

Computing measures of sets of infinite trees definable in weak-MSO logic

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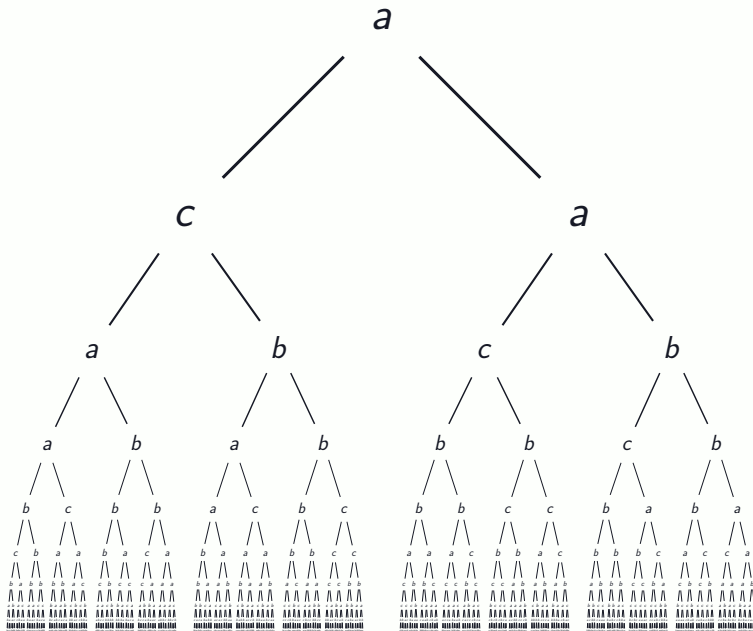
Infinite trees

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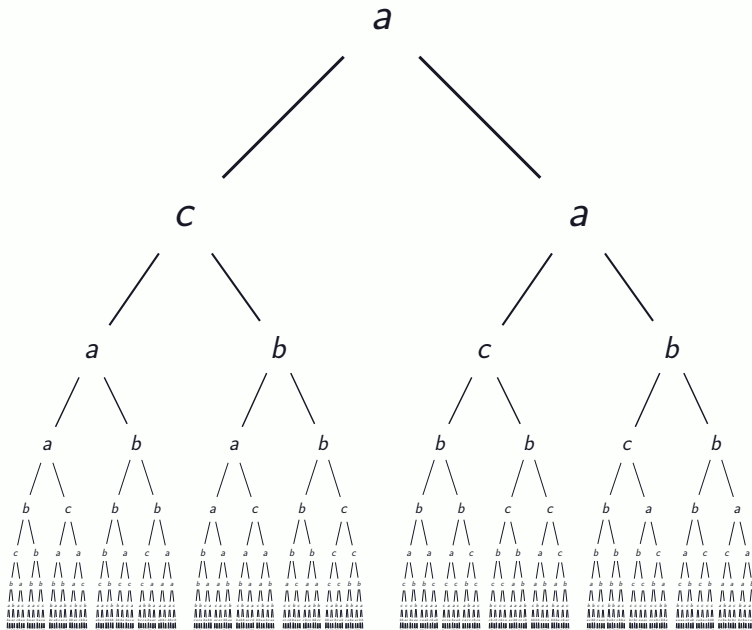
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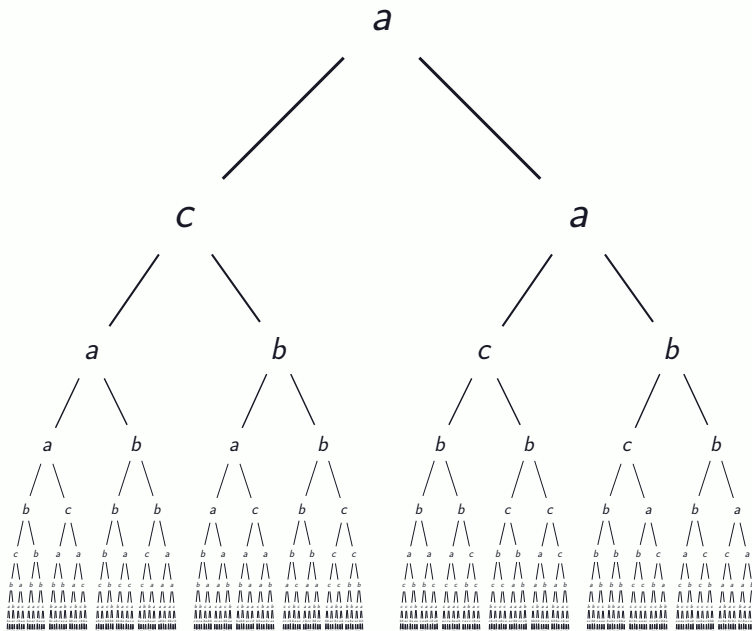
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Infinite trees

Regular languages

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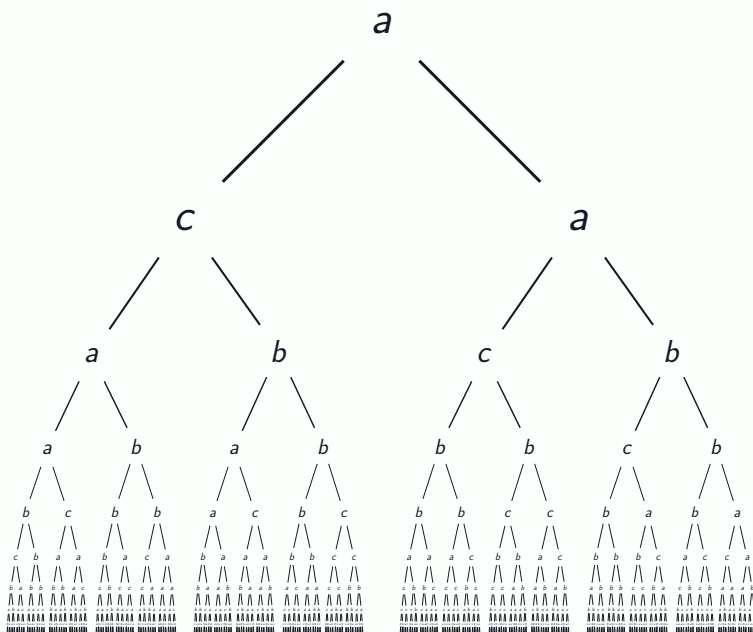
Monadic Second-order logic (MSO):

$$\varphi ::= \exists X. \varphi \mid \exists x. \varphi \mid \varphi \vee \varphi \mid \neg \varphi$$

$$x \in X \mid x \leq y \mid x \leq_{\text{lex}} y \mid a(x)$$

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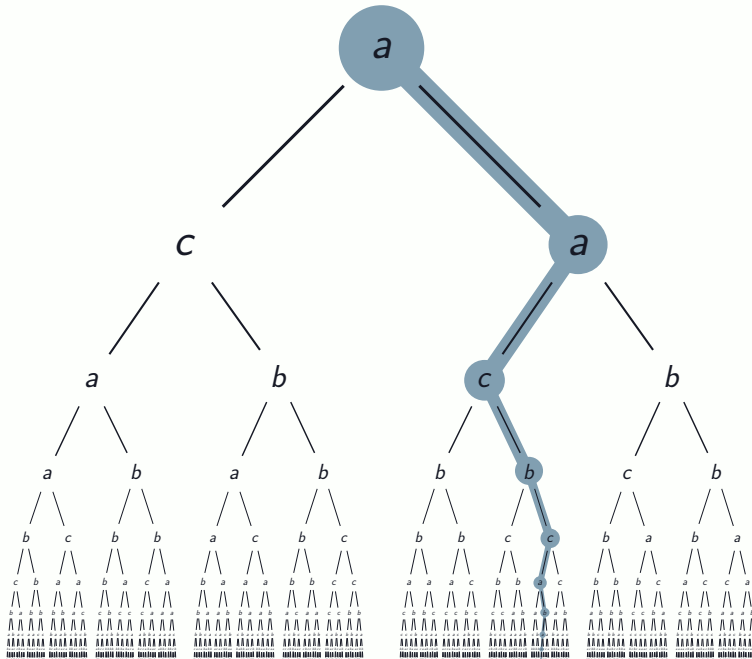
$$x \in X \mid x \leq y \mid x \leq_{\text{lex}} y \mid a(x)$$

Ex. $\varphi \equiv \forall B. \text{branch}(B) \Rightarrow$

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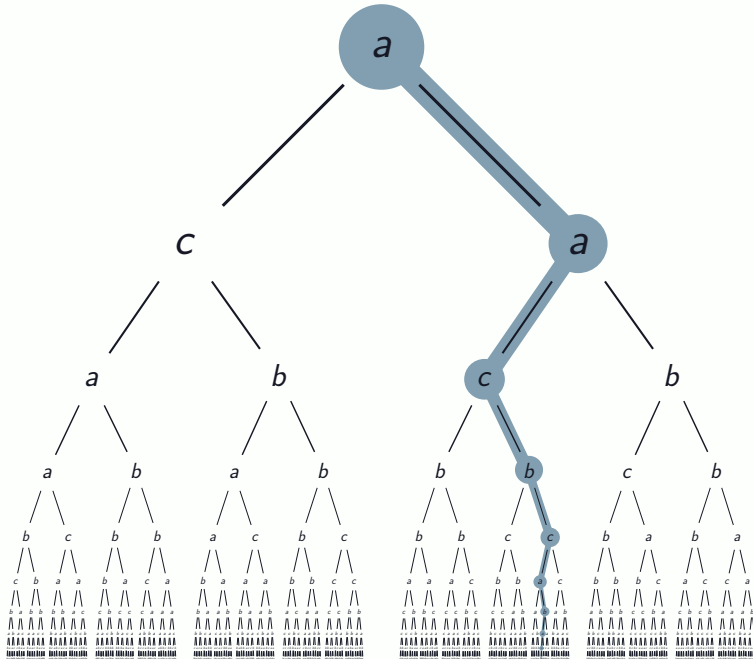
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$$L(\varphi) = \{t \in \text{Tr}_A \mid t \models \varphi\}$$

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Weak Monadic Second-order logic:

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Logics' zoo

(on infinite trees)

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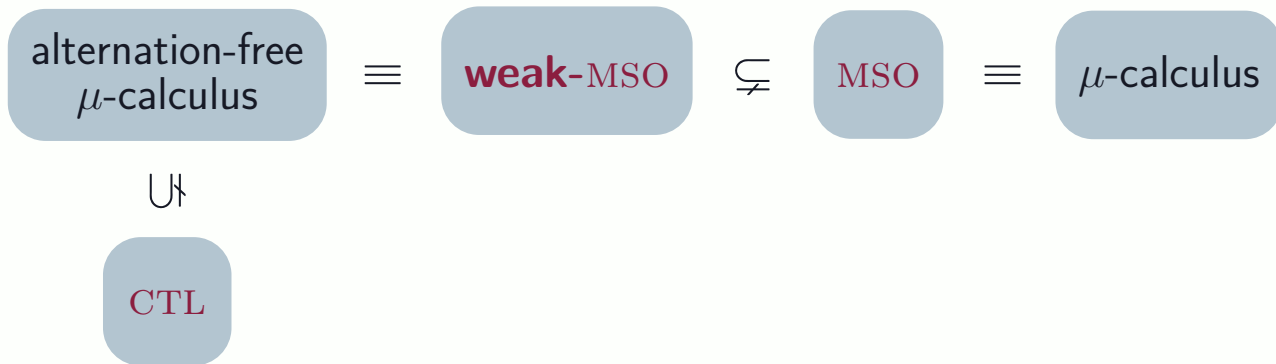
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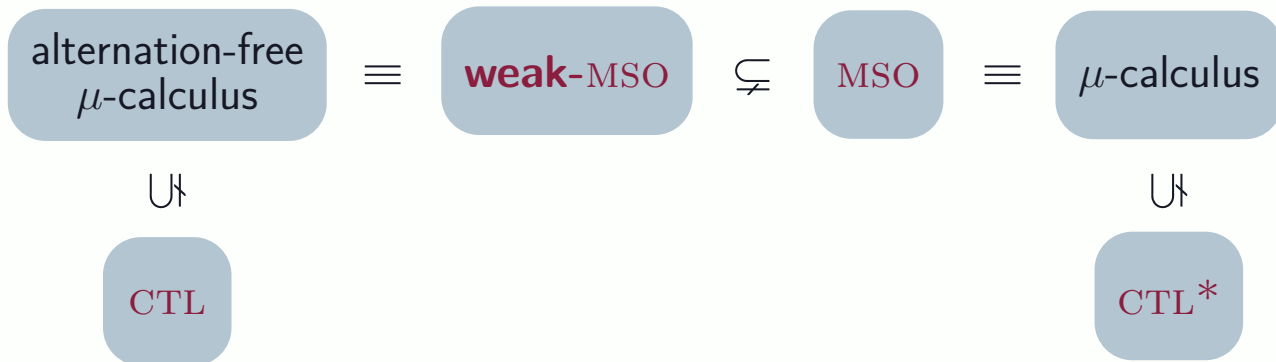
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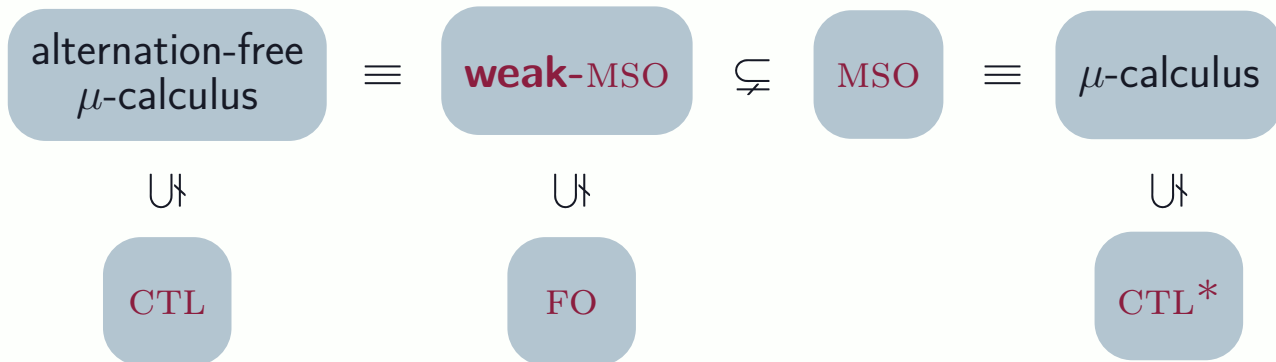
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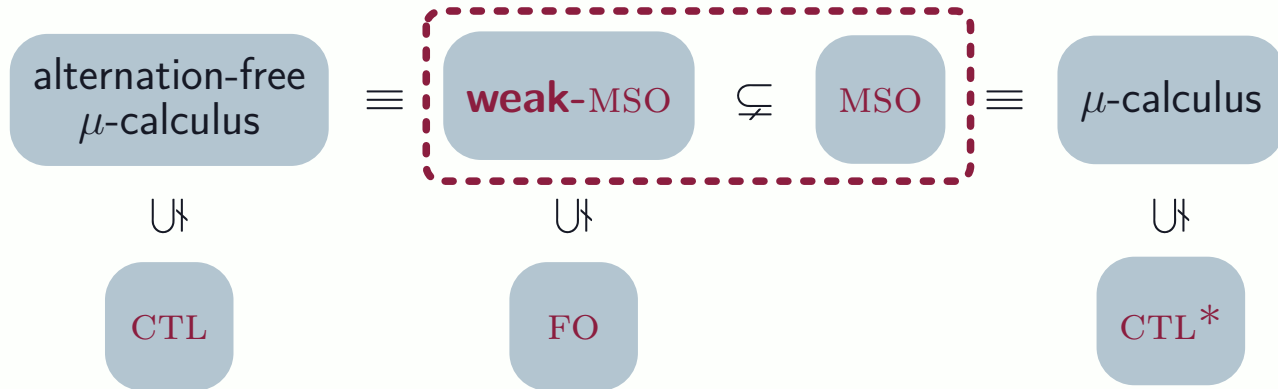
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Theorem (Gogacz, Michalewski, Mio, S. [2017])

Every regular language of infinite trees is **measurable**.

Example

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$$\varphi \equiv \forall B. \text{branch}(B) \Rightarrow \exists v \in B. a(v) \wedge (\forall u < v. b(u)) \wedge \text{even}(v)$$

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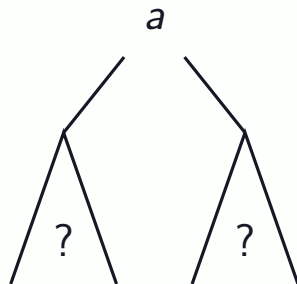
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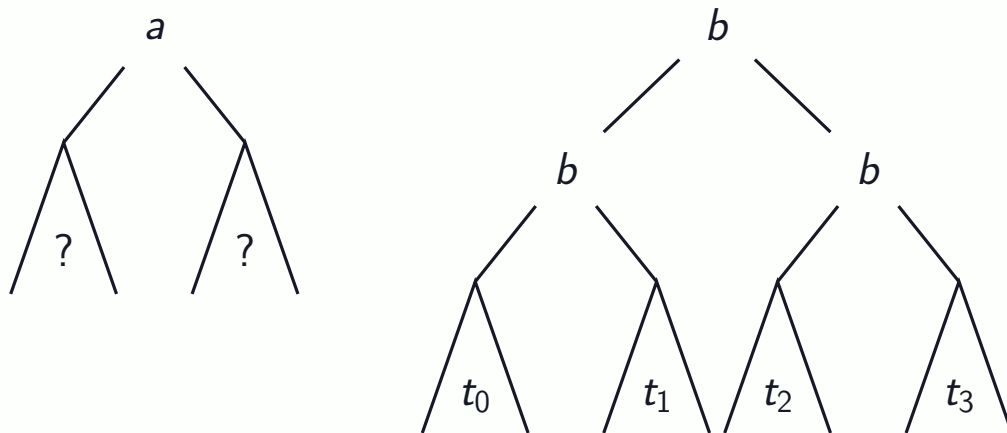
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$$t_0, t_1, t_2, t_3 \in L(\varphi)$$

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What if $x_0, x_1 \in [0, 1]$?

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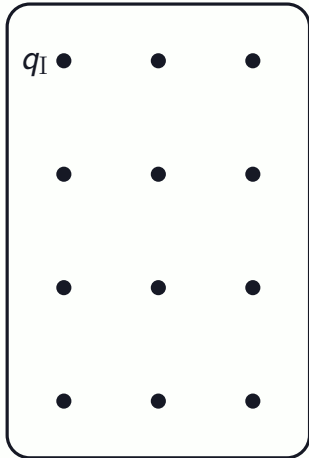
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CTL \subseteq weak-MSO \rightsquigarrow model checking of **stochastic branching processes**...

Weak-MSO \equiv Alternating weak parity automata
(Muller, Saoudi, Schupp [1986])

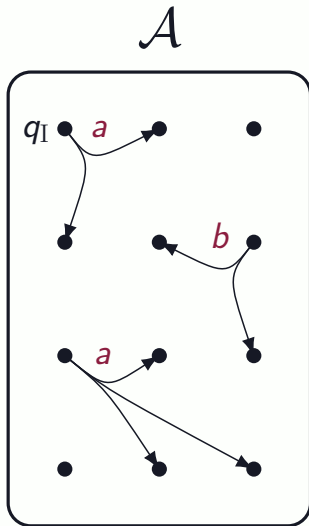
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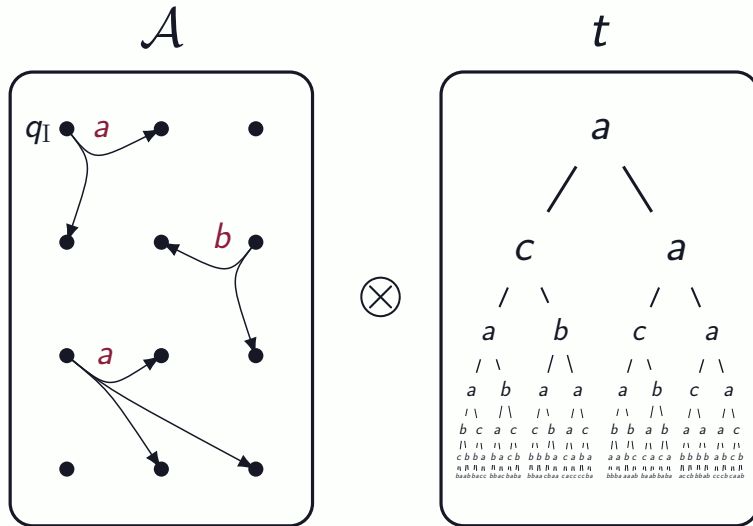
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\vdots \vdots \vdots \vdots

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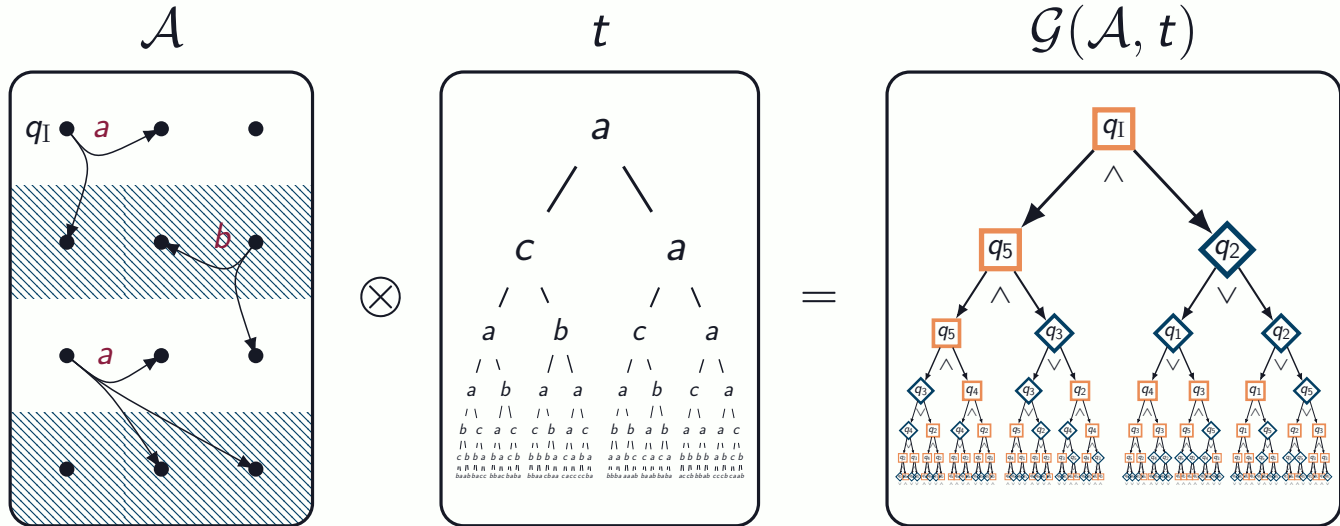
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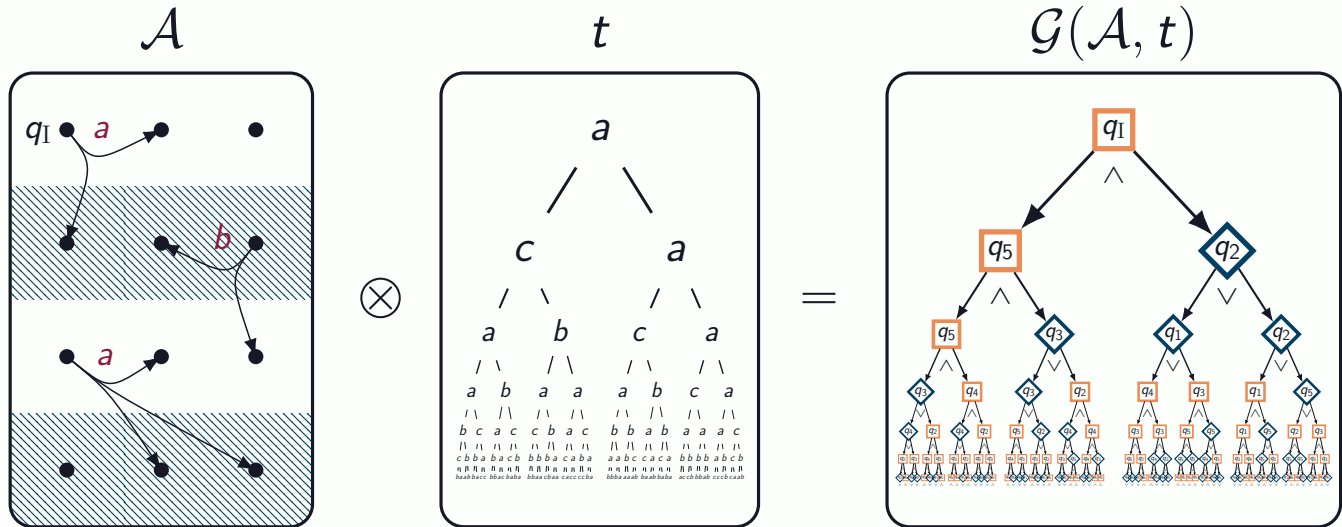
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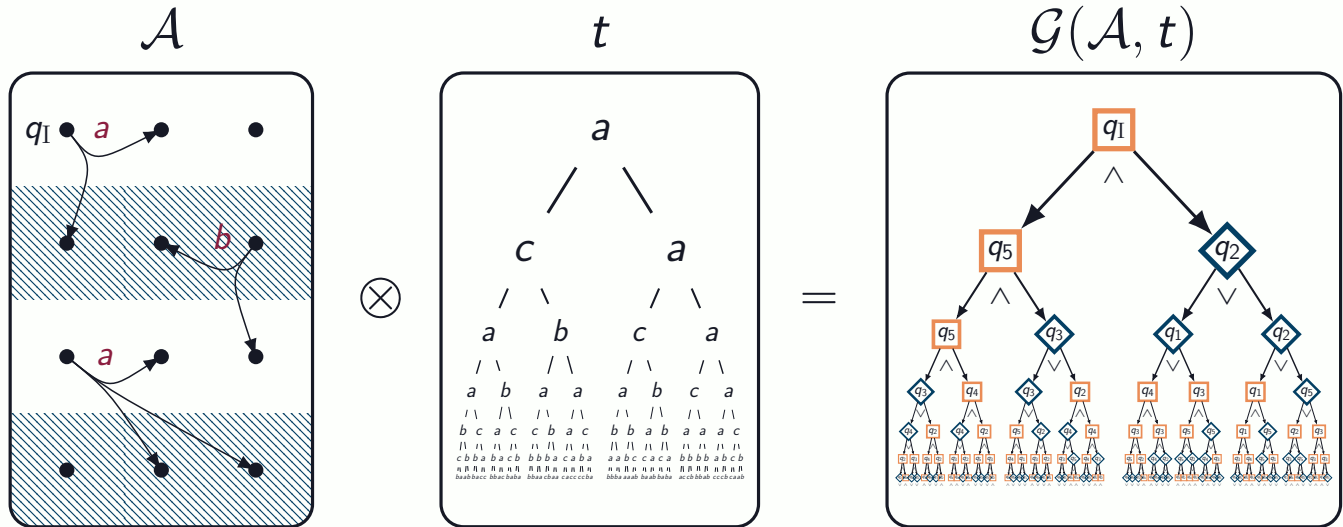


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Game played between \diamond and \square

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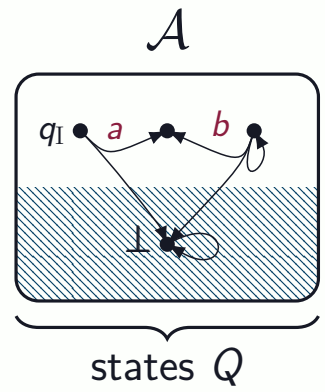
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Game played between \diamond and \square
 \diamond wins **iff** finitely many

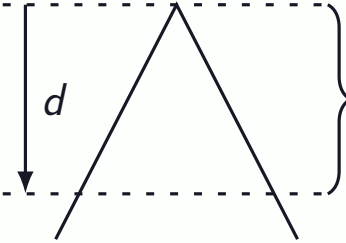
$$L(\mathcal{A}) = \left\{ t \in \text{Tr}_A \mid \diamond \text{ has a winning strategy in } \mathcal{G}(\mathcal{A}, t) \right\}.$$

Basic case: **safety automata**

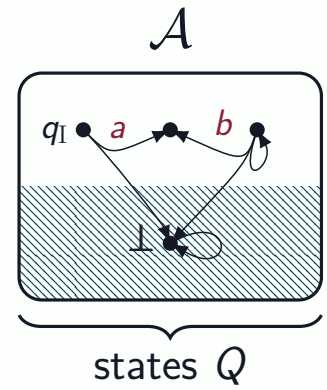
Basic case: safety automata



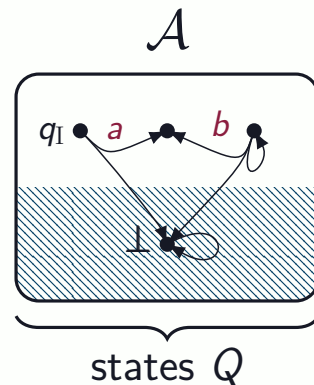
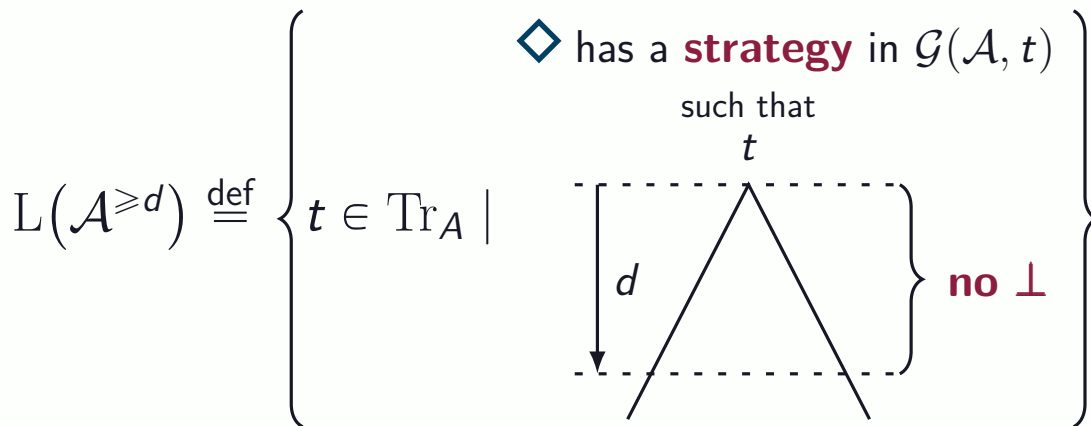
Basic case: safety automata

$$L(\mathcal{A}^{\geq d}) \stackrel{\text{def}}{=} \left\{ t \in \text{Tr}_A \mid \begin{array}{l} \diamond \text{ has a strategy in } \mathcal{G}(\mathcal{A}, t) \\ \text{such that} \\ \text{no } \perp \end{array} \right\}$$


The diagram shows a tree node t at the top. A vertical double-headed arrow labeled d indicates the distance from t to a horizontal dashed line below it. A bracket on the right side of this dashed line is labeled "no \perp ".

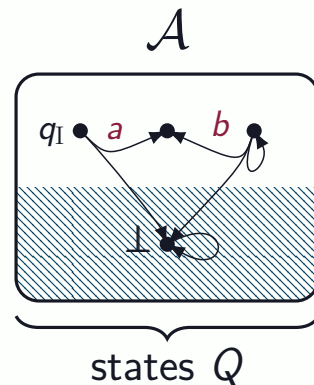
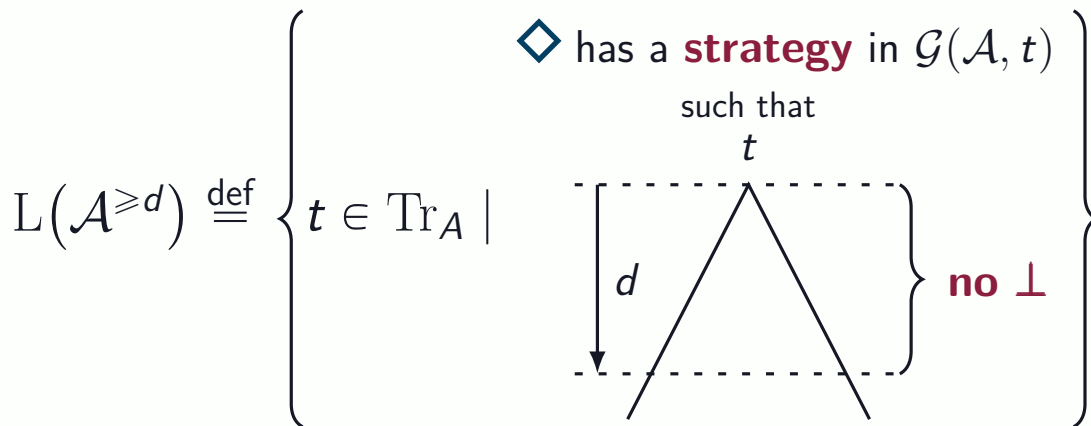


Basic case: **safety automata**



$$L(\mathcal{A}^{\geq 0}) \supseteq L(\mathcal{A}^{\geq 1}) \supseteq L(\mathcal{A}^{\geq 2}) \supseteq \dots \supseteq L(\mathcal{A})$$

Basic case: safety automata



$$L(\mathcal{A}^{\geq 0}) \supseteq L(\mathcal{A}^{\geq 1}) \supseteq L(\mathcal{A}^{\geq 2}) \supseteq \dots \supseteq L(\mathcal{A})$$

König's Lemma \rightsquigarrow

$$L(\mathcal{A}) = \bigcap_{d \in \mathbb{N}} L(\mathcal{A}^{\geq d})$$

From **languages** to **distributions**

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$$\text{tp}_{\mathcal{A}}: \text{Tr}_{\mathcal{A}} \longrightarrow \mathbb{P}(Q)$$

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From **languages** to **distributions**

$$\begin{aligned} \text{tp}_{\mathcal{A}}: \text{Tr}_{\mathcal{A}} &\longrightarrow \mathcal{P}(Q) \\ \text{tp}_{\mathcal{A}}(t) &\stackrel{\text{def}}{=} \{q \in Q \mid \blacklozenge \text{ wins } \mathcal{G}(\mathcal{A}, t) \text{ from } q\} \\ \left[t \in L(\mathcal{A}) \iff q_{\text{I}} \in \text{tp}_{\mathcal{A}}(t) \right] \end{aligned}$$

$$\mathbb{P} \text{ on } \text{Tr}_{\mathcal{A}} \rightsquigarrow \vec{\mathbb{P}}(\mathcal{A}) \text{ in } \underbrace{\mathcal{D}(\mathcal{P}(Q))}_{\text{probability distributions on } \mathcal{P}(Q)}$$

For $R \in \mathcal{P}(Q)$:

$$\vec{\mathbb{P}}(\mathcal{A})(R) \stackrel{\text{def}}{=} \mathbb{P}(\{t \in \text{Tr}_{\mathcal{A}} \mid \text{tp}_{\mathcal{A}}(t) = R\})$$

From **languages** to **distributions**

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From **languages** to **distributions**

$$\text{tp}_{\mathcal{A}}: \text{Tr}_A \longrightarrow P(Q)$$

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From languages to distributions

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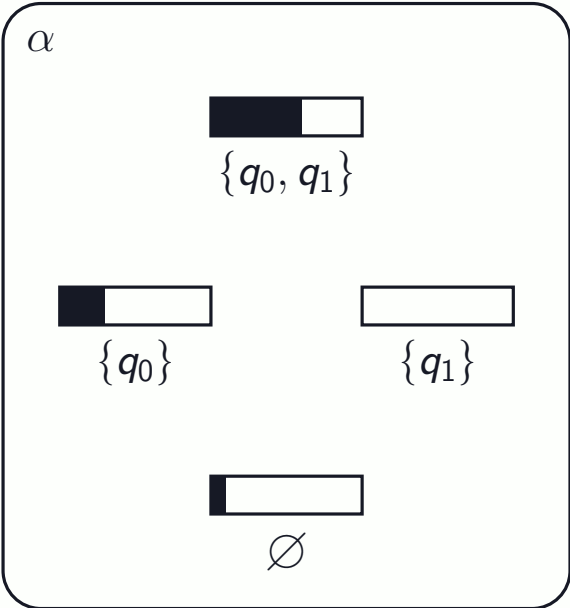
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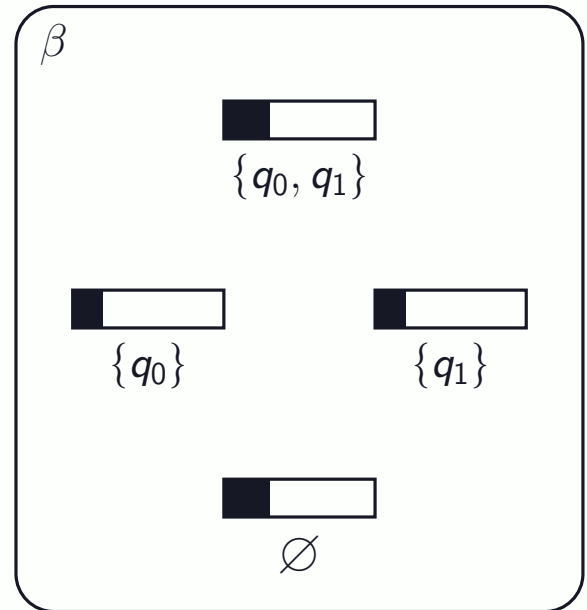
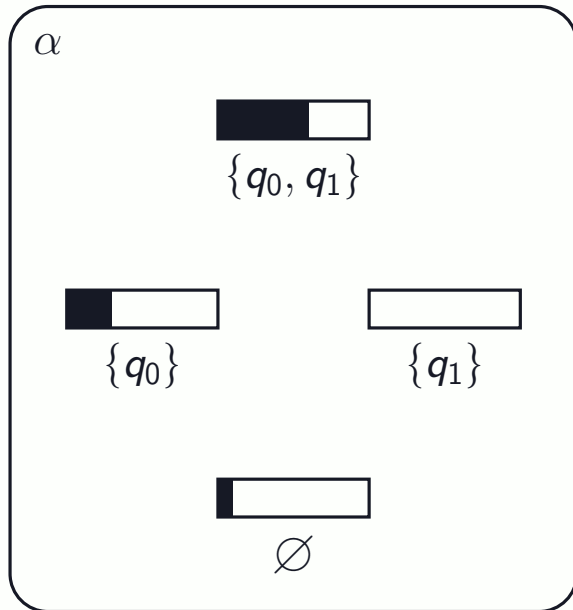
$$\begin{array}{ccccccc} L(\mathcal{A}^{\geq 0}) & \supseteq & L(\mathcal{A}^{\geq 1}) & \supseteq & L(\mathcal{A}^{\geq 2}) & \supseteq & \dots & \supseteq & L(\mathcal{A}) \\ \Downarrow & & \Downarrow & & \Downarrow & & & & \Downarrow \\ \vec{\mathbb{P}}(\mathcal{A}^{\geq 0}) & ??? & \vec{\mathbb{P}}(\mathcal{A}^{\geq 1}) & ??? & \vec{\mathbb{P}}(\mathcal{A}^{\geq 2}) & ??? & \dots & ??? & \vec{\mathbb{P}}(\mathcal{A}) \end{array}$$

Order on $\mathcal{D}(P(Q))$

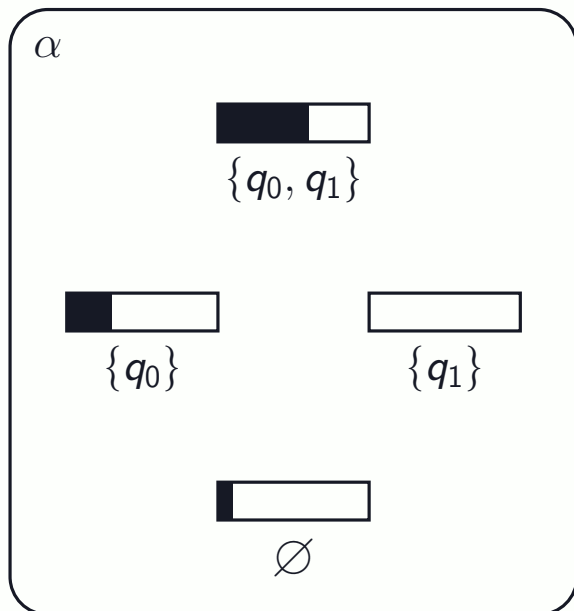
Order on $\mathcal{D}(P(Q))$



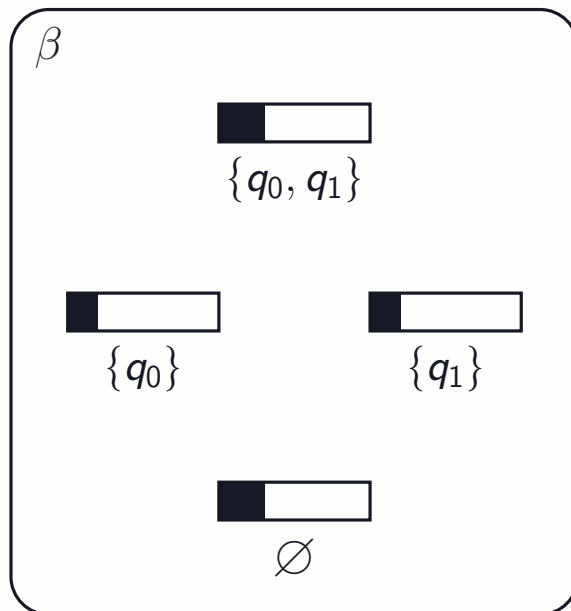
Order on $\mathcal{D}(P(Q))$



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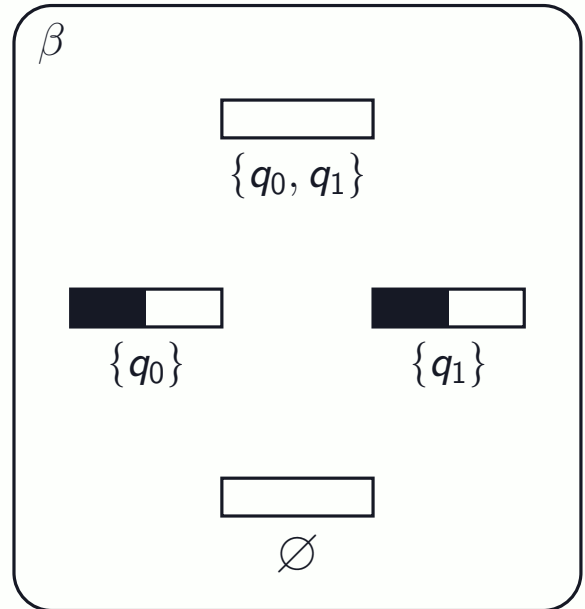
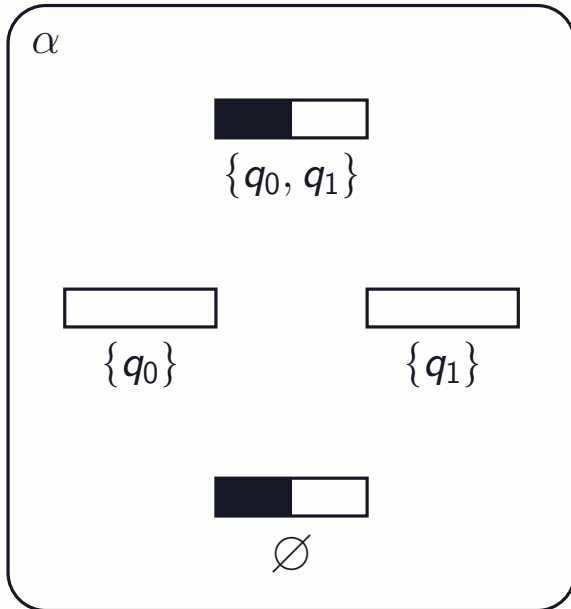


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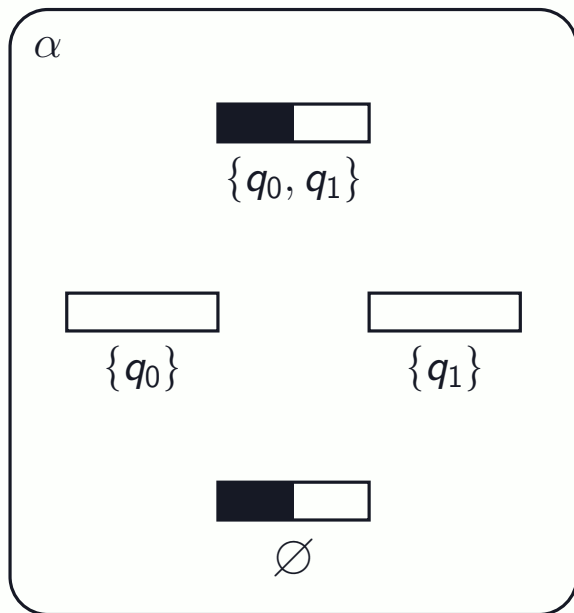


Order on $\mathcal{D}(P(Q))$

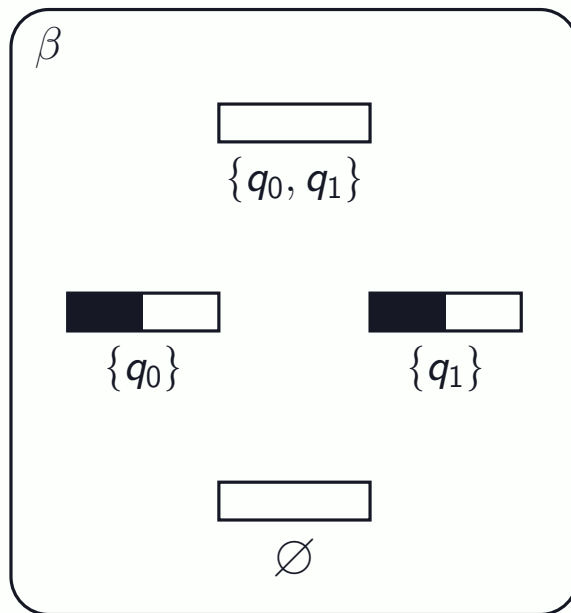
Order on $\mathcal{D}(P(Q))$



Order on $\mathcal{D}(P(Q))$



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Order on $\mathcal{D}(P(Q))$

Order on $\mathcal{D}(P(Q))$

$$\alpha \geq \beta$$

iff

$$\forall \mathcal{U} \subseteq P(Q), \mathcal{U} \text{ upward-closed. } \sum_{R \in \mathcal{U}} \alpha(R) \geq \sum_{R \in \mathcal{U}} \beta(R)$$

Order on $\mathcal{D}(P(Q))$

$$\alpha \geq \beta$$

“probabilistic powerdomains”

(Saheb-Djahromi [1980])

(Jones, Plotkin [1989])

iff

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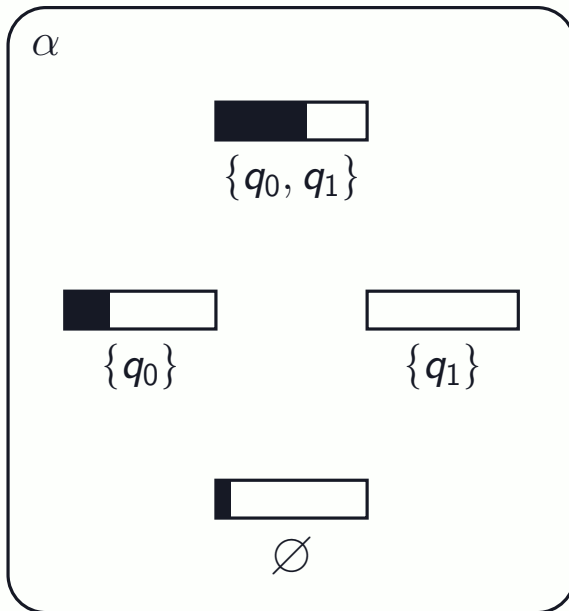
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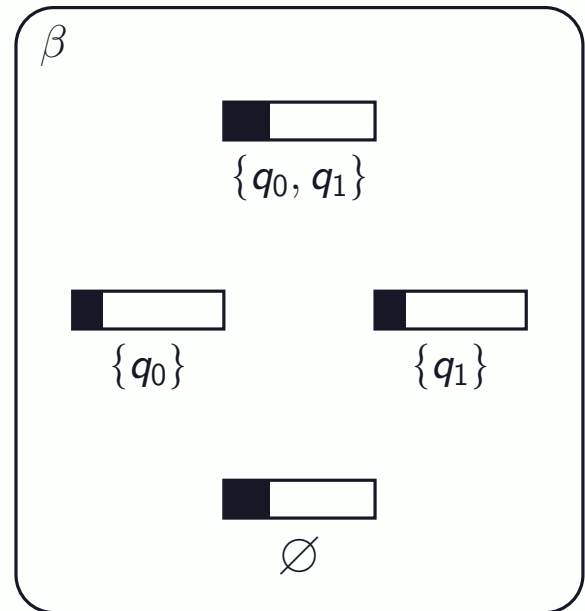
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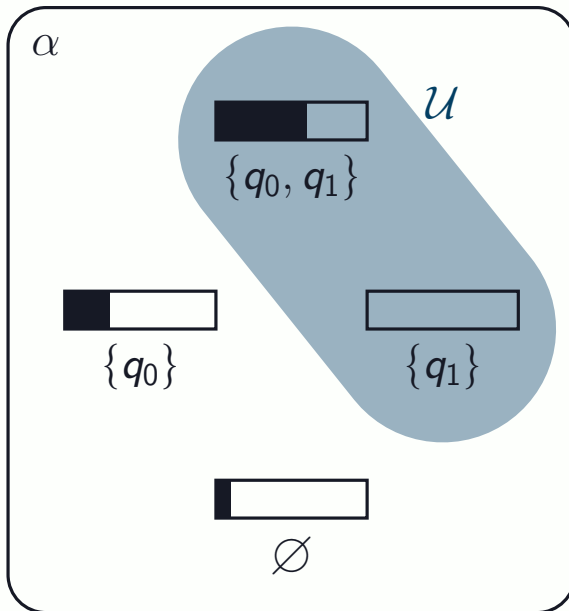
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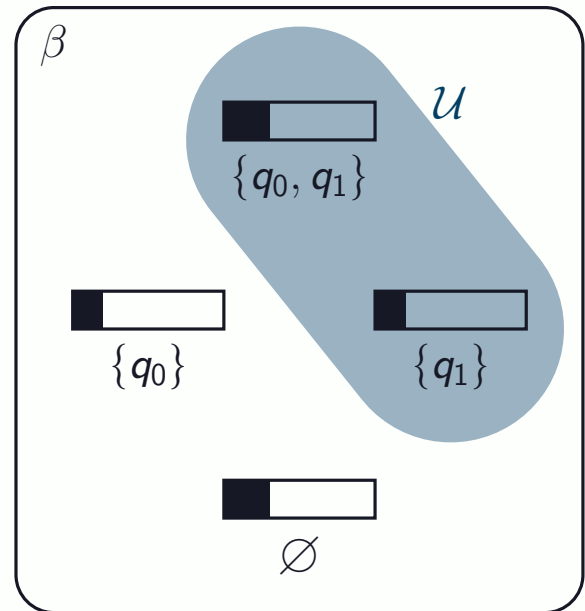
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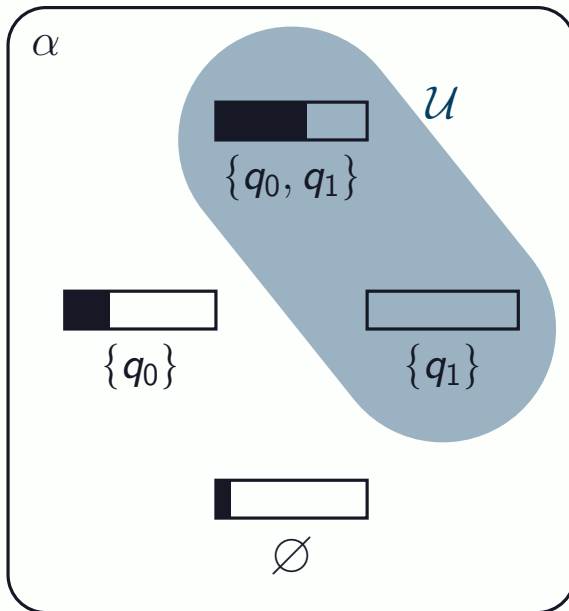
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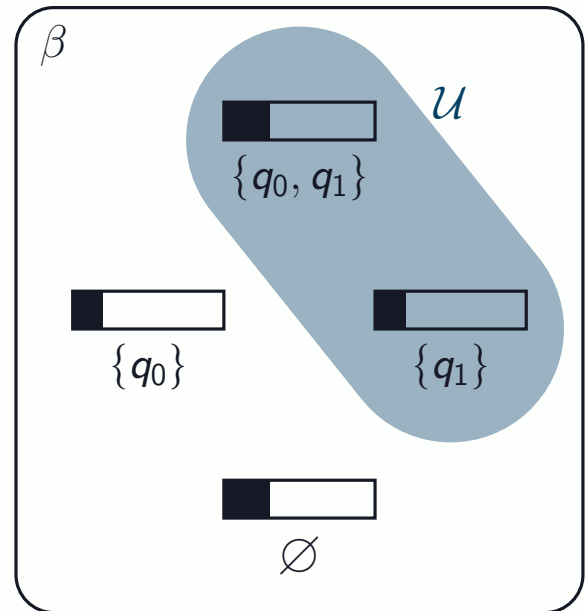
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$$\sum_{R \in \mathcal{U}} \alpha(R) = 0.6 + 0.0 = 0.6$$



$$0.5 = 0.3 + 0.2 = \sum_{R \in \mathcal{U}} \beta(R)$$

?

Order on $\mathcal{D}(P(Q))$

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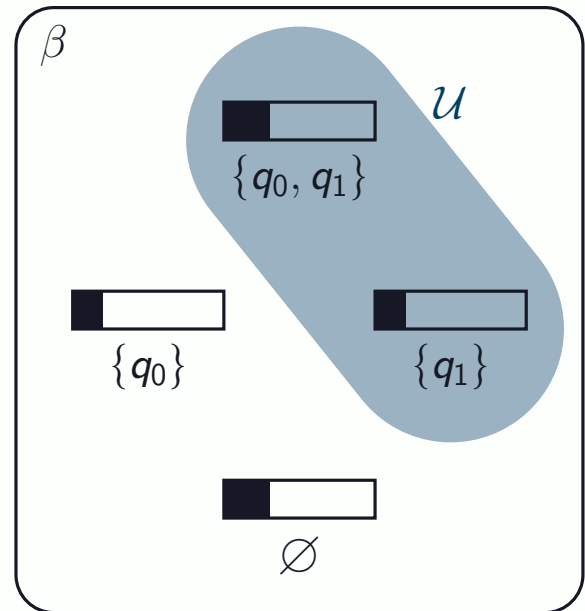
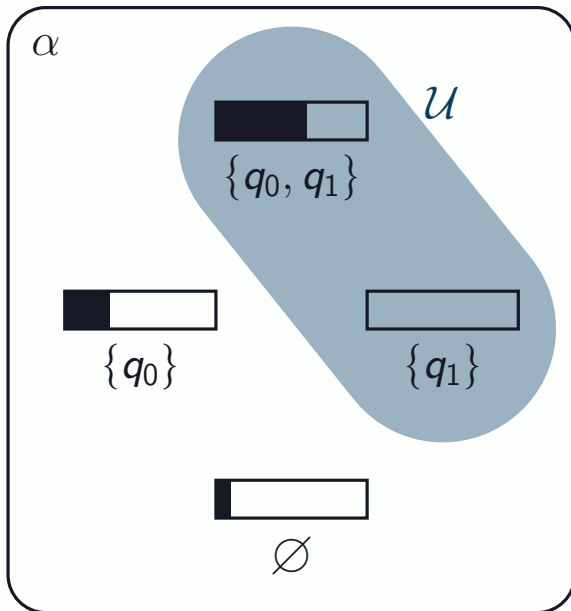
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Order on $\mathcal{D}(P(Q))$

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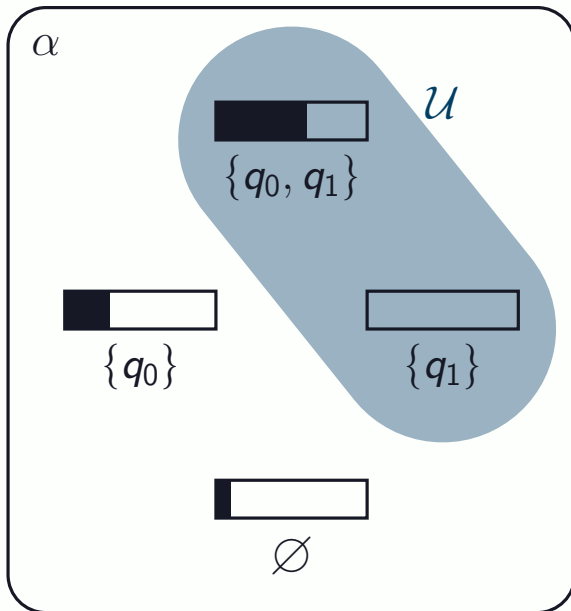
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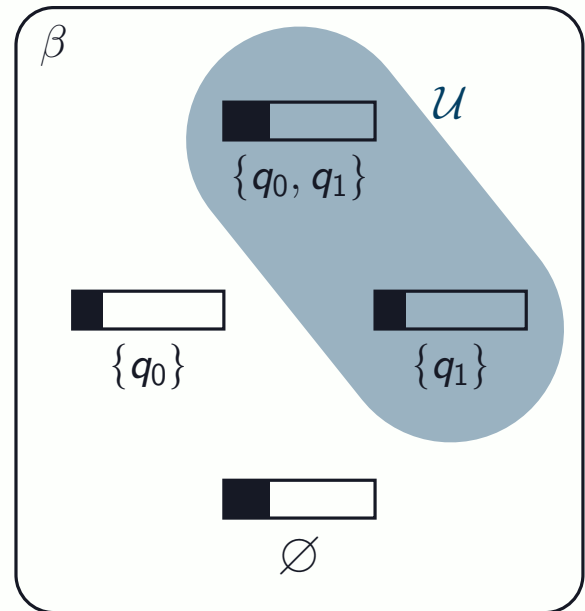
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$$L(\mathcal{A}) = \bigcap_{d \in \mathbb{N}} L(\mathcal{A}^{\geq d})$$

Order on $\mathcal{D}(\mathbb{P}(Q))$

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$\rightsquigarrow \vec{P}(\mathcal{A})$ is **definable** as a greatest **fixed point** in $\langle \mathcal{D}(P(Q)), \geq \rangle$

Order on $\mathcal{D}(\mathcal{P}(Q))$

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$$\forall \mathcal{U} \subseteq \mathcal{P}(Q), \mathcal{U} \text{ upward-closed. } \sum_{R \in \mathcal{U}} \alpha(R) \geq \sum_{R \in \mathcal{U}} \beta(R)$$

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$$\begin{array}{ccc} L(\mathcal{A}) = \bigcap_{d \in \mathbb{N}} L(\mathcal{A}^{\geq d}) & & \\ \Downarrow & & \Downarrow \\ \vec{\mathbb{P}}(\mathcal{A}) = \lim_{d \rightarrow \infty} \vec{\mathbb{P}}(\mathcal{A}^{\geq d}) & & [\text{in } \mathbb{R}^{\mathcal{P}(Q)}] \end{array}$$

$\rightsquigarrow \vec{\mathbb{P}}(\mathcal{A})$ is **definable** as a greatest **fixed point** in $\langle \mathcal{D}(\mathcal{P}(Q)), \geq \rangle$

using **First-order** theory of reals (Tarski [1951])

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