

# Nondeterminism in the Presence of a Diverse or Unknown Future

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## $\omega$ -words

$w = \text{ } \circlearrowleft \text{ } a \circlearrowleft \text{ } a \circlearrowleft \text{ } b \circlearrowleft \text{ } a \circlearrowleft \text{ } c \circlearrowleft \text{ } b \circlearrowleft \text{ } b \circlearrowleft \text{ } a \circlearrowleft \text{ } \dots \in \Sigma^\omega$

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$\exists_X \forall_{x \in X} a(x) \wedge \dots$

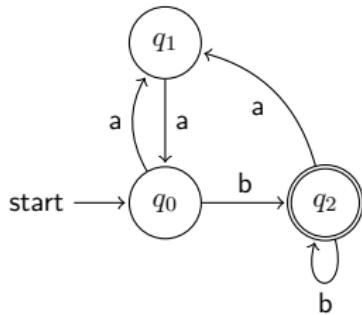
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## Finite automata



## Model checking

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(we focus on parity automata)

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Containment???

Size???

Determinisation???

## Synthesis problem

$\forall$  — environment

$\exists$  — system

$\varphi$  — specification

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► also known as **History Determinism**

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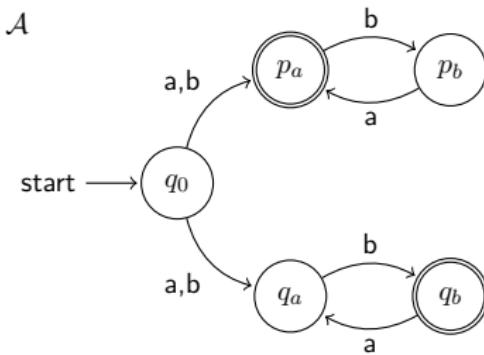
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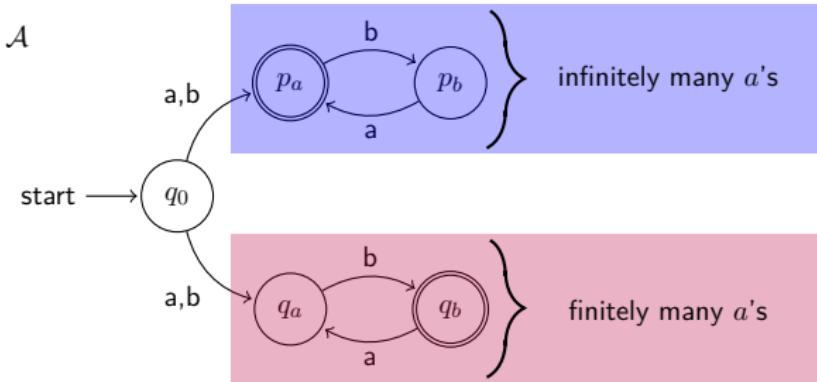
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- ▶ [Henzinger, Piterman]
- ▶ also known as **History Determinism**
- ▶ applications to counter automata  
[Colcombet]

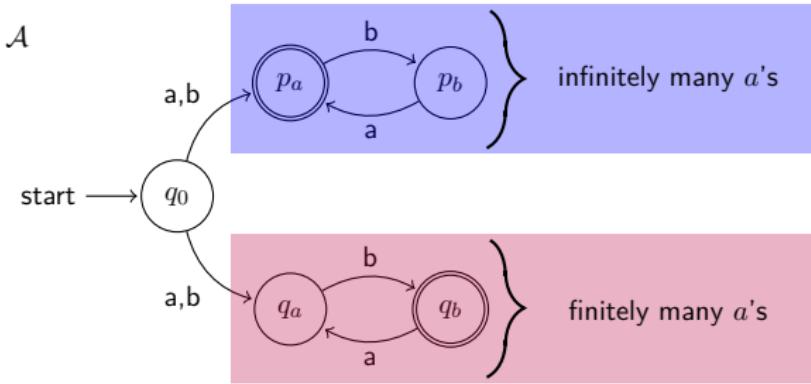
## A non-example



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$$L(\mathcal{A}) = \{a, b\}^\omega \text{ but } \mathcal{A} \text{ is } \mathbf{not} \text{ GFG}$$

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Given :  $\mathcal{A}$  for an LTL path formula  $\varphi$

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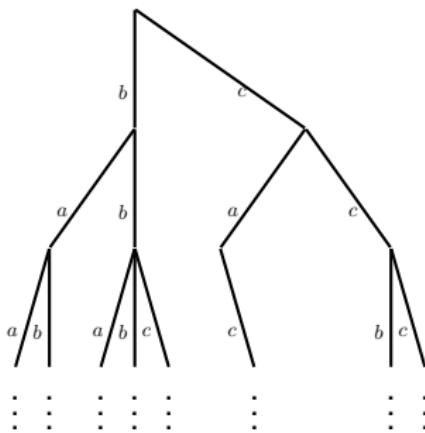
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$$\Sigma = \{a, b, c\}$$



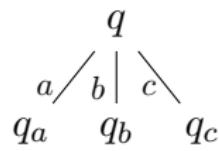
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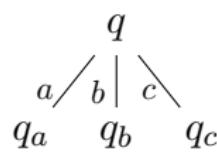
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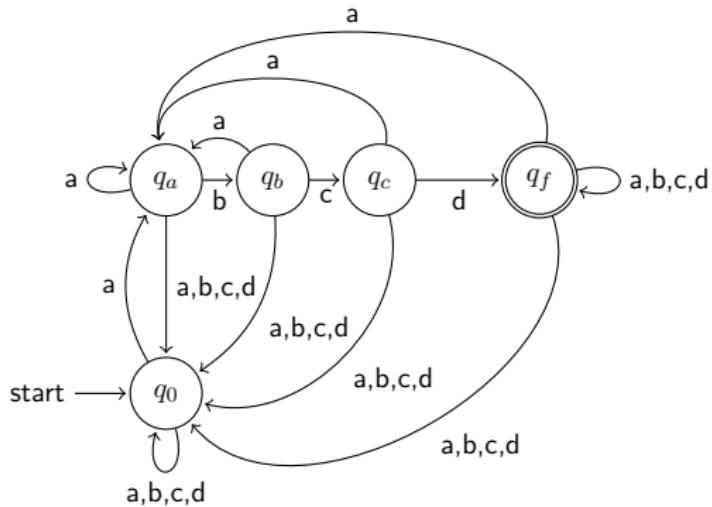


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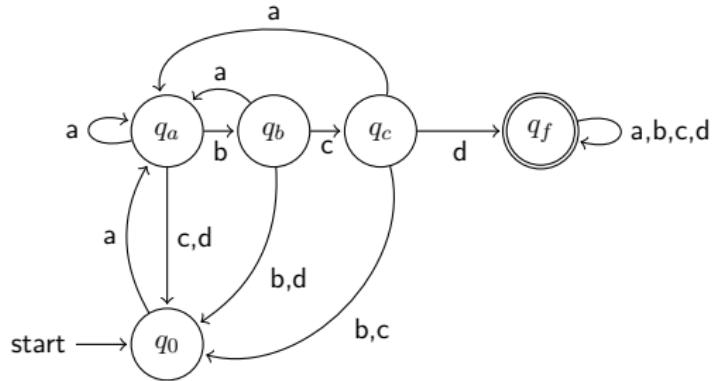
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$\mathcal{A}$  is Good For Trees if  $L(\widehat{\mathcal{A}}) = \text{der}(L)$

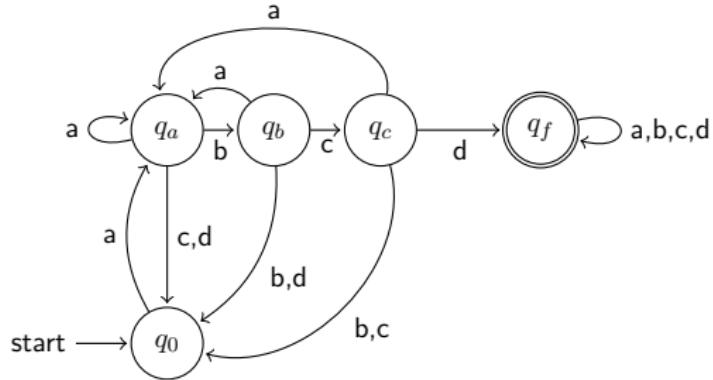
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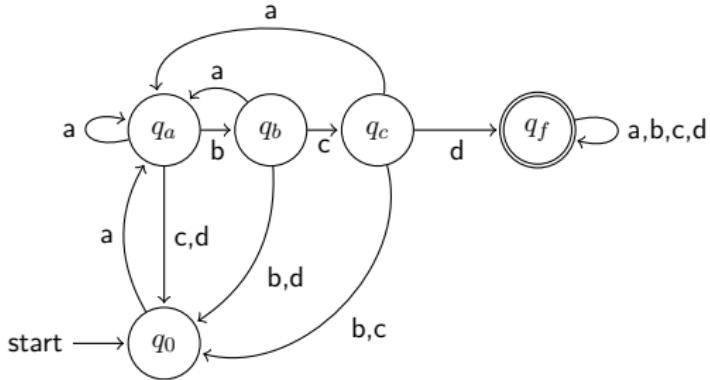


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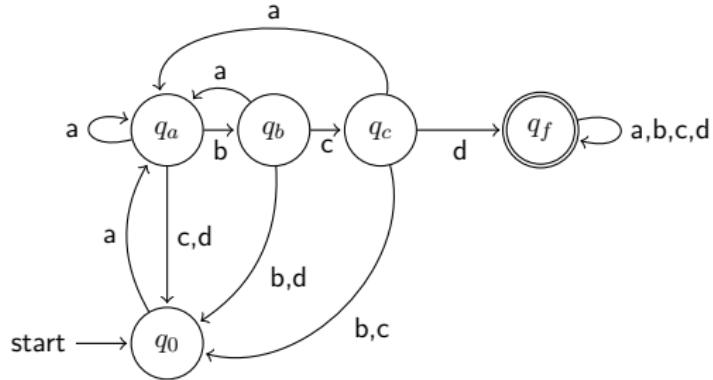
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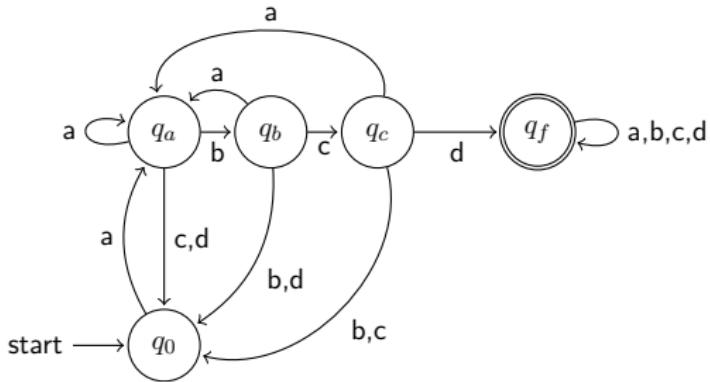
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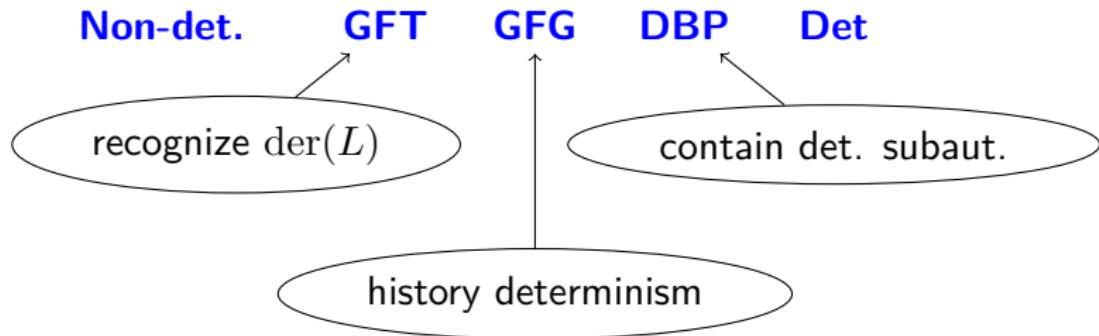
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**Non-det.**  $\supset$  **GFT**  $\stackrel{?}{\supseteq}$  **GFG**  $\stackrel{?}{\supseteq}$  **DBP**  $\supset$  **Det**

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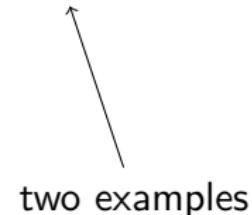
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~~~ **GFG**
- ▶ a winning strategy for  $\forall$  induces a tree  $t \in \text{der}(L) - L(\widehat{\mathcal{A}})$   
~~~ **not GFT**

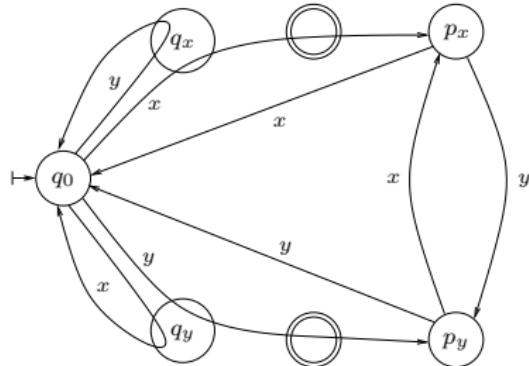
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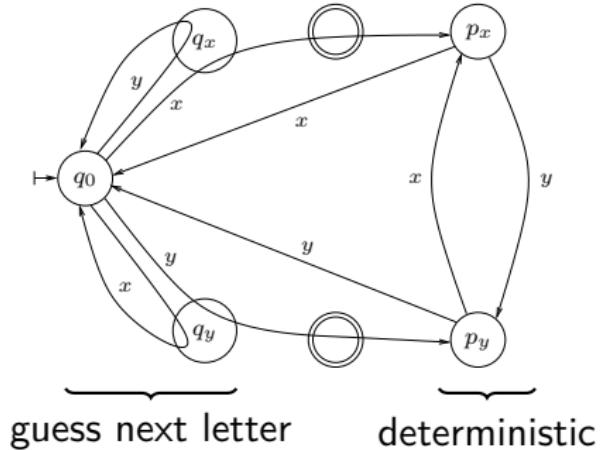
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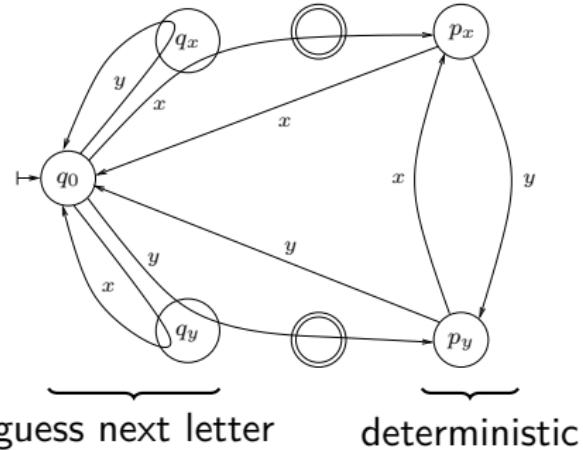
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**co-Büchi:** follows from the *blow-up*

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What about Büchi GFG?