

# LEARNING AND EPISTEMIC MODAL LOGIC PART 1

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# OUTLINE

A MOTIVATING EXAMPLE

VARIOUS INFERENCE PARADIGMS

LEARNING SETS

- Learning Sets and Some Logic
- Gold Theorems
- Limits and Knowledge

INTRODUCTION TO EPISTEMIC MODAL LOGIC

- Modeling Uncertainty
- Epistemic Logic
- Public Announcement Logic

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# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

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What is the rule behind this sequence of cards?

A♠

# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

A♠ Q♠

# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

A♠ Q♠ 3♠

# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

A♠ Q♠ 3♠ A♠

# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

A♠ Q♠ 3♠ A♠ Q♠

# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

A♠ Q♠ 3♠ A♠ Q♠ 4♥

# INDUCTIVE INFERENCE: CARD GAME

What is the rule behind this sequence of cards?

A♠ Q♠ 3♠ A♠ Q♠ 4♥ ...

# HOW MANY DIFFERENT ABSTRACT SCENARIOS?

Assume we have at our disposal unlimited amount of playing cards.

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# HOW MANY DIFFERENT ABSTRACT SCENARIOS?

Assume we have at our disposal unlimited amount of playing cards.

1. How many different (kinds of) playing cards do we have?
2. How many different beginnings of length 1?
3. How many different beginnings of length 2?
4. How many different infinite sequences?

# THE INFINITIES OF INDUCTIVE INFERENCE

1.	A♠	A♠	A♠	A♠	A♠	A♠	...
2.	A♣	A♣	A♣	A♣	A♣	A♣	...
3.	A♥	A♥	A♥	A♥	A♥	A♥	...
4.	A♦	Q♠	3♠	8♥	2♥	5♠	...
5.	A♠	Q♠	7♠	J♠	5♠	5♠	...
...							
m.	A♣	A♥	A♣	A♥	A♣	A♦	...
...							

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1.	A♠	A♠	A♠	A♠	A♠	A♠	...
2.	A♣	A♣	A♣	A♣	A♣	A♣	...
3.	A♥	A♥	A♥	A♥	A♥	A♥	...
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...							
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3.	A♥	A♥	A♥	A♥	A♥	A♥	...
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...							
m.	A♣	A♥	A♣	A♥	A♣	A♦	...
...							

# THE INFINITIES OF INDUCTIVE INFERENCE

1.							...
2.							...
3.							...
4.							...
5.							...
...							
m.							...
...							

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...							
m.	A♣	A♥	A♣	A♥	A♣	A♦	...
...							

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5.	A♠	Q♠	7♠	J♠	5♠	5♠	...
...							
m.	A♣	A♥	A♣	A♥	A♣	A♦	... m-th
...							

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...							
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...							

...

# HOW MANY POSSIBLE RULES ARE THERE?

1. In principle...

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3. Rule expressed by a natural language sentence.
4. Rule described by a theory that fills a 300 pages book.

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2. Rule written down on a piece of paper.
3. Rule expressed by a natural language sentence.
4. Rule described by a theory that fills a 300 pages book.
5. Rule encoded by a Turing Machine program.

Descriptions are finite, and there are countably many of them.

# HOW MANY SEQUENCES COMPLY TO ONE RULE?

1. The sequence has solely A♠-cards.

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2. The sequence has solely ♠-cards.
3. The sequence has ♥-cards on even places.
4. The sequence is definable in first-order logic.
5. etc...

# DIFFERENT HYPOTHESIS SPACES

WHAT CAN WE KNOW AND HOW CAN WE KNOW IT?

1.  $\{(\text{all cards are } \spadesuit), (\text{all cards are } \diamond)\}$
2.  $\{(\spadesuit \text{ at the 4-th position}), \neg(\spadesuit \text{ at the 4-th position})\}$
3.  $\{(\text{exactly } n \text{ cards are } \heartsuit) \mid n \in \mathbb{N}\}$
4.  $\{(\text{exactly } n \text{ cards are } \heartsuit) \mid n \in \mathbb{N}\} \cup \{(\infty \text{ cards are } \heartsuit)\}$

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A $\spadesuit$

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A Q

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A Q 3

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A♠ Q♠ 3♠ A♠

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A $\spadesuit$  Q $\spadesuit$  3 $\spadesuit$  A $\spadesuit$  Q $\spadesuit$  4 $\heartsuit$

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WHAT CAN WE KNOW AND HOW CAN WE KNOW IT?

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A♠ Q♠ 3♠ A♠ Q♠ 4♥ Q♠

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WHAT CAN WE KNOW AND HOW CAN WE KNOW IT?

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A Q 3 A Q 4 Q Q...

# THE GAME OF LEARNING IN THE LIMIT: LEARNER AND NATURE

- ▶ A class of possible worlds (known by both players).
- ▶ Nature chooses one of them (learner does not know which).
- ▶ Nature generates data about the world.
- ▶ From inductively given data learner draws her conjectures.
- ▶ With each input learner can answer with a different hypothesis.
- ▶ Learner succeeds if

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- ▶ With each input learner can answer with a different hypothesis.
- ▶ Learner succeeds if **she stabilizes to a correct hypothesis**.

Her success depends on her skills and on the problem.

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# LEARNING PARADIGMS

## Function Learning

1 Possible realities:

**Functions**

2 Hypotheses:

**Names of functions**

3 Information accessible to the learner:

**Sequences of pairs (argument, value)**

4 Learner:

**Function that takes a sequence and outputs a hypothesis**

5 Success criterion:

**After finite number of outputs stabilize on a correct answer**

## Model-theoretic Learning

1 Possible realities:

**Models of a given signature**

2 Hypotheses:

**First order sentences**

3 Information accessible to the learner:

**Sequences of atomic formulas and negations thereof**

4 Learner:

**Function that takes a sequence and outputs a hypothesis**

5 Success criterion:

**After finite number of outputs stabilize on a correct answer**

# LEARNING PARADIGMS

## Set Learning

1 Possible realities:

**Sets of integers**

2 Hypotheses:

**Names of sets**

3 Information accessible to the learner:

**Sequences of numbers**

4 Learner:

**Function that takes a sequence and outputs a hypothesis**

5 Success criterion:

**After finite number of outputs stabilize on a correct answer**

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# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{ 2, 3, 4, 5, \dots\}$

...

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{ 2, 3, 4, 5, \dots\}$

...

1

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{ 2, 3, 4, 5, \dots\}$

...

1, 3

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{2, 3, 4, 5, \dots\}$

...

1, 3, 4

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{ 2, 3, 4, 5, \dots\}$

...

1, 3, 4, 2

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{2, 3, 4, 5, \dots\}$

...

1, 3, 4, 2, 6

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{ 2, 3, 4, 5, \dots\}$

...

1, 3, 4, 2, 6, 7

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{2, 3, 4, 5, \dots\}$

...

1, 3, 4, 2, 6, 7, 8

# ANOTHER GAME

Consider the following class:

$\{1, 2, 3, 5, \dots\}$

$\{1, 3, 4, 5, \dots\}$

$\{1, 2, 4, 5, \dots\}$

$\{ 2, 3, 4, 5, \dots\}$

...

1, 3, 4, 2, 6, 7, 8, ...

## ANOTHER GAME

1. Are you confident? What would make you change your guess?
2. What was your “guessing rule”?
3. How do you like winning if at least one of your guess is correct?
4. And if you succeed to make a right guess and never change your mind after that? How many wrong guesses could you make under this condition?

## ANOTHER GAME

1. Assume that I'll give you all and only truthful clues. What would be the guessing rule to win according to the last winning condition?
2. Add  $\{1, 2, 3, 4, 5, \dots\}$ . Is your guessing rule still good?
3. While keeping  $\{1, 2, 3, 4, 5, \dots\}$  in, assume that I'll guarantee they are ordered increasingly. Can you win the game?
4. Now, remove  $\{1, 2, 3, 4, 5, \dots\}$ . You get only one guess—would you object to this winning condition?

## 1960s: THE BEGINNINGS

-  Hillary Putnam (1965). Trial and error predicates and the solution to...
-  E. Mark Gold (1967). Language identification in the limit.
-  Ray Solomonoff (1964). A formal theory of inductive inference.

# TRIAL AND ERROR PREDICATES

A predicate (set)  $P$  is decidable if there is a effective procedure  $\varphi$  such that

$$\begin{aligned} P(x) &\text{ iff } \varphi(x) = 1; \\ \neg P(x) &\text{ iff } \varphi(x) = 0. \end{aligned}$$

What happens if we modify the condition by:

1. allowing  $\varphi$  to change her mind any finite number of times;
2. making it impossible to diagnose termination?

$P$  is a trial and error predicate if there is a Turing Machine  $\varphi$  such that

$$\begin{aligned} P(x) &\text{ iff } \exists k \forall n \geq k \varphi(x, n) = 1; \\ \neg P(x) &\text{ iff } \exists k \forall n \geq k \varphi(x, n) = 0. \end{aligned}$$

Trial and error predicates are decidable in the limit.

# TRIAL AND ERROR PREDICATES

A predicate (set)  $P$  is decidable if there is a recursive function  $\varphi$  such that

$$\begin{aligned} P(x) &\text{ iff } \varphi(x) = 1; \\ \neg P(x) &\text{ iff } \varphi(x) = 0. \end{aligned}$$

What happens if we modify the condition by:

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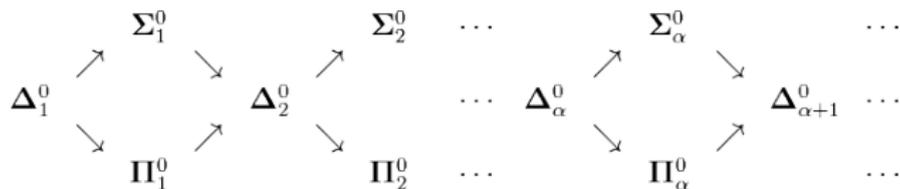
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Trial and error predicates are decidable in the limit.

# KLEENE-MOSTOWSKI ARITHMETICAL HIERARCHY

In this context one can think of  $\varphi$  as of a learning function,  
Especially if more than two answers are possible.

The quantifier prefix in the definition of trial and error predicates  
indicates their place in arithmetic hierarchy.



We will focus on a more general case,  
when learner has to pick from more than two options,  
in fact, from countably many options.

## SOME BASIC DEFINITIONS

Let  $\mathbb{N}$  stand for positive integers and  $S \subseteq \mathbb{N}$ .

Let  $\mathcal{S} = (S_i)_{i \in \mathbb{N}}$  be a family of sets.

### DEFINITION

By a stream  $t$  for  $S$  we mean an infinite sequence of elements from  $S$  enumerating all and only the elements from  $S$  (allowing repetitions).

### DEFINITION

We will use the following notation:

- ▶  $t_n$  is the  $n$ -th element of  $t$ ;
- ▶  $t[n]$  is the sequence  $(t_0, t_1, \dots, t_{n-1})$ ;
- ▶  $\text{content}(t)$  is the set of elements that occur in  $t$ ;
- ▶  $\varphi : \mathbb{N}^* \rightarrow \mathbb{N}$  is a learning function.

# IDENTIFIABILITY IN THE LIMIT

## DEFINITION

Learning function  $\varphi$ :

1. identifies  $S_i \in \mathcal{S}$  in the limit on  $t$  iff for co-finitely many  $m$ ,  $\varphi(t[m]) = i$ ;
2. identifies  $S_i \in \mathcal{S}$  in the limit iff it identifies  $S_i$  in the limit on every  $t$  for  $S_i$ ;
3. identifies  $\mathcal{S}$  in the limit iff it identifies in the limit every  $S_i \in \mathcal{S}$ .

$\mathcal{S}$  is identifiable in the limit iff some learning function identifies  $\mathcal{S}$  in the limit.

## SOME EXAMPLES

### EXAMPLE

Let  $\mathcal{S}_1 = \{S_i \mid i \in \mathbb{N} - \{0\}\}$ , where  $S_n = \{1, \dots, n\}$ .

$\mathcal{S}_1$  is identifiable in the limit by the following function  $\varphi : \mathbb{N}^* \rightarrow \mathbb{N}$ :

$$\varphi(t[n]) = \max(\text{content}(t[n])).$$

## SOME EXAMPLES

### EXAMPLE

Let  $\mathcal{S}_2 = \{S_i \mid i \in \mathbb{N}\}$ , where  $S_0 = \mathbb{N}$  and for  $n \geq 1$ ,  $S_n = \{1, \dots, n\}$ .

$\mathcal{S}_2$  is not identifiable in the limit.

### Argument

To show that this is the case, let us assume that there is a function  $\varphi$  that identifies  $\mathcal{S}_2$ . We will construct a text,  $t$  on which  $\varphi$  fails:

$t$  starts by enumerating  $\mathbb{N}$  in order:  $0, 1, 2, \dots$

if at a number  $k$  learner  $\varphi$  decides it is  $S_0$ ,  $t$  starts repeating  $k$  indefinitely.

This means  $t$  is a text for  $S_k$ .

As soon as  $\varphi$  decides it is  $S_k$  we continue with  $k + 1, k + 2, \dots$ , so  $t$  will become a text for  $S_0$ , etc.

This shows that there is a text for a set from  $\mathcal{S}_2$  on which  $\varphi$  fails.

## SOME EXAMPLES

### EXAMPLE

Let  $\mathcal{S}_4 = \{S_n \mid S_n = \mathbb{N} - \{n\}, n \in \mathbb{N}\}$ .

$\mathcal{S}_4$  is identifiable in the limit by the learning function  $\varphi : \mathbb{N}^* \rightarrow \mathbb{N}$ :

$$\varphi(t[n]) = \min(\mathbb{N} - \text{content}(t[n])).$$

# GOLD'S THEOREMS

## THEOREM (1)

*The class of all finite languages is identifiable.*

## THEOREM (2)

*The class containing all finite and at least one infinite language is not identifiable.*

# COGNITIVE CONTROVERSY

Gold's 2nd theorem



levels of Chomsky Hierarchy (except FIN) are not identifiable

## **Controversy**

either Chomsky Hierarchy or Gold's Learning must be off. Or both.

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**KABOOM**

## LIMITTING KNOWLEDGE

*True, there are good reasons for preferring the computable way of deriving knowledge. We know the results of computations and only think we know the results of trial and error procedures. There are many reasons for preferring knowing to thinking (as Popper, 1966, observed). But that does not change the fact that sometimes thinking may be more appropriate.*

# OUTLINE

A MOTIVATING EXAMPLE

VARIOUS INFERENCE PARADIGMS

LEARNING SETS

- Learning Sets and Some Logic
- Gold Theorems
- Limits and Knowledge

INTRODUCTION TO EPISTEMIC MODAL LOGIC

- Modeling Uncertainty
- Epistemic Logic
- Public Announcement Logic

# KNOWLEDGE AND POSSIBLE WORLDS

- ▶ Besides of the current state of affairs,
- ▶ there is a number of other **possible states of affairs** or “worlds”.

An agent knows a fact  $\varphi$  if  $\varphi$  is true at all the worlds she **considers possible**.

# SAN FRANCISCO EXAMPLE

Agent *a* is walking on the streets in San Francisco on a sunny day. She has no information at all about the weather in London.

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If the agent acquires additional information from a reliable source:

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# EPISTEMIC LOGIC: BRIEF HISTORY

**Epistemic logic** has been introduced as a modal logic in **1962** by **Jaakko Hintikka**, a Finnish philosopher and logician.

In his logic both knowledge and belief are introduced as two separate concepts. His logic had two modal operators  $K$  and  $B$  (for knowledge and belief) to represent the two attitudes separately.



# LANGUAGE OF EPISTEMIC LOGIC

## DEFINITION (LANGUAGE OF EPISTEMIC LOGIC)

$\Phi$  is a set of propositions, with  $p \in \Phi$ , and  $\mathcal{A} = \{1, \dots, n\}$  is a set of agents.

$$\varphi := \top \mid p \mid \neg\varphi \mid \varphi \wedge \varphi \mid K_i\varphi$$

where  $\top$  abbreviates a tautology and  $i \in \mathcal{A}$  is the name of some agent.

In case we are only dealing with one agent, we can also omit the index.

# SYNTAX: LANGUAGE OF EPISTEMIC LOGIC

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How can we express "I don't know whether  $\varphi$ "?

$$\neg(K\varphi \vee K\neg\varphi)$$

or, equivalently:

$$\neg K\varphi \wedge \neg K\neg\varphi.$$

# SEMANTICS: MODELS OF EPISTEMIC LOGIC

DEFINITION (POSSIBLE WORLD MODEL OR EPISTEMIC MODEL)

A **possible world model**  $M$  for  $n$  agents over  $\Phi$  is  $(S, \pi, \mathcal{K}_1, \dots, \mathcal{K}_n)$ , where:

1. a non-empty set states (or worlds)  $S$ ;
2. an interpretation  $\pi$  which associates with every state a truth assignment to the propositions, i.e.:  
for each state  $s \in S$ ,  $\pi(s) : Prop \rightarrow \{0, 1\}$ ;
3. for each agent  $i$ ,  $\mathcal{K}_i$  is a binary relation on  $S$ .

A **pointed possible world model** is a pair  $(M, s)$ , where  $M = (S, \pi, \mathcal{K}_1, \dots, \mathcal{K}_n)$  and  $s \in S$ .

## ADDITIONAL EXPLANATIONS

1.  $\pi(s)$  tells us whether a proposition is true or false in state  $s$ .
2.  $\mathcal{K}_i$  captures the possibility relation according to agent  $i$ , i.e.,  
 $(s, t) \in \mathcal{K}_i$  if agent  $i$  considers world  $t$  possible, given her information in world  $s$ .

$\mathcal{K}_i$  is a possibility (or accessibility) relation; it says what worlds agent  $i$  considers possible (or can access) in any given world.

# EQUIVALENCE POSSIBILITY RELATION

$\mathcal{K}_i$  is an **equivalence** relation on  $S$ , i.e., it is a binary relation that is:

1. reflexive: for all  $s \in S$ , we have  $(s, s) \in \mathcal{K}_i$ ,
2. symmetric: for all  $s, t \in S$ , we have  $(s, t) \in \mathcal{K}_i$  iff  $(t, s) \in \mathcal{K}_i$ ,
3. transitive: for all  $s, t, u \in S$ , we have that if  $(s, t) \in \mathcal{K}_i$  and  $(t, u) \in \mathcal{K}_i$ , then  $(s, u) \in \mathcal{K}_i$ .

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Unless specified otherwise, we will assume the relation to be equivalence.

# WHEN IS A FORMULA TRUE IN A SITUATION?

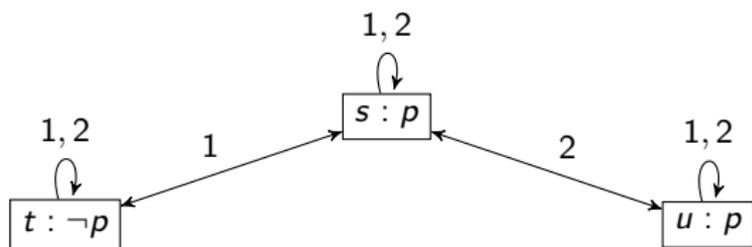
We write  $(M, s) \models \varphi$  to say that  $\varphi$  is true at  $s$  in  $M$ , and  $(M, s) \not\models \varphi$  to express that  $\varphi$  is false at  $s$  in  $M$ .

## DEFINITION

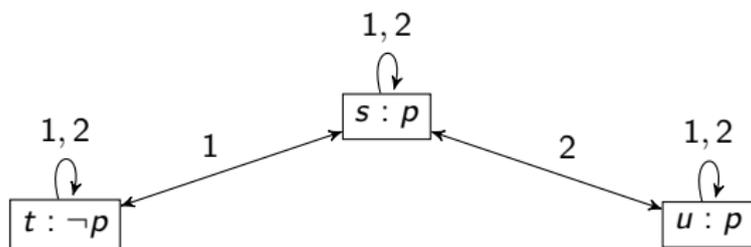
$(M, s) \models p$	iff	$\pi(s)(p) = 1$
$(M, s) \models \neg\varphi$	iff	$(M, s) \not\models \varphi$
$(M, s) \models \varphi \wedge \psi$	iff	$(M, s) \models \varphi$ and $(M, s) \models \psi$
$(M, s) \models K_i\varphi$	iff	<b>for all <math>v</math> with <math>(s, v) \in \mathcal{K}_i</math>, <math>(M, v) \models \varphi</math></b>

So,  $K_i\varphi$  is false at state  $s$  exactly when there is some  $v$  with  $(s, v) \in \mathcal{K}_i$  such that  $\varphi$  is false at  $v$ .

# EXAMPLE 1: IS IT SUNNY IN SAN FRANCISCO?

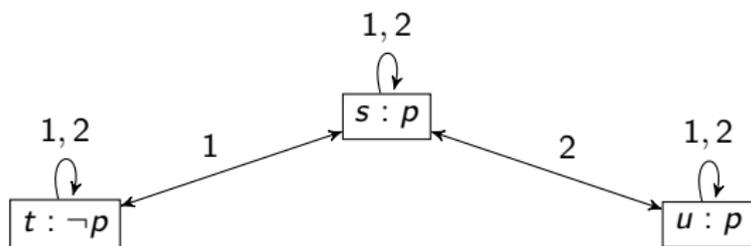


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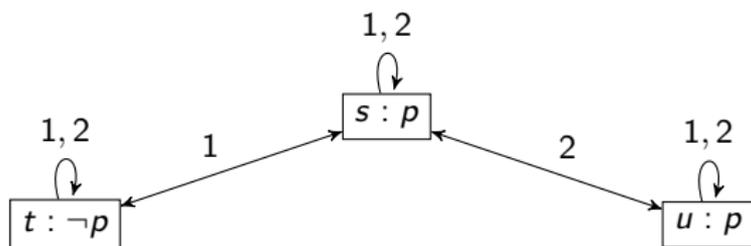
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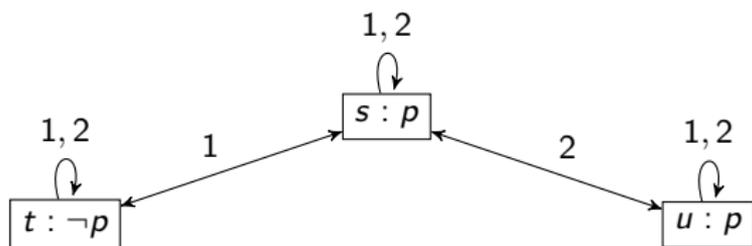


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$$(M, s) \models p$$

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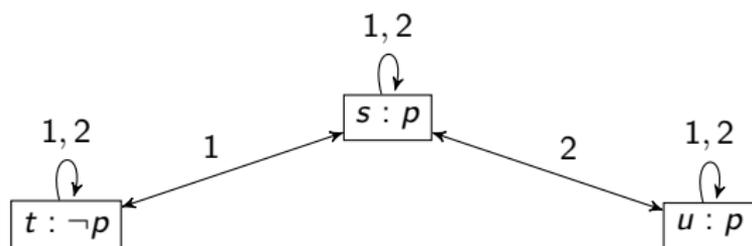
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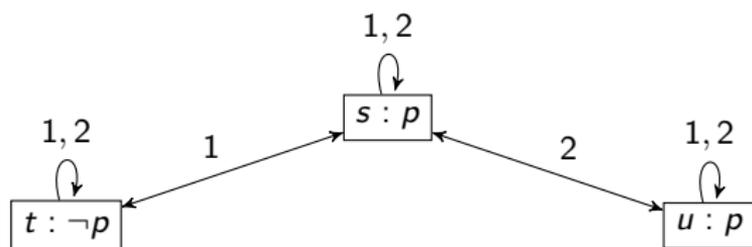
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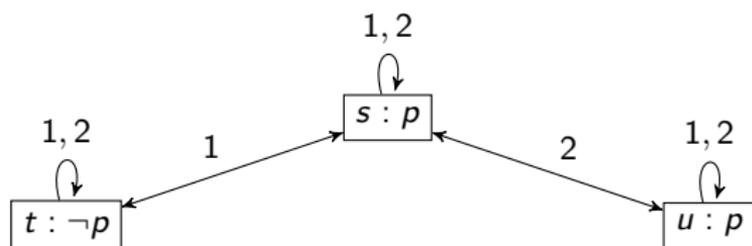
$$(M, s) \models K_2 p$$

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$$(M, s) \models K_1(K_2 p \vee K_2 \neg p)$$

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$$(M, u) \models K_1 p$$

$$(M, s) \models \neg K_2 \neg K_1 p$$

# MUDDY CHILDREN REVISITED

Imagine  $n$  children are playing outside together. Now it happens that during their play some of them, say  $k$  get mud on their foreheads. Each can see mud on others but not on his own forehead.

Along comes the father, who says, "At least one of you have mud on your forehead". The father then asks the following question, over and over: "Does any of you know whether you have mud on your own forehead?"

Assuming that all the children are perceptive, intelligent, truthful, and they answer simultaneously, what will happen?

Surprisingly, after the father asks the question for the  $k^{\text{th}}$  time all muddy children will say "yes". How come?



# MUDDY CHILDREN: THE UNDERLYING ASSUMPTIONS

- ▶ **Common knowledge** that the father is truthful,
- ▶ that all the children hear the father,
- ▶ that all the children see each other,
- ▶ that none of them can see their own forehead,
- ▶ and that all the children are truthful and intelligent.

# A MUDDY CHILDREN MODEL

$(w_1 : m_a, m_b, m_c)$

$(w_3 : m_a, m_b, \neg m_c)$

$(w_2 : m_a, \neg m_b, m_c)$

$(w_4 : \neg m_a, m_b, m_c)$

$(w_5 : m_a, \neg m_b, \neg m_c)$

$(w_7 : \neg m_a, m_b, \neg m_c)$

$(w_6 : \neg m_a, \neg m_b, m_c)$

$(w_8 : \neg m_a, \neg m_b, \neg m_c)$

FIGURE: Initial epistemic model of the Muddy Children puzzle

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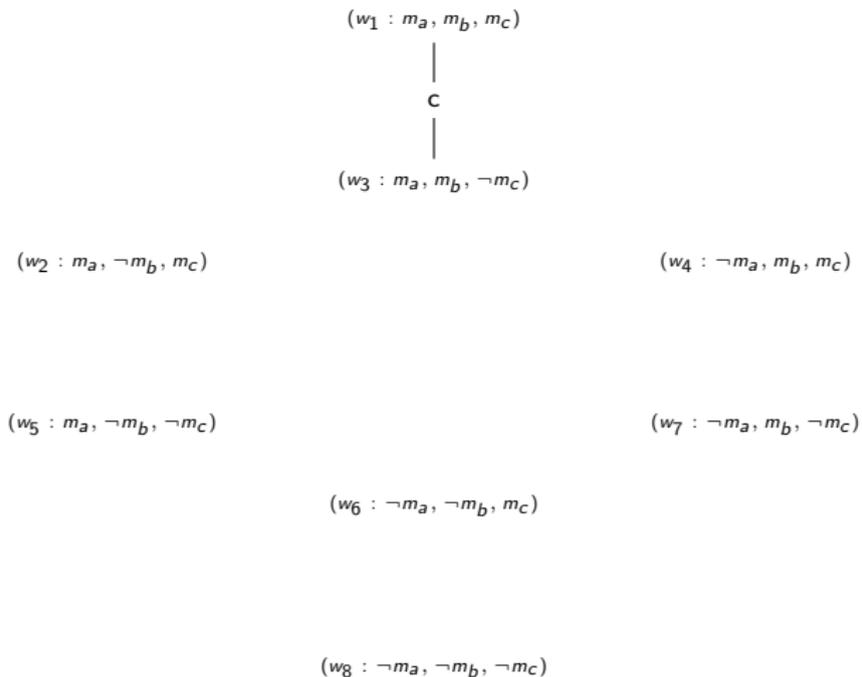


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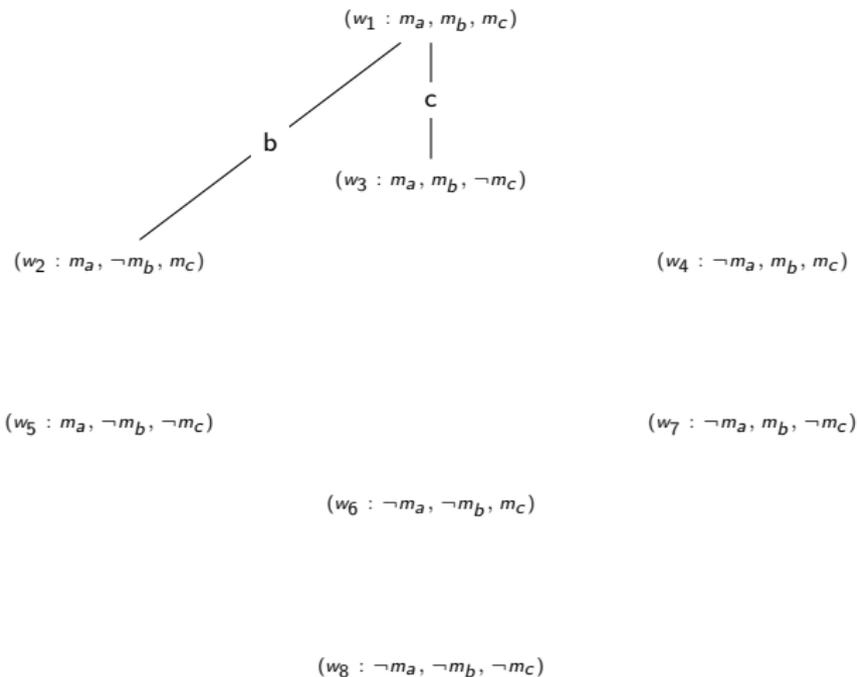


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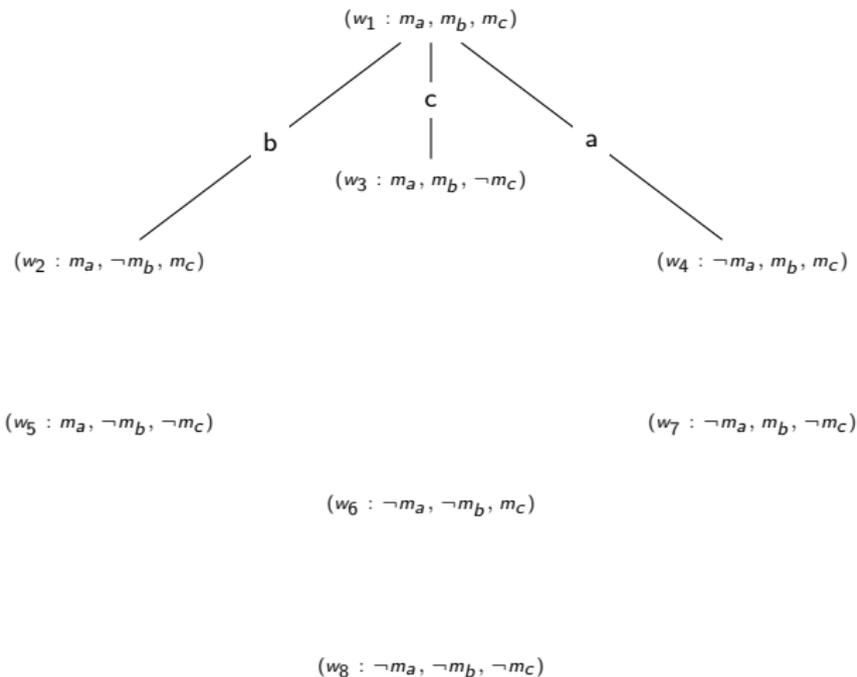


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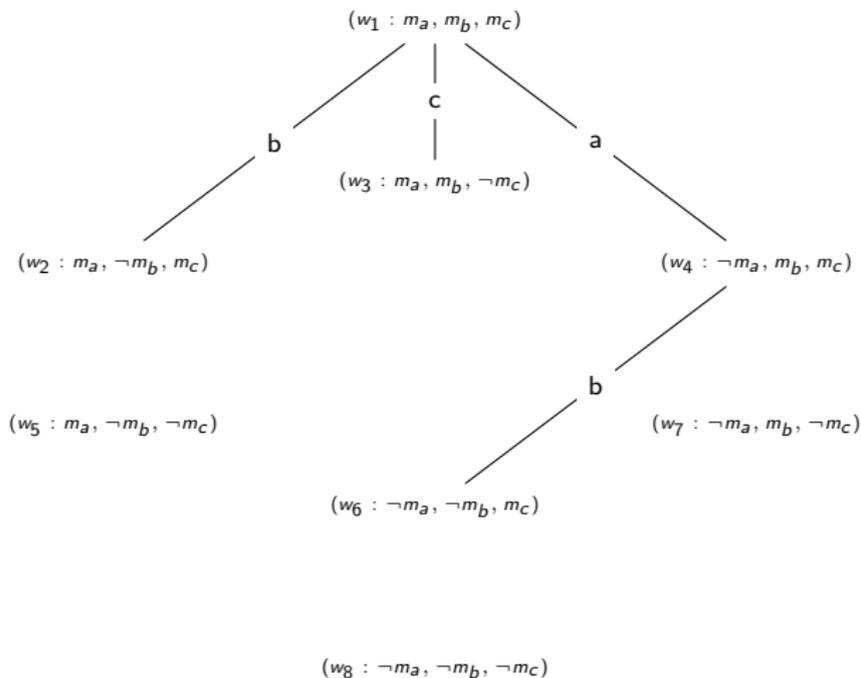


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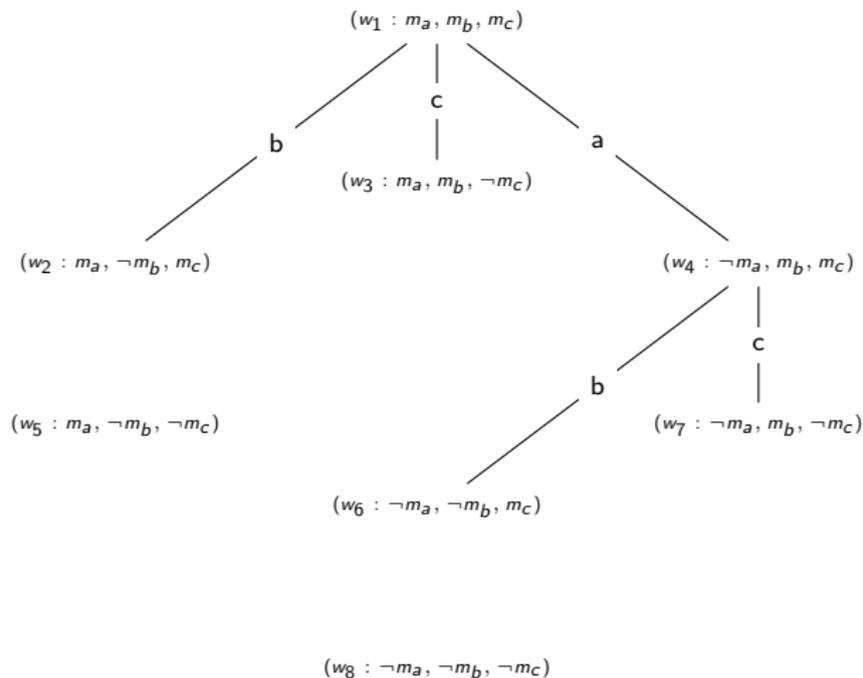


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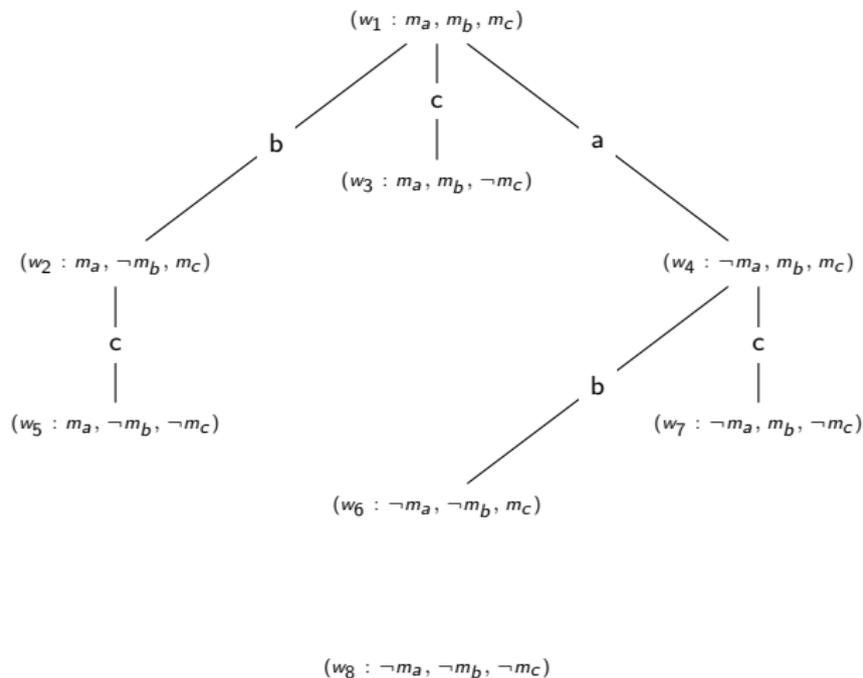


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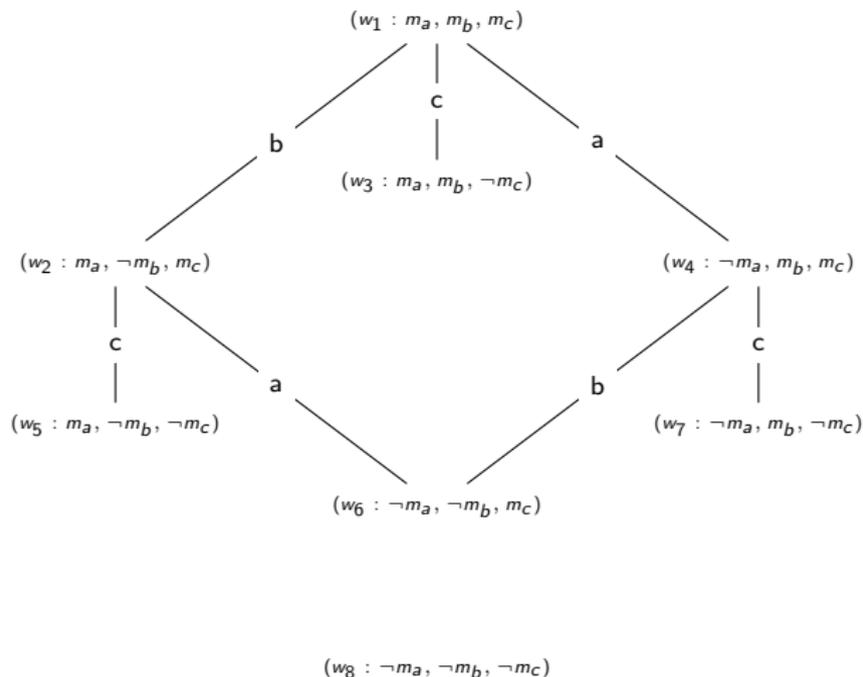


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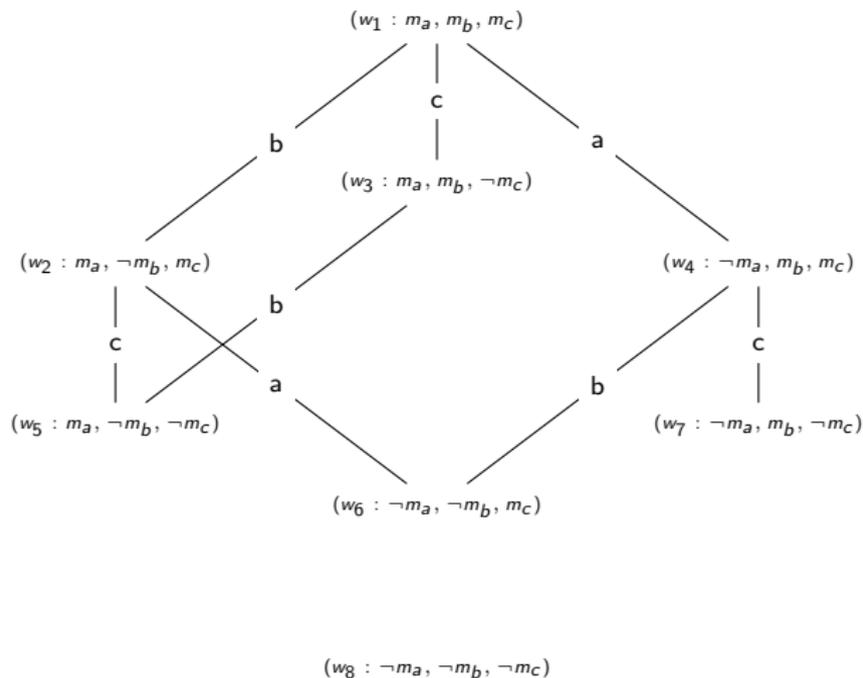


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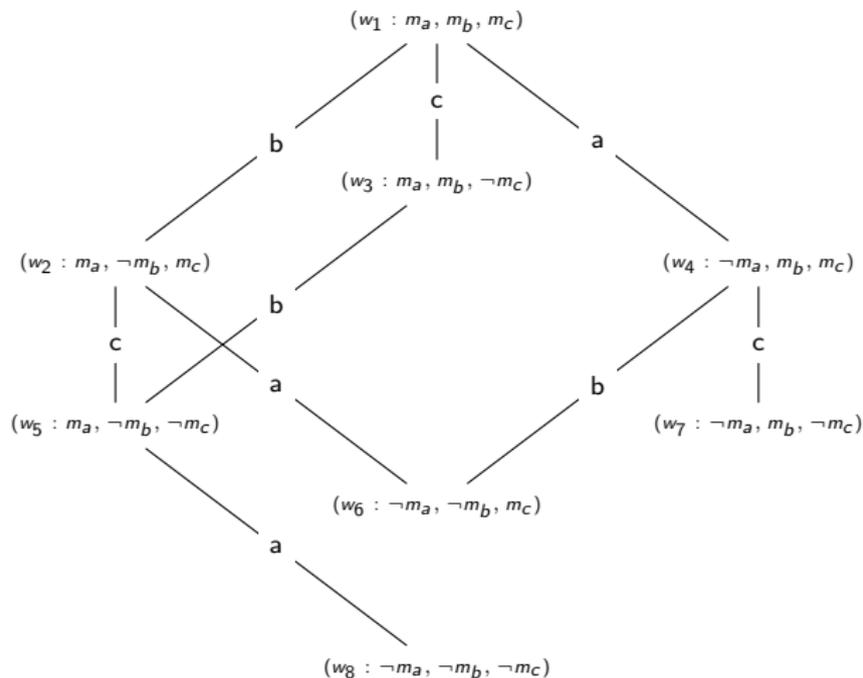


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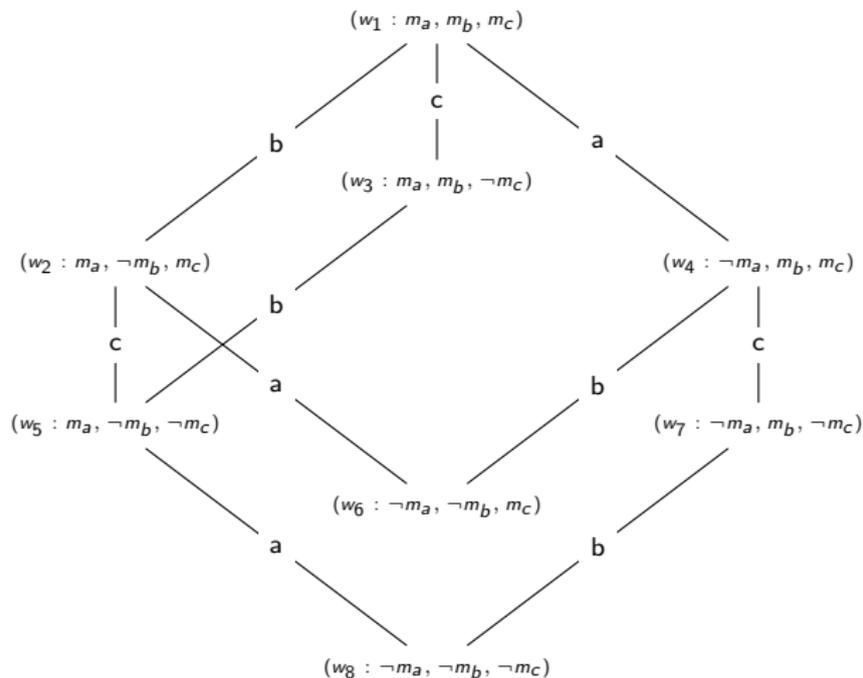


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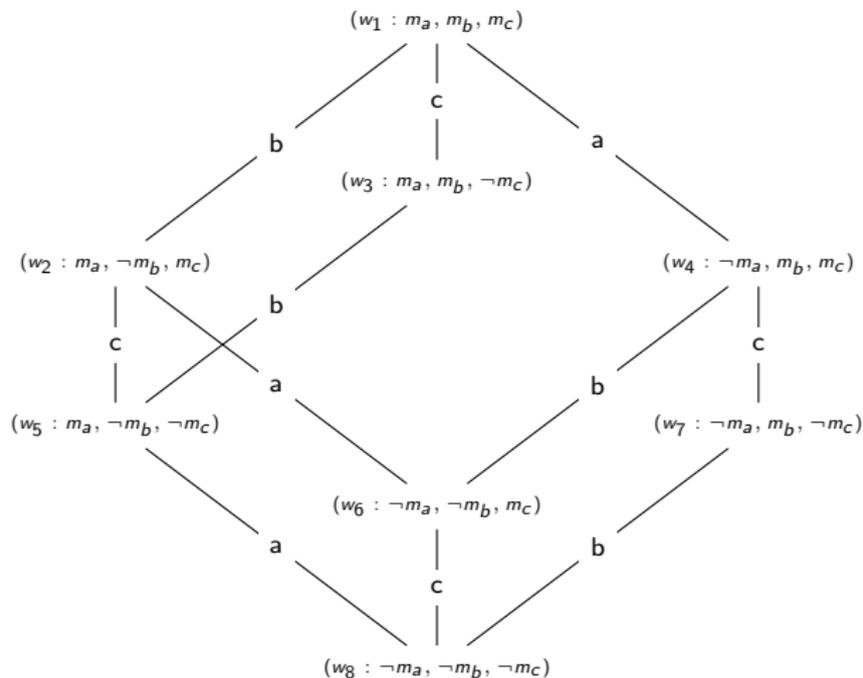


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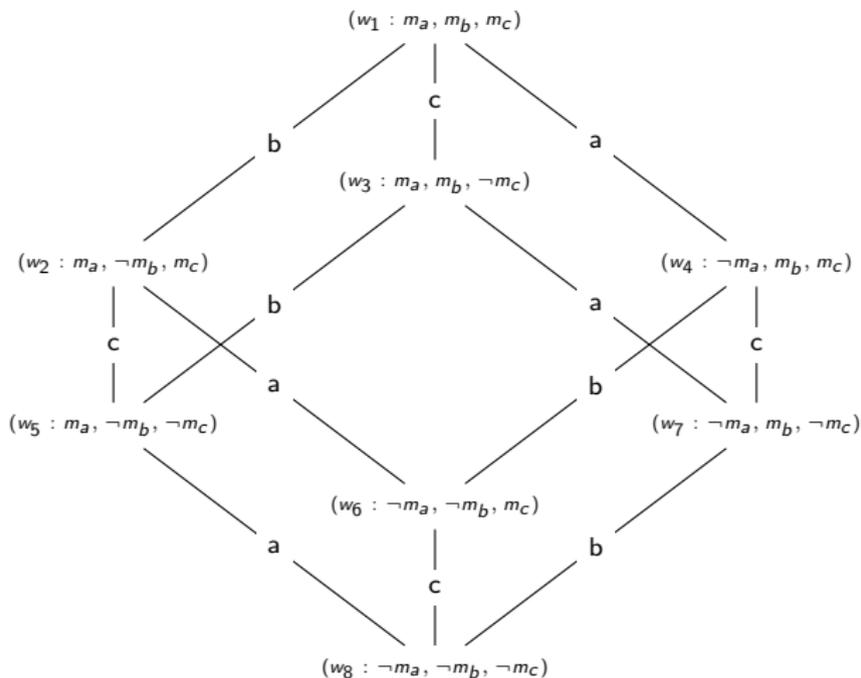
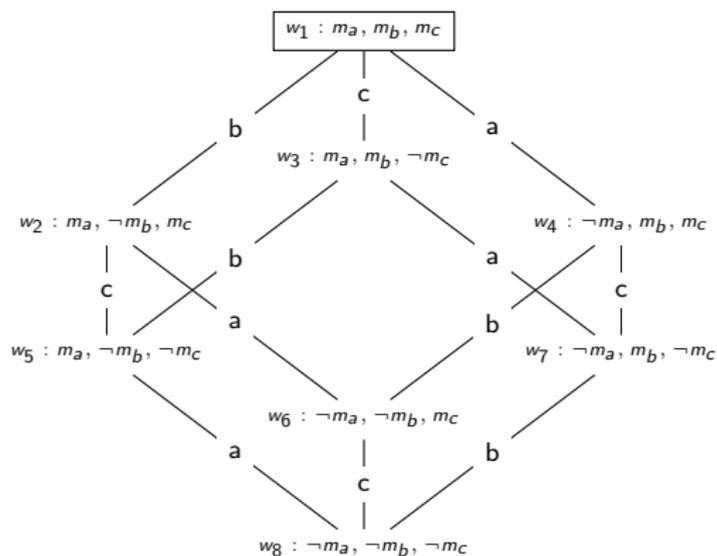


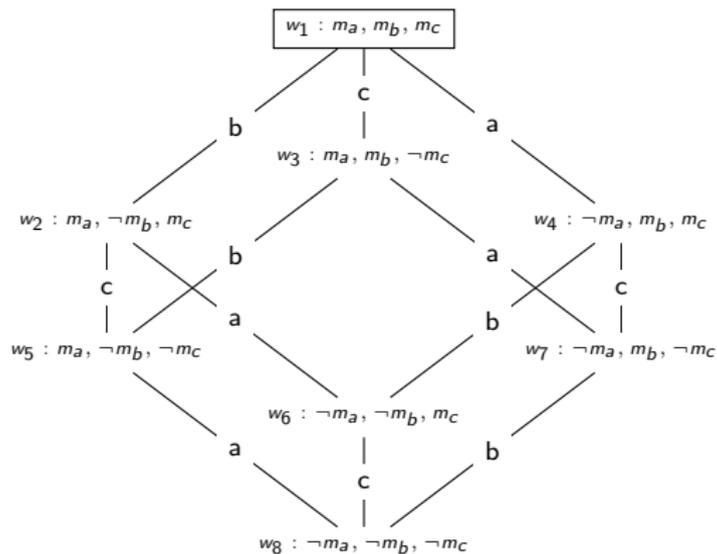
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# MUDDY CHILDREN SCENARIO MODELLED IN EPISTEMIC LOGIC



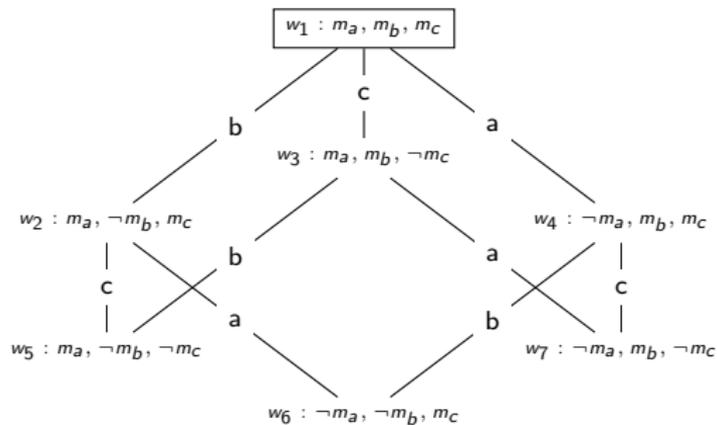
Before the announcement.

# MUDDY CHILDREN SCENARIO MODELLED IN EPISTEMIC LOGIC



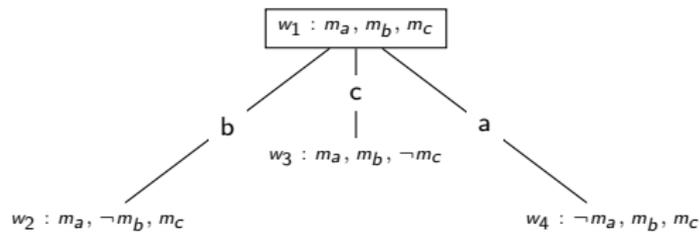
Father says:  
" $m_a \vee m_b \vee m_c$ "

# MUDDY CHILDREN SCENARIO MODELLED IN EPISTEMIC LOGIC



- Does any of you know?  
- No!

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$w_1 : m_a, m_b, m_c$

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What are the properties of  $K$ ?

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We will try to answer this question  
**by looking at formulas about knowledge that are always true.**

# FORMULAS AND TRUTH

## DEFINITION

Given a model  $M = (S, \pi, \mathcal{K}_1, \dots, \mathcal{K}_n)$ , we say that:

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**A formula  $\varphi$  is valid (in  $M$ ) if  $\neg\varphi$  is not satisfiable (in  $M$ ).**

# DISTRIBUTION AXIOM

Each agent knows all the logical consequences of her knowledge.

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$$\models (K_i\varphi \wedge K_i(\varphi \rightarrow \psi)) \rightarrow K_i\psi$$

This axiom allows us to **distribute** the  $K_i$  operator over implication.

# KNOWLEDGE GENERALIZATION RULE

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Note, that the above is not the same as:  $\varphi \rightarrow K_i\varphi$

# KNOWLEDGE AXIOM (TRUTH AXIOM)

Agents can only know facts.

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This property distinguishes knowledge from **belief**.

It holds because the agents always consider the actual world possible.

# AXIOMS OF POSITIVE AND NEGATIVE INTROSPECTION

Agents know what they know and what they do not know.

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Agents know what they know and what they do not know.

$$\models K_i\varphi \rightarrow K_iK_i\varphi$$

$$\models \neg K_i\varphi \rightarrow K_i\neg K_i\varphi$$

# THE S5 SYSTEM

1.  $\models (K_i\varphi \wedge K_i(\varphi \rightarrow \psi)) \rightarrow K_i\psi$
2. if  $M \models \varphi$  then  $M \models K_i\varphi$
3.  $\models K_i\varphi \rightarrow \varphi$
4.  $\models K_i\varphi \rightarrow K_iK_i\varphi$
5.  $\models \neg K_i\varphi \rightarrow K_i\neg K_i\varphi$

# THE S5 SYSTEM

## THEOREM

*For all formulas  $\varphi$  and  $\psi$ , all models  $M$ , where each possibility relation  $\mathcal{K}_i$  is an equivalence, and all agents  $i = 1, \dots, n$ , we have:*

1.  $M \models (K_i\varphi \wedge K_i(\varphi \rightarrow \psi)) \rightarrow K_i\psi$ ,
2. if  $M \models \varphi$  then  $M \models K_i\varphi$ ,
3.  $M \models K_i\varphi \rightarrow \varphi$ ,
4.  $M \models K_i\varphi \rightarrow K_iK_i\varphi$ ,
5.  $M \models \neg K_i\varphi \rightarrow K_i\neg K_i\varphi$ .

# THE S5 SYSTEM AND EQUIVALENCE ACCESSIBILITY RELATION

1.  $\models (K_i\varphi \wedge K_i(\varphi \rightarrow \psi)) \rightarrow K_i\psi$
2. if  $M \models \varphi$  then  $M \models K_i\varphi$
3.  $\models K_i\varphi \rightarrow \varphi$  **Reflexivity**
4.  $\models K_i\varphi \rightarrow K_iK_i\varphi$  **Transitivity**
5.  $\models \neg K_i\varphi \rightarrow K_i\neg K_i\varphi$  **Symmetry and Transitivity**

# AXIOMATIC CHARACTERISATIONS OF KNOWLEDGE

properties of knowledge in terms of **some** valid formulas

are there additional properties that are not consequences of those?

Is it possible to give a complete characterisation of the properties of knowledge?

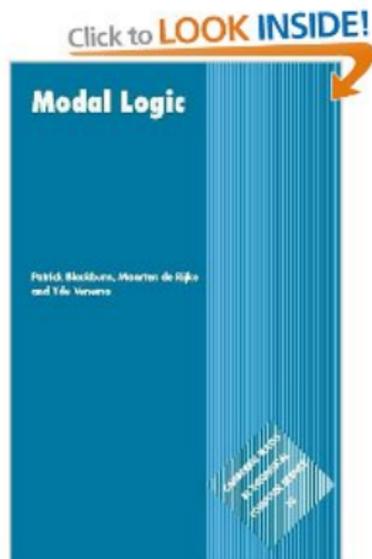
## OUTLOOK: COMPLETENESS RESULTS

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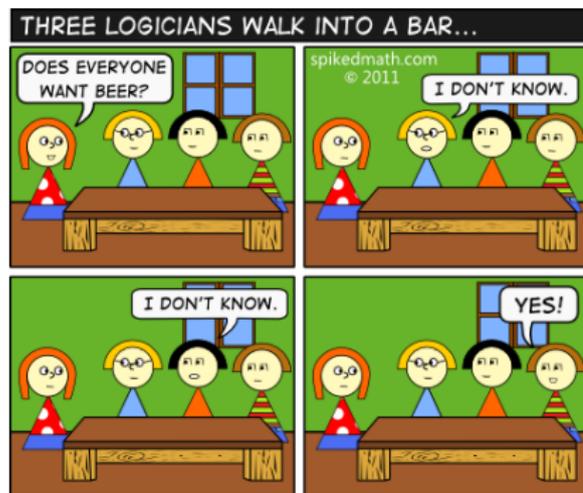
<b>K</b>	the class of all frames
<b>K4</b>	the class of transitive frames
<b>T</b>	the class of reflexive frames
<b>B</b>	the class of symmetric frames
<b>KD</b>	the class of right-unbounded frames
<b>S4</b>	the class of reflexive, transitive frames
<b>S5</b>	the class of frames whose relation is an equivalence relation
<b>K4.3</b>	the class of transitive frames with no branching to the right
<b>S4.3</b>	the class of reflexive, transitive frames with no branching to the right
<b>KL</b>	the class of finite transitive trees ( <i>weak</i> completeness only)

---

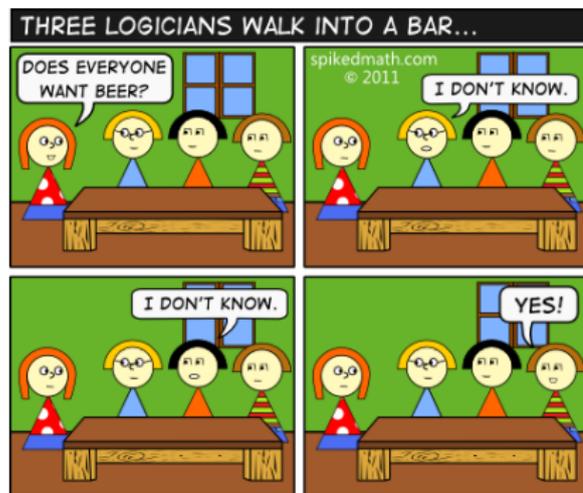
TO KNOW MORE...



# THREE LOGICIANS WALK INTO A BAR...

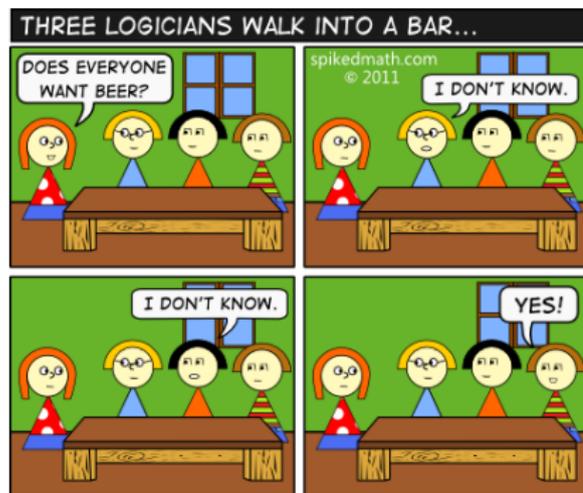


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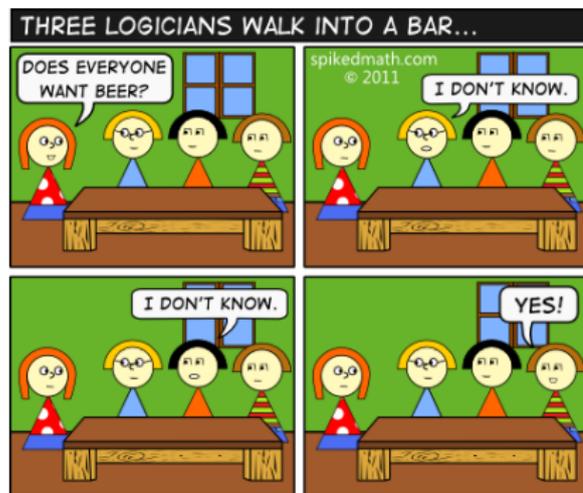
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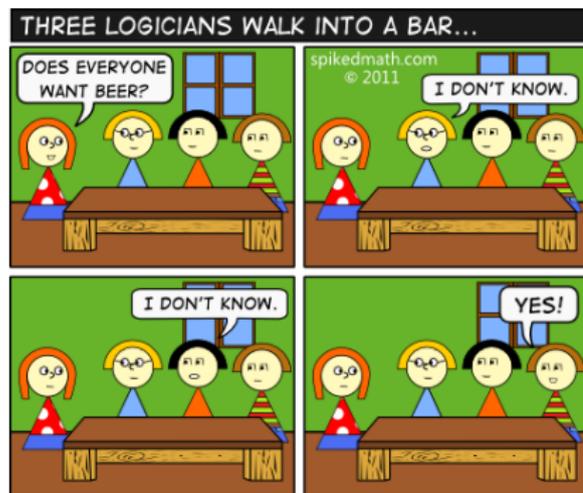
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- ▶ If  $K_i(b_1 \wedge b_2 \wedge b_3)$ ,  
then  $i$  says "Yes".
- ▶ If  $K_i\neg(b_1 \wedge b_2 \wedge b_3)$ ,  
then  $i$  says "No".





## THREE LOGICIANS: UPDATES

- ▶  $i$  says “Yes”: public announcement of  $K_i(b_1 \wedge b_2 \wedge b_3)$ .
- ▶  $i$  says “No”: public announcement of  $K_i\neg(b_1 \wedge b_2 \wedge b_3)$ .
- ▶  $i$  says “I don't know”: public announcement of  $\neg K_i(b_1 \wedge b_2 \wedge b_3) \wedge \neg K_i\neg(b_1 \wedge b_2 \wedge b_3)$ .

# THREE LOGICIANS: POSSIBLE-WORLD MODEL

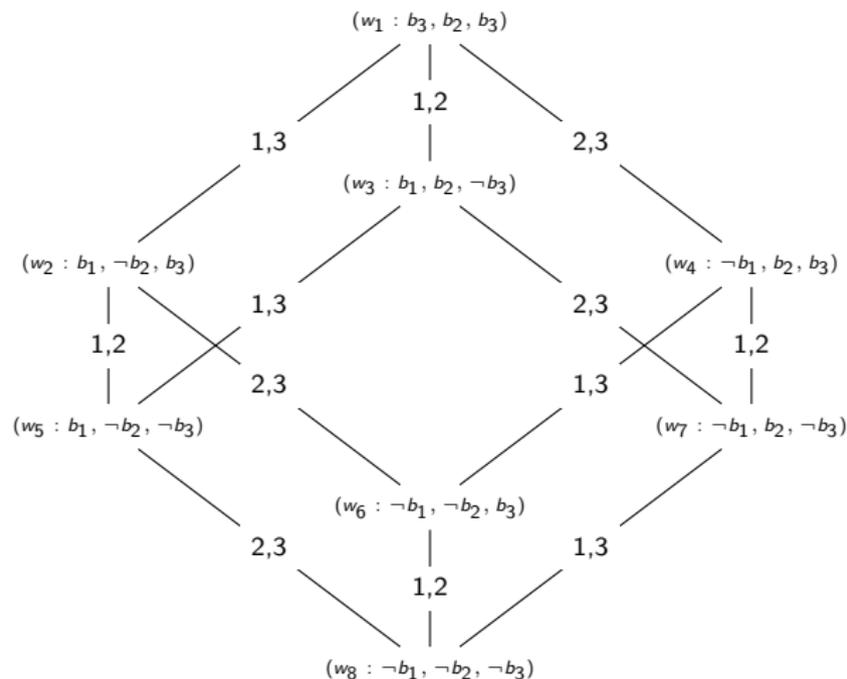


FIGURE: Initial epistemic model of the Three Logicians puzzle

# THREE LOGICIANS: POSSIBLE-WORLD MODEL

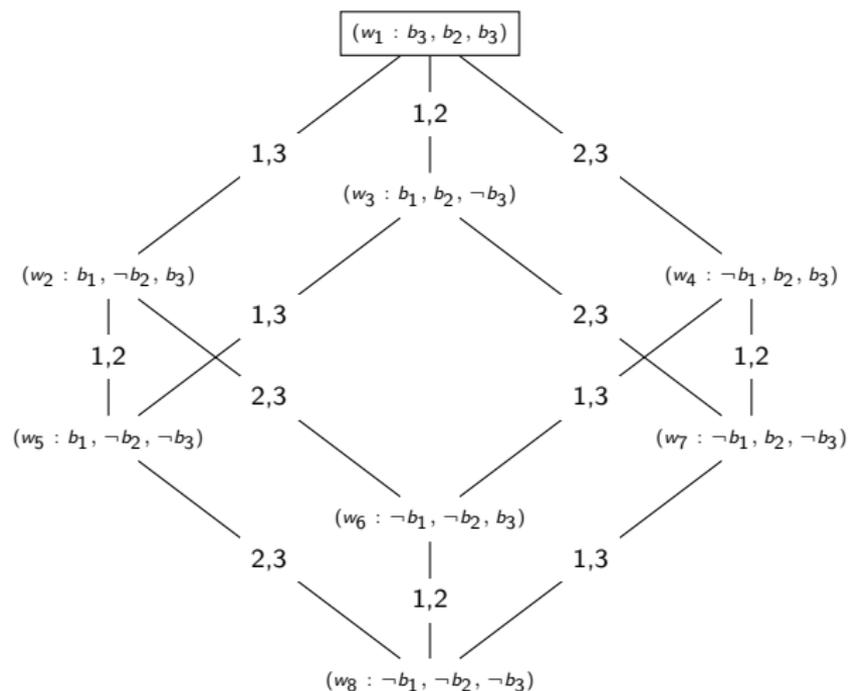


FIGURE: Public Announcement:  $\neg K_1(b_1 \wedge b_2 \wedge b_3) \wedge \neg K_1 \neg(b_1 \wedge b_2 \wedge b_3)$

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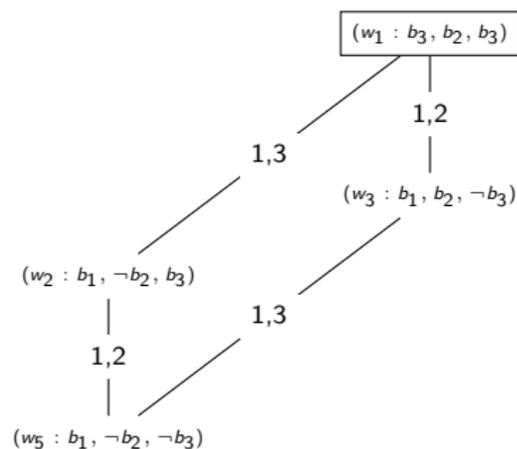


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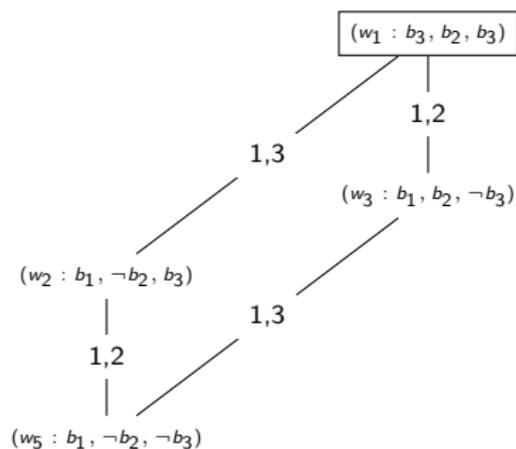


FIGURE: Public Announcement:  $\neg K_2(b_1 \wedge b_2 \wedge b_3) \wedge \neg K_2 \neg(b_1 \wedge b_2 \wedge b_3)$

# THREE LOGICIANS: POSSIBLE-WORLD MODEL

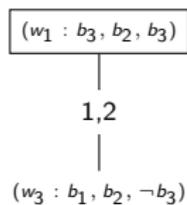


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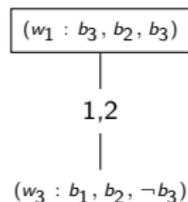


FIGURE: Public Announcement:  $K_3(b_1 \wedge b_2 \wedge b_3)$ , and the waitress knows!

# THREE LOGICIANS: POSSIBLE-WORLD MODEL

$(w_1 : b_3, b_2, b_3)$

FIGURE: Public Announcement:  $K_3(b_1 \wedge b_2 \wedge b_3)$ , and the waitress knows!

# LOGICS OF PUBLIC ANNOUNCEMENTS

- ▶ PAL (Public Announcement Logic) was first proposed by Jan Plaza in 1989

Dynamic Epistemic Logics formalize informational changes:  
the dynamics of knowledge/belief.

# DYNAMIC MODALITIES

To express informational changes, dynamic epistemic logics use a new kind of propositional operators, called **dynamic modalities**:

$$[\alpha]\varphi,$$

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Note:  $[\alpha]\varphi$  is by definition true in the worlds in which  $\alpha$  can't be performed.

# LANGUAGE OF PUBLIC ANNOUNCEMENT LOGIC

## DEFINITION (SYNTAX)

$\Phi$  is a set of propositions, with  $p \in \Phi$ , and  $\mathcal{A} = \{1, \dots, n\}$  is a set of agents, and  $G \subseteq \mathcal{A}$ .

$$\varphi := \top \mid p \mid \neg\varphi \mid \varphi \wedge \varphi \mid K_i\varphi \mid [!\varphi]\varphi$$

where  $\top$  abbreviates a tautology and  $i \in \mathcal{A}$  is the name of some agent.

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As before, these formulas are interpreted in possible world models.

# PUBLIC ANNOUNCEMENT AS JOINT UPDATE

How can we model the effect of a public announcement?

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LEARNING = ELIMINATING POSSIBILITIES

From now on, we denote by  $!\varphi$  the operation of deleting the non- $\varphi$  worlds, and call it **public announcement with  $\varphi$** , or **joint update with  $\varphi$** .

# SEMANTICS OF PUBLIC ANNOUNCEMENT LOGIC

## DEFINITION

Let  $M = (S, \pi, \mathcal{K}_1, \dots, \mathcal{K}_n)$  and let  $\|\varphi\|_M$  stand for the set of worlds in  $M$  that makes  $\|\varphi\|$  true.

$(M, s) \models p$	iff	$\pi(s)(p) = 1$
$(M, s) \models \neg\varphi$	iff	$(M, s) \not\models \varphi$
$(M, s) \models \varphi \wedge \psi$	iff	$(M, s) \models \varphi$ and $(M, s) \models \psi$
$(M, s) \models \varphi \vee \psi$	iff	$(M, s) \models \varphi$ or $(M, s) \models \psi$
$(M, s) \models \mathcal{K}_i\varphi$	iff	for all $v$ with $(s, v) \in \mathcal{K}_i$ , $(M, v) \models \varphi$
$(M, s) \models [!\varphi]\psi$	iff	if $(M, s) \models \varphi$ then $(M \varphi, s) \models \psi$

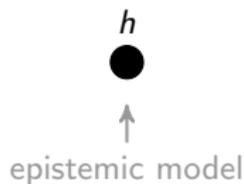
where  $M|\varphi = (S', \pi', \mathcal{K}'_1, \dots, \mathcal{K}'_n)$  is defined as follows:

- ▶  $S' := \|\varphi\|_M$
- ▶  $\pi' := \pi \cap \|\varphi\|_M$
- ▶ for each  $i \in \{1, \dots, n\}$ ,  $\mathcal{K}'_i := \mathcal{K}_i \cap (\|\varphi\|_M \times \|\varphi\|_M)$

# DEL BY EXAMPLE: A HIDDEN COIN TOSS

We use the **action models** of DEL with postconditions (ontic actions).

$h :=$  “the coin faces heads up”



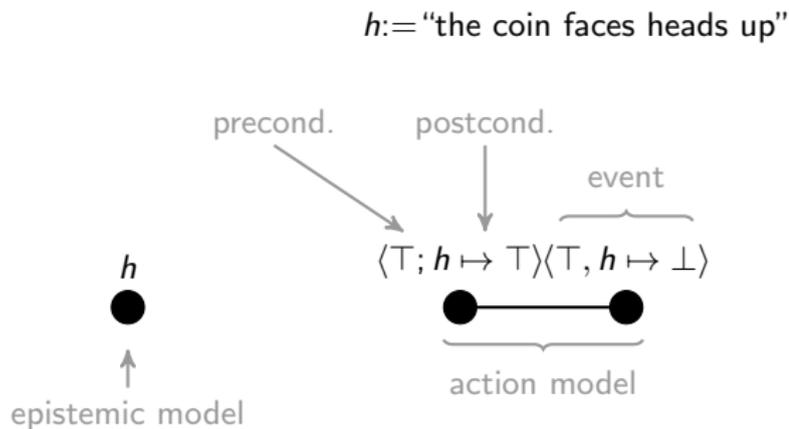
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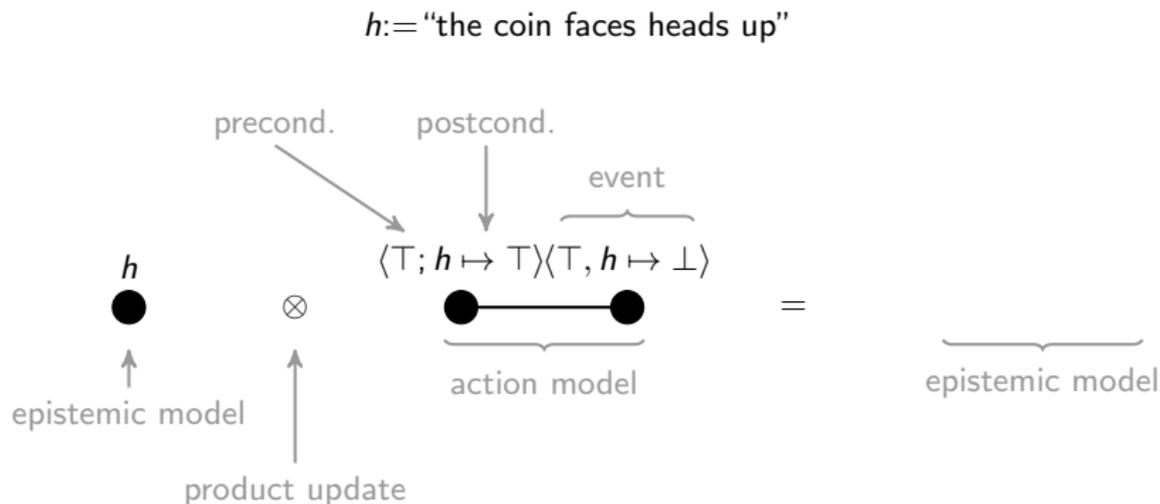
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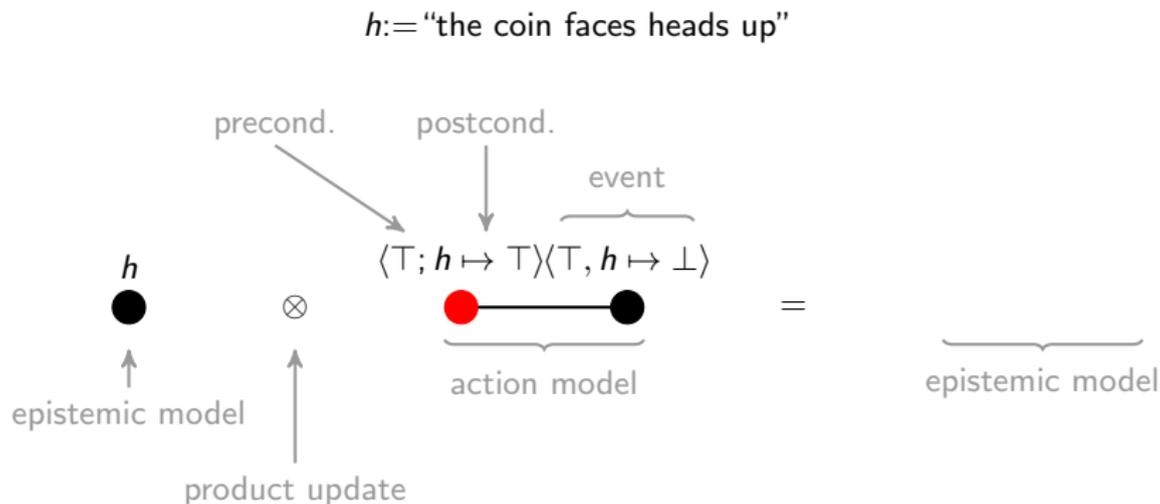
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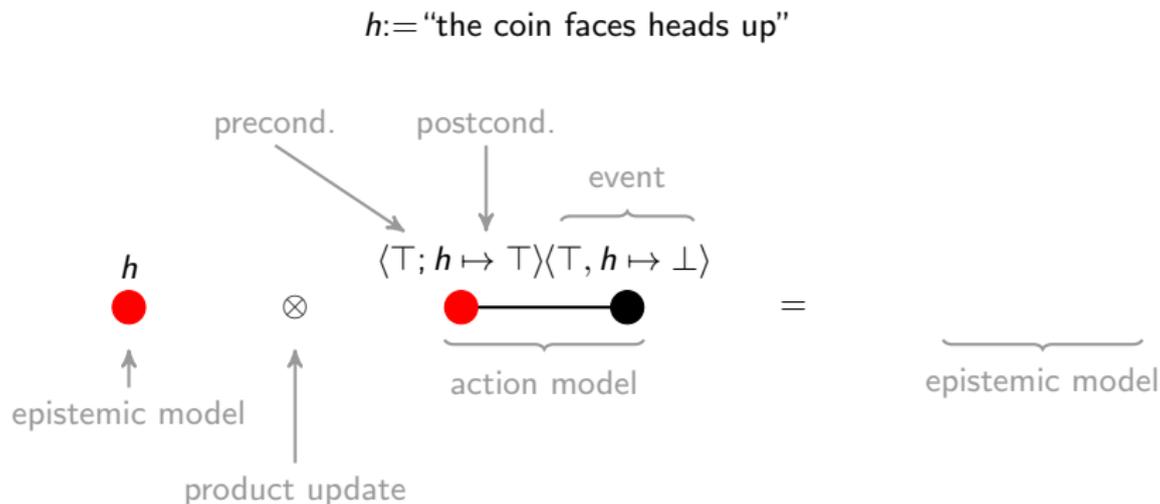
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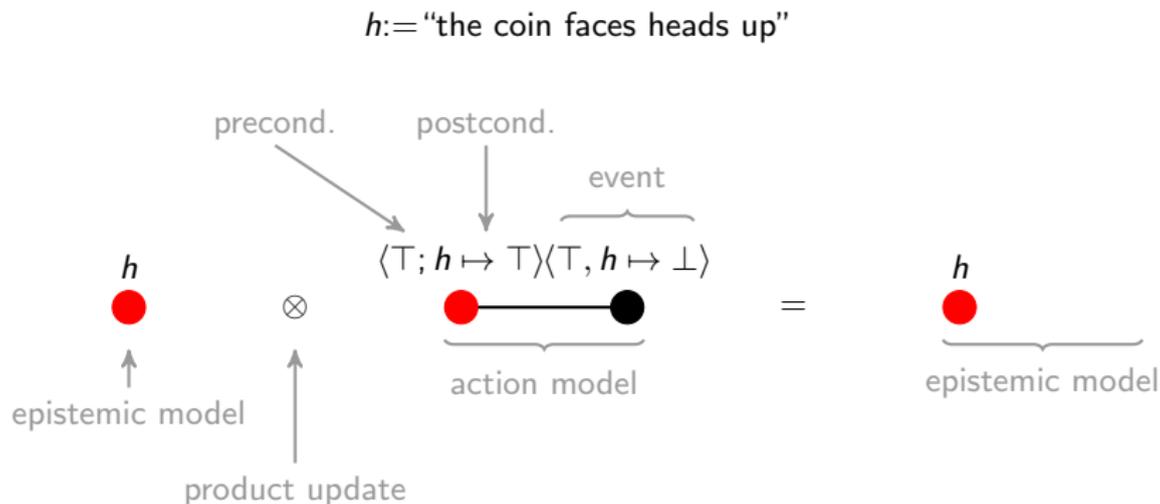
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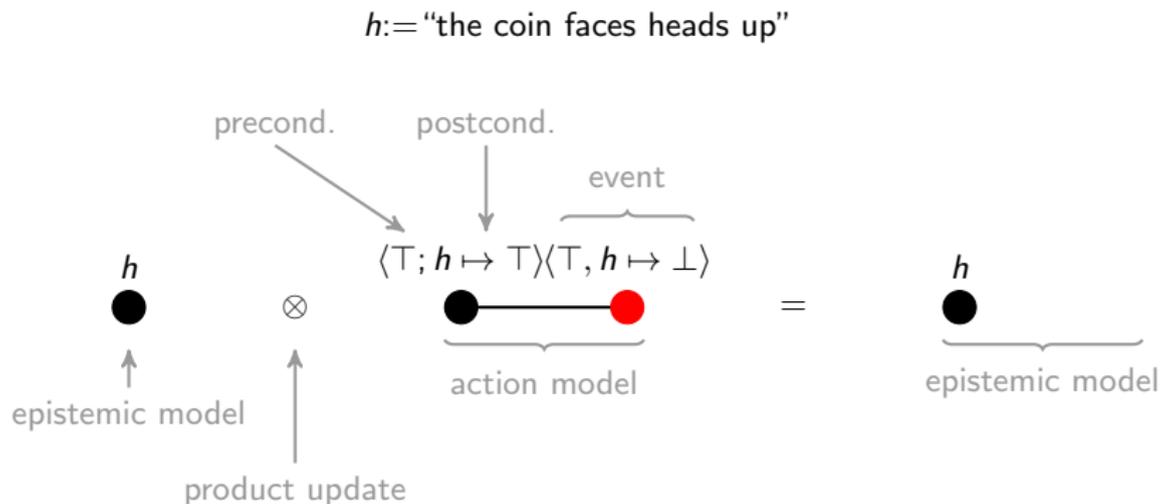
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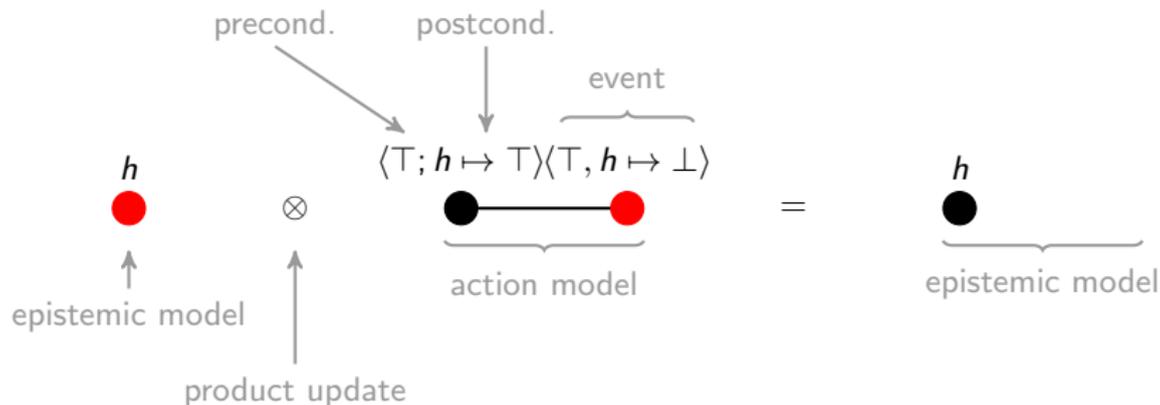


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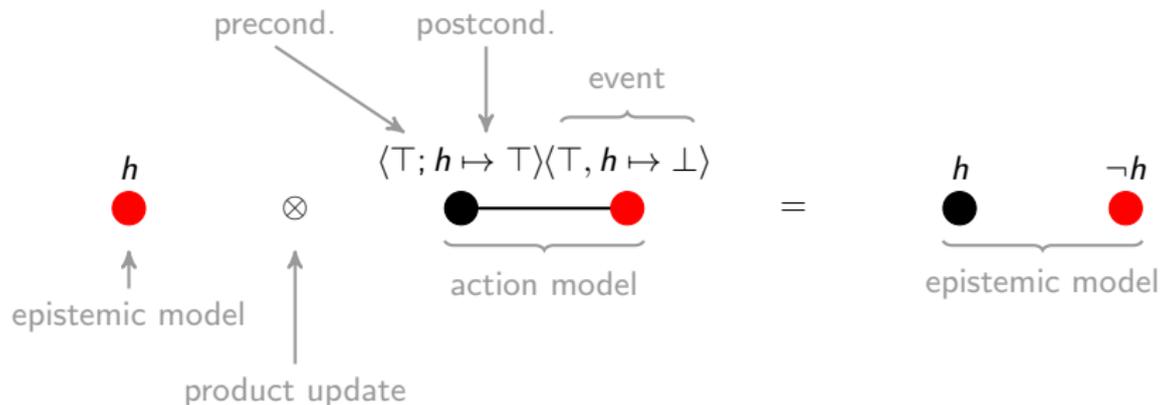


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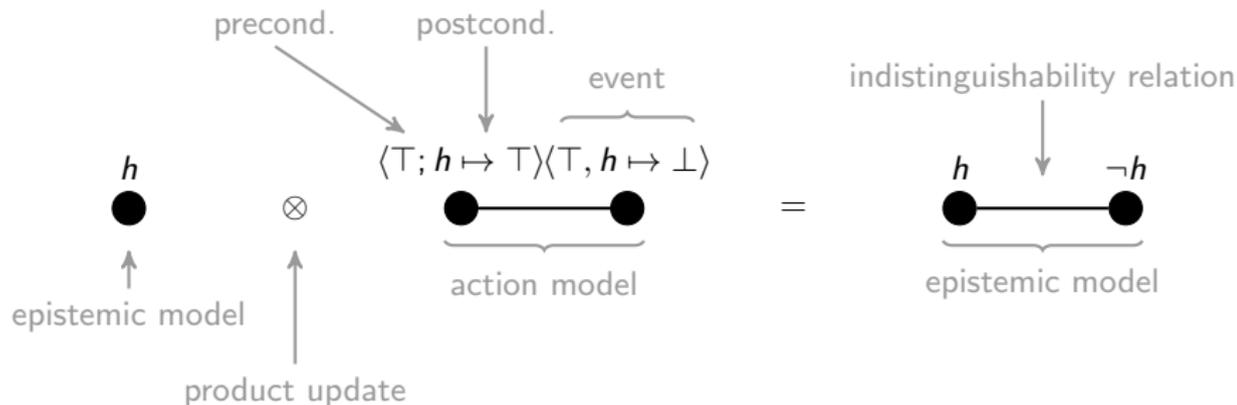


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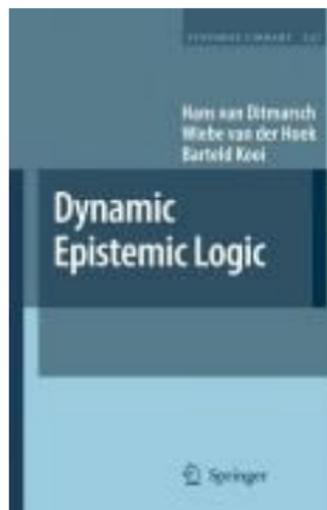


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TO KNOW MORE...



END OF PART 1

# GROUP KNOWLEDGE: EVERYBODY KNOWS

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EXAMPLE

Everybody in this class knows that logic is useful.

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Everybody in this class knows that logic is useful.

DEFINITION

We define inductively:

$$E_G^0\varphi := \varphi$$

$$E_G^{k+1}\varphi := E_G E_G^k\varphi$$

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EXAMPLE

It is common knowledge in Denmark that to drive on the right side of the road.

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# SEMANTICS OF EPISTEMIC LOGIC WITH GROUP OPERATORS

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$(M, s) \models C_G\varphi$	iff	$(M, s) \models E_G^k\varphi$ for every $k = 1, 2, \dots$
$(M, s) \models D_G\varphi$	iff	$(M, t) \models \varphi$ for all $t$ such that $(s, t) \in \bigcap_{i \in G} \mathcal{K}_i$