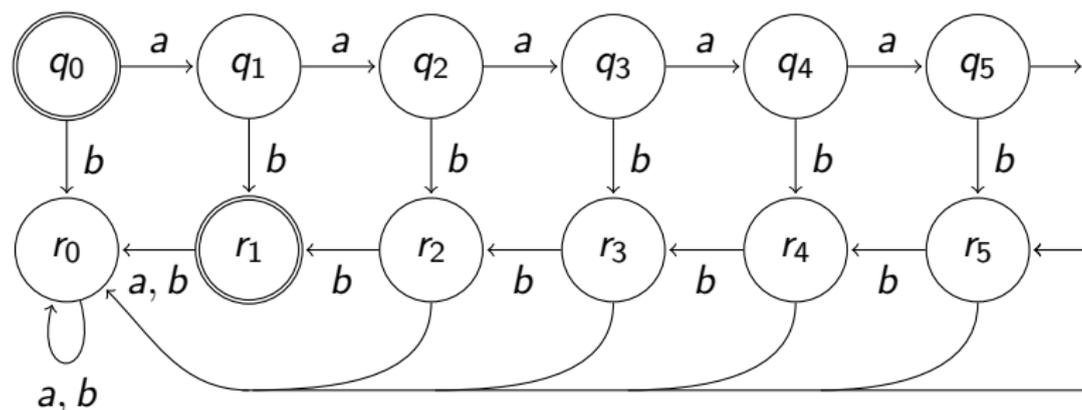
1.  $o(q) = o(r)$ , and  $\dots$
2.  $(q_a, r_a) \in R$  for all alphabet symbols  $a$ .

# Bisimulation (2)

## Fact

If  $(q, r) \in R$  for some bisimulation  $R$ , then  $\llbracket q \rrbracket = \llbracket r \rrbracket$ .

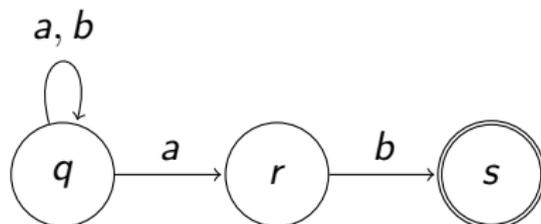
## Bisimulation (3)



$$R = \{(q_i, a^n b^{n+i}) \mid i \in \mathbb{N}\} \cup \{(r_0, 0), (r_1, 1)\} \cup \{(r_{i+2}, b^{i+1}) \mid i \in \mathbb{N}\}$$

is a bisimulation. Hence,  $\llbracket q_0 \rrbracket = a^n b^n$ , etc. . .

# A nondeterministic automaton



$$\begin{array}{lll} o(q) = 0 & q_a = q + r & q_b = q \\ o(r) = 0 & r_a = 0 & r_b = s \\ o(s) = 1 & s_a = 0 & s_b = 0 \end{array}$$

Right hand sides of the equations: sums of states.

We can transform a nondeterministic automaton  $(Q, o, \delta)$  into a deterministic automaton  $(\mathcal{P}(Q), \hat{o}, \hat{\delta})$ , by enforcing the rules

$$\begin{array}{ll} \hat{o}(0) = 0 & 0_a = 0 \\ \hat{o}(s + t) = \max(o(s), o(t)) & (s + t)_a = s_a + t_a \end{array}$$

(Representing elements  $\{q_1, \dots, q_n\} \in \mathcal{P}(Q)$  as sums  $\sum_{1 \leq i \leq n} q_i$ ).

# This is not a categorical diagram (2)

$$\begin{array}{ccccc} Q & \hookrightarrow & \mathcal{P}(Q) & \xrightarrow{\llbracket - \rrbracket} & \mathcal{L} \\ \downarrow & & \searrow & & \downarrow \\ \mathbb{B} \times \mathcal{P}(Q)^A & & & & \mathbb{B} \times \mathcal{L}^A \end{array}$$

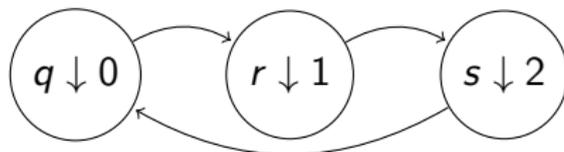
The diagram shows a commutative square with the following components:

- Top-left node:  $Q$
- Top-middle node:  $\mathcal{P}(Q)$
- Top-right node:  $\mathcal{L}$
- Bottom-left node:  $\mathbb{B} \times \mathcal{P}(Q)^A$
- Bottom-right node:  $\mathbb{B} \times \mathcal{L}^A$

Arrows and labels:

- $Q \hookrightarrow \mathcal{P}(Q)$  (inclusion arrow)
- $\mathcal{P}(Q) \xrightarrow{\llbracket - \rrbracket} \mathcal{L}$  (double-bracketed arrow)
- $Q \downarrow \mathbb{B} \times \mathcal{P}(Q)^A$  (vertical arrow labeled  $(o, \delta)$ )
- $\mathcal{L} \downarrow \mathbb{B} \times \mathcal{L}^A$  (vertical arrow)
- $\mathbb{B} \times \mathcal{P}(Q)^A \xrightarrow{\quad} \mathbb{B} \times \mathcal{L}^A$  (horizontal arrow)
- A diagonal arrow from  $\mathcal{P}(Q)$  to  $\mathbb{B} \times \mathcal{P}(Q)^A$  labeled  $(\delta, \delta)$ .

# A simple stream automaton

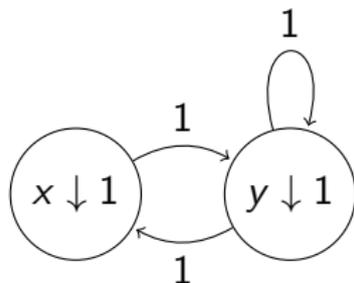


$$\begin{array}{lll} o(q) = 0 & q' = r & \llbracket q \rrbracket = (0, 1, 2, 0, 1, 2, \dots) \\ o(r) = 1 & r' = s & \llbracket r \rrbracket = (1, 2, 0, 1, 2, 0, \dots) \\ o(s) = 2 & s' = q & \llbracket s \rrbracket = (2, 0, 1, 2, 0, 1, \dots) \end{array}$$

(Finite stream automata are not very spectacular)

# A weighted automaton (1)

A weighted automaton...



... and the corresponding system of equations ...

$$\begin{aligned}o(x) &= 1 & x' &= y \\ o(y) &= 1 & y' &= y + x\end{aligned}$$

Right hand side: linear combination of states

## Determinization (2)

We can transform a weighted automaton  $(Q, o, \delta)$  into a stream automaton  $(\text{span}(Q), \hat{o}, \hat{\delta})$ , by enforcing the rule

$$\hat{o} \left( \sum_{0 \leq i < k} r_i q_i \right) = \sum_{0 \leq i < k} r_i o(q_i) \quad \left( \sum_{0 \leq i < k} r_i q_i \right)' = \sum_{0 \leq i < k} r_i q_i'$$

for all linear combinations of elements  $q \in Q$ .

# The Fibonacci sequence



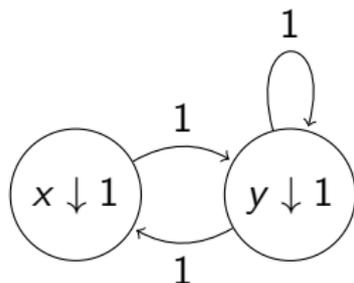
$$\mathbf{fib} = (1, 1, 2, 3, 5, 8, 13, 21, 34, \dots)$$

Inductive definition:

$$\mathbf{fib}(0) = \mathbf{fib}(1) = 1 \quad \mathbf{fib}(n + 2) = \mathbf{fib}(n + 1) + \mathbf{fib}(n)$$

# A weighted automaton (2)

A weighted automaton...



... and the corresponding system of equations ...

$$\begin{aligned}o(x) &= 1 & x' &= y \\ o(y) &= 1 & y' &= y + x\end{aligned}$$

Proposition

$$\llbracket x \rrbracket = \mathbf{fib}$$

# A proof

The relation

$$R = \{(\mathbf{fib}, x), (\mathbf{fib}', y)\} \cup \{(\mathbf{fib}^{(n+2)}, \mathbf{fib}(n)x + \mathbf{fib}(n+1)y) \mid n \in \mathbb{N}\}$$

is a bisimulation w.r.t. the function **fib** and the system

$$o(x) = 1 \quad o(y) = 1 \quad x' = y \quad y' = x + y.$$

# A proof

The relation

$$R = \{(\mathbf{fib}, x), (\mathbf{fib}', y)\} \cup \{(\mathbf{fib}^{(n+2)}, \mathbf{fib}(n)x + \mathbf{fib}(n+1)y) \mid n \in \mathbb{N}\}$$

is a bisimulation w.r.t. the function **fib** and the system

$$o(x) = 1 \quad o(y) = 1 \quad x' = y \quad y' = x + y.$$

E.g.:

$$\begin{aligned} \mathbf{fib}^{(n+2)'} &= \mathbf{fib}^{(n+3)} \\ R \quad \mathbf{fib}(n+1)x + \mathbf{fib}(n+2)y \\ &= \mathbf{fib}(n+1)x + (\mathbf{fib}(n+1) + \mathbf{fib}(n))y \\ &= (\mathbf{fib}(n)x + \mathbf{fib}(n+1)y)' \end{aligned}$$

# More complex systems

We now look at systems where the right hand side of any derivative can be a polynomial over the set  $X$  of variables, e.g.

$$x^3y^3 + xy^2 + y$$

We determinize using the product rule

$$o(st) = o(s)o(t) \quad (st)_a = s_a t + o(s)t_a$$

(in addition to the earlier linearity rules)

Resulting class of languages: the context-free languages!

# A context-free system

An example of such a system:

$$\begin{array}{llll} o(x) = 1 & x_a = xy & x_b = 0 \\ o(y) = 0 & y_a = 0 & y_b = 1 \end{array}$$

# A context-free system

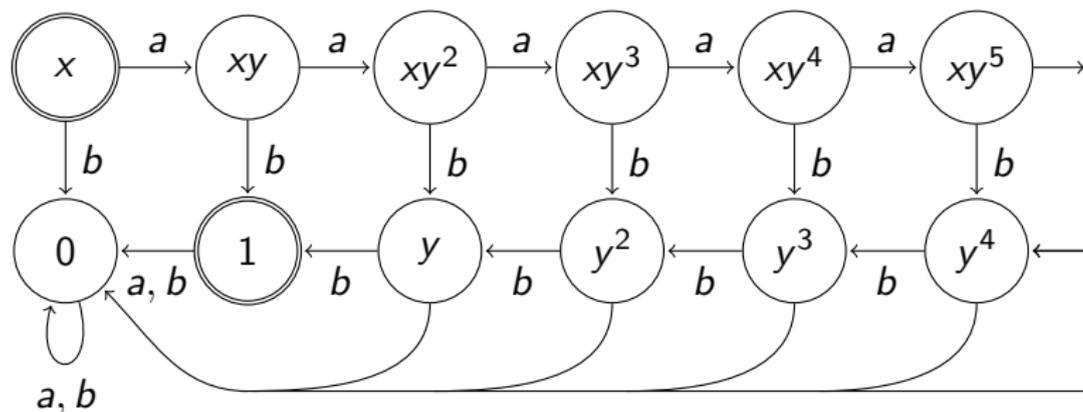
An example of such a system:

$$\begin{array}{lll} o(x) = 1 & x_a = xy & x_b = 0 \\ o(y) = 0 & y_a = 0 & y_b = 1 \end{array}$$

We get

$$[[x]] = a^n b^n$$

# Determinization of a context-free system



# Classes of b.d.e., their languages and streams

rhs	Class of languages	Class of streams
Single element	Regular	Finitary
Linear combination	(Nondeterministic) regular	Rational
Polynomial	Context-free	Algebraic

- ▶ Bisimulation is a very nice coinductive proof technique!
- ▶ Behavioural differential equations are an effective way of defining automata-like structures.
- ▶ Casting a new light on the existing theory of (weighted) automata.