

A characterisation of Π_2^0 regular tree languages

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Abstract

We show an algorithm that for a given regular tree language L decides if $L \in \Pi_2^0$, that is if L belongs to the second level of Borel Hierarchy. Moreover, if $L \in \Pi_2^0$, then we construct a weak alternating automaton of index $(0, 2)$ which recognises L . We also prove that for a given language L , L is definable by a weak alternating $(1, 3)$ -automaton if and only if it is definable by a weak non-deterministic $(1, 3)$ -automaton.

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1 Introduction

Automata on infinite trees and the corresponding Monadic Second Order Logic provide a rich framework for expressing properties of regular languages of trees. Characterising natural subclasses of regular tree languages can be considered one of the fundamental problems related to automata on infinite trees. When we additionally require that the characterisation should be of an algorithmic nature, the problem usually turns to be very difficult and so far solved only in few instances.

► **Problem 1. (The Characterisation Problem)** For a given class of sets of trees \mathcal{C} design an algorithm which decides if a given regular tree language L belongs to \mathcal{C} .

Let us consider the problem for the following classes of tree languages: 1) languages definable in First Order Logic, 2) languages definable in Weak Monadic Second Order Logic, or 3) Borel languages. Providing an effective characterisation for any of the above classes among all regular languages of trees seems to be beyond the reach of currently available methods. In all the above instances it would be desirable to prove a dichotomy *simple* versus *difficult* languages; with *difficult* languages being characterised by existence of an embedding of a standard difficult language. In this work we resolve the **Characterisation Problem** for the case of $\mathcal{C} = \Pi_2^0$, i.e. for the set of languages that belong to the second level of the Borel hierarchy. A posteriori, it turns out that \mathcal{C} is the class of languages recognisable by weak alternating automata of *index* $(0, 2)$, that is the class of parity automata that involve priorities 0, 1, and 2; such that the transitions of the automaton are monotone wrt. priorities.

► **Theorem 1.** *If L is a regular tree language then either:*

- L can be recognised by a weak alternating $(0, 2)$ -automaton and so $L \in \Pi_2^0$,
- L cannot be recognised by a weak alternating $(0, 2)$ -automaton, $L \notin \Pi_2^0$, and L is Σ_2^0 -hard.

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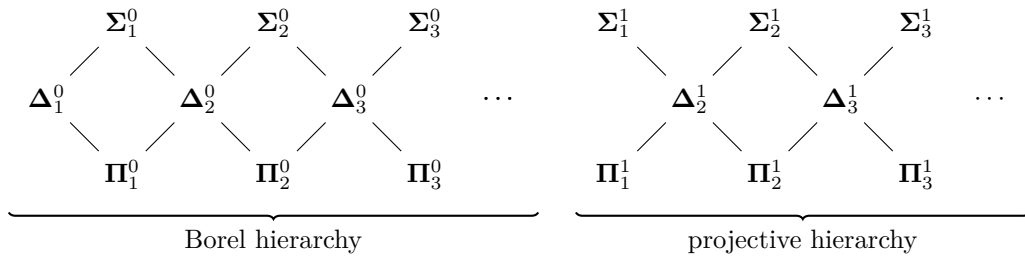


Moreover, it can be effectively decided which of the cases holds. If $L \in \Pi_2^0$ then a weak alternating $(0, 2)$ -automaton can effectively be constructed for L .

All regular languages of trees are Σ_2^1 sets and from Rabin's Complementation Theorem [20] follows that every regular language of trees is in the class Δ_2^1 . In the case of weak alternating automata (see e.g. [13]) one can provide a much more precise upper bound for the complexity:

► **Lemma 2** (See e.g. [6]). *If L is a language recognised by a weak alternating $(0, n)$ -automaton then $L \in \Pi_n^0$.*

Combining [24] and [6] we obtain that this is the optimal upper bound for the languages definable in Weak Monadic Second Order Logic.



■ **Figure 1** Borel and projective hierarchies.

The **Characterisation Problem** seems to be settled only for few families \mathcal{C} . The following list summarises all the cases which according to authors' knowledge have been considered in the literature so far, with the unrestricted input of general regular tree languages:

1. The simple case of clopen sets considered a mathematical folklore.
2. The case of open and closed sets, see [1, page 1] or [14, page 83-84]
3. The case of Boolean combinations of open sets settled in [1] using sophisticated algebraic methods.
4. The techniques of [1] were further reused in [7] to provide an effective characterisation of the class Δ_2^0 . However, as it turned out, the application of the tools of [1] presented in that paper was not correct and the proofs contain some missing arguments¹; as a corollary of the present article we also obtain another algorithm solving Problem 1 for the case $\mathcal{C} = \Delta_2^0$. Additionally, this paper provides a new automata theoretic observation: regular languages in Δ_2^0 belong to the respective delta class of the weak alternating index hierarchy: for any regular language L in Δ_2^0 there exist a weak alternating $(0, 2)$ -automaton and a weak alternating $(1, 3)$ -automaton that recognise L .
5. From [9] we know that regular tree languages occupy the first ω -levels of Kolmogorov's \mathcal{R} -hierarchy.

The following problem that can be seen as a reversed version of Lemma 2 requires a fine-grained analysis of Π_n^0 regular languages of trees:

► **Problem 2.** Given a regular tree language that belongs to Π_n^0 , does there exist a weak alternating $(0, n)$ -automaton that recognises it?

In the case of $n = 1$ the positive answer is considered folklore (it also follows from [1]), however for every $n > 1$ the problem was open. Our article gives the positive answer for the specific case when $n = 2$.

¹ The statement of Theorem 1 in [7] is correct but a critical combinatorial Proposition 5 requires a different and a more sophisticated argument which will be presented in a journal version of that work.

Related work

Characterising WMSO among Büchi automata. The proof presented in this paper is inspired by a characterisation [23] of Borel languages (as well as recognisable by all weak alternating automata) among the languages recognisable by Büchi automata. Although the similar structure of the proof and the idea behind the characterisation game \mathcal{F} , there are certain differences between the two proofs. Firstly, the structure of the game \mathcal{F} is much simpler here than in [23]. Moreover, the construction of the automata \mathcal{G}_K from Section 6 requires certain new ideas because we deal with arbitrary parity automata (in [23] the input is restricted to Büchi automata and the construction is just an unravelling of the respective game \mathcal{G}). In particular, in this work we introduce the concept of K -acceptance.

Deterministic and other special classes of languages. In absence of a method solving Problem 1 for all regular languages, a number of attempts was made for special families of regular languages [18, 17, 16, 8] that are recognised by automata with restricted forms of non-determinism.

Cost-MSO and counter automata. Another take on characterising various classes of languages via games can be found in [5, 4, 3]. The authors of this paper are not aware of results directly applicable to weak alternating parity automata of index (1, 3). However, as shown in this paper, weak non-deterministic parity automata of index (1, 3) are equivalent with weak alternating parity automata of the same index. Therefore, it seems feasible to obtain the automata-theoretic part (without the correspondence to topological classes) of Theorem 1 using the tools presented in [5, 12, 4].

2 Basic notions

Trees. Let us fix a finite alphabet A , that is just a finite non-empty set of symbols (e.g. $A = \{a, b\}$). We work on the space of labelled complete infinite binary trees over A . An A -labelled tree t (shortly *tree*) is a function $t: \{\mathsf{L}, \mathsf{R}\}^* \rightarrow A$ where the symbols L, R are called *directions*. The set of all A -labelled trees is denoted by Tr_A .

Elements $u \in \{\mathsf{L}, \mathsf{R}\}^*$ are called *nodes* of a tree. The elements $u_{\mathsf{L}}, u_{\mathsf{R}}$ are called *children* of u . The empty sequence ϵ is called the root of a tree. A *branch* of a tree is just an infinite sequence of directions $\beta \in \{\mathsf{L}, \mathsf{R}\}^\omega$. A node u is on a branch α if it is a prefix of α , i.e. $u \prec \alpha$. In that case $u = \alpha|_u$. If u is a node of a tree then by $t|_u$ we indicate the tree t truncated in u in the usual sense: $t|_u(w) \stackrel{\text{def}}{=} t(uw)$.

Topological complexity. In this work we use the standard topological notions for the space of infinite trees, see [11, 26]. The relevant topological notions in the context of infinite trees are described in Sections 1.6.1 and 1.6.2 of [22].

The space Tr_A with the standard product topology is known to be an uncountable Polish space (homeomorphic with the Cantor set). Thus, all the standard notions of Descriptive Set Theory naturally apply to trees.

Assume that \mathcal{X} is a topological space known from the context. By Σ_1^0 (resp. Π_1^0) we denote the set of open (resp. closed) sets in \mathcal{X} . The classes Σ_{n+1}^0 and Π_{n+1}^0 are defined inductively: Σ_{n+1}^0 contains countable unions of sets in Π_n^0 ; Π_{n+1}^0 contains countable intersections of sets in Σ_n^0 . In particular Σ_2^0 are countable unions of closed sets; this class is often denoted F_σ . Similarly, Π_2^0 are countable intersections of open sets; often denoted G_δ .

For a class Γ of sets (e.g. Π_2^0), we say that a set $Y \subseteq \mathcal{X}$ is Γ -hard if for every set $Y' \in \Gamma'$ that is in Γ there exists a continuous reduction $f: \mathcal{X}' \rightarrow \mathcal{X}$ such that $Y' = f^{-1}[Y]$. A set Y is Γ -complete if Y is Γ -hard and belongs to Γ .

Automata Theory. In this work we use both notions of *non-deterministic* and *alternating* parity tree automata. Again, we refer the reader to [19, 25]. The notation we use comes from Sections 1.3 and 1.4 of [22].

A *parity tree automaton* \mathcal{A} is a tuple $\mathcal{A} = \langle A^{\mathcal{A}}, Q^{\mathcal{A}}, q_1^{\mathcal{A}}, \Delta^{\mathcal{A}}, \Omega^{\mathcal{A}} \rangle$, where: $A^{\mathcal{A}}$ is the alphabet we are working on; $Q^{\mathcal{A}}$ is the set of *states* of the automaton \mathcal{A} ; $q_1^{\mathcal{A}}$ is a particular element of $Q^{\mathcal{A}}$ and it is called the *initial state*; $\Delta^{\mathcal{A}}$ will be defined in a moment; and $\Omega^{\mathcal{A}}$ is a function $\Omega^{\mathcal{A}}: Q^{\mathcal{A}} \rightarrow \omega$ that assigns a *priority* to every state of the automaton. If the automaton is known from the context then we omit the superscript \mathcal{A} .

An automaton \mathcal{A} is *non-deterministic* if $\Delta \subseteq Q \times A \times Q \times Q$ contains *transitions* of the form (q, a, q_L, q_R) . A non-deterministic automaton \mathcal{A} *accepts* a tree $t \in \text{Tr}_A$ if there exists an *accepting run* ρ , i.e. a $Q^{\mathcal{A}}$ -labelled tree that is consistent with the transitions of \mathcal{A} and the parity condition is satisfied on every branch β of t : $\limsup_{n \rightarrow \infty} \Omega(\rho(\beta \upharpoonright_n))$ is even.

An automaton \mathcal{A} is *alternating* if Δ is a function that assigns to each pair $q \in Q$, $a \in A$ a finite positive Boolean combination of pairs (d, q') where $d \in \{\text{L}, \text{R}\}$ is a direction and $q' \in Q$ is the consecutive state. For instance $\Delta(q, a)$ can be of the form $((\text{L}, q'_L) \wedge (\text{L}, q''_L)) \vee (\text{R}, q''_R)$.

An alternating automaton \mathcal{A} induces, for every tree $t \in \text{Tr}_A$, a parity game $\mathcal{A}(t)$ called the *acceptance game* of \mathcal{A} on t . \mathcal{A} *accepts* t if \exists has a winning strategy in the game $\mathcal{A}(t)$.

We require our automata to be *complete*, meaning that for every state $q \in Q$ and letter $a \in A$ there needs to be some transition.

For both non-deterministic and alternating tree automata \mathcal{A} we define the *language* of \mathcal{A} (denoted $L(\mathcal{A})$) as the set of all trees accepted by \mathcal{A} . It is known that the expressive power of non-deterministic and alternating automata is the same:

► **Theorem 3** ([10]). *Let $L \subseteq \text{Tr}_A$. There exists an alternating parity tree automaton \mathcal{A} such that $L(\mathcal{A}) = L$ if and only if there exists a non-deterministic parity tree automaton \mathcal{B} such that $L(\mathcal{B}) = L$. Moreover, both translations are effective.*

If for $L \subseteq \text{Tr}_A$ there exists a non-deterministic (equivalently alternating) automaton \mathcal{A} such that $L = L(\mathcal{A})$ then we say that L is *regular*. A parity automaton is *weak* if the values of Ω are non-decreasing along transitions. The *index* of an automaton is the pair (i, j) where i is the minimal and j is the maximal value of Ω on Q .

3 Overview of the proof of Theorem 1

Let L be a regular language and let us fix once and for all two non-deterministic parity tree automata \mathcal{A} and \mathcal{B} that recognise respectively: $L(\mathcal{B}) = L$ is the given language and $L(\mathcal{A}) = L^c$ is its complement. The proof will consist of the following steps:

- First we define a game \mathcal{F} of infinite duration and perfect information. The game \mathcal{F} is played by two players: Eve (\exists) and Adam (\forall). Player \exists constructs a tree t together with three runs: one of the automaton \mathcal{A} and two of the automaton \mathcal{B} . The second of them is influenced by \forall who can ask \exists to *restart* whenever he wants. The crucial property of the game \mathcal{F} is that it is played over a finite arena and the winning condition is ω -regular.
- If \exists wins \mathcal{F} then her winning strategy can be used to prove that the language $L(\mathcal{B})$ is actually Σ_2^0 -hard. In particular it cannot be recognised by a weak alternating automaton of index $(0, 2)$. To prove this topological hardness we test the winning strategy of \exists against a well-designed family of strategies of \forall . In terms of Descriptive Set Theory it can be seen as finding an embedding of the Cantor set 2^ω that intersects $L(\mathcal{B})$ on rationals.
- If \forall wins \mathcal{F} then we use his finite-memory winning strategy to construct a finite approximation of the automaton \mathcal{B} that is denoted \mathcal{G}_{K_0} . The construction ensures that \mathcal{G}_{K_0} is a weak alternating automaton of index $(0, 2)$ that recognises $L(\mathcal{B})$.

4 The game \mathcal{F}

We start by defining a game \mathcal{F} of infinite duration that is based on the non-deterministic parity tree automata $\mathcal{A} = \langle A, Q^{\mathcal{A}}, q_1^{\mathcal{A}}, \Delta^{\mathcal{A}}, \Omega^{\mathcal{A}} \rangle$ and $\mathcal{B} = \langle A, Q^{\mathcal{B}}, q_1^{\mathcal{B}}, \Delta^{\mathcal{B}}, \Omega^{\mathcal{B}} \rangle$ for L^c and L respectively. The purpose of \mathcal{F} is to satisfy the following two propositions.

- Proposition 4. If \exists wins \mathcal{F} then $L(\mathcal{B})$ is Σ_2^0 -hard.
- Proposition 5. If \forall wins \mathcal{F} then $L(\mathcal{B})$ is recognised by a weak alternating $(0, 2)$ -automaton.

The above propositions together with Lemma 2 give a complete characterisation of the topological complexity and the weak index of $L(\mathcal{B})$.

Positions of \mathcal{F} . The positions of \mathcal{F} are of the form $(p, q, s) \in Q^{\mathcal{A}} \times Q^{\mathcal{B}} \times Q^{\mathcal{B}}$ where: $p \in Q^{\mathcal{A}}$ is called an \mathcal{A} -state, $q \in Q^{\mathcal{B}}$ is called a \mathcal{B} -state, $s \in Q^{\mathcal{B}}$ is called an *active state*. The initial position of \mathcal{F} is $(q_1^{\mathcal{A}}, q_1^{\mathcal{B}}, q_1^{\mathcal{B}})$.

Rounds of \mathcal{F} . Assume that a round of \mathcal{F} starts in a position (p, q, s) . The choices done by the players are as follows:

1. \forall can choose to *restart* by letting $s' = q$ or to *stay* by keeping $s' = s$.
2. \exists declares: (i) a letter $a \in A$; (ii) a transition $(p, a, p_L, p_R) \in \Delta^{\mathcal{A}}$ of \mathcal{A} ; (iii) a transition $(q, a, q_L, q_R) \in \Delta^{\mathcal{B}}$ of \mathcal{B} ; (iv) another transition $(s', a, s'_L, s'_R) \in \Delta^{\mathcal{B}}$ of \mathcal{B} .
3. \forall responds by selecting a direction $d \in \{L, R\}$.

After such a round the game proceeds to the position (p_d, q_d, s'_d) . Four example rounds of \mathcal{F} are presented in Figure 2.

If π is a finite or infinite play of \mathcal{F} , a *trace* is a finite or infinite sequence of active states s in consecutive rounds in which \forall has not *restarted*. Thus, those active states come from successive transitions of the automaton \mathcal{B} .

Winning condition of \mathcal{F} . Now we will define the winning condition for \exists in \mathcal{F} . It will depend on a Boolean combination of the following three properties, speaking about the sequence of rounds that were played:

- (WR) \forall has *restarted* infinitely many times.
 - (WA) The sequence of \mathcal{A} -states p is accepting in \mathcal{A} .
 - (WB) The sequence of active states s is accepting in \mathcal{B} (i.e. it satisfies the parity condition).
- A play of \mathcal{F} is winning for \exists if it satisfies

$$((\text{WR}) \wedge (\text{WA})) \vee (\neg(\text{WR}) \wedge (\text{WB})). \quad (1)$$

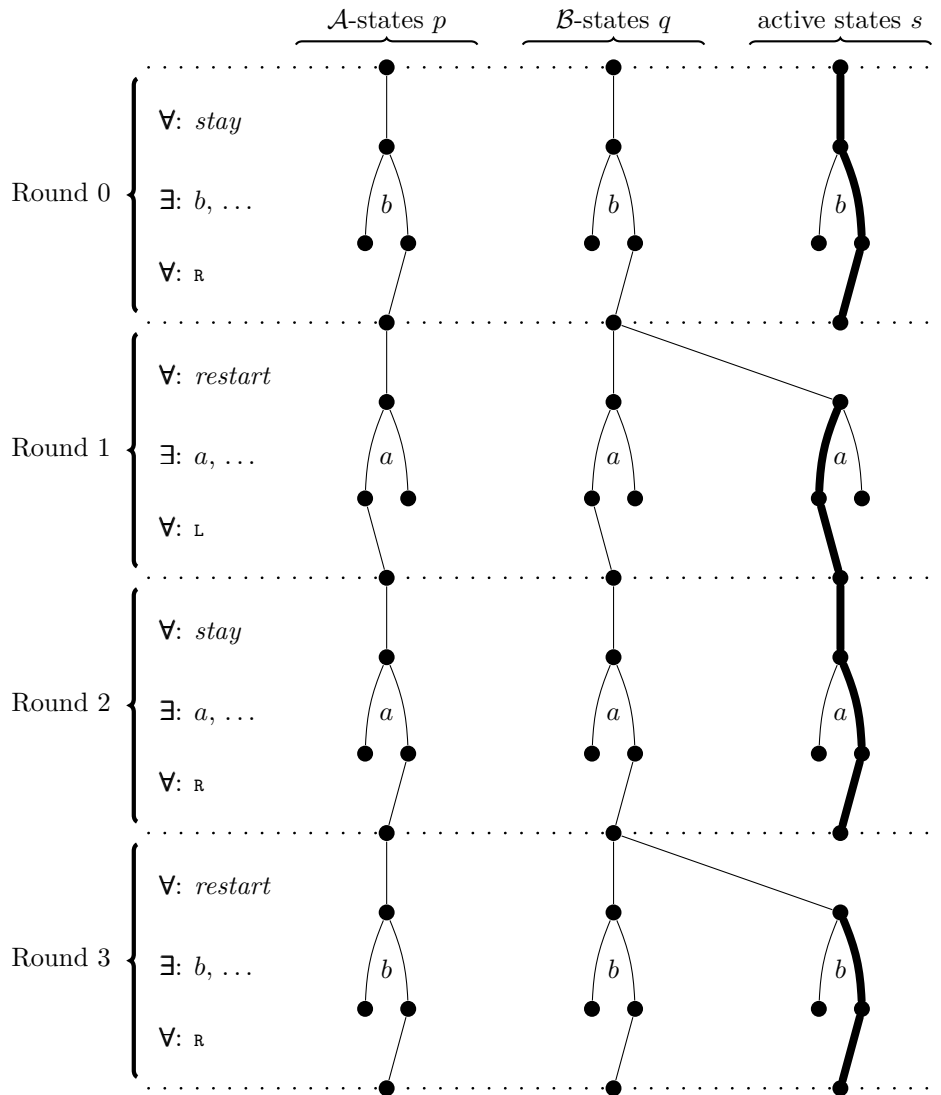
In other words, there are two cases: If \forall has restarted infinitely many times then \exists wins iff the sequence of visited \mathcal{A} -states satisfies the parity condition. If \forall has restarted only finitely many times then \exists wins iff the sequence of visited active states satisfies the parity condition. Notice that a priori both (WA) and (WB) can happen simultaneously, because for example there may exist two runs $\rho_{\mathcal{A}}$ and $\rho_{\mathcal{B}}$ of the automata \mathcal{A} and \mathcal{B} that both satisfy the parity condition on some particular branch.

By the definition, the winning condition of \mathcal{F} is an ω -regular property of sequences of rounds. Additionally, there are only finitely many positions of \mathcal{F} and each round allows finitely many possible choices by the players. Therefore, we obtain the following fact.

- Fact 6 ([2]). The winner of \mathcal{F} can be effectively found and he/she can win using a finite memory winning strategy.

5 Proof of Proposition 4

In this section we prove that if \exists wins \mathcal{F} then $L(\mathcal{B})$ is Σ_2^0 -hard. Let σ_{\exists} be her winning strategy. Let $C \subseteq \{0, 1\}^{\omega}$ be the set of sequences containing only finitely many 1s.



■ **Figure 2** Four consecutive rounds of the game \mathcal{F} . The black dots are the states of the automata \mathcal{A} and \mathcal{B} . Each round consists of three choices: first \forall either *restarts* or *stays*, then \exists provides a letter and three transitions (depicted by those Λ -shaped gadgets), finally \forall chooses a direction. The three boldfaced paths are three traces formed by the active states: the first one lasts in Round 0; the second one in Rounds 1 and 2; the third one starts in Round 3.

It is known that C is Σ_2^0 -complete [26]. We will construct a continuous reduction from C to $L(\mathcal{B})$ and so we obtain that $L(\mathcal{B})$ is Σ_2^0 -hard.

We will say that σ is a *quasi-strategy* of \forall in \mathcal{F} if σ specifies when to *restart* and leaves undecided the choice of directions d . Notice that if σ is a quasi-strategy of \forall then we can construct a tree t consisting of the letters a played by σ_{\exists} against σ : the letter $t(u)$ is the $(|u|+1)$ th letter played by σ_{\exists} against \forall playing accordingly to σ and choosing successive directions of u .

To each sequence $\alpha \in \{0, 1\}^\omega$ we will assign a quasi-strategy σ_α of \forall in \mathcal{F} . Consider $\alpha \in \{0, 1\}^\omega$ and an M th round of \mathcal{F} for $M = 0, 1, \dots$

- If $\alpha(M) = 0$ then σ_α *stays* by keeping $s' = s$.
- If $\alpha(M) = 1$ then σ_α *restarts* by putting $s' = q$.

Let the tree t_α be the effect of confronting the strategy σ_{\exists} against the quasi-strategy σ_α . Since the behaviour of the strategy σ_α in an M th round of \mathcal{F} depends only on the first M bits of α , the function $\alpha \mapsto t_\alpha$ is continuous. A routine verification (see below) shows that

$$\alpha \in C \iff t_\alpha \in L(\mathcal{B}). \quad (2)$$

When $\alpha \in C$. First assume that $\alpha \in C$, i.e. that there are only finitely many 1s in α . Let M be the maximal number such that $\alpha(M-1) = 1$ (or $M = 0$ if there is no such M). Let $\rho^{\mathcal{B}}$ be the run of \mathcal{B} defined as follows:

- For $|u| \leq M$ let $\rho^{\mathcal{B}}(u)$ be the \mathcal{B} -state q from the beginning of the $|u|$ th round of the play consistent with σ_{\exists} and σ_α in which the sequence of directions chosen by \forall was u .
- For $|u| > M$ let $\rho^{\mathcal{B}}(u)$ be the active state s from the beginning of the $|u|$ th round of the play consistent with σ_{\exists} and σ_α in which the sequence of directions chosen by \forall was u .

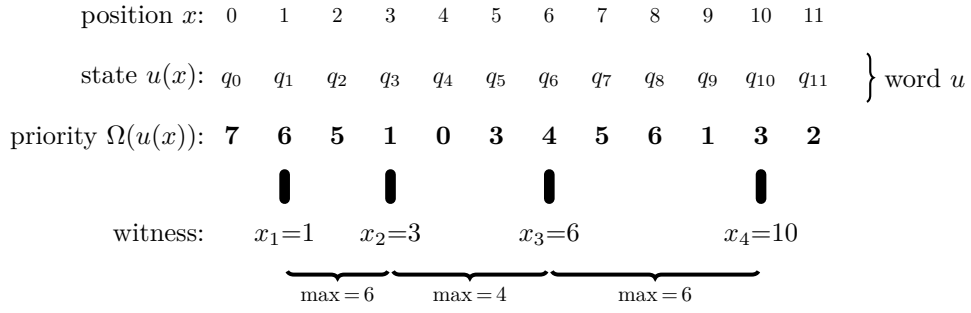
It is easy to see that $\rho^{\mathcal{B}}$ is in fact a run of \mathcal{B} over t_α . It remains to see that it is accepting. Consider an infinite branch of t_α . This branch corresponds to an infinite play of \mathcal{F} consistent with σ_{\exists} and the quasi-strategy σ_α . Since in all the rounds after the M th one, \forall has *stayed* by putting $s' = s$, the states of $\rho^{\mathcal{B}}$ form an infinite trace in that play. Therefore, the condition $\neg(\text{WR})$ holds. As the play is won by \exists , also (WB) must hold. It means that the trace must be accepting in \mathcal{B} , thus the run $\rho^{\mathcal{B}}$ is accepting on our branch. This way we have proved that $\rho^{\mathcal{B}}$ is accepting and $t_\alpha \in L(\mathcal{B})$.

When $\alpha \notin C$. Now assume that $\alpha \notin C$, i.e. that there are infinitely many 1s in α . Our aim is to prove that the run $\rho^{\mathcal{A}}$ formed by the \mathcal{A} -states p played by \exists in all the plays consistent with σ_{\exists} and σ_α is accepting. Consider an infinite branch of t_α and the corresponding play π of \mathcal{F} . Since infinitely many times \forall has *restarted*, this play satisfies (WR) . As the play is won by \exists , also (WA) must hold. It means that the sequence of \mathcal{A} -states p must be accepting in \mathcal{A} . Thus, we have proved that $t_\alpha \in L(\mathcal{A})$ and therefore $t_\alpha \notin L(\mathcal{B})$. This concludes the proof of Σ_2^0 -hardness of $L(\mathcal{B})$.

6 Proof of Proposition 5

In this section we prove that if \forall wins \mathcal{F} then $L(\mathcal{B})$ can be recognised by a weak alternating parity automaton of index $(0, 2)$. Since the winning condition of \mathcal{F} is ω -regular, we can assume that \forall wins using a strategy σ_{\forall} based on a finite-memory structure M . Our aim is to construct an automaton recognising $L(\mathcal{B})$.

K -accepting runs. We start by defining a notion of K -accepting sequences — sequences of states of \mathcal{B} that are similar to accepting ones. We will show that the strategy σ_{\forall} must avoid such sequences.



■ **Figure 3** A word u that is 4-accepting. The sequence x_1, x_2, x_3, x_4 witnesses that. If we loop u between the positions 1 and 6, we get the sequence $q_0, q_1, \dots, q_6, q_1, q_2, \dots, q_6, q_1 \dots$ that satisfies the parity condition.

Let u be a finite or infinite sequence of states of \mathcal{B} . Consider a number $K \in \omega$. We say that u is K -accepting if there exists a sequence of positions $0 \leq x_1 < x_2 < \dots < x_K < |u|$ such that for every $n = 1, 2, \dots, K - 1$ we have:

$$\max \left\{ \Omega^{\mathcal{B}}(u(x)) \mid x_n \leq x \leq x_{n+1} \right\} \text{ is even.} \quad (3)$$

In other words, for $n = 1, \dots, K - 1$, the maximal priority of states between positions x_n and x_{n+1} of u must be even. We call such a sequence of positions (x_1, \dots, x_K) a *witness* of K -acceptance, see Figure 3.

The above definition is constructed in such a way to guarantee the following properties:

- (P1) If u is K -accepting then it contains K positions such that each cycle built using an interval between two of them gives us a sequence of states satisfying the parity condition.
- (P2) For every K , the set of all finite words that are K -accepting is regular. It is not obvious how a regular expression for this language should look like, however, the definition of the property of being K -accepting is clearly MSO-definable, thus by the results of Rabin, Scott [21], and Trakhtenbrot [27] (cf. e.g. [19]), we know that this language is regular.
- (P3) If u is K -accepting then every word of the form uw is also K -accepting.
- (P4) If $\alpha \in (Q^{\mathcal{B}})^{\omega}$ satisfies the parity condition then for every $K \in \omega$ there exists a finite prefix of α that is K -accepting.

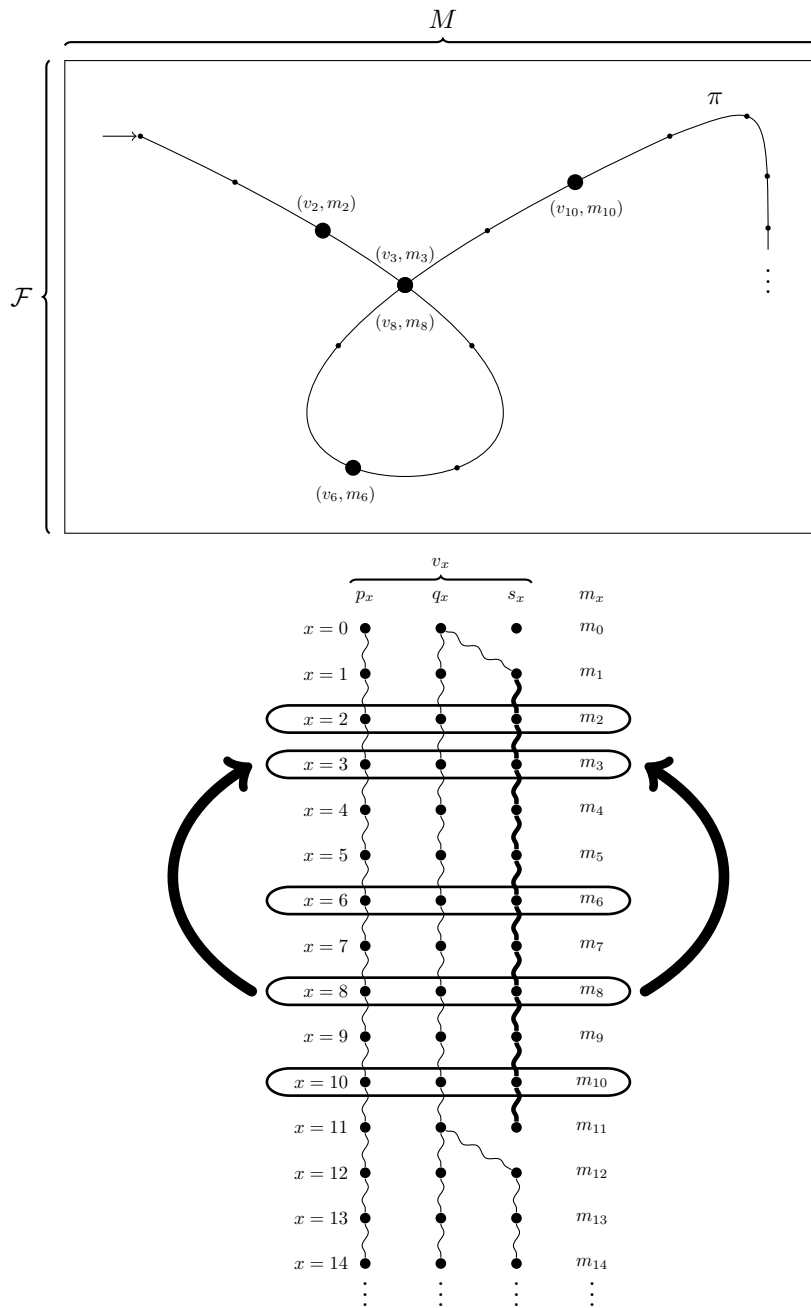
► **Lemma 7.** *There exists a value $K_0 \in \omega$ such that if π is an infinite play of \mathcal{F} consistent with $\sigma_{\mathcal{V}}$ then no trace of π is K_0 -accepting.*

Proof. Let $K_0 \stackrel{\text{def}}{=} \left(|Q^{\mathcal{A}}| \times |Q^{\mathcal{B}}| \times |Q^{\mathcal{B}}| \right) \times |M| + 1$ where inside the brackets is the number of positions of \mathcal{F} and M is the memory structure of $\sigma_{\mathcal{V}}$.

Assume for the sake of contradiction that there exists a play π that is consistent with $\sigma_{\mathcal{V}}$ and contains a K_0 -accepting trace. For a round number $x \in \omega$ during π let (v_x, m_x) be the configuration of the game at the moment when x rounds were played: $v_x = (p_x, q_x, s_x)$ for an \mathcal{A} -state p_x , \mathcal{B} -state q_x , and active state s_x ; and m_x is the current memory value of $\sigma_{\mathcal{V}}$.

By the assumption we know that for some $x < y < \omega$ the sequence of active states s_x, s_{x+1}, \dots, s_y is a trace (i.e. there is no *restart* during these rounds) and it is K_0 -accepting. Let $x \leq x_1, \dots, x_{K_0} \leq y$ be a sequence of numbers of rounds that is a witness for the K_0 -acceptance of this trace, see Equation (3).

Figure 4 provides an illustration for this construction. The upper picture presents a play π seen in the product of the game \mathcal{F} and the memory structure M used by $\sigma_{\mathcal{V}}$. Small dots



■ **Figure 4** An illustration to the proof of Lemma 7.

mark positions before successive rounds of this play. The lower picture presents the play π in a chronological way. The boldfaced vertical snake-like shape is a trace that is 5-accepting; the rounded shapes indicate a witness of this fact: $x_1 = 2$, $x_2 = 3$, $x_3 = 6$, $x_4 = 8$, and $x_5 = 10$. Since 5 is bigger than the number of available pairs (v, m) we have a repetition: $(v_3, m_3) = (v_8, m_8)$. This allows us to construct a new play π' , by staying forever on the loop between the rounds 3 and 8. The play π' obtained this way contains an infinite trace that satisfies the parity condition.

By the choice of K_0 we know that for some $1 \leq n < n' \leq K_0$ we have: $v_{x_n} = v_{x_{n'}}$ and $m_{x_n} = m_{x_{n'}}$; i.e. there must be a repetition of the position of \mathcal{F} and the memory of σ_{\forall} among the positions witnessing K_0 -acceptance of the trace.

Consider a play π' of \mathcal{F} which starts as π for the first x_n rounds. Then π' follows the loop between the rounds $x_n + 1$ and $x_{n'}$. Notice that π' is in fact a play because $v_{x_n} = v_{x_{n'}}$. Since we have chosen the positions $x_n, x_{n'}$ from a trace, this loop does not contain a *restart*. Clearly π' is consistent with σ_{\forall} because the memory values m_{x_n} and $m_{x_{n'}}$ are equal.

Because x_n and $x_{n'}$ are chosen from a witness of K_0 -acceptance of the trace, Property (P1) implies that π' contains an infinite accepting trace. Therefore, the play π' satisfies $(\neg(\text{WR}) \wedge (\text{WB}))$ and thus is winning for \exists in \mathcal{F} , what contradicts the assumption that σ_{\forall} was a winning strategy of \forall . \blacktriangleleft

Construction of automata \mathcal{G}_K . Take a number $K \in \omega$. We will now define a weak alternating parity automaton \mathcal{G}_K of index $(0, 2)$. The language $L(\mathcal{G}_K)$ will be an over-approximation of $L(\mathcal{B})$. Later on we will prove that the strategy σ_{\forall} witnesses the fact that $L(\mathcal{B})$ actually equals $L(\mathcal{G}_K)$ for some $K \in \omega$ (in fact for $K = K_0$ from Lemma 7).

The idea behind the automaton \mathcal{G}_K is the following: \mathcal{G}_K accepts a tree t if there exists a run $\rho_0^{\mathcal{B}}$ of \mathcal{B} over t such that for every node u of the tree, it is possible to find another run of \mathcal{B} over the subtree $t|_u$ starting from the state $\rho_0^{\mathcal{B}}(u)$ that is K -accepting on every branch of this subtree.

Assume that $\mathcal{D}(K) = \langle Q^{\mathcal{B}}, Q^{\mathcal{D}}, q_1^{\mathcal{D}}, \Delta^{\mathcal{D}}, F^{\mathcal{D}} \rangle$ is a deterministic automaton over finite words (DFA) with the alphabet $Q^{\mathcal{B}}$ that recognises the language of K -accepting sequences of states of \mathcal{B} , see Property (P2).

The states of \mathcal{G}_K are of the form (q, τ) where $q \in Q^{\mathcal{B}}$ is a state of \mathcal{B} and $\tau \in \{?\} \sqcup Q^{\mathcal{D}}$ is either ? or a state of $\mathcal{D}(K)$.

The initial state of \mathcal{G}_K is $(q_1^{\mathcal{B}}, ?)$. The transitions of \mathcal{G}_K are built by the following rules. Given a state (q, τ) and a letter a , the successive state and direction are constructed in the following way (formally the following choices should be encoded as a finite positive Boolean combination of the consecutive directions and states).

1. If $\tau = ?$ then \forall can choose to *start* by letting $\tau' = q_1^{\mathcal{D}}$ or to *skip* by keeping $\tau' = ?$. If $\tau \in Q^{\mathcal{D}}$ then \forall has no choice and in that case $\tau' = \tau$.
2. If $\tau' \in Q^{\mathcal{D}}$ then we let² $\tau'' = \Delta^{\mathcal{D}}(\tau, q)$, otherwise $\tau'' = \tau' = ?$ is unchanged.
3. \exists proposes a transition of \mathcal{B} of the form (q, a, q_L, q_R) .
4. \forall chooses a direction $d \in \{\mathcal{L}, \mathcal{R}\}$.

After these choices are done, the automaton moves in the direction d to the state (q_d, τ'') . Let the priority of a state (q, τ) of \mathcal{G}_K be: (i) If $\tau = ?$ then the priority is 0. (ii) If $\tau \in Q^{\mathcal{D}} \setminus F^{\mathcal{D}}$ then the priority is 1. (iii) If $\tau \in F^{\mathcal{D}}$ then the priority is 2.

² We follow the transition of \mathcal{D} from τ over q : $\tau \in Q^{\mathcal{D}}$ is a state of \mathcal{D} and $q \in Q^{\mathcal{B}}$ is a letter read by \mathcal{D} .

Notice that because of the structure of the transitions of \mathcal{G}_K , the above defined condition is a weak parity condition of index $(0, 2)$. It is important to notice that Property (P3) implies that once a state of priority 2 is reached then we never move to a state of priority 1.

► **Lemma 8.** *For every $K \in \omega$ we have $L(\mathcal{B}) \subseteq L(\mathcal{G}_K)$.*

Proof. Take a tree $t \in L(\mathcal{B})$ and let $\rho^{\mathcal{B}}$ be an accepting run of \mathcal{B} on t . Then clearly \exists can win the acceptance game $\mathcal{G}_K(t)$ by just playing consecutive transitions of $\rho^{\mathcal{B}}$. When \forall chooses at some point to *start*, ultimately a state with $\tau \in F^{\mathcal{D}}$ will be reached because of Property (P4). Therefore, every play will be won by \exists . ◀

Equivalence. We will now conclude the proof of Proposition 5 using the following lemma.

► **Lemma 9.** *For K_0 from Lemma 7 we have $L(\mathcal{G}_{K_0}) = L(\mathcal{B})$.*

Proof. Assume contrarily that $L(\mathcal{G}_{K_0}) \neq L(\mathcal{B})$. Lemma 8 says that $L(\mathcal{B}) \subseteq L(\mathcal{G}_{K_0})$, so there must exist a tree $t \in L(\mathcal{G}_{K_0}) \setminus L(\mathcal{B})$. From that assumption we know that:

- there exists an accepting run $\rho^{\mathcal{A}}$ of \mathcal{A} over t ,
- \exists has a winning strategy δ_{\exists} in the acceptance game $\mathcal{G}_{K_0}(t)$.

Our aim is to prove that \exists can win in \mathcal{F} against σ_{\forall} by using a strategy σ_{\exists} that is based on $\rho^{\mathcal{A}}$ and δ_{\exists} . Let us define the strategy σ_{\exists} .

First, σ_{\exists} plays the letters a and the transitions of \mathcal{A} from the \mathcal{A} -states p according to the tree t and the run $\rho^{\mathcal{A}}$. This way we guarantee that every play of this strategy will satisfy (WA). Additionally σ_{\exists} chooses the transitions of \mathcal{B} from the \mathcal{B} -states q according to the strategy δ_{\exists} simulating the situation that \forall has never *started*. Thus, at every moment of a play consistent with σ_{\exists} , there is a unique play of δ_{\exists} ending in a node u and a state of \mathcal{G}_{K_0} of the form $(q, ?)$ with u being the sequence of directions played so-far by \forall in \mathcal{F} and q being the current \mathcal{B} -state. What remains is the choice of transitions of \mathcal{B} from the active states s . For that, \exists will keep track of a play of the acceptance game $\mathcal{G}_{K_0}(t)$ with $\tau \in Q^{\mathcal{D}}$. At the initial position of \mathcal{F} the play is the one which begins by \forall *starting* (i.e. $\tau = q_1^{\mathcal{D}}$). Whenever \forall *restarts* in \mathcal{F} , \exists forgets about the previously tracked play of $\mathcal{G}_{K_0}(t)$ and begins to track the play that comes with the current \mathcal{B} -state q by simulating the situation in which \forall has just *started* in $\mathcal{G}_{K_0}(t)$.

Consider the play π that is consistent with both σ_{\exists} and σ_{\forall} . We need to prove that π is winning for \exists . As we have already observed, such a play satisfies (WA). We will prove that it also satisfies (WR) by proving the following claim. This concludes the proof of Lemma 9 by giving a contradiction: σ_{\forall} is a winning strategy of \forall but π is a play consistent with σ_{\forall} that is winning for \exists .

► **Claim 10.** In the play π Player \forall must have *restarted* infinitely many times.

Assume contrarily that from some point on \forall has not *restarted*. Thus, π contains an infinite trace on which \exists has played successive transitions of \mathcal{B} in the active states s according to her strategy δ_{\exists} in $\mathcal{G}_{K_0}(t)$. Since the strategy δ_{\exists} is winning, some prefix of the considered trace must be K_0 -accepting. This gives a contradiction with Lemma 7. ◀

7 Weak non-deterministic $(1, 3)$ -automata

In this section we prove the following additional result that may be considered folklore, although we have not found it in the literature. The construction is based on the standard de-alternation techniques together with the idea from [15].

► **Theorem 11.** *If L is a language that can be recognised by a weak alternating parity automaton \mathcal{A} of index $(1, 3)$ then L can be recognised by a weak non-deterministic parity automaton \mathcal{B} of index $(1, 3)$.*

This observation was important to properly define the game \mathcal{F} . However, somehow surprisingly, it does not play any role in the final proof of Theorem 1.

The idea of the proof is as follows. Given a tree $t \in \text{Tr}_A$ the automaton \mathcal{B} will guess a positional strategy of \exists in the acceptance game $\mathcal{A}(t)$. Then it will verify that the guessed strategy is in fact winning. Therefore, it will track all the possible choices performed by \forall along all the branches of the tree t . Thus, the set of states of \mathcal{B} is the power set $\mathcal{P}(Q^{\mathcal{A}})$. Notice that the guessed strategy of \exists is winning if for every branch of t the following conditions are satisfied: (i) no state of \mathcal{A} of priority 3 is ever reached, (ii) every play ultimately reaches a state of priority 2.

An easy application of König’s lemma shows that the second condition above actually implies that at some point no state of priority 1 can belong to the set of reachable states of \mathcal{A} . This way, the automaton \mathcal{B} can be seen as a naïve power set construction over \mathcal{A} . Such a construction can be performed for any alternating automaton (even not weak), however, in most of the cases the assignment of priorities to the states of the power set automaton is not correct. The crucial ingredient of this construction relies on the fact that the weak parity condition of index $(1, 3)$ admits a correct priority assignment for the power set automaton.

8 Conclusions and further work

This work provides a relatively simple effective characterisation of the class of regular languages in Π_2^0 . Additionally, it proves that the considered class of languages coincides with the respective level of the alternating index hierarchy (i.e. weak alternating $(0, 2)$ -automata).

The simplicity of involved techniques comes from certain specific properties of the considered classes. Firstly, there are ω -regular languages that are complete for the class Π_2^0 . In our case the examples are: the language C of infinite binary sequences containing infinitely many 1s; and the property (WR) used in the winning condition of the game \mathcal{F} . Secondly, similarly to the case of Büchi languages, the class of weak alternating $(1, 3)$ -automata admits a dealternation technique, see Theorem 11. Although this dealternation result does not play any role in the proof of Theorem 1, it was used in the design of the game \mathcal{F} and stays behind the fact that the game actually characterises the class of languages recognisable by weak alternating $(0, 2)$ -automata.

We plan to investigate generalisations of Theorem 1 to Π_n^0 for $n \geq 3$. Since decidability results related to the **Characterisation Problem** are not that easy to obtain, we propose for further investigation the topological problems related to the **Characterisation Problem** and Problem 2 formulated in Introduction.

Moreover, our work gives a quite clear situation up to the second level of Borel Hierarchy in terms of decidability and correspondence between the Borel index and the weak index, but there are still some “holes” that have to be filled regarding e.g. *Wadge Hierarchy*:

► **Problem 3.** Find all Wadge degrees inhabited by regular Δ_2^0 languages of trees.

From [6] it follows that every Wadge degree less than ω^ω is inhabited by a regular language. We believe that this is the maximum regular languages can get:

► **Conjecture 1.** There is no regular tree language in Δ_2^0 with Wadge degree above ω^ω .

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A Polish Spaces and Borel Hierarchy

When we work in Descriptive Set Theory, the class of topological spaces that we study is the class of the so-called *Polish spaces*:

► **Definition 12.** Let (X, \mathcal{T}) be a topological space. X is said a *Polish space* if \mathcal{T} is a completely metrisable topology and X is separable.

Well-known examples of Polish spaces are: \mathbb{R} , \mathbb{C} , 2^ω , ω^ω , ...

The general goal of Descriptive Set Theory is to stratify subsets of Polish spaces by using some useful hierarchies. One of the most natural topological hierarchies is *Borel Hierarchy*. Let us see the formal definition:

► **Definition 13.** Let (X, \mathcal{T}) be a topological space. Let ω_1 be the first uncountable ordinal. By a transfinite recursion, we construct *Borel Hierarchy* of X by defining the following classes of subsets of X :

1. The class $\Sigma_1^0(X)$ is the class of open sets of \mathcal{T} . When X is clear from the context, we write just Σ_1^0 instead of $\Sigma_1^0(X)$. For all the other classes we are going to define we avoid to write X not to be too pedantic.
2. For any $1 \leq \xi < \omega_1$, we define the class $\Pi_\xi^0 = \{Y \subseteq X \mid Y^c \in \Sigma_\xi^0\}$, where Y^c is the complement of Y .
3. For any $1 < \xi < \omega_1$, we define

$$\Sigma_\xi^0 = \left\{ \bigcup_n Y_n \mid Y_n \in \Pi_{\xi_n}^0, \xi_n < \xi, n \in \omega \right\}.$$

4. For any $1 \leq \xi < \omega_1$, we define:

$$\Delta_\xi^0 = \Sigma_\xi^0 \cap \Pi_\xi^0.$$

Moreover, the class of the *Borel sets* of X is the union:

$$\text{Borel} = \bigcup_{\xi < \omega_1} \Sigma_\xi^0 = \bigcup_{\xi < \omega_1} \Pi_\xi^0 = \bigcup_{\xi < \omega_1} \Delta_\xi^0.$$

When we work with uncountable Polish spaces, Borel Hierarchy is a very useful tool because it turns out that the hierarchy does not collapse until the level ω_1 , so as a matter of fact the hierarchy is strict. Later on we will define the space of trees labelled over a finite alphabet, that is an uncountable Polish space. In this article we will focus on the class Π_2^0 of this space (often denoted by G_δ).

► **Definition 14.** Let Γ be a class of sets in Polish spaces (e.g. $\Gamma = \Pi_2^0$). Let X be a Polish space. We say that $Y \subseteq X$ is Γ -hard if there exists a zero-dimensional Polish space X' such that for any $Z \in \Gamma(X')$ there exists a continuous function $f: X' \rightarrow X$ such that $f^{-1}[Y] = Z$, where

$$f^{-1}[Y] = \{x \in X' \mid f(x) \in Y\}.$$

Moreover, if $Y \in \Gamma(X)$, we call Y Γ -complete.

Now let us introduce the standard topology on infinite trees.

► **Definition 15.** A *prefix* p is a partial function $p: \{L, R\}^* \rightarrow A$ with a finite and prefix-closed domain $\text{dom}(p)$. If t is an A -labelled tree, we write $p \subset t$ if $p(u) = t(u)$ for any $u \in \text{dom}(p)$.

► **Definition 16.** On Tr_A we can define the *prefix topology*: a base of this topology is given by the sets of all the trees that extend a given prefix p :

$$N_p \stackrel{\text{def}}{=} \{t \in \text{Tr}_A \mid p \subset t\}.$$

► **Fact 17.** Tr_A with the prefix topology is an uncountable Polish topological space.

B Automata

In this section of Appendix we provide more formal definitions of non-deterministic and alternating tree automata.

A *run* of a non-deterministic automaton over a tree $t \in \text{Tr}_A$ is a map $\rho: \{L, R\}^* \rightarrow Q$ (i.e. it is a Q -labelled tree) such that $\rho(\epsilon) = q_I$ and $(\rho(u), t(u), \rho(u_L), \rho(u_R)) \in \Delta$ for any $u \in \{L, R\}^*$. A run ρ is *accepting* if for every branch β of t , the sequence of states of ρ on β satisfies the *parity condition*, i.e. the highest priority repeating infinitely often is even. In symbols:

$$\limsup_{n \rightarrow \infty} \Omega(\rho(\beta|_n)) \text{ is even, for any path } \beta \in \{L, R\}^\omega \text{ of } t.$$

An infinite tree t is *accepted* by a non-deterministic automaton \mathcal{A} if there exists a run ρ of \mathcal{A} on t that is accepting.

An alternating tree automaton \mathcal{A} induces, for every tree $t \in \text{Tr}_A$, a parity game $\mathcal{A}(t)$ called the *acceptance game* of \mathcal{A} on t . The positions of this game are of the form (u, ϕ) where $u \in \{L, R\}^*$ is a node of the tree and ϕ is either a finite positive Boolean combination of $Q \times \{L, R\}$ or a state of \mathcal{A} . The initial position is (ϵ, q_I) .

- A position of the form $(u, \phi \vee \psi)$ is controlled by Player \exists , she can choose to move either to (u, ϕ) or (u, ψ) .
- Dually, a position of the form $(u, \phi \wedge \psi)$ is controlled by Player \forall , he can choose to move either to (u, ϕ) or (u, ψ) .
- Positions of the form $(u, (d, q))$ are deterministic, the only available move from them is to the position (ud, q) .
- Positions of the form (u, q) are also deterministic, the only available move from them is to the position $(u, \Delta(q, t(u)))$.

An infinite play π of $\mathcal{A}(t)$ is winning for \exists if the sequence of states visited during the play satisfies the parity condition. The automaton \mathcal{A} *accepts* a tree $t \in \text{Tr}_A$ if \exists has a winning strategy in the game $\mathcal{A}(t)$.

We require our automata to be *complete*, meaning that for every state $q \in Q$ and letter $a \in A$ there needs to be some transition: in the case of non-deterministic automata, Δ must contain a tuple of the form (q, a, q_L, q_R) ; in the case of alternating automata, $\Delta(q, a)$ needs to be a non-empty Boolean combination.

A parity automaton is *weak* if the values of Ω are non-decreasing along transitions: in the case of non-deterministic automata it means that for every $(q, a, q_L, q_R) \in \Delta$ we have $\Omega(q) \leq \Omega(q_L)$ and $\Omega(q) \leq \Omega(q_R)$; in the case of alternating automata it means that if (d, q') appears in $\Delta(q, a)$ then $\Omega(q) \leq \Omega(q')$.

B.1 Proof of Property (P4)

We need to prove that if $\alpha \in (Q^B)^\omega$ satisfies the parity condition and $K \in \omega$ then α contains a prefix that is K -accepting. Assume that the maximal priority that appears infinitely often on α is k . Since α is accepting, k is even. Let M be a position on α such that if $M' \geq M$ then

$\Omega^{\mathcal{B}}(\alpha(M')) \leq k$, i.e. no priorities higher than k appear after M in α . Since the priority k appears infinitely many times in α , we can find K positions $M < x_1 < \dots < x_K$ such the priority of α in them equals k . Now clearly (x_1, \dots, x_K) is a witness of K -acceptance of $\alpha \upharpoonright_{x_{K+1}}$ because the maximal priority that appears in-between every two positions x_n and x_{n+1} is exactly k .

C Dealternation of weak $(1, 3)$ -automata

In this section we provide a formal proof of Theorem 11, showing that if \mathcal{A} is a weak alternating $(1, 3)$ -automaton then one can affectively construct an equivalent weak non-deterministic $(1, 3)$ -automaton.

Let $\mathcal{A} = \langle A, Q, q_I, \Delta, \Omega \rangle$ be a weak alternating automaton of index $(1, 3)$ that recognises our language L . Without loss of generality we can assume that Δ is given in a *disjunctive normal form*, i.e. for every $q \in Q$, $a \in A$ we have

$$\Delta(q, a) = \bigvee_{Y \in \mathcal{Y}_{q,a}} \bigwedge_{(d, q') \in Y} (d, q'), \quad (4)$$

for some family³ $\mathcal{Y}_{q,a} \subseteq \mathcal{P}(\{\mathbb{L}, \mathbb{R}\} \times Q)$. Notice that since our automata are complete, $\mathcal{Y}_{q,a}$ is non-empty and all its elements are non-empty.

We will now describe a weak non-deterministic automaton of index $(1, 3)$

$$\mathcal{B} = \langle A, Q^{\mathcal{B}}, q_I^{\mathcal{B}}, \Delta^{\mathcal{B}}, \Omega^{\mathcal{B}} \rangle$$

such that $L(\mathcal{B}) = L$.

First, let $Q_{1,2} \subseteq Q$ be the set of states of \mathcal{A} of priorities 1 and 2. Let us define the set of states $Q^{\mathcal{B}} \stackrel{\text{def}}{=} \mathcal{P}(Q_{1,2}) \cup \{\perp\}$, i.e. the power set of $Q_{1,2}$ together with a bottom state \perp . The initial state $q_I^{\mathcal{B}} \stackrel{\text{def}}{=} \{q_I\}$ is the singleton of the initial state of \mathcal{A} (without loss of generality we can assume that $q_I \in Q_{1,2}$). Let the priority of a state $X \in Q^{\mathcal{B}}$ of \mathcal{B} be defined as follows:

- if $X = \perp$ then $\Omega^{\mathcal{B}}(X) = 3$;
- otherwise $\Omega^{\mathcal{B}}(X) \stackrel{\text{def}}{=} 2$ if all the states in $X \subseteq Q_{1,2}$ have priority 2;
- otherwise $X \subseteq Q_{1,2}$ contains a state of priority 1 and $\Omega^{\mathcal{B}}(X) \stackrel{\text{def}}{=} 1$.

We now move to the definition of $\Delta^{\mathcal{B}}$. First, for every letter $a \in A$ we have the transition $(\perp, a, \perp, \perp) \in \Delta^{\mathcal{B}}$.

Consider a non-bottom state $X \subseteq Q_{1,2}$ of \mathcal{B} and a letter $a \in A$. Intuitively, a transition of \mathcal{B} from X over a is constructed in the following way:

- a) We non-deterministically guess choices of \exists in the acceptance game of \mathcal{A} for all the states $q \in X$. Thus, for each $q \in X$ we guess an element $Y_q \in \mathcal{Y}_{q,a}$.
- b) We simulate all the possible choices of \forall by taking their union:

$$X' \stackrel{\text{def}}{=} \bigcup_{q \in X} Y_q \subseteq \{\mathbb{L}, \mathbb{R}\} \times Q^{\mathcal{A}}.$$

- c) We split the obtained set into the two directions: $X'_d \stackrel{\text{def}}{=} X' \cap (\{d\} \times Q^{\mathcal{A}})$ for $d = \mathbb{L}, \mathbb{R}$.

³ Such a disjunctive normal form is often used for non-deterministic automata, however here we put no restrictions on the directions used in the elements of a set $Y \in \mathcal{Y}_{q,a}$. Therefore, transitions of every alternating automaton can be easily transformed into such a form.

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- d) If a set X'_d contains a set of priority 3 then we substitute it with \perp .
- e) This way we obtain a single transition (X, a, X'_L, X'_R) of \mathcal{B} .
- f) We add to $\Delta^{\mathcal{B}}$ all such transitions for all the possible choices of $(Y_q)_{q \in X}$.

Now we will formally define $\Delta^{\mathcal{B}}$ for non-bottom states $X \neq \perp$. $\Delta^{\mathcal{B}}$ contains a transition (X, a, X''_L, X''_R) if there exists a function $\delta: X \rightarrow \mathcal{P}(Q^{\mathcal{A}})$ such that for every $q \in X$ we have

$$\delta(q) \in \mathcal{Y}_{q,a},$$

and additionally for

$$X' \stackrel{\text{def}}{=} \bigcup_{q \in X} \delta(q) \subseteq \{\text{L}, \text{R}\} \times Q^{\mathcal{A}},$$

$$X'_d \stackrel{\text{def}}{=} \{q' \mid (d, q) \in X'\} \subseteq Q^{\mathcal{A}} \quad \text{for } d = \text{L}, \text{R},$$

we have $X''_d = X'_d$ if $X'_d \subseteq Q_{1,2}$ and $X''_d = \perp$ otherwise.

This way we have accomplished the definition of the automaton \mathcal{B} . Since the transitions of \mathcal{A} are non-decreasing with respect to $\Omega^{\mathcal{A}}$ and \mathcal{A} is complete, it easily implies that the transitions of \mathcal{B} are also non-decreasing. Thus, \mathcal{B} is a weak non-deterministic automaton of index (1, 3). It remains to prove the following lemma.

► **Lemma 18.** *The automaton \mathcal{B} recognises the same language as \mathcal{A} .*

Proof. First note that if \mathcal{B} accepts a tree t using a run ρ then this run indicates a strategy σ of \exists in the game $\mathcal{A}(t)$. Since the run ρ is accepting, ultimately only 2 is a priority of states visited in the plays consistent with σ . Thus, σ is winning in $\mathcal{A}(t)$ and $t \in \text{L}(\mathcal{A})$.

Now assume that $t \in \text{L}(\mathcal{A})$ and take σ as a positional winning strategy of \exists in $\mathcal{A}(t)$. We can inductively construct a run ρ of \mathcal{B} over t that, given a state X in a position u , puts $\delta(q)$ as the choice of σ in the position $(u, \Delta(q, a))$ of the game $\mathcal{A}(t)$, see (4). This way we preserve an invariant that if $\rho(u) = X$ with $q \in X$ then there exists a play of $\mathcal{A}(t)$ consistent with σ that reaches the position (u, q) .

It remains to see that the run ρ is accepting. First assume that on some branch a state of priority 3 is reached. It means that the strategy σ reaches a state of priority 3 in the acceptance game $\mathcal{A}(t)$ what contradicts the fact that σ is winning. Now assume that on certain branch β of t the run ρ uses only states of the priority 1 (never reaching the priority 2). It means that for every $u \prec \beta$ there is a finite play of $\mathcal{A}(t)$ consistent with σ that reaches a position (u, q) with $\Omega^{\mathcal{A}}(q) = 1$. By applying König's lemma (or a compactness argument) we can find a single play consistent with σ that uses only states of priority 1 in $\mathcal{A}(t)$. This again contradicts the fact that σ is a winning strategy. Thus, the run ρ must satisfy the parity condition on every branch of t and therefore $t \in \text{L}(\mathcal{B})$. ◀