

Regularity results for bounded minimizers

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Monday's Nonstandard Seminar 2020/21

University of Warsaw, April 12, 2021

THE PROBLEM

Regularity results for local bounded minimizers of integral functionals of the type

$$\mathcal{F}(v, \Omega) = \int_{\Omega} f(x, Dv) dx \quad \Omega \subset \mathbb{R}^n$$

in case

- *unconstrained* problem
- *constrained* problem

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In both cases the integrand f

- ▶ $\xi \rightarrow f(x, \xi)$ p -growth
- ▶ can be **discontinuous** with respect to the x -variable.

- ▶ **R. G. & A. Passarelli di Napoli** *Regularity results for a priori bounded minimizers of non autonomous functionals with discontinuous coefficients* Adv. Calc. Var. **12** (2019)
- ▶ **M. Caselli, A. Gentile, R. G.** *Regularity results for solutions to obstacle problems with Sobolev coefficients.* J. Differential Equations **269** (2020)

ASSUMPTIONS

Let us consider

$$\mathcal{F}(v, \Omega) = \int_{\Omega} f(x, Dv) dx \quad (\text{F})$$

Ω open bounded set in \mathbb{R}^n , $n > 2$

- $v : \Omega \rightarrow \mathbb{R}^N$ $N \geq 2$
- $f : \Omega \times \mathbb{R}^{n \times N} \rightarrow \mathbb{R}$ is a Carathéodory mapping satisfying

ASSUMPTIONS W.R.T ξ -VARIABLE

there exist $p \geq 2$ and positive constants $L, \ell, \nu > 0$ s.t.

$$\frac{1}{L}|\xi|^p \leq f(x, \xi) \leq L(1 + |\xi|^p). \quad (\text{F1})$$

$$\langle D_{\xi}f(x, \xi) - D_{\xi}f(x, \eta), \xi - \eta \rangle \geq \nu(1 + |\xi|^2 + |\eta|^2)^{\frac{p-2}{2}} |\xi - \eta|^2 \quad (\text{F2})$$

$$|D_{\xi}f(x, \xi) - D_{\xi}f(x, \eta)| \leq \ell(1 + |\xi|^2 + |\eta|^2)^{\frac{p-2}{2}} |\xi - \eta| \quad (\text{F3})$$

for all $\xi, \eta \in \mathbb{R}^{n \times N}$ and for almost every $x \in \Omega$.

ASSUMPTIONS W.R.T x -VARIABLE

There exists $g(x) \in L^\sigma(\Omega)$, $\sigma > 1$ s.t.

$$|D_\xi f(x, \xi) - D_\xi f(y, \xi)| \leq (|g(x)| + |g(y)|)|x - y|(1 + |\xi|^2)^{\frac{p-1}{2}} \quad (\text{F4})$$

for a.e. $x, y \in \Omega$ and for all $\xi \in \mathbb{R}^{n \times N}$.

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for a.e. $x, y \in \Omega$ and for all $\xi \in \mathbb{R}^{n \times N}$.

Assumption (F4) with $g \in L_{\text{loc}}^\sigma(\Omega)$ implies that

$$x \rightarrow D_\xi f(x, \xi) \in W_{\text{loc}}^{1, \sigma}(\Omega, \mathbb{R}^{n \times N})$$

(see [Hajlasz](#), Potential Anal. **5** (1996))

(see [Kristensen–Mingione](#), Arch. Ration. Mech. Anal. (2006)-
Arch. Ration. Mech. Anal.(2010))

MODEL CASE

$$\int_{\Omega} a(x)(1 + |Du|^2)^{\frac{p}{2}} dx \quad \text{with} \quad a(x) \in L^{\infty} \cap W^{1,\sigma}(\Omega)$$

$$p \geq 2 \text{ and } \sigma > 1$$

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Question:

How does the regularity of $a(x)$ transfer to Du ?

Unconstrained case

ABOUT THE ASSUMPTION ON x -VARIABLE

Classical Theory

- $x \mapsto D_{\xi}f(x, \xi) \in Lip(\Omega)$

i.e. there exists a constant $K > 0$

$$|D_{\xi}f(x, \xi) - D_{\xi}f(y, \xi)| \leq K|x - y|(1 + |\xi|^2)^{\frac{p-1}{2}}$$

\Downarrow

$$(1 + |Du|^2)^{\frac{p-2}{4}} Du \in W^{1,2}$$

SOBOLEV ASSUMPTION

More recent Developments

- $x \mapsto D_{\xi}f(x, \xi) \in W^{1,n}$

i.e. there exists a non negative function $g \in L^n$ such that

$$|D_{\xi}f(x, \xi) - D_{\xi}f(y, \xi)| \leq (|g(x)| + |g(y)|)|x - y|(1 + |\xi|^2)^{\frac{p-1}{2}}$$



Higher differentiability results with integer order

$W^{1,n}$ ASSUMPTION: HIGHER DIFFERENTIABILITY
RESULTS WITH INTEGER ORDER

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Beltrami Equations

- ▶ **Clop, Faraco, Mateu, Orobitg & Zhong** - Publ. Mat. (2009)
($n = 2$ and $A(x, \xi) = A(x) \cdot \xi$ with $\det A = 1$)
in connections with **planar mappings with finite distortion**

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Systems and integral functionals

- ▶ **Passarelli di Napoli** - Pot. Anal.(2014), Adv. Cal. Var.(2014)
 $p = n = 2 \quad 2 \leq p < n$
- ▶ **Giannetti & Passarelli di Napoli** - Math. Z.(2015)
variable exponents
- ▶ **G.** - J. Differential Equation (2015) $p = n > 2$
- ▶ **G.** - NoDEA (2016) **Orlicz – Sobolev coefficients**
- ▶ **Cruz Uribe, Moen & Rodney** - Ann. Math. Pura Appl.(2016) **Dirichlet problem**

$W^{1,n}$ ASSUMPTION: HIGHER DIFFERENTIABILITY RESULTS WITH INTEGER ORDER

- ▶ **Giannetti, Passarelli di Napoli & Scheven** - J. Lond. Math. Soc. (2016) **parabolic case**- Proc. Roy. Soc. Edinburgh Sect. A (2019) **p-q growth**
- ▶ **Cupini, Giannetti, G. & Passarelli di Napoli** - J. Differential Equation (2018) **convexity only at ∞**
- ▶ **Gentile** - Adv. Calc. Var. (2020) **sub-quadratic growth**
- ▶ **Capone & Radice** - Journal of Elliptic and Parabolic Equations (2020) - preprint(2021)**lower order terms.**
- ▶ **Cupini, Marcellini, Mascolo & Passarelli di Napoli** , Preprint (2021) **degenerate ellipticity**

FURTHER RESULTS IN CASE OF SOBOLEV COEFFICIENTS

- ▶ **Kristensen & Mingione** - Arch. Ration. Mech. Anal. (2010)
- ▶ **Kuusi & Mingione** - J. Funct. Anal. (2012)
- ▶ **Eleuteri, Marcellini & Mascolo**
 - ▶ Ann. Mat. Pura Appl. (2016),
 - ▶ Atti Accad. Naz. Lincei Rend. Lincei Mat. Appl. (2016)
 - ▶ Discrete Contin. Dyn. Syst. (2019)
 - ▶ Adv. Calc. Var. (2020)
- ▶ **Giannetti & Passarelli di Napoli** J. Differential Equation (2015)
- ▶ **Cupini, Giannetti, G. & Passarelli di Napoli** Nonlinear Anal.(2017)
- ▶ **De Filippis & Mingione**, Preprint (2020)
- ▶ **Clop, G., Hatami & Passarelli di Napoli** Forum Math. (2020)
- ▶ **Cupini, Marcellini, Mascolo & Passarelli di Napoli** , Preprint (2021)

$W^{1,n}$

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- ▶ **Iwaniec & Sbordone** J. Anal. Math. (1998)
- ▶ **Kinnunen & Zhou** Comm. Partial Differential Equations (1999)
- ▶ **Bögelein, Duzaar, Habermann & Scheven**, Proc. Lond. Math. Soc. (2011)
- ▶ **Bögelein**, J. Differential Equation (2012)
- ▶ **Di Fazio, Fanciullo & Zamboni**, Algebra i Analiz (2013)
- ▶ **Goodrich & Ragusa** , Nonlinear Anal (2019)
- ▶ **Goodrich, Scilla & Stroffolini** , Preprint (2021)

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- ▶ **Goodrich & Ragusa** , Nonlinear Anal (2019)
- ▶ **Goodrich, Scilla & Stroffolini** , Preprint (2021)
- ▶ **Balci, Diening, G. & Passarelli di Napoli** preprint (2020)

Question:

What happens if we weaken the assumption on g ?

A PRIORI BOUNDED MINIMIZERS

Theorem. [**G.- Passarelli di Napoli** (2019)]

Let $f : \Omega \times \mathbb{R}^{n \times N} \rightarrow \mathbb{R}$ be an integrand satisfying the assumptions (F1)–(F4) for a function $g \in L_{\text{loc}}^{p+2}(\Omega)$. If $u \in W_{\text{loc}}^{1,p}(\Omega, \mathbb{R}^N) \cap L_{\text{loc}}^\infty(\Omega, \mathbb{R}^N)$ is a local minimizer of the functional \mathcal{F} , then

$$(1 + |Du|^2)^{\frac{p-2}{4}} Du \in W_{\text{loc}}^{1,2}(\Omega, \mathbb{R}^{n \times N})$$

Moreover, for every balls $B_R \subset B_{2R} \subset \Omega$, we have that

$$\begin{aligned} \int_{B_R} \left| D \left((1 + |Du|^2)^{\frac{p-2}{4}} Du \right) \right|^2 dx \\ \leq c \int_{B_{2R}} (1 + |Du|^2)^{\frac{p}{2}} dx + c \int_{B_{2R}} |g(x)|^{p+2} dx, \end{aligned}$$

where $c = c(\|u\|_\infty, R, p, n, N, L, \nu)$.

REMARKS

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2. this is a weaker assumption with respect to previous papers when $2 \leq p < n - 2$

PROOF OF THE THEOREM

Step 1: The approximation. We construct the approximating problems:

Fix a compact set $\Omega' \Subset \Omega$, and for a smooth kernel $\phi \in \mathcal{C}_c^\infty(B_1(0))$ with $\phi \geq 0$ and $\int_{B_1(0)} \phi = 1$, let us consider the corresponding family of mollifiers $(\phi_\varepsilon)_{\varepsilon > 0}$. Put

$$g_\varepsilon = g * \phi_\varepsilon$$

and

$$f_\varepsilon(x, \xi) = \int_{B_1} \phi(\omega) f(x + \varepsilon\omega, \xi) d\omega$$

on Ω' , for each positive $\varepsilon < \text{dist}(\Omega', \Omega)$.

Fix a real number $a \geq \|u\|_{L^\infty(\Omega')}$ and, for $m > \frac{p}{2}$, let $u_{\varepsilon,m}$ be a minimizer to the functional

$$\mathfrak{F}_{\varepsilon,m}(v, \Omega') = \int_{\Omega'} \left(f_\varepsilon(x, Dv) + (|v| - a)_+^{2m} \right)$$

(Carozza – Kristensen – Passarelli di Napoli, Annales Inst. H. Poincaré (C) Non Linear Analysis , (2011))

PROOF OF THE THEOREM

Step 2: Uniform higher differentiability estimates (by using interpolation inequality)

$$\tau_{s,h}u_{\varepsilon,m}(x) = u_{\varepsilon,m}(x + he_s) - u_{\varepsilon,m}(x)$$

Choosing $\varphi = \tau_{s,-h}(\rho^{p+2}\tau_{s,h}u_{\varepsilon,m})$ as test function in the Euler–Lagrange system associated to the functional $\mathfrak{F}_{\varepsilon,m}(v, \Omega')$ and using the assumptions and some properties of the difference quotients we obtain

$$\begin{aligned} & \int_{B_{2R}} |\tau_{s,h}(\rho^{\frac{p+2}{2}}V(Du_{\varepsilon,m}))|^2 \\ & \leq c|h|^2 \int_{B_{2R}} \rho^{p+2}(g_{\varepsilon}(x) + g_{\varepsilon}(x+h))^2(1 + |Du_{\varepsilon,m}|^2)^{\frac{p}{2}} \\ & \quad + c\frac{|h|^2}{R^2} \int_{B_{3R}} (1 + |Du_{\varepsilon,m}|^2)^{\frac{p}{2}}. \end{aligned}$$

PROOF OF THE THEOREM

By a suitable interpolation inequality we have

$$Du_{\varepsilon,m} \in L^{\frac{m}{m+1}(p+2)}$$

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we can use Hölder's inequality with exponents $\frac{m}{m+1} \frac{p+2}{p}$ and $\frac{m(p+2)}{2m-p}$ to get

$$\begin{aligned} & \int_{B_{2R}} |\tau_{s,h}(\rho^{\frac{p+2}{2}} V(Du_{\varepsilon,m}))|^2 \\ & \leq c|h|^2 \left(\int_{B_{2R}} \rho^{p+2} (g_{\varepsilon}(x) + g_{\varepsilon}(x+h))^{\frac{2m(p+2)}{2m-p}} \right)^{\frac{2m-p}{m(p+2)}} \\ & \quad \cdot \left(\int_{B_{2R}} \rho^{p+2} (1 + |Du_{\varepsilon,m}|^2)^{\frac{m}{m+1} \frac{(p+2)}{2}} \right)^{\frac{m+1}{m} \frac{p}{p+2}}, \\ & + c \frac{|h|^2}{R^2} \int_{B_{3R}} (1 + |Du_{\varepsilon,m}|^2)^{\frac{p}{2}} \end{aligned}$$

PROOF OF THE THEOREM

Step 3: we show that such estimates are preserved in passing to the limit.

SYSTEMS UNDER SUITABLE STRUCTURE ASSUMPTIONS

We consider elliptic systems of the form

$$\operatorname{div} A(x, Du) = \sum_{i=1}^n D_{x_i} \left(\sum_{j=1}^n a_{ij}(x, Du) u_{x_j}^\alpha \right) = 0, \quad 1 \leq \alpha \leq N, \quad \text{in } \Omega \subset \mathbb{R}^n \quad (*)$$

satisfying

$$A(x, 0) = 0 \quad (\text{A0})$$

$$\langle A(x, \xi) - A(x, \eta), \xi - \eta \rangle \geq \alpha |\xi - \eta|^2 (1 + |\xi|^2 + |\eta|^2)^{\frac{p-2}{2}} \quad (\text{A1})$$

$$|A(x, \xi) - A(x, \eta)| \leq \beta |\xi - \eta| (1 + |\xi|^2 + |\eta|^2)^{\frac{p-2}{2}} \quad (\text{A2})$$

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There exists a nonnegative function $g \in L_{\text{loc}}^{p+2}(\Omega)$, such that

$$|A(x, \xi) - A(y, \xi)| \leq (g(x) + g(y)) |x - y| (1 + |\xi|^2)^{\frac{p-1}{2}}; \quad (\text{A3})$$

for every $\xi \in \mathbb{R}^{n \times N}$ and for almost every $x, y \in \Omega$.

Theorem. [**G.- Passarelli di Napoli** (2019)]

Let $A: \Omega \times \mathbb{R}^{N \times n} \rightarrow \mathbb{R}^{N \times n}$ be a Carathéodory function satisfying the assumptions (A0)–(A3). If $u \in W_{\text{loc}}^{1,p}(\Omega)$ is a local solution of the system (*), then

$$(1 + |Du|^2)^{\frac{p-2}{4}} Du \in W_{\text{loc}}^{1,2}(\Omega, \mathbb{R}^{n \times N})$$

Moreover, for every ball $B_r \Subset \Omega$

$$\int_{B_{r/4}} (1 + |Du|^2)^{\frac{p-2}{2}} |D^2u|^2 dx \leq \frac{c}{r^2} \int_{B_r} (1 + |Du|^2)^{\frac{p}{2}} dx \\ \frac{c}{r^n} \|u\|_{L^{p^*}(B_{2r})}^p \left(\int_{B_r} (1 + g(x))^{p+2} dx \right),$$

for a constant $c = c(\alpha, \beta, p, n)$.

PROOF OF THE THEOREM

Step 1 A priori estimate

- difference quotient method
- local boundedness of the solutions $u \in W_{\text{loc}}^{1,p}(\Omega)$ of the system and following estimate

$$\sup_{B_{\frac{R}{2}}(x_0)} |u| \leq c \left\{ \int_{B_R(x_0)} (|u| + 1)^{p^*} dx \right\}^{\frac{1}{p^*}}$$

(see **Cupini, Marcellini & Mascolo**,
Manuscripta Math. (2012) J. Optim. Theory Appl.(2015)-
Nonlinear Anal.(2017))

(see also **Leonetti** Boll. Un. Mat. Ital. (1991))

- interpolation inequality

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Step 2 Approximation procedure

REMARK

If is assumed a priori

$$u \in L^q, \quad \text{with } q > \frac{np}{n-p-2} \quad (\text{instead of } u \in L^\infty)$$

the interpolation inequality gives

$$Du \in L^{\frac{q}{q+2}(p+2)} \quad (\text{instead of } Du \in L^{p+2})$$

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the interpolation inequality gives

$$Du \in L^{\frac{q}{q+2}(p+2)} \quad (\text{instead of } Du \in L^{p+2})$$

Such higher integrability allow us to obtain the same higher differentiability result assuming $g \in L^{\frac{q}{q-p}(p+2)}$.

We'd like to point out that for $p < n - 2$ it results $\frac{q}{q-p}(p+2) < n$.

Constrained case

OBSTACLE PROBLEM

We consider the following *obstacle problem*

$$\min \left\{ \int_{\Omega} f(x, Dv(x)) : v \in \mathcal{K}_{\psi}(\Omega) \right\}, \quad (1)$$

where $\Omega \subset \mathbb{R}^n$ is a bounded open set,

- $\psi : \Omega \mapsto [-\infty, +\infty)$ belonging to $W_{\text{loc}}^{1,p}$ is the *obstacle*,
- $\mathcal{K}_{\psi}(\Omega) = \{v \in W_{\text{loc}}^{1,p}(\Omega, \mathbb{R}) : v \geq \psi \text{ a.e. in } \Omega\}$ is the class of the admissible functions.

OBSTACLE PROBLEMS AND VARIATIONAL FORMULATION

We observe that

$u \in W_{\text{loc}}^{1,p}(\Omega)$ is a solution to the obstacle problem in \mathcal{K}_ψ



$u \in \mathcal{K}_\psi(\Omega)$ is a solution to the variational inequality

$$\int_{\Omega} \langle A(x, Du), D(\varphi - u) \rangle dx \geq 0 \quad \forall \varphi \in \mathcal{K}_\psi(\Omega),$$

where $A(x, \xi) = D_\xi f(x, \xi)$.

REGULARITY

It is well known that:

the regularity of solutions to the obstacle problems depends on the regularity of the obstacle itself

Analysis of the **extra differentiability** of the solutions of the obstacle problems

$$\int_{\Omega} \langle A(x, Du(x)), D(\varphi(x) - u(x)) \rangle dx \geq 0 \quad \forall \varphi \in \mathcal{K}_{\psi}(\Omega),$$

assuming that the gradient of the **obstacle** $D\psi$ has **some differentiability** property

ASSUMPTIONS

Let us fix $\psi \in W_{\text{loc}}^{1,p}(\Omega)$ and consider

$$\int_{\Omega} \langle A(x, Du), D(\varphi - u) \rangle dx \geq 0, \quad (**)$$

for every $\varphi \in \mathcal{K}_{\psi}(\Omega) = \{v \in W_{\text{loc}}^{1,p}(\Omega, \mathbb{R}) : v \geq \psi \text{ a.e. in } \Omega\}$

There exist constants $\nu, L > 0$ and an exponent $p \geq 2$ such that

$$\langle A(x, \xi) - A(x, \eta), \xi - \eta \rangle \geq \nu |\xi - \eta|^2 (1 + |\xi|^2 + |\eta|^2)^{\frac{p-2}{2}} \quad (\text{A1})$$

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There exists a nonnegative function $g \in L_{\text{loc}}^{p+2}(\Omega)$, such that

$$|A(x, \xi) - A(y, \xi)| \leq (g(x) + g(y)) |x - y| (1 + |\xi|^2)^{\frac{p-1}{2}}; \quad (\text{A3})$$

for all $\xi, \eta \in \mathbb{R}^n$ and for almost every $x, y \in \Omega$.

REMARK

The regularity of the solutions to the obstacle problem (***) is strictly connected to the regularity of the solutions to PDE's of the form

$$\operatorname{div}A(x, Du) = \operatorname{div}A(x, D\psi).$$

It is well known that no extra differentiability properties for the solutions of equations of the type

$$\operatorname{div}A(x, Du) = \operatorname{div}G$$

can be expected even if G is smooth, unless some assumption is given on the x -dependence of the operator A .

SOME RESULTS

$$x \mapsto A(x, \xi) \in W^{1,r} \quad \text{with} \quad r \geq n$$

- ▶ **Eleuteri & Passarelli di Napoli** - Calc. Var. Partial Differential Equations.(2018) - Nonlinear Anal. (2020)
- ▶ **Gavioli** - Forum Math. (2019)
- ▶ **Ma & Zhang** - J. Math. Anal. Appl. (2019)
- ▶ **De Filippis** - J. Math. Anal. Appl. (2019)
- ▶ **Chlebicka& De Filippis** - Ann. Mat. Pura Appl. (2019)
- ▶ **De Filippis & Mingione** - (2020)
- ▶ **Gentile** - Forum Math. (2021)

Theorem. [Caselli – Gentile – G.(2020)]

Let $A(x, \xi)$ satisfy the conditions (A1)–(A4) for an exponent $p \geq 2$ and let $u \in \mathcal{K}_\psi(\Omega)$ be a solution to the obstacle problem. Then, if $\psi \in L_{\text{loc}}^\infty(\Omega)$ the following implication holds

$$D\psi \in W_{\text{loc}}^{1, \frac{p+2}{2}}(\Omega) \Rightarrow \left(\mu^2 + |Du|^2 \right)^{\frac{p-2}{4}} Du \in W_{\text{loc}}^{1,2}(\Omega),$$

Theorem. [Caselli – Gentile – G.(2020)]

Let $A(x, \xi)$ satisfy the conditions (A1)–(A4) for an exponent $p \geq 2$ and let $u \in \mathcal{K}_\psi(\Omega)$ be a solution to the obstacle problem. Then, if $\psi \in L^\infty_{\text{loc}}(\Omega)$ the following implication holds

$$D\psi \in W^{1, \frac{p+2}{2}}_{\text{loc}}(\Omega) \Rightarrow \left(\mu^2 + |Du|^2 \right)^{\frac{p-2}{4}} Du \in W^{1,2}_{\text{loc}}(\Omega),$$

Remark: the assumption $\psi \in L^\infty_{\text{loc}}(\Omega)$ is needed to get the boundedness of the solution. Therefore if we deal with a priori bounded minimizers, then the result holds without the hypothesis $\psi \in L^\infty$.

(see Caselli – Eleuteri – Passarelli di Napoli, ESAIM - Control. Optim. Calc. Var. (2021))

PROOF OF THE THEOREM

- A priori estimate
- Approximation procedure

TEST FUNCTIONS

The main point is the choice of suitable test functions φ :

1. involving the difference quotient of the solution
2. belonging to the class of the admissible functions $\mathcal{K}_\psi(\Omega)$,

Let us consider $\varphi := u + \tau v$ for a suitable $v \in W_0^{1,p}(\Omega)$ such that

$$u - \psi + \tau v \geq 0 \quad \forall \tau \in [0, 1], \quad (***)$$

Then $\varphi \in \mathcal{K}_\psi(\Omega)$ for all $\tau \in [0, 1]$, since $\varphi = u + \tau v \geq \psi$.

TEST FUNCTIONS

Let η be a cut off function, we consider

$$v_1(x) = \eta^2(x) [(u - \psi)(x + h) - (u - \psi)(x)],$$

v_1 satisfies (***) . Indeed, for a.e. $x \in \Omega$ and for any $\tau \in [0, 1]$

$$\begin{aligned} u(x) - \psi(x) + \tau v_1(x) &= \\ &= u(x) - \psi(x) + \tau \eta^2(x) [(u - \psi)(x + h) - (u - \psi)(x)] \\ &= \tau \eta^2(x) (u - \psi)(x + h) + (1 - \tau \eta^2(x)) (u - \psi)(x) \geq 0, \end{aligned}$$

since $u \in \mathcal{K}_\psi(\Omega)$ and $0 \leq \eta \leq 1$.

So we can use $\varphi = u + \tau v_1$ as a test function in variational inequality.

TEST FUNCTIONS

In a similar way, we consider

$$v_2(x) = \eta^2(x) [(u - \psi)(x - h) - (u - \psi)(x)],$$

and we have (***) still is satisfied for any $\tau \in [0, 1]$, since

$$\begin{aligned} & u(x) - \psi(x) + \tau v_2(x) = \\ &= u(x) - \psi(x) + \tau \eta^2(x) [(u - \psi)(x - h) - (u - \psi)(x)] \\ &= \tau \eta^2(x)(u - \psi)(x - h) + (1 - \tau \eta^2(x))(u - \psi)(x) \geq 0. \end{aligned}$$

So we can use $\varphi = u + \tau v_2$ as a test function in variational inequality .

Thanks for your attention!