

Non Linear Asymptotic Mean Value Properties for Monge-Ampère Equations

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Theorem

$$\Delta u(x) = 0$$

if and only if

$$(1) \quad u(x) = \int_{\partial B(x,r)} u(y) d\sigma(y)$$

or

$$\left(\lim_{r \rightarrow 0} \right) \frac{1}{r^2} \left[\int_{\partial B(x,r)} u(y) d\sigma(y) - u(x) \right] = 0.$$

$$(2) \quad u(x) = \int_{B(x,r)} u(y) d\sigma(y)$$

or

$$\left(\lim_{r \rightarrow 0} \right) \frac{1}{r^2} \left[\int_{B(x,r)} u(y) d\sigma(y) - u(x) \right] = 0.$$

Theorem (Blasche, 1916)

An upper-semicontinuous function u is subharmonic, $\Delta u \geq 0$, if and only if

$$\limsup_{\epsilon \rightarrow 0} \frac{1}{\epsilon^2} \left[\int_{\partial B(x, \epsilon)} u(y) d\sigma(y) - u(x) \right] \geq 0$$

Theorem (Privaloff, 1916)

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Theorem

A function u is harmonic, $\Delta u = 0$, if and only if

$$u(x) = \frac{1}{n} \sum_{j=1}^n \left\{ \frac{1}{2} u(x + \varepsilon e_j) + \frac{1}{2} u(x - \varepsilon e_j) \right\} + o(\varepsilon^2) \quad \text{as } \varepsilon \rightarrow 0,$$

where $\{e_1, \dots, e_n\}$ is the canonical basis of \mathbb{R}^n , or

$$u(x) = \left[\int_{B(x, \varepsilon)} u(y) d(y) \right] + o(\varepsilon^2) \quad \text{as } \varepsilon \rightarrow 0.$$

Modern Linear results

If we replace the Laplace equation $\Delta u = 0$ by a linear elliptic equation with constant coefficients $Lu = \sum_{i,j} a_{ij} u_{x_i x_j} = 0$ then mean value formulas hold for appropriate ellipsoids instead of balls.

Nonlinear operators. (Manfredi-Parvianen-R., 2010)

Viscosity solutions to the 1-homogeneous p -Laplacian

$$\Delta_p^N u = \frac{1}{p-2} |\nabla u|^{2-p} \operatorname{div}(|\nabla u|^{p-2} \nabla u) = \frac{1}{p-2} \Delta u + \Delta_\infty^N u = 0,$$

for $1 < p \leq \infty$ are characterized by a mean value formula

$$u(x) - \left(\frac{p-2}{p+n} \right) \left(\frac{\max_{\overline{B_\varepsilon(x)}} u + \min_{\overline{B_\varepsilon(x)}} u}{2} \right) + \left(\frac{2+n}{p+n} \right) \int_{B_\varepsilon(x)} u(y) dy \\ = o(\varepsilon^2) \quad \text{as } \varepsilon \rightarrow 0.$$

We will discuss mean value properties for solutions to the

Monge-Ampère equation

$$\det D^2 u = f,$$

with $f \geq 0$ in a convex domain Ω .

As usual, we look for convex solutions u , thus the $D^2 u \geq 0$ and hence f is non-negative. In terms of eigenvalues of $D^2 u$ we have

$$\min_{\lambda \text{ eigenvalue of } D^2 u} \{\lambda\} \geq 0.$$

Let $\phi(\epsilon), \phi : \mathbb{R}_+ \mapsto \mathbb{R}_+$ be such that

$$\lim_{\epsilon \rightarrow 0} \phi(\epsilon) = +\infty$$

and

$$\lim_{\epsilon \rightarrow 0} \epsilon \phi(\epsilon) = 0.$$

($\phi(\epsilon) = \epsilon^{-1/2}$ works).

Theorem (Convex C^2 Case)

Let u be convex and C^2 in Ω . Fix $x \in \Omega$. We have

$$u(x) - \inf_{\substack{\det A=1 \\ A \leq \phi(\epsilon)I}} \left\{ \int_{B_\epsilon(0)} u(x+Ay) dy \right\} + \frac{n}{2(n+2)} (\det D^2 u(x))^{1/n} \epsilon^2 = o(\epsilon^2),$$

as $\epsilon \rightarrow 0$.

- Notice that for every A with $\det A = 1$, it holds

$$\left\{ \int_{B_\epsilon(0)} u(x + Ay) dy \right\} = \left\{ \int_{E_\epsilon(A,x)} u(z) dz \right\}$$

where $E_\epsilon(A, x) = \{x + Ay : y \in B_\epsilon(0)\}$.

- The restriction $A \leq \phi(\epsilon)I$ in the infimum makes the formula local. For every $x \in \Omega$, the conditions $A \leq \phi(\epsilon)I$ and $|y| \leq \epsilon$ imply that

$$\text{dist}(E_\epsilon(A, x), x) = \text{dist}(x + Ay, x) = |Ay| \leq |A||y| \leq \epsilon \phi(\epsilon) \rightarrow 0$$

(since $\epsilon \phi(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$).

Hence, $E_\epsilon(A, x) \subset \Omega$ for ϵ small enough.

Replace the condition $A \leq \phi(\epsilon)$ by requiring

$$E_\epsilon(A, x) = \{x + Ay : y \in B_\epsilon(0)\} \subset \Omega.$$

Theorem (Non-Local Convex C^2 -case)

Let u be convex and C^2 in Ω . Fix $x \in \Omega$. We have

$$u(x) - \inf_{\substack{\det A=1 \\ E_\epsilon(A, x) \subset \Omega}} \left\{ \int_{B_\epsilon(0)} u(x+Ay) dy \right\} + \frac{n}{2(n+2)} (\det D^2 u(x))^{1/n} \epsilon^2 = o(\epsilon^2)$$

as $\epsilon \rightarrow 0$.

Corollary (Characterization of C^2 -solutions)

Let u be convex and C^2 in Ω , $f \geq 0$. TFAE:

$$(\det D^2 u(x))^{1/n} = f(x)$$

$$u(x) - \inf_{\substack{\det A=1 \\ A \leq \phi(\epsilon)I}} \left\{ \int_{B_\epsilon(0)} u(x + Ay) dy \right\} + \frac{\epsilon^2 n}{2(n+2)} f(x) = o(\epsilon^2)$$

$$u(x) - \inf_{\substack{\det A=1 \\ E_\epsilon(A,x) \subset \Omega}} \left\{ \int_{B_\epsilon(0)} u(x + Ay) dy \right\} + \frac{\epsilon^2 n}{2(n+2)} f(x) = o(\epsilon^2).$$

Theorem (Characterization of viscosity solutions)

Let $f \in C(\Omega)$ be non-negative and $u \in C(\Omega)$ be convex. TFAE:
 u is a viscosity subsolution (respectively, supersolution) of

$$\det D^2 u = f \quad \text{in } \Omega, \quad (\det D^2 u \geq f)$$

$$u(x) \leq \inf_{\substack{\det A=1 \\ A \leq \phi(\epsilon)I}} \left\{ \int_{B_\epsilon(0)} u(x + Ay) \, dy \right\} - \frac{\epsilon^2 n}{2(n+2)} f(x) + o(\epsilon^2)$$

$$u(x) \leq \inf_{\substack{\det A=1 \\ E_\epsilon(A,x) \subset \Omega}} \left\{ \int_{B_\epsilon(0)} u(x + Ay) \, dy \right\} - \frac{\epsilon^2 n}{2(n+2)} f(x) + o(\epsilon^2)$$

(respectively, \geq) in the viscosity sense (the mean value expansions are satisfied for convex paraboloids P that touch u at x).

Discrete asymptotic expansion

For $u \in C^2$ convex we have the asymptotic expansion

$$u(x) = \inf_{V \in \mathbb{O}} \inf_{\alpha_j \in I_\epsilon^n} \left\{ \frac{1}{n} \sum_{i=1}^n \frac{u(x + \epsilon \sqrt{\alpha_i} v_i) + u(x - \epsilon \sqrt{\alpha_i} v_i)}{2} \right\} \\ - \frac{\epsilon^2}{2} (\det(D^2 u)(x))^{1/n} + o(\epsilon^2)$$

as $\epsilon \rightarrow 0$.

Here \mathbb{O} is the set all orthonormal bases $V = \{v_1, \dots, v_n\}$ of \mathbb{R}^n and

$$I_\epsilon^n = \left\{ (\alpha_1, \dots, \alpha_n) \in \mathbb{R}^n : \prod_{j=1}^n \alpha_j = 1 \quad \text{and} \quad 0 < \alpha_j < \phi^2(\epsilon) \right\}.$$

Theorem (Characterization of viscosity solutions by Discrete Mean Values)

Let u be a convex function in a domain $\Omega \subset \mathbb{R}^n$. Then, u is a solution to the Monge-Ampère equation

$$\det(D^2 u(x)) = f(x)$$

in the viscosity sense if and only if

$$u(x) = \inf_{V \in \mathbb{O}} \inf_{\alpha_i \in I_\epsilon^n} \left\{ \frac{1}{n} \sum_{i=1}^n \frac{u(x + \epsilon \sqrt{\alpha_i} v_i) + u(x - \epsilon \sqrt{\alpha_i} v_i)}{2} \right\} - \frac{\epsilon^2}{2} (f(x))^{1/n} + o(\epsilon^2)$$

as $\epsilon \rightarrow 0$, holds in the viscosity sense.

Determinant identity for $M \geq 0$

$$n(\det M)^{1/n} = \inf_{\det A=1} \text{trace}(A^t M A),$$

where the matrix A is symmetric and positive definite.

Linear averages

Let M be a square matrix of dimension n . We have

$$\text{trace}(M) = \frac{n+2}{\varepsilon^2} \int_{B_\varepsilon(0)} \langle My, y \rangle dy.$$

Suppose $D^2u(x) > 0$. Extra work is needed when $\det D^2u(x) = 0$.

Given $x \in \Omega$, consider the paraboloid

$$P(z) = u(x) + \langle \nabla u(x), z - x \rangle + \frac{1}{2} \langle D^2u(x)(z - x), (z - x) \rangle.$$

Since $u \in C^2(\Omega)$, we have

$$u(z) - P(z) = o(|z - x|^2) \quad \text{as } z \rightarrow x,$$

that is,

$$P(z) - \frac{\eta}{2}|z - x|^2 \leq u(z) \leq P(z) + \frac{\eta}{2}|z - x|^2,$$

for every $z \in B_\delta(x)$, with equality only when $z = x$. Let us denote

$$P_\eta^\pm(z) = P(z) \pm \frac{\eta}{2}|z - x|^2.$$

$$\begin{aligned}
 \int_{B_\epsilon(0)} (P_\eta^\pm(x + Ay) - u(x)) dy &= \frac{1}{2} \int_{B_\epsilon(0)} (\langle A^t D^2 u(x) Ay, y \rangle \pm \eta |Ay|^2) dy \\
 &= \frac{1}{2} \int_{B_\epsilon(0)} \langle A^t (D^2 u(x) \pm \eta I) Ay, y \rangle dy \\
 &= \frac{\epsilon^2}{2(n+2)} \text{trace} (A^t (D^2 u(x) \pm \eta I) A),
 \end{aligned}$$

Using

$$n(\det M)^{1/n} = \inf_{\det A=1} \text{trace}(A^t M A),$$

and that $P_\eta^\pm(x) = u(x)$ we obtain

$$\inf_{\substack{\det A=1 \\ A \leq \phi(\epsilon)I}} \left\{ \int_{B_\epsilon(0)} (P_\eta^\pm(x + Ay) - P_\eta^\pm(x)) dy \right\} = \frac{n\epsilon^2}{2(n+2)} (\det (D^2 u(x) \pm \eta I))^{1/n}$$

Now we use that

$$P_{\eta}^{-}(x + Ay) \leq u(x + Ay) \leq P_{\eta}^{+}(x + Ay) \quad \text{for every } y \in B_{\epsilon}(0).$$

to obtain

$$\inf_{\substack{\det A=1, \\ A \leq \phi(\epsilon)I}} \left\{ \int_{B_{\epsilon}(0)} (u(x + Ay) - u(x)) \, dy \right\} \leq \frac{n \epsilon^2}{2(n+2)} (\det (D^2 u(x) + \eta I))^{1/n}$$

$$\inf_{\substack{\det A=1, \\ A \leq \phi(\epsilon)I}} \left\{ \int_{B_{\epsilon}(0)} (u(x + Ay) - u(x)) \, dy \right\} \geq \frac{n \epsilon^2}{2(n+2)} (\det (D^2 u(x) - \eta I))^{1/n}.$$

The result follows from

$$(\det (D^2 u(x) \pm \eta I))^{1/n} \rightarrow (\det D^2 u(x))^{1/n} \quad \text{as } \eta \rightarrow 0.$$

We describe a one-player game (or control problem)

RULES OF THE GAME :

- Fix a convex domain $\Omega \subset \mathbb{R}^n$
- Fix a final payoff $g: \mathbb{R}^n \setminus \Omega \mapsto \mathbb{R}$ and a running cost $f \in C(\Omega)$, $f \geq 0$,
- Fix $\varepsilon > 0$ small
- Place a token at an initial position $x_0 \in \Omega$
- The player chooses an orthonormal basis $\{v_1, \dots, v_n\}$ and n real nonnegative numbers $(\alpha_1, \dots, \alpha_n) \in I_\varepsilon^n$ where

$$I_\varepsilon^n = \left\{ (\alpha_i)_{i=1, \dots, n} \in \mathbb{R}^n : \prod_{i=1}^n \alpha_i = 1 \quad \text{and} \quad 0 < \alpha_i < \frac{1}{\varepsilon} \right\}.$$

- The token is moved to

$$x_1 = x_0 \pm \varepsilon \sqrt{\alpha_i} v_i$$

with equal probabilities $\frac{1}{2n}$

- Player 1 pays $\frac{1}{2} \varepsilon^2 (f(x_0))^{1/n}$

- Repeat the process starting at x_1 to get x_2 and so on
- Get a sequence of positions $\{x_0, x_1, \dots, x_j \dots\}$
- The game stops when the token leaves Ω . Let τ be first time that $x_\tau \notin \Omega$. The player gets paid $g(x_\tau)$
- At the end the player obtains

$$g(x_\tau) - \frac{1}{2}\varepsilon^2 \sum_{j=0}^{\tau-1} (f(x_j))^{1/n}$$

- A STRATEGY S for the player is a choice of orthonormal basis and numbers $(\alpha_j) \in I_\varepsilon^n$.
- Given a strategy S we can look for the expected outcome

$$\mathbb{E}_S^{x_0} \left[g(x_\tau) - \frac{1}{2}\varepsilon^2 \sum_{j=0}^{\tau-1} [f(x_j)]^{1/n} \right]$$

Suppose that the player wants to minimize the payment.

The value of the game at $x_0 \in \Omega$

$$u_\varepsilon(x_0) = \inf_S \mathbb{E}_S^{x_0} \left[g(x_\tau) - \frac{1}{2} \varepsilon^2 \sum_{j=0}^{\tau-1} [f(x_j)]^{1/n} \right]$$

The value function satisfies the DPP

$$u_\varepsilon(x) = \inf_{V \in \mathbb{O}} \inf_{\alpha_i \in I_\varepsilon^n} \left\{ \frac{1}{n} \sum_{i=1}^n \frac{u_\varepsilon(x + \varepsilon \sqrt{\alpha_i} v_i) + u_\varepsilon(x - \varepsilon \sqrt{\alpha_i} v_i)}{2} \right\} \\ - \frac{\varepsilon^2}{2} (f(x))^{1/n} \quad \text{for } x \in \Omega$$

$$u_\varepsilon(x) = g(x) \quad \text{for } x \notin \Omega$$

Existence and Uniqueness for the DPP hold.

Solving the DPP for each $\varepsilon > 0$ we get a family of functions $\{u_\varepsilon\}$.

Theorem

When the domain Ω is strictly convex we have

$$u_\varepsilon \rightarrow u \quad \text{as } \varepsilon \rightarrow 0$$

uniformly in $\bar{\Omega}$, where u is the unique viscosity solution to the problem

$$\begin{cases} \det D^2 u = f & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega. \end{cases}$$

General picture

MVP (continuous, discrete) \iff DPP (usually discrete) \iff
PDE (usually continuous)

(Meta) Theorem

For an appropriate real function u we have a meta-equivalence among

- 1 u satisfies a Mean Value Property (in an appropriate asymptotic sense)*
- 2 u can be approximated by solutions to a Dynamic Programming Principle associated to a game or control problem*
- 3 u solves a (possibly nonlinear) PDE*

Flexibility of this approach

Euclidean spaces, Riemannian manifolds, Sub-Riemannian manifolds (Heisenberg group), graphs (trees), metric-measure spaces, parabolic versions.

But limited to \mathbb{R} -valued functions and 2nd order PDEs (we use viscosity theory).

References

- P. Blanc and J. D. R., *Game Theory and Partial Differential Equations*, 2019
- M. Lewicka, *A course on Tug-of-War Games with Random Noise*, 2020.
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Thanks !!! Gracias !!!