

On guidable index of tree automata

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MFCS 2021, Tallinn



UNIVERSITY
OF WARSAW

Infinite trees t

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$$\text{Tr}_\Sigma \ni t: \{L, R\}^* \rightarrow \Sigma$$

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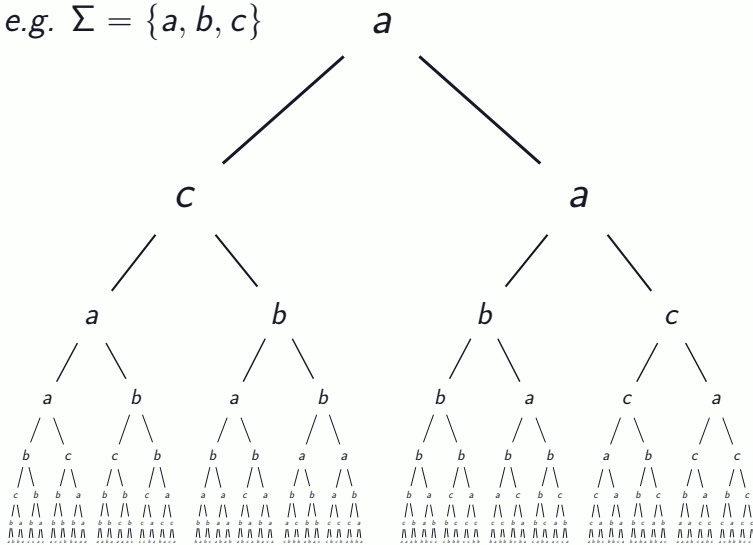
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e.g. $\Sigma = \{a, b, c\}$

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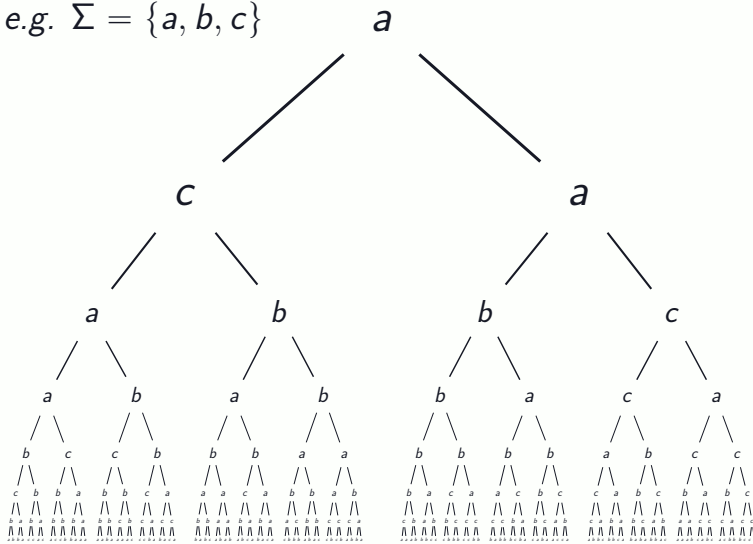
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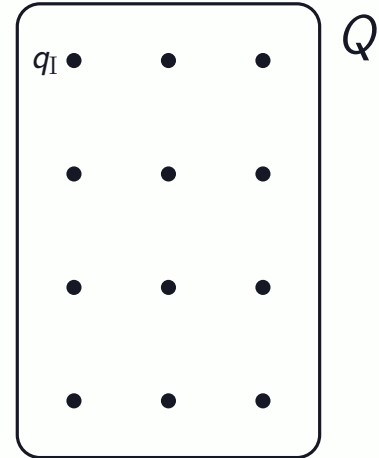
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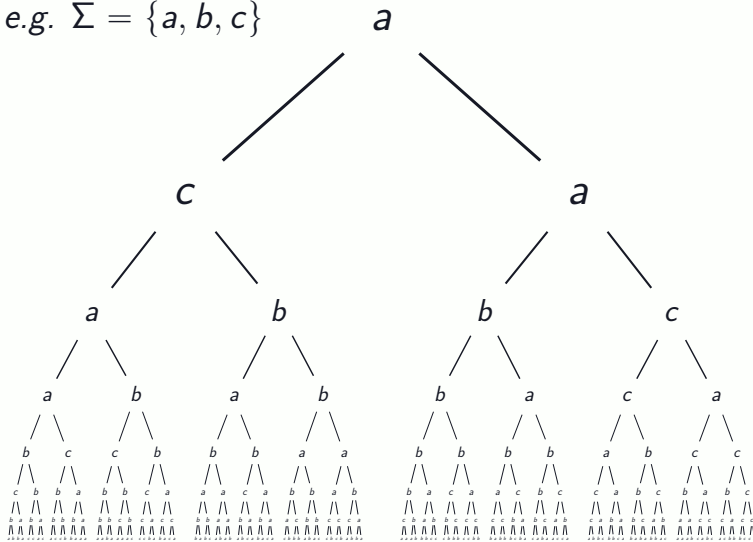
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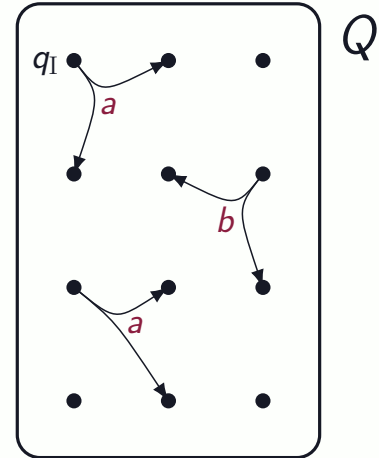
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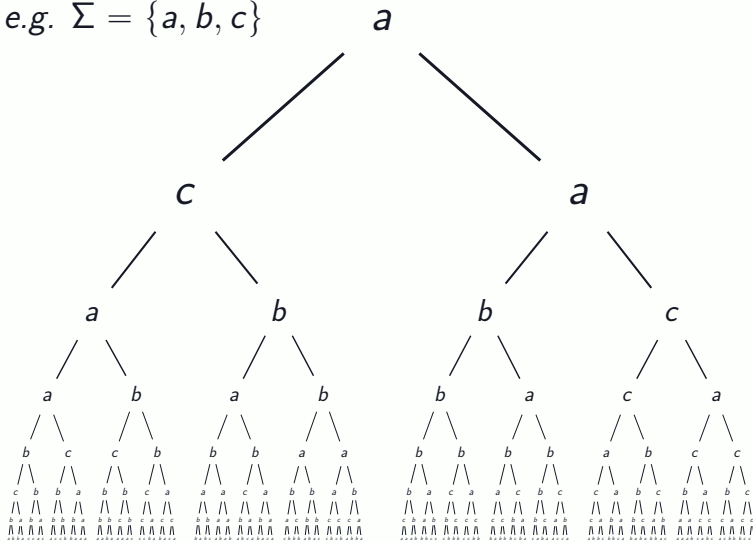
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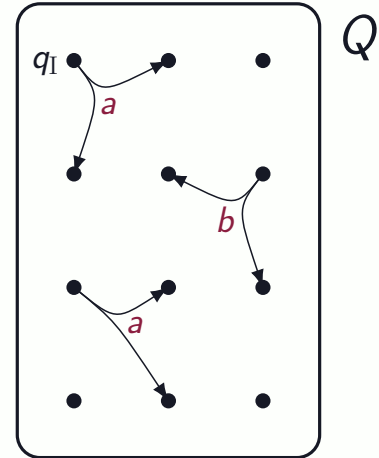
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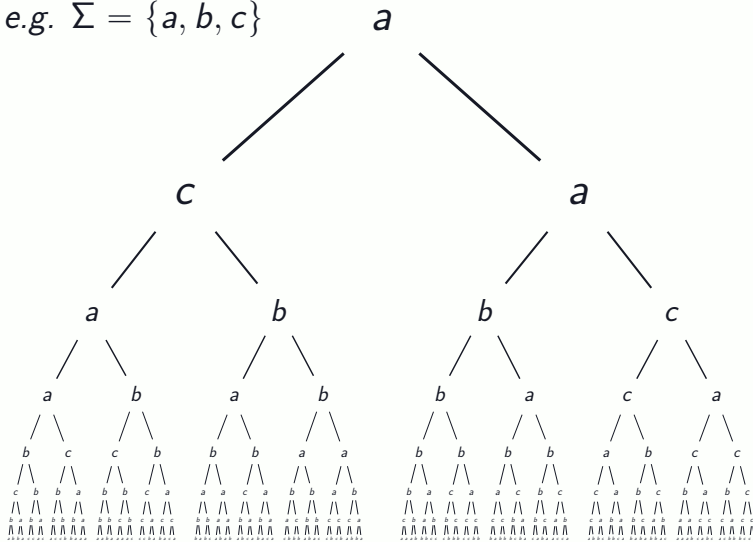


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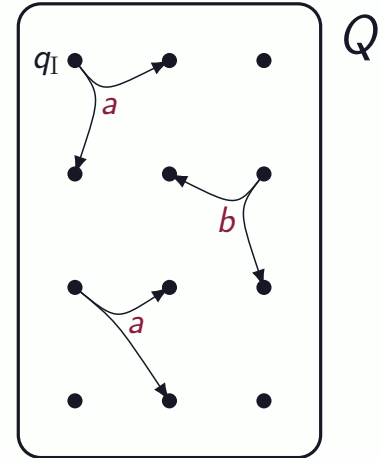
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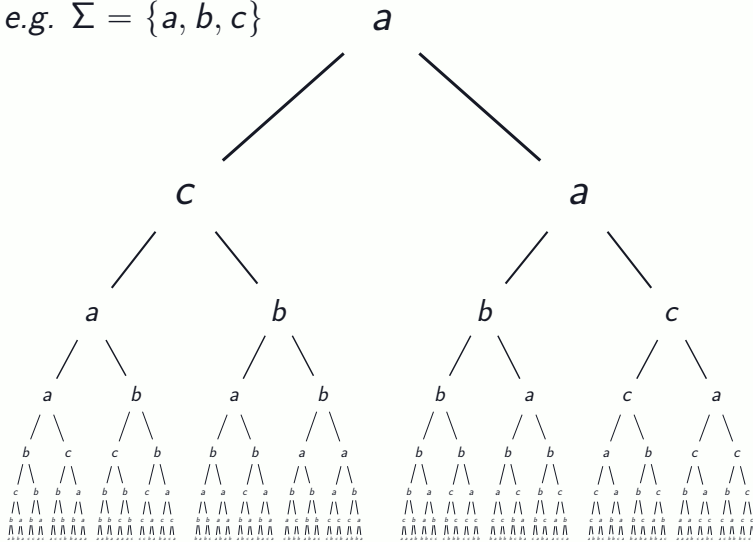


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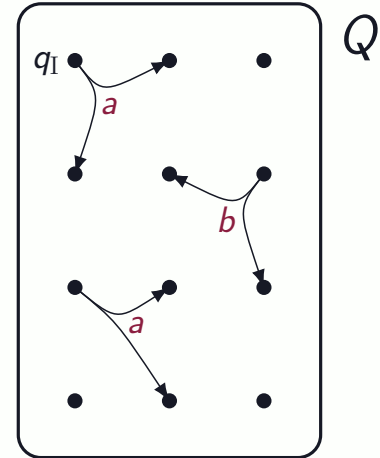
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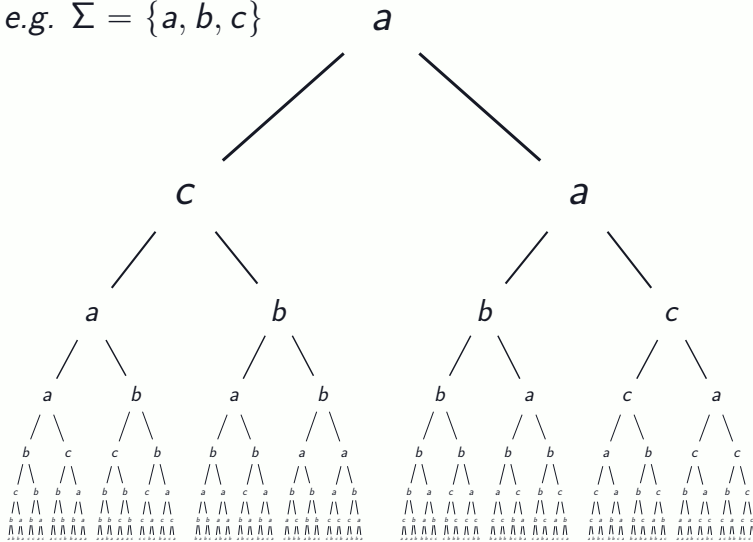
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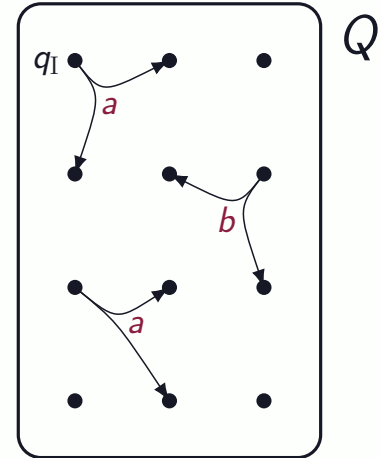
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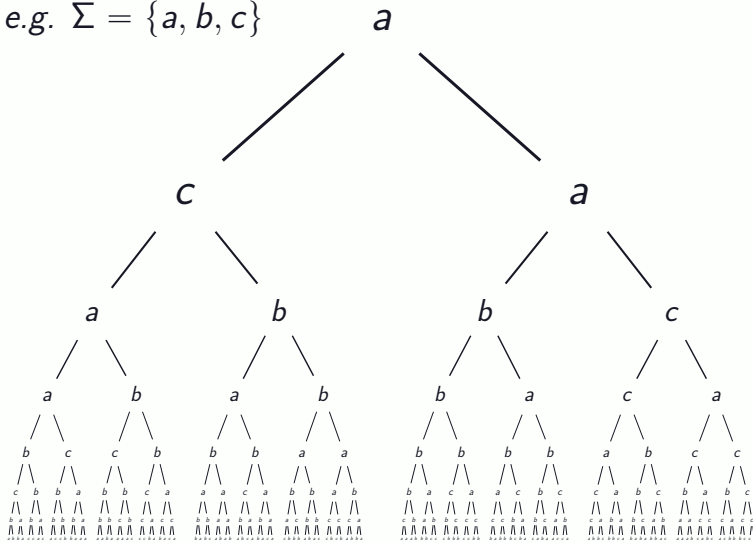
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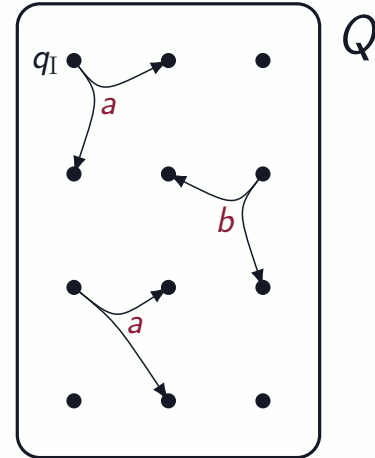
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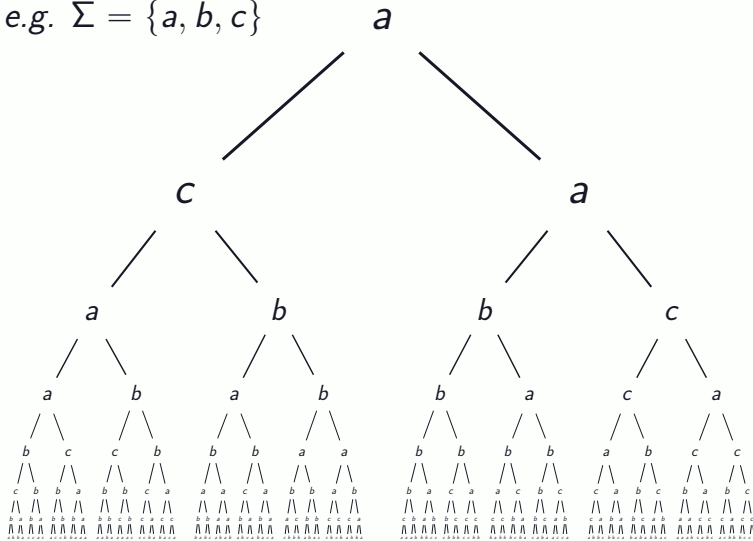
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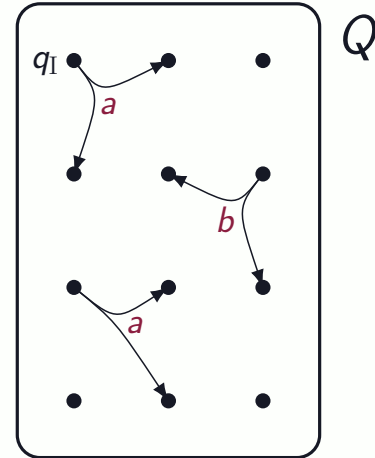
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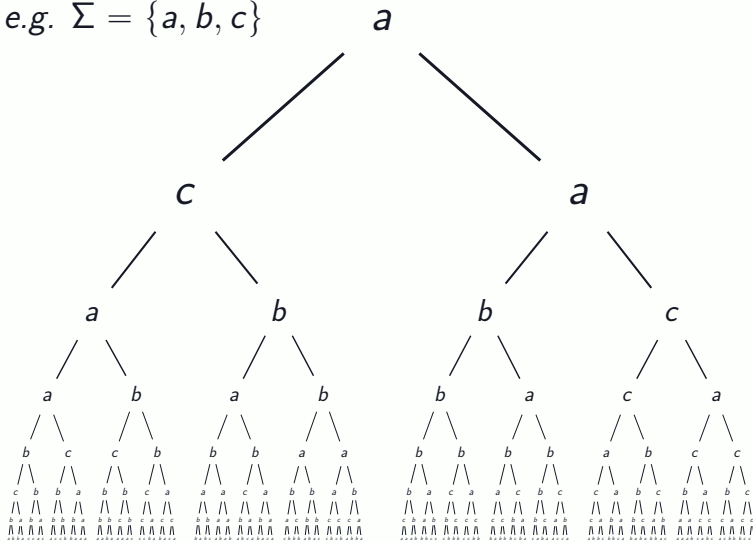
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→ regular tree languages → model checking of **Monadic Second-Order logic**

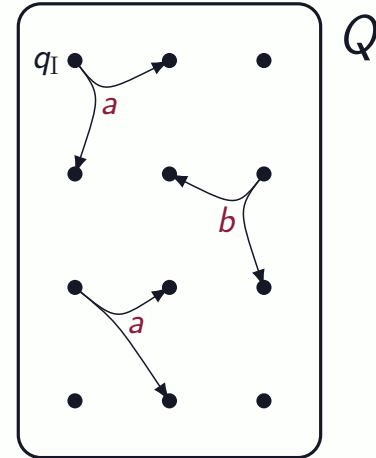
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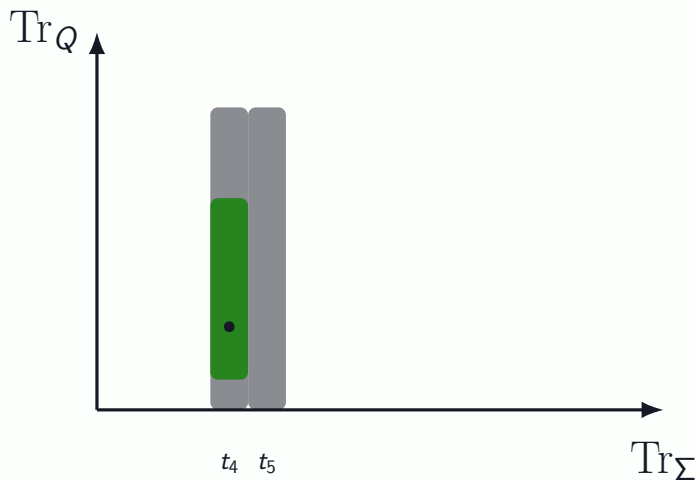
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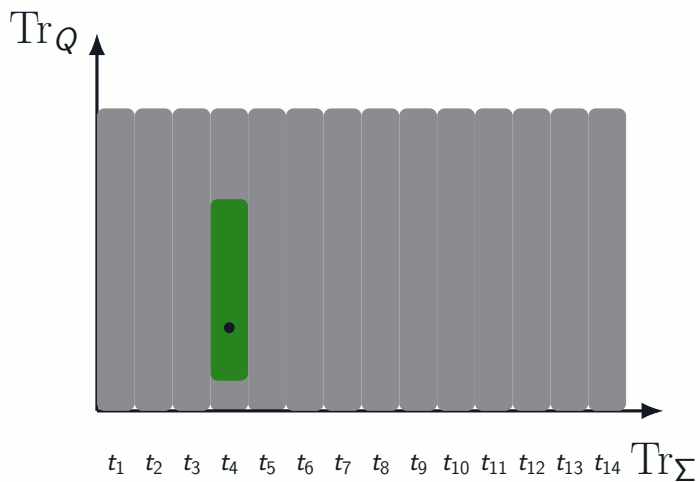
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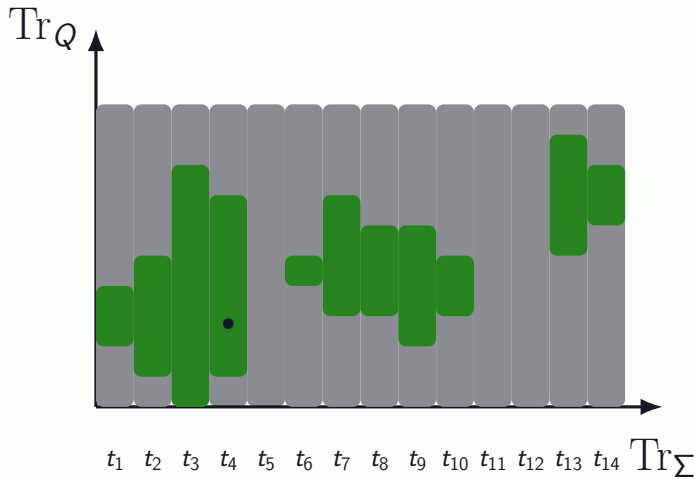


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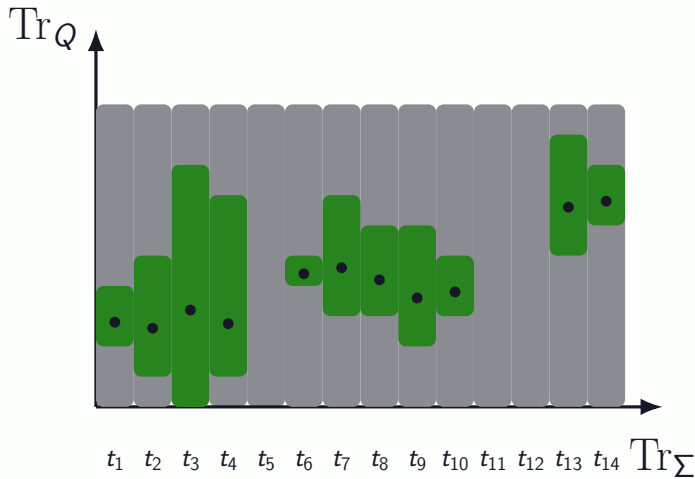


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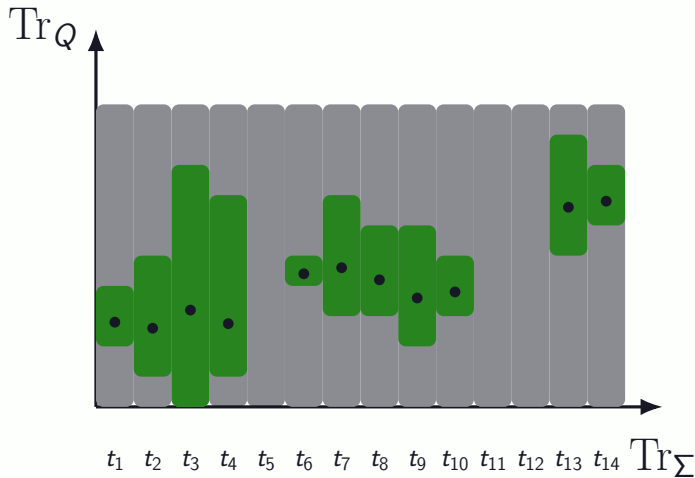


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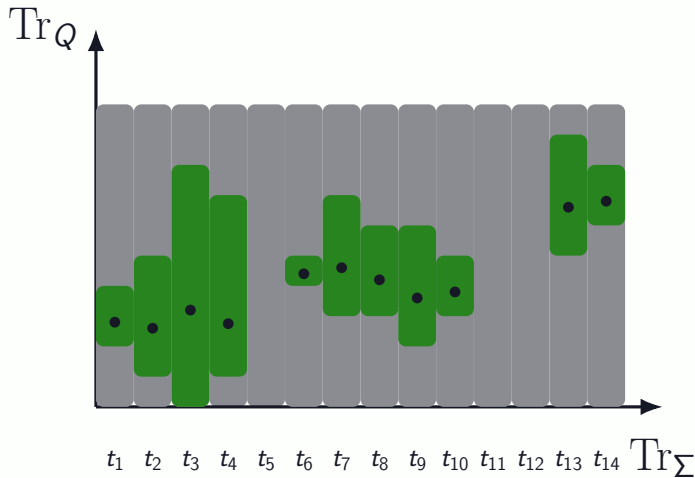
no unambiguity / uniformisation

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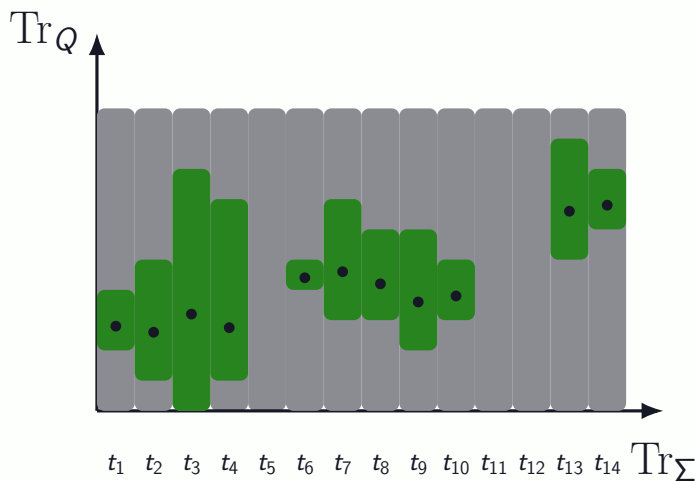
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→ **no unambiguity / uniformisation**

→ **no minimality / canonical form**

→ several **decidability questions** still open for automata on infinite trees...

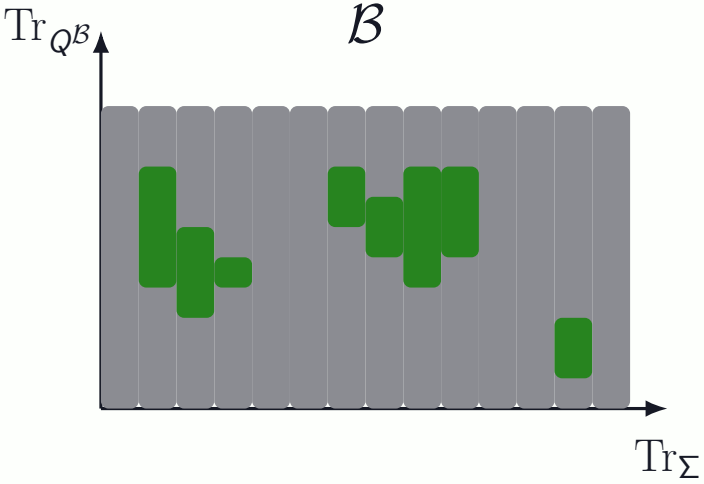
Guidability relation

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(Colcombet, Löding [2008])

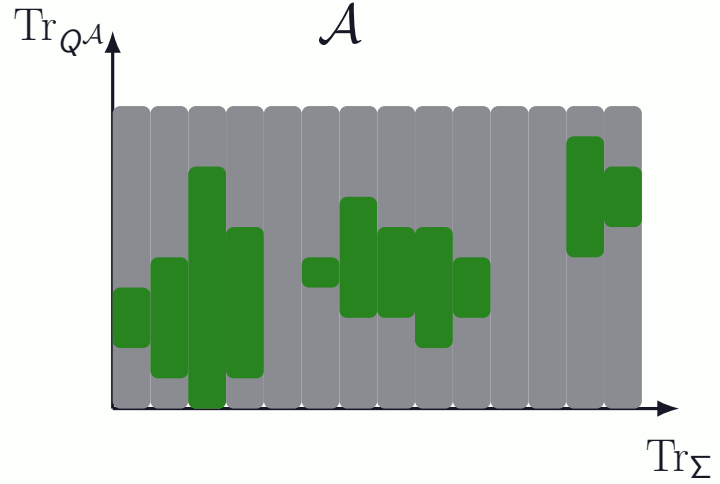
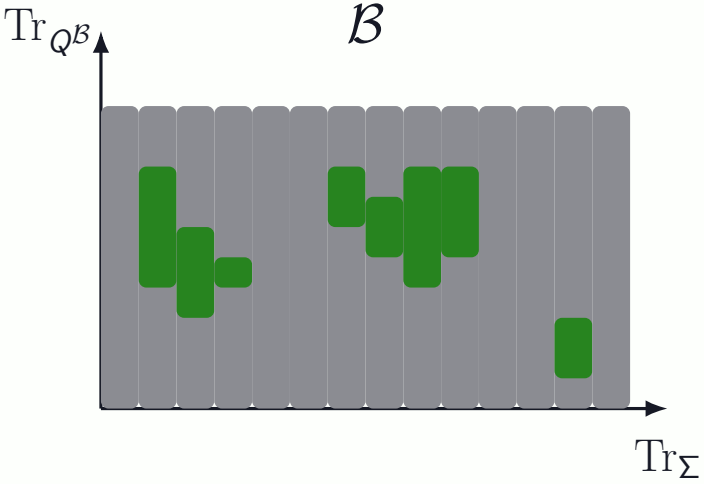
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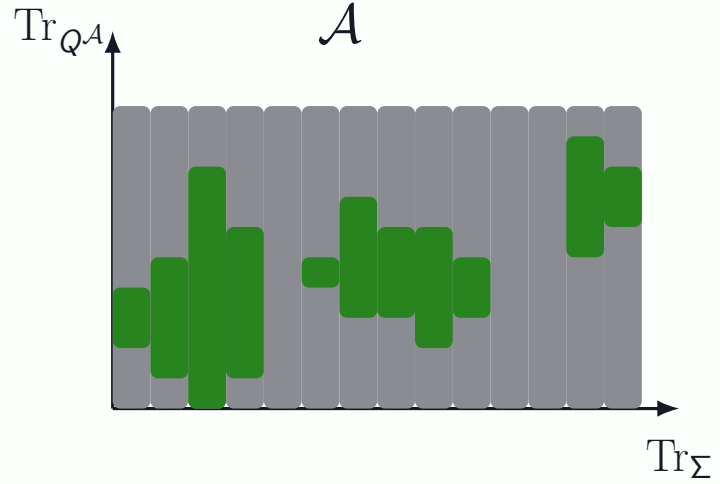
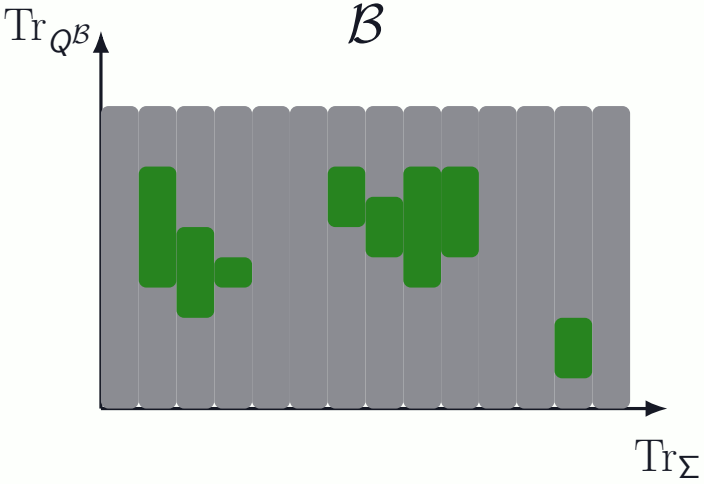
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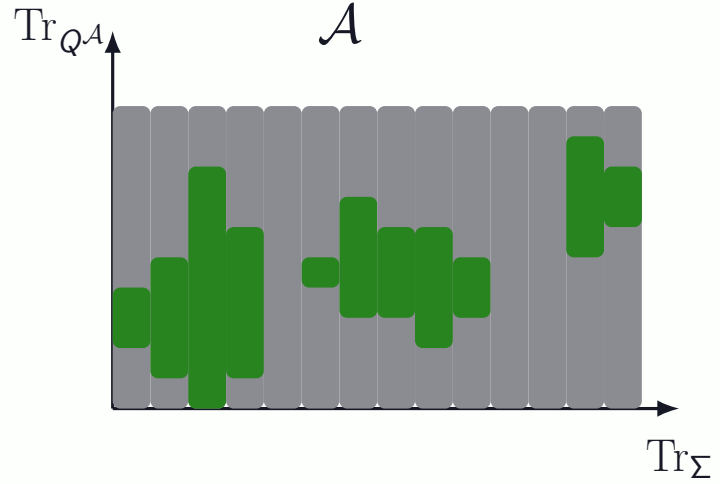
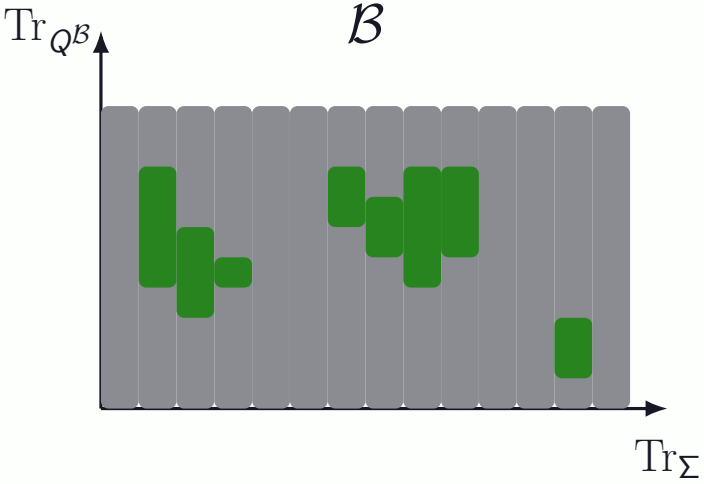
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\mathcal{B} guides \mathcal{A}

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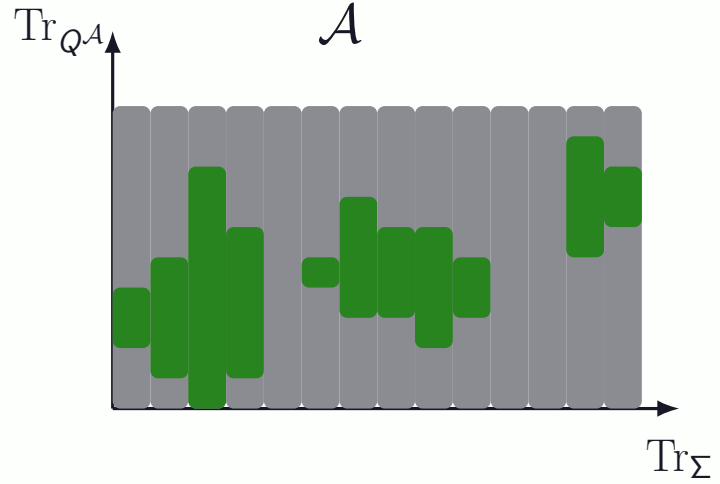
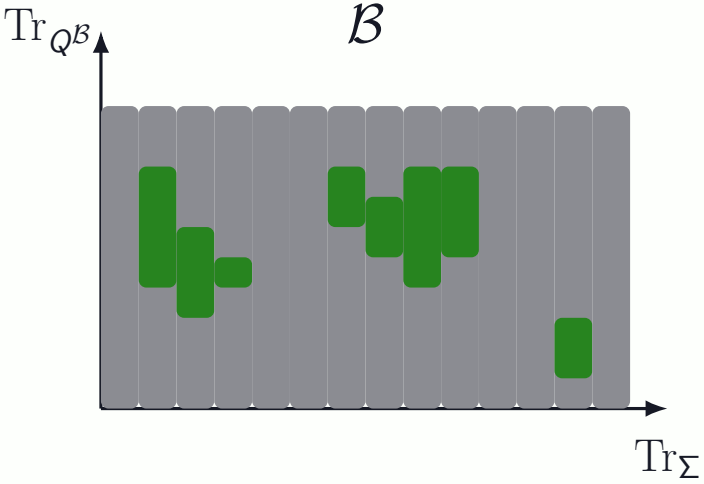


B guides **A**

(denoted $\mathcal{B} \leftrightarrow \mathcal{A}$)

Guidability relation

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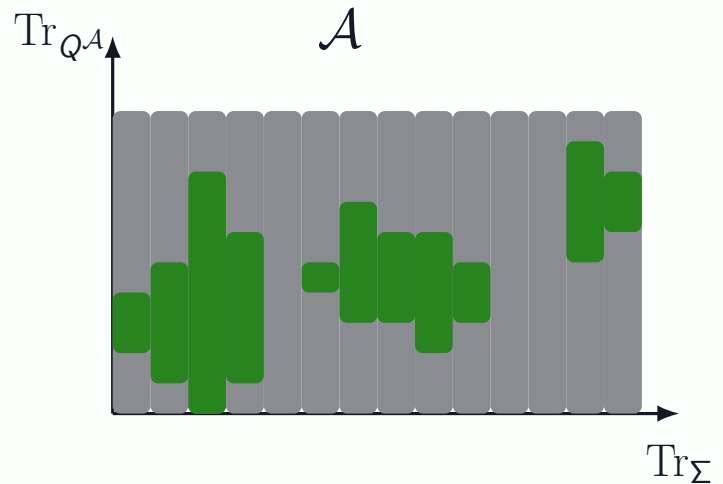
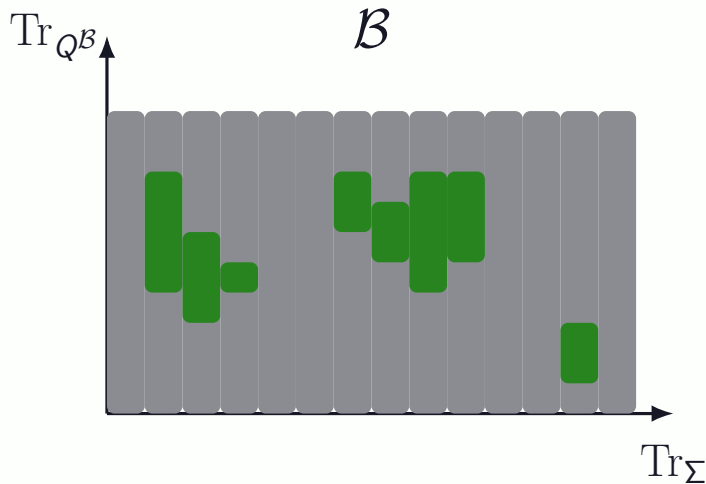
iff

There exists a **transducer**

$$\mathcal{T} : (\rho^{\mathcal{B}}, t) \mapsto (\rho^{\mathcal{A}}, t)$$

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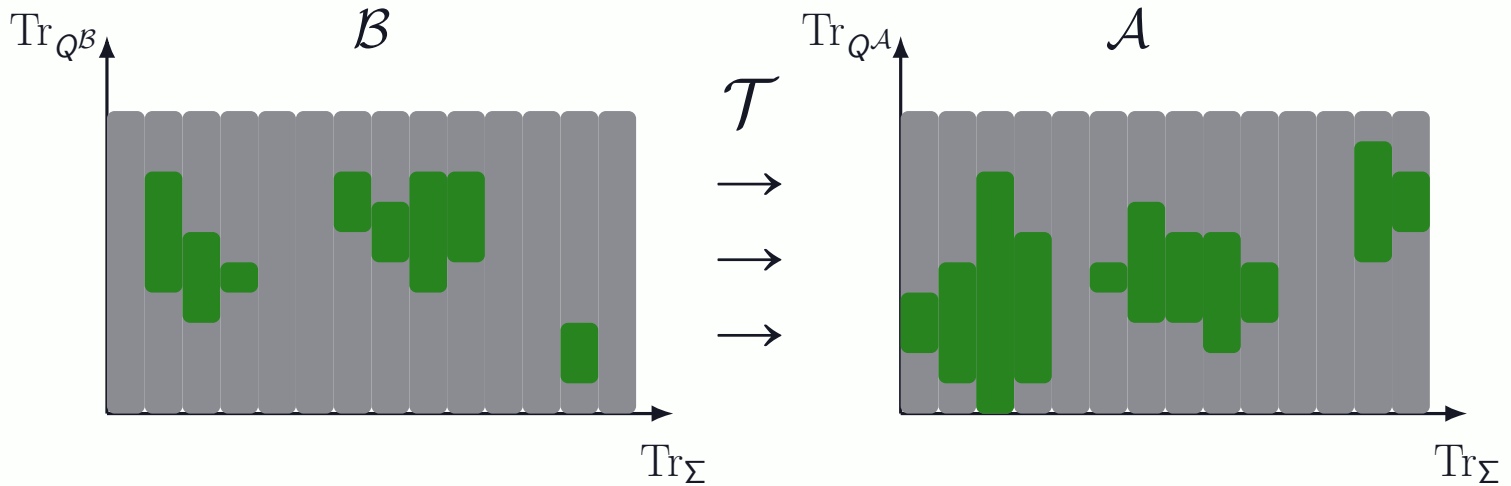
iff

There exists a **transducer** $\mathcal{T}: (\rho^{\mathcal{B}}, t) \mapsto (\rho^{\mathcal{A}}, t)$

which maps **accepting runs** $\rho^{\mathcal{B}}$ into **accepting runs** $\rho^{\mathcal{A}}$.

Guidability relation

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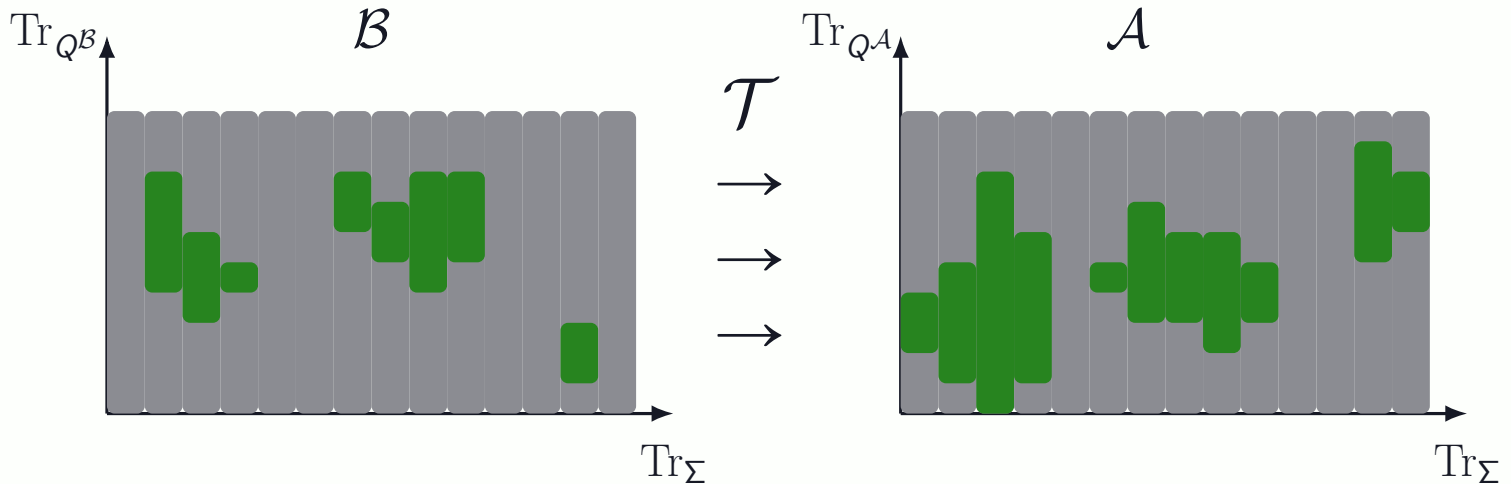
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Guidability relation

(Colcombet, Löding [2008])



\mathcal{B} guides \mathcal{A}

(denoted $\mathcal{B} \hookrightarrow \mathcal{A}$)

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In particular:

$$\mathcal{B} \hookrightarrow \mathcal{A} \implies L(\mathcal{B}) \subseteq L(\mathcal{A})$$

Guidable automata

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for every \mathcal{B} s.t. $L(\mathcal{B}) \subseteq L(\mathcal{A})$ we have $\mathcal{B} \leftrightarrow \mathcal{A}$

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For every automaton one can construct an **equivalent guidable** automaton.

↪ every **regular tree language** is recognised by some **guidable** automaton

Structure of guidable automata

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Lemma (Colcombet, Löding [2008]; Löding [2009])

If $\mathcal{B} \leftrightarrow \mathcal{A}$ then there exists a **memoryless** transducer

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$$\mathcal{A} \text{ is guidable } \text{ iff } \mathcal{B} \hookrightarrow \mathcal{A}$$

Fact

Top-down **deterministic** automata are **guidable**.

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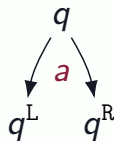
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Fact

Top-down deterministic automata are **guidable**.

For each $q \in Q$, $a \in \Sigma$
exactly one transition



Deterministic and game automata

Deterministic and game automata

Deterministic automata

For each $q \in Q$, $a \in \Sigma$ there is a **unique** transition



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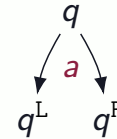
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Acceptance game for $t \in L(\mathcal{A})$: positions are $(q, u) \in Q \times \{L, R\}^*$

Deterministic and game automata

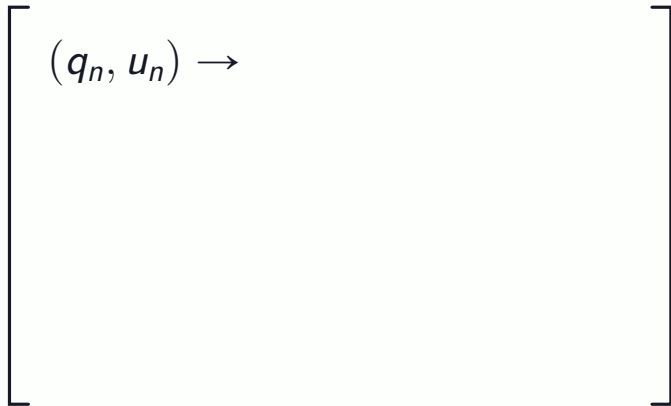
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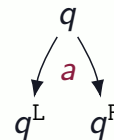
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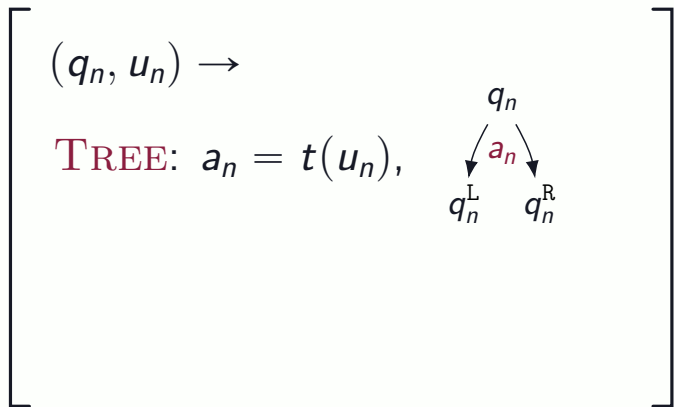
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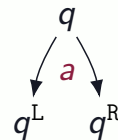
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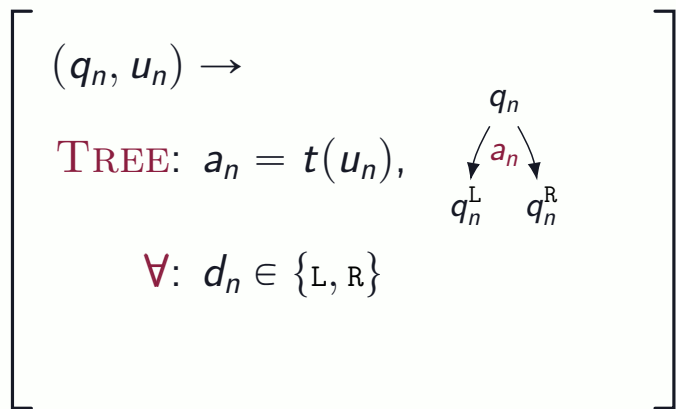
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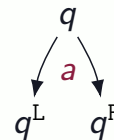
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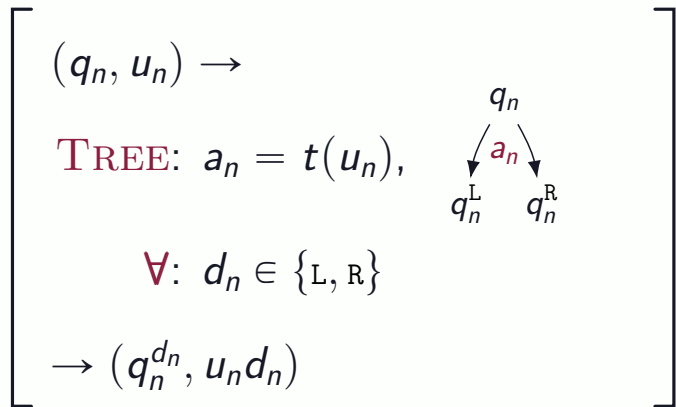
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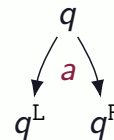
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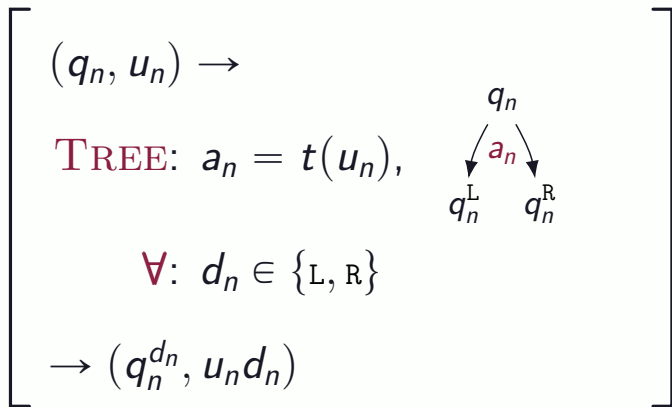
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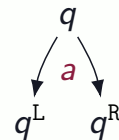


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 $(q_n)_{n \in \omega}$ is **accepting**

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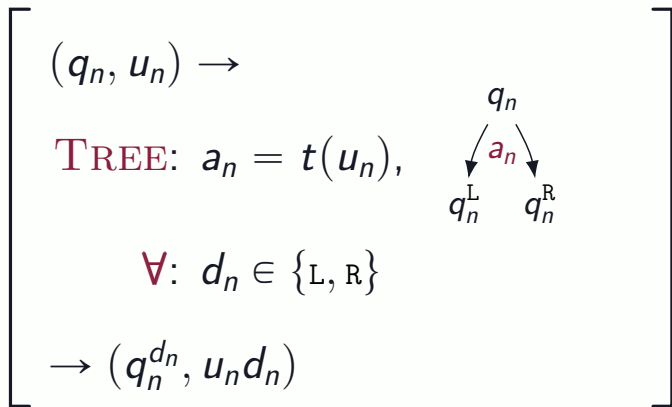
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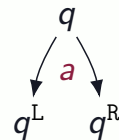
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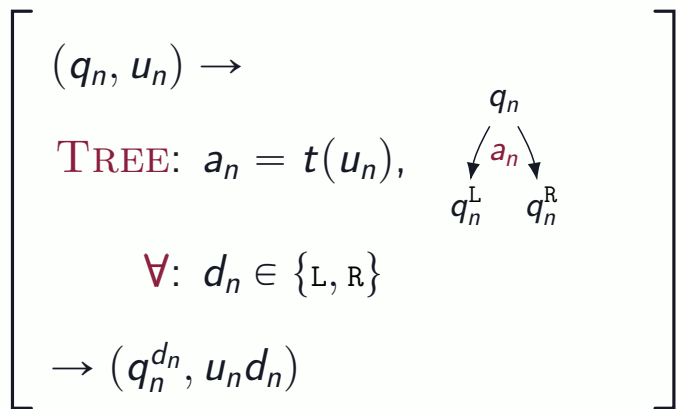
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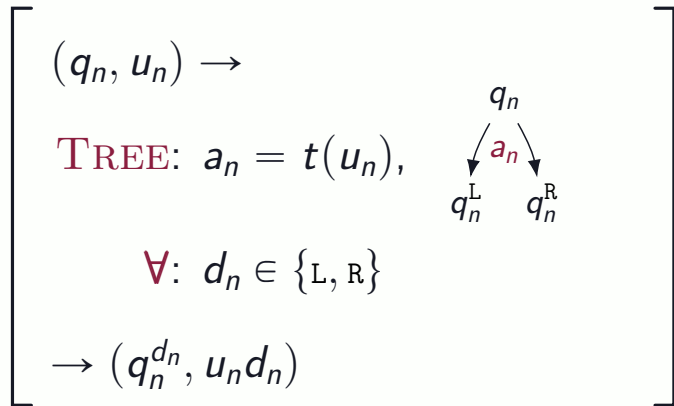
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Γ -index problem

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(Non-det.)-index problem	???	attempt in (Colcombet, Löding [2007])

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Proof (W.l.o.g. assume that \mathcal{A} is **guidable**.)

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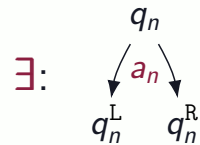
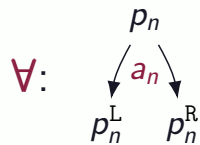
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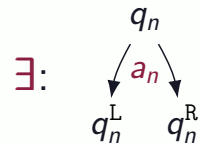
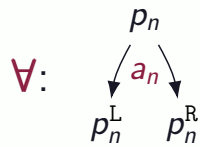
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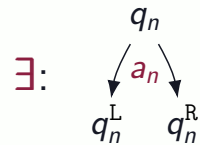
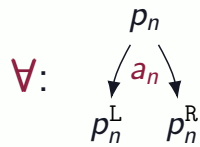
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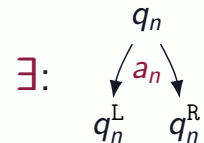
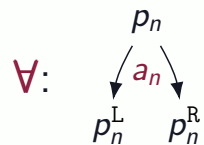
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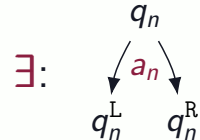
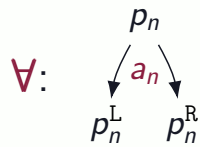
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Claim

\exists has a **winning strategy** iff there exists such \mathcal{B}

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Assume that $\Delta \subseteq \Gamma$ are some of the above classes.

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Remark

But **no** such transfer for $\Gamma = \text{(Non-det.)!}$

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+ New **game-based** characterisation!