A variational approach to fluid-structure interactions

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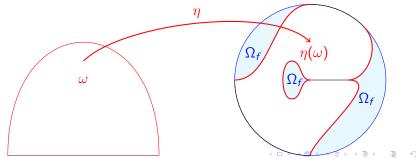
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Fluid-Structure interactions

- **1** $\Omega = \Omega_f \cup \Omega_s \subset \mathbb{R}^3$ is the (Eulerian) domain under investigation.
- ② The solid will be situated on Ω_s which is characterized by its **deformation** $\eta:\omega\to\eta(\omega)=\Omega_s\subset\Omega$ in **Lagrangian** coordinates.
- **3** The fluid will be contained in Ω_f , prescribed in **Eulerian** coordinates by its **velocity** $v: \Omega_f \to \mathbb{R}^3$ and its pressure $p: \Omega_f \to \mathbb{R}$.
- The velocities and stresses are in equilibrium at the interface.



The solid-and why a variational approach is needed

Unsteady solutions are (formally) given by:

$$\rho_s \partial_t^2 \eta + \operatorname{div} \sigma = \rho_s f \circ \eta \text{ in } [0, T] \times \omega.$$

where $\operatorname{div} \sigma = E'(\eta) + D_2 R(\eta, \partial_t \eta)$.

Here E is the elastic potential of the deformation and R is the dissipation potential.

The (regularized) Saint Venant-Kirchhoff energy as prototype:

$$E(\eta) := \int_{Q} \frac{1}{8} \left(\mathcal{C}(\nabla \eta^{T} \nabla \eta - I) \right) \cdot \left(\nabla \eta^{T} \nabla \eta - I \right) + \frac{1}{(\det \nabla \eta)^{a}} + \frac{1}{q} \left| \nabla^{2} \eta \right|^{q} dx.$$

Steady solutions are considered to be **minimizers** over **non-convex sets** (e.g. $\{\eta \in W^{2,q}(\omega) : \det(\nabla \eta) > 0\}$).

Problem: Energy is **not convex**—minimizers are not unique, no linearisation is possible, no fixed point methods...

Kelvin Voigt dissipation potential: $R(\eta, \partial_t \eta) = \frac{1}{2} \int_Q |\partial_t (\nabla \eta^T \nabla \eta)|^2 dx$.

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The weak formulation for a quasi-steady model

Strong formulation: For all $t \in [0, T]$ (with simplified dissipation):

$$\begin{aligned} \operatorname{div}\sigma(\eta,\partial_t\eta) &= \rho_s f \circ \eta & \text{in } \omega, \\ \operatorname{div}\sigma(\eta,\partial_t\eta) &= DE(\eta) - \Delta\partial_t\eta & \text{in } \omega, \\ -\Delta v + \nabla p &= \rho_f f & \text{on } \Omega \setminus \eta(t,\omega), \\ \operatorname{div}v &= 0 & \text{on } \Omega \setminus \eta(t,\omega). \end{aligned}$$

At the interface: $\partial_t \eta(t,x) = v \circ \eta(t,x)$ and $\sigma(t,x)n(x) = (\nabla_{sym}v(t,\eta(t,x)) \cdot \hat{n} + p(t,\eta(t,x))I)\hat{n}$. Coupled weak formulation:

$$\int_{0}^{T} \langle E'(\eta), \varphi \rangle_{\omega} + \langle \nabla \partial_{t} \eta, \nabla \varphi \rangle_{\omega} + \langle \nabla_{sym} v, \nabla \xi \rangle_{\Omega_{f}(t)} - \langle p, \operatorname{div} \xi \rangle_{\Omega_{f}(t)} dt$$

$$= \int_{0}^{T} \rho_{f} \langle f, \xi \rangle_{\Omega_{f}(t)} + \rho_{s} \langle f \circ \eta, \varphi \rangle_{\omega} dt$$

for all smooth (φ, ξ) satisfying $\varphi = \xi \circ \eta$ on ω .

How to couple fluid and solid variationally

Theorem: There exists a solution to the quasi-steady FSI (until collision).

Proof: Via De Giorgi's minimizing movements.

Inductive time-stepping $t_k - t_{k-1} = \tau$, $N\tau = T$.

Principle: Make the scheme *explicit* w.r.t. fluid-domain, but *implicit* w.r.t. the coupled Dirichlet boundary values.

Assume $\exists \eta_{k-1}: \omega \to \Omega$ and $v_{k-1}: \Omega_f^{k-2} \to \mathbb{R}^3$ with

$$\frac{\eta_{k-1}-\eta_{k-2}}{\tau}=\nu_{k-1}\circ\eta_{k-2} \text{ on } \partial\omega.$$

Energy class:

$$\{(\beta, w) \in W^{2,q}_{\mathrm{det}}(\omega) \times W^{1,2}_{\mathrm{div}}(\Omega_f^{k-1}) : \frac{\beta - \eta_{k-1}}{\tau} = w \circ \eta_{k-1} \text{ on } \partial\omega\}.$$

 $(\eta_k, v_k) = \text{arg min of}$

$$\int_{\omega} \frac{|\nabla (\beta - \eta_{k-1})|^2}{2\tau} \, dx + E(\beta) + \tau \int_{\Omega_f^{k-1}} \frac{|\nabla_{\mathsf{sym}} w|^2}{2} \, dy - \langle \rho_{\mathsf{s}} f \circ \eta_{k-1}, \beta \rangle_{\omega} - \tau \langle \rho_{\mathsf{f}} f, w \rangle_{\Omega_f^{k-1}}.$$

Estimates and Euler-Lagrange

We take $(\eta_{k-1}, 0)$ as competitor and find

$$\tau \int_{\omega} \frac{|\nabla (\eta_{k} - \eta_{k-1})|^{2}}{2\tau^{2}} dx + E(\eta_{k}) + \tau \int_{\Omega_{f}^{k-1}} \frac{|\nabla_{sym} v_{k}|^{2}}{2} dy$$

$$\leq E(\eta_{k-1}) + \tau \|f\|_{\infty} \Big(\|v_{k}\|_{\Omega_{f}^{k-1}} + \|\frac{\eta_{k} - \eta_{k-1}}{\tau}\|_{\omega} \Big)$$

Korn's inequality implies estimates.

Take
$$(\xi, \varphi)$$
 such that $\xi \circ \eta_{k-1} = \varphi$
 $\Rightarrow v_k \circ \eta_{k-1} + \frac{\xi}{\tau} \circ \eta_{k-1} = \frac{\eta_k - \eta_{k-1} + \varphi}{\tau}$ (on $\partial \omega$).
 $\langle E'(\eta_k), \varphi \rangle_{\omega} + \langle \nabla \frac{\eta_k - \eta_{k-1}}{\tau}, \nabla \varphi \rangle_{\omega} + \langle \nabla_{sym} v_k, \nabla \xi \rangle_{\Omega_f^{k-1}}$
 $= \rho_f \langle f, \xi \rangle_{\Omega_f^{k-1}} + \rho_s \langle f \circ \eta, \varphi \rangle_{\omega}$

 $E'(\eta)$ exists due to the regularizing potentials.

No previous literature on FSI involving large deformations.

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Small deformation: (Grandemont 2002).

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$$\leq E(\eta_{k-1}) + \tau ||f||_{\infty} \left(||v_{k}||_{\Omega_{f}^{k-1}} + ||\frac{\eta_{k} - \eta_{k-1}}{\tau}||_{\omega} \right)$$

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Theorem: There exists a weak solution to $\rho_s \partial_t^2 \eta + E'(\eta) - \Delta \partial_t \eta = \rho_s f \circ \eta$.

Parabolic De Giorgi's MM. Inductive time-stepping. $t_k - t_{k-1} = \tau$:

$$\begin{split} \eta_k &= \arg\min_{\beta} \int_{\omega} \frac{|\nabla(\beta - \eta_{k-1})|^2}{2\tau} \, dx + E(\beta) - \rho_s \langle f \circ \eta_{k-1}, \beta \rangle \\ &\quad \text{E-L} \ : \langle \frac{\nabla(\eta_k - \eta_{k-1})}{\tau}, \nabla \varphi \rangle + \langle E'(\eta_k), \varphi \rangle = \rho_s \langle f \circ \eta_{k-1}, \varphi \rangle. \end{split}$$

Hyperbolic De Giorgi's MM. Introduce: $h = N\tau$ as acceleration

$$\begin{split} &\eta_{k}^{\ell} = \arg\min_{\beta} \int_{\omega} \rho_{s} \left| \frac{\frac{\beta - \eta_{k-1}^{\ell}}{\tau} - \frac{\eta_{k}^{\ell-1} - \eta_{k-1}^{\ell-1}}{\tau}}{2h} \right|^{2} + \frac{\left| \nabla (\beta - \eta_{k-1}^{\ell}) \right|^{2}}{2\tau} \, dx + E(\beta) - \rho_{s} \langle f \circ \eta_{k-1}, \beta \rangle \\ & \text{E-L: } \rho_{s} \langle \frac{\eta_{k}^{\ell} - \eta_{k-1}^{\ell}}{\tau} - \frac{\eta_{k}^{\ell-1} - \eta_{k-1}^{\ell-1}}{\tau}, \varphi \rangle + \langle \frac{\nabla (\eta_{k} - \eta_{k-1})}{\tau}, \nabla \varphi \rangle + \langle E'(\eta_{k}), \varphi \rangle = \rho_{s} \langle f \circ \eta_{k-1}, \varphi \rangle \end{split}$$

Important: Hyperbolic a-priori estimates are by E-L Equations!

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Assume $\exists \{\eta_1^{\ell-1},....,\eta_N^{\ell-1}\}$ define:

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Solids coupled to Navier Stokes equations

Aim: Find solutions to:

$$\rho_{s}\partial_{t}^{2}\eta + E'(\eta) - \Delta\partial_{t}\eta = \rho_{s}f \circ \eta \qquad \text{in } \omega,$$

$$\rho_{f}(\partial_{t}v + [\nabla v]v) = \Delta v - \nabla p + \rho_{f}f \qquad \text{on } \Omega \setminus \eta(t, \omega),$$

$$\text{div}v = 0 \qquad \text{on } \Omega \setminus \eta(t, \omega).$$

And coupling of velocities and stresses at the interface.

$$u:[0,T]\times\Omega\to\mathbb{R}^d,\quad u|_{\Omega_f}=v|_{\Omega_f},\quad u|_{\Omega_s}=\partial_t\eta\circ\eta^{-1}.$$

Define
$$\Phi: [0,T] \times \Omega \to \Omega$$
, such that $\partial_t \Phi(t,x) = u(t,\Phi(t,x))$.
For $y = \Phi(t,x) \in \Omega_f$: $\partial_t (v(t,\Phi(t,x)) = \partial_t v(t,y) + [\nabla_y v(t,y)]v(t,y)$.
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Navier Stokes as *hyperbolic* Minimizing Movements

Let $v_k^{\ell-1}: \Omega_k^{\ell-1} \to \mathbb{R}^d$ be given and $\Phi_k^{\ell-1}: \Omega_f(0) \to \Omega_k^{\ell-1} = \Omega \setminus \eta_k^{\ell-1}(\omega)$. Introduce inductively:

$$v_k^\ell = \text{arg} \ \min_{w: \Omega_{k-1}^\ell \to \mathbb{R}^d} \int_{\Omega_f(0)} \rho_f \left| \frac{w \circ \varPhi_{k-1}^\ell - v^{(\ell-1)} \circ \varPhi_{k-1}^{\ell-1}}{2h} \right|^2 dx + \int_{\Omega_{k-1}^\ell} \frac{\left| \nabla w \right|^2}{2} \, dy - \rho_f \langle f, w \rangle.$$

Next introduce Φ_k^ℓ such that $\partial_t \Phi_k^\ell = v_k^\ell \circ \Phi_{k-1}^\ell$. For fixed domains see: (Gigli, Mosconi, 2012).

Important for FSI:

- Make the scheme explicit w.r.t. fluid-domain, but implicit w.r.t. the coupled Dirichlet boundary values.
- Do not change (mollify) the domain since this masses with the flow map Φ .
- Beware that the domain where the global velocity is divergence free changes in time.

Open Problem: Existence of steady solutions to fluid-structure interactions.

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Main Result (Benešová, Kampschulte, Sch 2020)

There exist $\eta:[0,T]\times\omega\to\Omega$, $v:[0,T]\times\Omega(t)\to\mathbb{R}^n$ and $p:[0,T]\times\Omega(t)\to\mathbb{R}$, satisfying an energy inequality. And

$$\begin{split} &\int_0^T -\rho_s \langle \partial_t \eta, \partial_t \varphi \rangle_\omega - \rho_s \langle v, \partial_t \xi - v \cdot \nabla \xi \rangle_{\Omega_f} \, dt \\ &\quad + \int_0^T \langle E'(\eta), \varphi \rangle_\omega + \langle D_2 R(\eta, \partial_t \eta), \varphi \rangle_\omega + \langle \nabla_{\mathit{sym}} v, \nabla_{\mathit{sym}} \xi \rangle_{\Omega_f(t)} \\ &\quad - \langle p, \mathrm{div} \xi \rangle_{\Omega_f} dt = \int_0^T \rho_s \langle f \circ \eta, \varphi \rangle_\omega + \rho_f \langle f, \xi \rangle_{\Omega_f} dt + \mathrm{initial conditions}. \end{split}$$

for all (φ, ξ) smooth, with $\varphi(t) = \xi(t) \circ \eta(t)$ on $\partial \omega$.

