## DATA MINING IN TIME RELATED

 DATA
## Time Series Data Mining

$\square$ Data mining concepts to analyzing time series data
$\square$ Revels hidden patterns that are characteristic and predictive time series events
$\square$ Traditional analysis is unable to identify complex characteristics (complex, non-periodic, irregular, chaotic)

## Time series

$\square$,,a sequence of observed data, usually ordered in time"
$\square X=\left(x_{t,} t=1 . . N\right)$

## Example 1: seismic time series

$\square$ Diamonds = observations
$\square$ E.g. Seismic activity
$\square$ Squares $=$ important observations = events

- E.g. Earthquakes
$\square$ Goal: to

characterize, when peeks occur


## Example 2: welding time series

$\square$ Diamonds: measured stickout length of droplet (in pixels)
$\square$ Squares: droplet release (chaotic, noisy, irregular nature - impossible using traditional methods)
$\square$ Goal: prediction of
 release of metal droplet

## Example 3: stock prices

$\square$ Diamonds: daily open price
$\square$ Squares: days when price increases more than 5\%
$\square$ Goal: to find hidden patterns that provide th desired trading edge


## Event = important occurrence

$\square E x 1$ : earthquake
$\square E x 2$ : release of the droplet
$\square E x 3$ : sharp rise (fall) of stock price

## Temporal pattern

$\square$ Hidden structure in time series that is characteristic and predictive of events
$\square$ Temporal pattern $\mathbf{p}=$ real vector of length $\mathbf{Q}$


## Temporal pattern cluster

$\square$ Temporal patterns usually do not match time series
$\square$ TPC is a set of all points within delta from temporal pattern: $P=\left\{\boldsymbol{a} \in \mathbf{R}^{Q}: d(\mathbf{p}, \mathbf{a}) \leq \delta\right\}$


## Phase space

$\square$ Q dimensional metric space embedding time series
$\square$ Mapping of set of $Q$ observations of time series into $x_{t}=\left(x_{t-(Q-1) \tau}, \ldots, x_{t-2 \tau}, x_{t-\tau}, x_{t}\right)$

## Phase space example - constant

$\square X=\left\{x_{t}=c: t=1 . . N\right\}$
$\square \tau=1, \mathrm{Q}=2$


## Phase space example - seismic



## Phase space example - welding



Phase space example - stock open price


## Event characterization function

$\square$ Represents the value of future „eventness" for current time index
$\square$ Addresses the specific goal
$\square$ Examples:

$$
\begin{aligned}
& g(t)=x_{t+1} ; \\
& g(t)=x_{t+3} ; \\
& g(t)=\max \left\{x_{t+1}, x_{t+2}, x_{t+3}\right\}
\end{aligned}
$$

$\square$ Welding: $g(t)=y_{t+1} ;$
$\square$ Stock prices change: $g(t)=\left(x_{t+1}-x_{t}\right) / x_{t}$

## Augmented Phase space

$\square \mathrm{Q}+1$ dimensional space formed by extending phase space with $g(\cdot)=$ space of vectors $<\mathbf{x}_{t}$, $g(t)>\in \mathbf{R}^{Q+1}$

## Augmented Phase space example

## seismic



## Augmented Phase space example

## $\square$ welding



## Augmented Phase space example

## stock open price



## Objective function

$\square$ Measures how a temporal pattern cluster characterizes events
$\square M\left(\tilde{M}\right.$ - set of all time indices $t$ when $\mathbf{x}_{t}$ is within (outside) temporal pattern cluster $P$

$$
\begin{gathered}
M=\left\{t: \mathbf{x}_{t} \in P, t \in \Lambda\right\} \\
\mu_{M}=\frac{1}{\operatorname{card}(M)} \sum_{t \in M} g(t) \\
\sigma_{M}^{2}=\frac{1}{\operatorname{card}(M)} \sum_{t \in M}\left(g(t)-\mu_{M}\right)^{2}
\end{gathered}
$$

## Objective function

$\square \boldsymbol{t}$ test for the difference between two independent means (for statistically significant and high average eventness clusters)

$$
f(P)=\frac{\mu_{M}-\mu_{\tilde{M}}}{\sqrt{\frac{\sigma_{M}^{2}}{\operatorname{card}(M)}-\frac{\sigma_{\tilde{M}}^{2}}{\operatorname{card}(\tilde{M})}}}
$$

## Objective function

- When every event is required to be predicted by temporal pattern
- $g()$ is binary
- $C$ - collection of temporal pattern clusters
- Ratio of correct predictions to all predictions

$$
f(C)=\frac{t_{p}+t_{n}}{t_{p}+t_{n}+f_{p}+f_{n}}
$$

$\square t_{p}=\operatorname{card}\left(\left\{\mathbf{x}_{t}: \exists P_{i} \in C \quad \mathbf{x}_{t} \in P_{i} \wedge g(t)=1\right\}\right)$
$\square f_{p}=\operatorname{card}\left(\left\{\mathbf{x}_{t}: \exists P_{i} \in C \quad x_{t} \in P_{i} \wedge g(t)=0\right\}\right)$
$\square t_{n}=\operatorname{card}\left(\left\{x_{t}: \forall P_{i} \in C \quad x_{t} \notin P_{i} \wedge g(t)=1\right\}\right)$
$\square f_{n}=\operatorname{card}\left(\left\{\mathbf{x}_{i}: \forall P_{i} \in C \quad \mathbf{x}_{t} \notin P_{i} \wedge g(t)=0\right\}\right)$

## Optimization problem

$$
\max _{\mathbf{x}, \delta} f(p)
$$

Genetic Algorithm
$\square$ Chromosome consists of $\mathrm{Q}+1$ genes
$\square$ E.g. Q=2
$\square\left(x_{t-1}, x_{t}, \delta\right)$

## Seismic example



## DISCOVERY OF FREQUENT EPISODES IN EVENT SEQUENCES

## Events, event sequences

$\square$ event: $(A, t) A \in E$
event sequence $s$ on $E:\left(s, T_{s} T_{\mathrm{e}}\right)$

$$
s=\left\langle\left(A_{1}, t_{1}\right),\left(A_{2}, t_{2}\right), \ldots,\left(A_{n}, t_{n}\right)\right\rangle
$$

$\square$ window on $\mathbf{s}: \mathbf{w}=\left(w, t_{s}, t_{\mathrm{e}}\right), t_{\mathrm{s}}<T_{\mathrm{e}^{\prime}} t_{\mathrm{e}}>T_{\mathrm{s}}$
$\square$ width(w)= $t_{\mathrm{e}}-t_{s}$


## Episodes

$\square$ Collection of events occurring together
$\square$ serial, parallel, non-serial \& non-parallel
$\square(V, \leq, g)$
$V-$ set of nodes
$\leq-$ partial order on $V$
$g: V \rightarrow E$ mapping associating each node with event type

$\alpha$

$\gamma$

## Occurrence of episodes

$$
\square \mathbf{w}=(w, 37,44)
$$


$\alpha$


## Frequency of an episode

$\square \mathrm{W}(\mathrm{s}$, win $)-$ all windows in $\mathbf{s}$ of length win

$$
\operatorname{fr}(\alpha, \mathbf{s}, \operatorname{win})=\frac{\operatorname{card}(\{\mathbf{w} \in W(\mathbf{s}, \operatorname{win}): \alpha \text { occursin } \mathbf{w}\})}{\operatorname{card}(W(\mathbf{s}, \operatorname{win}))}
$$

## Goal

$\square$ Given (1) a frequency threshold min_fr, (2) window width win, discover all episodes $\alpha$ (from a given class of episodes) such that

$$
\operatorname{fr}(\alpha, \mathbf{s}, \text { win }) \geq m i n \_f r
$$

## Episode rule generation algorithm

INPUT: event sequence s, win, min_fr, confidence threshold min_conf
OUTPUT: Episode rules that hold in swith respect to win, min_fr, min_conf

1. /* find all frequent episodes */
2. compute $\mathcal{F}(\mathbf{s}$, win,min_fr)
3. /* generate rules */
4. for all $\alpha \in \mathcal{F}\left(\mathbf{s}\right.$, win, $\left.m i n \_f r\right)$ do
5. for all $\beta \prec \alpha$ do
if $\operatorname{fr}(\alpha) / \operatorname{fr}(\beta) \geq$ min_conf then output the rule $\beta \rightarrow \alpha$ and the conf. $\operatorname{fr}(\alpha) / \operatorname{fr}(\beta)$

## Example

- $\beta<\gamma$
$\square$ if we know that $\beta$ occurs in $4.2 \%$ of windows and $\gamma$ in $4.0 \%$ we can estimate that after seeing a window with $A$ and $B$ there is a chance 0.95 that $C$ follows in the same window.



## Frequent episode generation algorithm

INPUT: event sequence $\mathbf{s}$, win, min_fr
OUTPUT: Collection $\mathcal{F}(s$, win,min_fr) of frequent episodes
compute $C_{1}=\{\alpha:|\alpha|=1\}$
2. $\quad I=1$
3. while $C_{l} \neq \varnothing$ do
4.
5.
6.

$$
\begin{aligned}
& \text { compute } F_{l}=\left\{\alpha \in C_{l}: f r(\alpha, \mathbf{s}, \text { win }) \geq \text { min_fr }\right\} \\
& I=I+1 \\
& \text { compute } C_{l}=\{\alpha:|\alpha|=\mid \text { and for all } \beta \prec \alpha \text { such that }|\beta|<I \\
& \text { we have } \left.\beta \in F_{|\beta|}\right\}
\end{aligned}
$$

7. for all I do output $F_{1}$
