# Teoria współbieżności 

Piotr Hofman<br>Theoretical aspects of concurrency

Lecture 3-4

## HML and Bisimulation

## Example

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```
Lemma
If two Kripke structures S and S' have the same traces i.e.
\mathbb{R}(S)=\mathbb{R}(\mp@subsup{S}{}{\prime})\mathrm{ then for any LTL formula }\phi\mathrm{ does not distinguish S and}
S'.
```

Concluding: some interesting properties can not be analysed if we look only into traces.

## Transition Tree (derivation tree)



Figure 15. Example of a Kripke structure


Figure 16. The unfolded tree of the Kripke structure of Figure

## HMS Logic

## Hennessy-Milner logic

A minimum to speak about tree, $\phi=$

- tt (true), ff (false),
- $\phi_{1} \vee \phi_{2}$,
- $\phi_{1} \wedge \phi_{2}$,
- [] $\phi \quad$ or $\square \phi$ or $A X \phi$,
- $<>\phi \quad$ or $\diamond \phi$ or $E X \phi$.


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## Unlabelled case:

## Definition

Bisimulation $B$ is any relation on a set of configurations (nodes) that satisfies following conditions
(1) if $\left(s, s^{\prime}\right) \in B$ then for every $t$ such that $s \rightarrow t$ there is $t^{\prime}$ such that $s^{\prime} \rightarrow t^{\prime}$ and $\left(t, t^{\prime}\right) \in B$,
(2) if $\left(s, s^{\prime}\right) \in B$ then for every $t^{\prime}$ such that $s^{\prime} \rightarrow t^{\prime}$ there is $t$ such that $s \rightarrow t$ and $\left(t, t^{\prime}\right) \in B$.
We denote it by $s \sim_{B} s^{\prime}$.

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## Labelled case:

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Bisimulation $B$ is any relation on a set of configurations (nodes) that satisfies following conditions
(1) if $\left(s, s^{\prime}\right) \in B$ then $L(s)=L\left(s^{\prime}\right)$,
(2) if $\left(s, s^{\prime}\right) \in B$ then for every $t$ such that $s \rightarrow t$ there is $t^{\prime}$ such that $s^{\prime} \rightarrow t^{\prime}$ and $\left(t, t^{\prime}\right) \in B$,
(3) if $\left(s, s^{\prime}\right) \in B$ then for every $t^{\prime}$ such that $s^{\prime} \rightarrow t^{\prime}$ there is $t$ such that $s \rightarrow t$ and $\left(t, t^{\prime}\right) \in B$.
We denote it by $s \sim_{B} s^{\prime}$.

## Bisimulation relation

## Theorem

A pair of configurations ( $s, s^{\prime}$ ) can not be distinguished by HML formula if and only if there is a bisimulation relation $B$ such that $s \sim_{B} s^{\prime}$.

We need a few lemmas.

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Union of bisimulations is a bisimulation.

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## Corollary

There is a biggest bisimulation.

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- The biggest bisimulation is called the bisimilarity relation and denoted by $\sim$.
- We say that two configurations $\left(s, s^{\prime}\right)$ are bisimilar if $s \sim s^{\prime}$.


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- The biggest bisimulation is called the bisimilarity relation and denoted by $\sim$.
- We say that two configurations $\left(s, s^{\prime}\right)$ are bisimilar if $s \sim s^{\prime}$.
- Bisimilarity is an equivalence relation.


## The proof of the theorem (idea).

(1) By negation, suppose there is a formula $\phi$ that distinguishes $\left(s, s^{\prime}\right)$, we prove that $\left(s, s^{\prime}\right)$ is not en element of any bisimulation relation.


## The proof of the theorem (idea).

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## The proof of the theorem (idea).

(1) By negation, suppose there is a formula $\phi$ that distinguishes $\left(s, s^{\prime}\right)$, we prove that $\left(s, s^{\prime}\right)$ is not en element of any bisimulation relation.
(2) By induction on the modal depth of the formula.
(1) Let $X$ be a set of pairs of states that can not be distinguished by HML.
(2) We prove that $X$ is a bisimulation relation.

## CTL and CTL*

## An extension of HML - CTL

## Definition

(1) A state formula $\phi=t t\left|\neg \phi_{1}\right| \phi_{1} \wedge \phi_{2}\left|p_{i}\right| A \alpha \mid E \alpha$
(2) A path formula (restricted LTL) $\alpha=X \phi_{1}\left|\phi_{1} U \phi_{2}\right| F \phi_{1} \mid G \phi_{1}$
(3) where $\phi$ are state formulas and $\alpha$ are path formulas.

## Semantics

- $p_{i}$ means that the predicate $p_{i}$ holds in the configuration in which the formula is evaluated (current configuration).
- $A \alpha$ for every run $r$ starting at the current configuration the formula $\alpha$ holds for a sequence of states of $r$.
- E $\alpha$ there is a run $r$ starting at the current configuration such that the formula $\alpha$ holds for the sequence of states of $r$.


## Exercise

- $F \phi=\operatorname{true} U \phi$,
- $G \phi=\neg(F \neg \phi)$

Which of the following pairs of CTL formulas are equivalent? For those which are not, find a model of one of the pair which is not a model of the other: ${ }^{a}$

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## Exercise

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(1) $E F \phi$ and $E G \phi$,
(2) $E F \phi \vee E F \tau$ and $E F(\phi \vee \tau)$,

[^2]
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(3) $A F \phi \vee A F \tau$ and $A F(\phi \vee \tau)$,

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(3) $A F \phi \vee A F \tau$ and $A F(\phi \vee \tau)$,
(9) $A F \neg \phi$ and $\neg E G \phi$.

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Which of the following pairs of CTL formulas are equivalent? For those which are not, find a model of one of the pair which is not a model of the other: ${ }^{a}$
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(2) $E F \phi \vee E F \tau$ and $E F(\phi \vee \tau)$,
(3) $A F \phi \vee A F \tau$ and $A F(\phi \vee \tau)$,
(4) $A F \neg \phi$ and $\neg E G \phi$.

- Write a CTL formula which stays that there is always a possibility of braking.

[^5]
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Evaluation of LTL in a state.
We consider all traces starting in a given state.

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A G E F (brake == true)

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(1) $\left(T_{i}, s_{0}\right) \models A F G\left(\right.$ black = true) but $\left(T_{i}^{\prime}, s_{0}\right) \not \models A F G$ (black = true).
(2) $\left(T_{i}, s_{0}\right)$ and $\left(T_{i}^{\prime}, s_{0}^{\prime}\right)$ are not distinguished by any CTL formula of the modal depth $i$.

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Look: https://www.youtube.com/watch?v=0Af7q3X71-o (min 58)

## Proof.



Let $\sim_{i}$ not distinguishable by CTL formulas of depth $i$.

Lemma (Auxiliary)
$P_{i} \sim_{i} P_{j}$ for $i \leq j . R_{i} \sim_{i} R_{j}$ for $i \leq j$.

## Proof.

Via induction on $i$, ( the size of the formula).
Induction hypothesis:
$P_{k} \sim_{i} P_{j}, R_{k} \sim_{i} R_{j}$ for $i \leq k \leq j$.

## Proof.



Let $\sim_{i}$ not distinguishable by CTL formulas of depth $i$.

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T_{i} \sim_{i} T_{i}^{\prime}
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T_{k} \sim_{i} T_{j}^{\prime} \text { for } i \leq k \leq j
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## Evaluation of CTL

## Lemma

A CTL formula $\phi$ can be evaluated in time proportional to the length of the formula times size of the Kripke structure.

## Proof.

By induction on the derivation tree of the formula.

## Bisimulation and CTL

## Lemma

Two configurations $s$ and $s^{\prime}$ are bisimilar if and only if $s$ and $s^{\prime}$ can not be distinguished by any CTL formula $\phi$.

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- If they are not distinguishable by CTL, then they are not distinguishable by HML with predicates.


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- Indeed, HML with predicates is a fragment of CTL.


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- We already proved that if $\left(s, s^{\prime}\right)$ are not distinguished by HML then they are bisimilar.


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- The proof for HML extended with predicates is the same.


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## Proof $\rightarrow$

We need to extend our understanding of bisimulation first.

## Game characterisation of Bisimilarity

## Definition

A bisimulation game is played in rounds between two players Spoiler and Duplicator. Arena is a set of pairs of configurations of the Kripke structure. Suppose that current pair of configurations is $\left(s, s^{\prime}\right)$. Rules of a round are as follows:

- First Spoiler chooses one of configurations $s$ or $s^{\prime}$. Without lost of generality we may assume that it is $s$.
- Next he chooses a configuration $t$ such that $s \rightarrow t$.
- Next Duplicator chooses a configuration $t^{\prime}$ such that $s^{\prime} \rightarrow t^{\prime}$ where $s^{\prime}$ is a configuration no chosen by Spoiler.
- The next round of the game will be plaid from $\left(t, t^{\prime}\right)$.

Winning conditions:

- If $L(s) \neq L\left(s^{\prime}\right)$ then Spoiler wins.
- If any player can not make his part of the move then he looses.
- Infinite plays are won by Duplicator.


## Lemma

Duplicator has a winning strategy in the bisimulation game starting from a pair of configurations $\left(s, s^{\prime}\right)$ if and only if $s \sim s^{\prime}$.

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A winning strategy for Spoiler is a tree.

## Bisimulation and CTL

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Two configurations $s$ and $s^{\prime}$ are bisimilar if and only if $s$ and $s^{\prime}$ are not distinguished by any CTL formula $\phi$.

Proof $\rightarrow$ ( bisimilar $\Longrightarrow$ not distinguishable by any CTL formula).

- If they are distinguishable by CTL, then they are distinguishable by some formula $\phi$.
- We construct a winning strategy for Spoiler via induction on the modal depth of the formula.


## Extend even more - CTL*

## Definition

A state formula $\phi=t t\left|\neg \phi_{1}\right| \phi_{1} \wedge \phi_{2}\left|p_{i}\right| A \alpha \mid F \alpha$
A path formula (restricted LTL) $\alpha=\phi\left|\neg \alpha_{1}\right| \alpha_{1} \wedge \alpha_{2}\left|X \alpha_{1}\right| \alpha_{1} U \alpha_{2}$

## Semantics

- A $\alpha$ for every run $r$ starting at the current configuration the formula $\alpha$ holds for $\mathbb{T} \mathbb{R}(r)$.
- $F \alpha$ there is a run $r$ starting at the current configuration such that the formula $\alpha$ holds for $\mathbb{T} \mathbb{R}(r)$.


## Fact <br> CTL* subsumes CTL and LTL.

## Bibliography

## CTL, CTL*

https://www.youtube.com/channel/UCUXDMaaobCO1He1HBiFZnPQ
Unites: 9, 10, 11.
Bisimulation + CTL and more:
https://pdfs.semanticscholar.org/cb9f/
325389bd6ee5894dcf435159d34f9e20da2d.pdf


[^0]:    ${ }^{a}$ exercise from
    https://www.win.tue.nl/ andova/education/2IF25/Ex2Solutions.pdf

[^1]:    ${ }^{a}$ exercise from
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[^2]:    ${ }^{a}$ exercise from
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