

### [Wykład 3]

① Example 1  $G = O(n)$   
 What is  $L(O(n)) = \mathfrak{o}(n)$ ?

Given by the equation  $A^T A = I$

Take  $\gamma(t)$  a curve in  $O(n)$

$$\gamma(0) = I \quad \dot{\gamma}(0) = X \in \mathfrak{o}(n)$$

$$\forall t \quad \gamma(t)^T \gamma(t) = I \quad \Big| \frac{d}{dt}$$

$$\dot{\gamma}(t)^T \gamma(t) + \gamma(t)^T \dot{\gamma}(t) = 0 \quad |_{t=0}$$

$$\dot{\gamma}(0)^T + \dot{\gamma}(0) = 0$$

$$X^T + X = 0 \quad \text{i.e. } X \text{ is real antisymmetric}$$

What is the complexification  $O(n)_{\mathbb{C}}$ ?

$O(n)_{\mathbb{C}} = O(n, \mathbb{C})$  is the group of complex matrices st.  $A^T A = I$

(this is a polynomial equation for entries of the matrix)

In another words  $A$  preserves the quadratic nondegenerate form  $z_1^2 + z_2^2 + \dots + z_n^2$ .

The Lie algebra  $\mathfrak{o}(n, \mathbb{C})$  is given by  $X^T + X = 0 \quad X \in M_n(\mathbb{C})$   
 (complex antisymmetric matrices)

Example 2  $G = U(n)$

The equation  $A^T \bar{A} = I$

Lie algebra:  $\gamma^T(t) \cdot \bar{\gamma}(t) = I \quad \Big| \frac{d}{dt}$

$$\dot{\gamma}(t)^T \bar{\gamma}(t) + \gamma^T(t) \cdot \dot{\bar{\gamma}}(t) = 0 \quad |_{t=0}$$

$$\dot{\gamma}(0)^T + \dot{\bar{\gamma}}(0) = 0$$

$$X^T + \bar{X} = 0$$

in another form  $\bar{X}^T = -X$

What is the complexification?

$$U(n) \subset GL_n(\mathbb{C})$$

$$u(n) \subset \mathfrak{gl}_n(\mathbb{C}) = M_{n \times n}(\mathbb{C})$$

Claim  $u(n) + iu(n) = M_{n \times n}(\mathbb{C})$

Cartan involution:  $X \mapsto \bar{X}^T$

decomposes  $M_{n \times n}(\mathbb{C})$  into eigenspaces for the eigenvalues 1 and -1

$$M_{n \times n}(\mathbb{C}) = \{ \bar{X}^T = X \} \oplus \{ \bar{X}^T = -X \}$$

$$\mathfrak{gl}_n(\mathbb{C}) = i \cdot u(n) \oplus u(n)$$

we check:  $\overline{(iX)}^T = -i \bar{X}^T = iX$ .

Conclusion

$$u(n)_{\mathbb{C}} = \mathfrak{gl}_n(\mathbb{C})$$

$$U(n)_{\mathbb{C}} = GL_n(\mathbb{C})$$

Remark  $GL_n(\mathbb{C})$  can be embedded as a closed set in  $M_{(n+1) \times (n+1)}(\mathbb{C})$

$$A \mapsto \begin{bmatrix} A & 0 \\ 0 & (\det A)^{-1} \end{bmatrix}$$

In fact it is embedded in  $SL_{n+1}(\mathbb{C})$ .  
Again it is given by polynomial equations.

# The list of algebras, complexifications, equations

Compact		Complexification	
$so = o(n)$	$X + X^T = 0$ $X$ real	$o(n, \mathbb{C})$	$X + X^T = 0$ $X$ complex
$u(n)$	$\bar{X} + X^T = 0$	$u(n, \mathbb{C})$	no equation
$su(n)$	$\begin{cases} \bar{X} + X^T = 0 \\ \text{tr } X = 0 \end{cases}$	$sl_n(\mathbb{C})$	$\text{tr } X = 0$
$sp(n)$	$\begin{cases} XJ + JX = 0 \\ \bar{X} + X^T = 0 \end{cases}$	$sp(n, \mathbb{C})$	$XJ + JX = 0$

Exercise: Check the remaining cases.

Denote by  $X^*$  the cartesian involution  $\bar{X}^T$ .  
 Let  $\mathfrak{g} \subset \mathfrak{gl}_n(\mathbb{C})$  be a subalgebra.  
 We call  $\mathfrak{g}$  reductive if

$X^* \in \mathfrak{g}$  for  $X \in \mathfrak{g}$ . As for  $\mathfrak{gl}_n(\mathbb{C})$   
 $\mathfrak{g}$  decomposes into eigen-spaces of  $*$

$$\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_1$$

$$\text{let } \mathfrak{k} = \mathfrak{g}_{-1} \quad \mathfrak{p} = \mathfrak{g}_1.$$

Since  $[X, Y]^* = -[X^*, Y^*]$  we  
 have:  $[\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k}$  (i.e.  $\mathfrak{k}$  is a subalgebra)  
 in fact  $\mathfrak{k} = \mathfrak{g} \cap u(n)$

$$[\mathfrak{k}, \mathfrak{p}] \subset \mathfrak{p}$$

$$[\mathfrak{p}, \mathfrak{p}] \subset \mathfrak{k}$$

## Polar Decomposition

④ Let  $G$  be a subgroup of  $GL_n(\mathbb{C})$  with the reductive Lie algebra

Theorem: The map

$$K \times \mathfrak{p} \rightarrow G, (B, P) \mapsto B \cdot \exp(P)$$

is a diffeomorphism. Here

$$K = U(n) \cap G, \quad L(K) = \mathfrak{k} = \mathfrak{g}_{-1}$$

Proof For  $G = GL_n(\mathbb{C})$ .

Hermitian symmetric matrices = self adjoint  
 $A = A^*$  maps  $\mathbb{C}^n \rightarrow \mathbb{C}^n$

for  $P \in \mathfrak{p}$  there exists an orthonormal basis in which it is diagonal

$$D = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \quad P = C D C^T \quad C^T = C^{-1}$$

$$\text{Then } \exp(P) = C \exp(D) C^T = C \begin{bmatrix} e^{\lambda_1} & & \\ & \ddots & \\ & & e^{\lambda_n} \end{bmatrix} C^T$$

$\exp(P)$  is a symmetric matrix with real positive eigenvalues.

$$\exp : \mathfrak{p} \longrightarrow \mathfrak{p}_+$$

There exists an inverse map which for diagonal matrices is of the form  $\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \xrightarrow{\log} \begin{bmatrix} \ln \lambda_1 & & \\ & \ddots & \\ & & \ln \lambda_n \end{bmatrix}$ .

Claim  $\log$  is  $C^\infty$  map.

5) Proof: The sequence

$$\log(I+A) = A - \frac{A^2}{2} + \frac{A^3}{3} - \dots$$

converges if all the eigenvalues of  $A$  are in  $(-1, 1)$ .

Therefore  $\log(P)$  defined and smooth if eigenvalues  $\in (0, 2)$ .

Moreover for all  $t \in \mathbb{R}$   $t > 0$

$$\log(tP) = \log P + \log(t \cdot I) \quad \textcircled{\times}$$

(because  $\log(AB) = \log(A) + \log(B)$  if  $A$  and  $B$  commute)

For arbitrary  $P$  we define  $\log P$  by the formula  $\textcircled{\times}$  for sufficiently small  $t$ :

$$\log(P) := \log(tP) - \log t \cdot I \quad \textcircled{\times}$$

Now let  $A \in \text{GL}(n, \mathbb{C})$   $\bar{A}^T A$  is a positive definite symmetric matrix.

$$\text{let } P = \frac{1}{2} \log(\bar{A}^T A) \quad Q = \exp(P)$$

$$\text{then } \bar{A}^T A = Q^2.$$

$$\text{let } B = A \cdot Q^{-1}, \quad (\bar{A} Q^{-1})^T A Q^{-1} = Q^{-1} \bar{A}^T A Q^{-1} = I$$

hence  $B \in U(n)$ .

$$\text{We get } A = B \cdot Q = B \exp(P)$$

The map  $A \mapsto (B, P)$  is  $C^\infty$  map inverse to  $B \cdot \exp(P)$ .

(6) Other classical groups:  
 The general case:  $G \subset GL_n(\mathbb{C})$   
 closed subgroup described by polynomials  
 We have to show that for  $A \in G$   
 constructed  $B$  and  $P$  belong to  
 $G \cap U(n)$  and of  $n$  symmetric matrices.

$\bar{A}^T \in G$  since  $G$  is reductive  
 $\bar{A}^T A \in G$  and equal to  $(\exp(P))^2$

Changing coordinates can assume  
 that  $P$  is diagonal.  $Q = \exp(P)$ .  
 $Q^t = \begin{pmatrix} a_1^t & & 0 \\ & \ddots & \\ 0 & & a_n^t \end{pmatrix}$  satisfy the equations  
 of  $G$  for  $t$  even natural  $t=2n$   
 $(Q^{2n} = (\bar{A}^T A)^n \in G)$ .

Therefore (this is a small lemma-exercise\*)

$Q^t = \exp(tP) \in G$  for all  $t$ .

Hence  $B = A Q^{-1} \in G$ .

\* use that  $G$  is given by polynomial equations

# (7) ( Baker ) - Campbell - Hausdorff formulas

exp:  $\mathfrak{g} \rightarrow G$  is diffe on  $U \subset \mathfrak{g}$

The inverse is denoted by  $\log$ .

For matrix groups

$$\log(1+A) = A - \frac{A^2}{2} + \frac{A^3}{3} - \dots$$

The logarithm allows to define a multiplication in  $\mathfrak{g}$  (defined locally)

$$X * Y = \log(\exp(X) \cdot \exp(Y)) =$$

$$\log\left(\left(1+A+\frac{A^2}{2}+\dots\right)\left(1+B+\frac{B^2}{2}+\dots\right)\right) = \log\left(1+A+B+\frac{A^2}{2}+AB+\frac{B^2}{2}+\dots\right)$$

$$= A+B+\frac{A^2}{2}+AB+\frac{B^2}{2}-\frac{(A+B)^2}{2}+\dots = A+B+AB-\frac{1}{2}AB-\frac{1}{2}BA+\dots$$

$$= AB+\frac{1}{2}[A,B]+\dots$$

Theorem (we will not prove it) All the higher terms can be expressed using  $[, ]$  only.

e.g. 3rd term:  $\frac{1}{12}([A, [A, B]] + [B, [B, A]])$

(exercise: compute few terms)

Easy: if  $[A, B] = 0$ , then  $\exp(A), \exp(B)$  commute.

Conclusion The multiplication in  $G$  is determined by  $[, ]$ .

Proof Given locally  $\Rightarrow$  at the component of  $\frac{1}{2}$

For example we deduce that the multiplication formulas are analytic.

## ⑧ Theorem The functor

see Segal's proof

Lie Groups  $\longrightarrow$  Lie Algebras

Connected + Simply connected  
 $\pi_1(G) = 1$

is an equivalence of categories.

This means:

- for any Lie algebra  $\mathfrak{g}$  there exists a Lie group  $G$  s.t.  $L(G) \cong \mathfrak{g}$
- for any map of Lie algebras  $\mathfrak{g} \rightarrow \mathfrak{h}$  there exists a unique map of corresponding Lie groups (in particular if  $L(G) \cong L(H)$  then  $G \cong H$ ).

For non simply connected groups might be a problem with existence of maps

eg  $L(S^1) \cong \mathbb{R} = L(\mathbb{R}^1)$  but there is no map  $S^1 \rightarrow \mathbb{R}$  except the constant.

## Abelian Lie Groups

One of corollaries: if  $[X, Y] = 0$  for all  $X, Y$ , then  $G$  is commutative. (if  $G$  is connected)

Pf for matrix groups it follows from  $\exp(X) \cdot \exp(Y) = \exp(X+Y)$  whenever  $XY = YX$ .

Or for general group it follows from B-C-H. Then  $\exp: \mathfrak{g} \rightarrow G$  is a homomorphism.

hence  $G = \mathfrak{g} / \text{discrete subgroup} \cong \frac{\mathbb{R}^n}{\mathbb{Z}^k}$

• (ex. show that  $\exp$  is epi) for some  $k \leq n$



## (9) Adjoint representation

Let  $\phi_g : G \rightarrow G$   
 $h \mapsto ghg^{-1}$

be the conjugation.

$$\phi_g(1) = 1 \quad \text{and} \quad \phi_{g_1} \circ \phi_{g_2} = \phi_{g_1 g_2}$$

Therefore  $G$  acts on  $T_1 G = \mathfrak{g}$ .

$$\text{Ad} : G \rightarrow GL(\mathfrak{g})$$

Action of a Lie group on a vector space is called a representation.  
This one is called the adjoint representation.

If  $G$  is compactive, then  $\text{Ad}(g) = 1$   
for any  $g$ . In general for  
connected groups  $\ker(\text{Ad}) = Z(G)$   
where  $Z(G)$  denotes the center:

$$Z(G) = \{g \in G : \forall h \in G \quad ghg^{-1} = g\}$$

Corollary We get for free an  
embedding  $G/Z(G) \hookrightarrow GL(\mathfrak{g})$

For example all simple (in the  
algebraic sense) groups (i.e. those  
which have no normal subgroups)  
embed in  $GL(\mathfrak{g})$ .

$$\text{For example } PGL_n(\mathbb{C}) = GL_n(\mathbb{C}) / \mathbb{C}^* \cdot \text{Id}$$
$$PGL_n(\mathbb{C}) \subset GL_{n^2}(\mathbb{C})$$

(10) Small ad :  $\mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$  is  
 the derivative of the map  
 $G \rightarrow \mathfrak{GL}(\mathfrak{g})$ .

For matrix groups

$$\Phi_A(B) = ABA^{-1}$$

It is linear with respect to  $B$ .

Hence  $\text{Ad}_A(X) = (D\Phi_A)_1(X) = AXA^{-1}$ .

The derivative of  $\text{Ad}_A(X)$  (with respect to  $A$  at 1 in the direction  $Y$ ):

$$(D\text{Ad}_A(X))_1(Y) = \left. \frac{d}{dt} \gamma(t) X \gamma(t)^{-1} \right|_{t=0}$$

where  $\gamma(t)$  is a curve s.t.

$$\gamma(0) = 1$$

$$\dot{\gamma}(0) = Y$$

- can assume it is 1-parameter subgroup  $\gamma(t) = \gamma(-t)$

$$= \dot{\gamma}(0) X \gamma(0)^{-1} + \gamma(0) X \dot{\gamma}^{-1}(0)$$

$$= YX - XY = [Y, X].$$

Notation  $\text{ad}_Y(X) = [Y, X]$ .

Theorem Every complex connected compact group is iso to  $\mathbb{C}^n/\Lambda$ , where  $\Lambda \cong \mathbb{Z}^{2n}$ .

Proof: There are no linear compact complex groups (no nonconstant maps  $G \rightarrow M_{n \times n}(\mathbb{C})$ ).

Consider  $\text{Ad} : G \rightarrow \mathfrak{GL}(\mathfrak{g})$ . This map is constant. It follows that  $\forall X, Y \in \mathfrak{g}$   
 $\text{ad}_Y(X) = [Y, X] = 0$ . Hence  $G$  is commutative.