Analytic Cut-free Tableaux for Regular Modal Logics of Agent Beliefs

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Abstract. We present a sound and complete tableau calculus for a class $\mathcal{BR}eg$ of extended regular modal logics which contains useful epistemic logics for reasoning about agent beliefs. Our calculus is cut-free and has the analytic superformula property so it gives a decision procedure. Applying sound global caching to the calculus, we obtain the first optimal (EXPTime) tableau decision procedure for $\mathcal{BR}eg$. We demonstrate the usefulness of $\mathcal{BR}eg$ logics and our tableau calculus using the wise men puzzle and its modified version, which requires axiom (5) for single agents.

1 Introduction

Context-free grammar logics are normal multimodal logics characterised by "inclusion axioms" of the form $[t]\varphi\supset [s_1]\dots [s_k]\varphi$, where [t] and $[s_i]$ are modalities indexed by members t and s_i from some fixed set \mathcal{MOD} of indices. Such logics are useful for modelling interactions between agents and groups of agents when indices from \mathcal{MOD} denote agents/groups of agents. The general satisfiability problem of context-free grammar logics is undecidable [4], so researchers paid attention also to regular grammar logics, which are context-free grammar logics whose set of the corresponding grammar rules $t\to s_1\dots s_k$ forms either a left/right linear grammar or is specified by finite automata [4,6,7,9]. Note that a left/right linear grammar can be transformed in polynomial time to an equivalent finite automaton, and vice versa, and checking whether a context-free grammar generates a regular language is undecidable (see, e.g., [17]). To avoid ambiguity, we refer to regular grammar logics specified by finite automata as regular modal logics. (Due to the polynomial transformation, there is no big difference between the two notions.)

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Regular modal logics cannot be directly used for reasoning about belief due to the lack of axioms (D) and (5). It is commonly assumed that modal logics of belief invariably utilise the following:

Belief Consistency: Since $\langle t \rangle \varphi \equiv \neg [t] \neg \varphi$, axiom $(D) : [t] \varphi \supset \langle t \rangle \varphi$ states that agents cannot believe both φ and $\neg \varphi$.

Positive Introspection: Axiom (4): $[t]\varphi\supset [t][t]\varphi$ states that agents are aware of what they believe.

Negative Introspection: Axiom (5) : $\langle t \rangle \varphi \supset [t] \langle t \rangle \varphi$, or alternatively $\neg [t] \psi \supset [t] \neg [t] \psi$, states that agents are aware of what they do not believe.

In [21], Nguyen studied a multimodal logic $KD4I_g5_a$ for reasoning about belief and common belief of agents in multi-agent systems. He adopted axioms (D) and (4) for all agents and groups of agents, and axiom $(I):[t]\varphi\supset[s]\varphi$ for any (proper) super-group t of a group (or a single agent) s, but adopted axiom $(5):\langle t\rangle\varphi\supset[t]\langle t\rangle\varphi$ only for single agents t. If t is a non-singleton group and s is a single agent belonging to t, then the contra-positive of $[t]\varphi\supset[s]\varphi$ gives us $\langle s\rangle\varphi\supset\langle t\rangle\varphi$. If axiom (5) were present for the proper group t then $\langle s\rangle\varphi$ would give us $[t]\langle t\rangle\varphi$. But $\langle s\rangle\varphi\supset[t]\langle t\rangle\varphi$ states that the belief of a single agent s leads to a belief among the whole super-group t about φ . Conversely, the contra-positive $\langle t\rangle[t]\varphi\supset[s]\varphi$ states that if the group jointly does not believe that it does not jointly believe φ , then single agent s believes φ , which seems equally absurd. The logic $KD4I_g5_a$ formalises the most important properties of belief and common belief but does not give an exact formulation of common belief. It is similar to the well-known modal logic with common belief $KD45_n^C$ [13] and the modal logic with mutual belief [1] but it lacks the induction rule for common belief.

In this paper, we study the class $\mathcal{BR}eg$ of regular modal logics of agent beliefs, which are regular modal logics extended with axioms (D) and (5), where axiom (5) is adopted only for modal indices with the "terminal KD45-condition" as for the case of single agents in $KD4I_g5_a$ (see Section 2.2 for a formal definition). We extend our tableau calculus for regular modal logics [9] to a tableau calculus for $\mathcal{BR}eg$ logics. Our calculus for $\mathcal{BR}eg$ is sound, complete, cut-free and has the analytic superformula property. Applying sound global caching [9,11] to it, we obtain the first optimal (EXPTime) tableau decision procedure for $\mathcal{BR}eg$. Note that standard tableau algorithms without global caching for regular modal logics and $\mathcal{BR}eg$ logics do not belong to EXPTime (but NEXPTime or 2NEXPTime).

The rest of this paper is structured as follows. In the end of this section, we present motivational examples and mention related works. In Section 2, we formally specify $\mathcal{BR}eg$ logics, introduce automaton-modal operators, and give definitions for tableau calculi. In Section 3, we present our tableau calculus for $\mathcal{BR}eg$, prove its soundness, and present "closed" tableaux for the motivational examples. In Section 4, we prove completeness of our tableau calculus. In Section 5, we present an EXPTime decision procedure with global caching for $\mathcal{BR}eg$. Section 6 concludes this work.

1.1 Motivational Examples

We will study two motivational examples about reasoning about beliefs and common beliefs of agents using our tableau calculus for $\mathcal{BR}eg$. The first one is the wise men puzzle, which is a famous benchmark introduced by McCarthy [18] for AI and has previously been studied in a considerable number of works (see [21] for some of them). The puzzle can be stated as follows (cf. [16]). A king wishes to know whether his three advisors (a, b, c) are as wise as they claim to be. Three chairs are lined up, all facing the same direction, with one behind the other. The wise men are instructed to sit down in the order a, b, c. Each of the men can see the backs of the men sitting before them (e.g. c can see a and b). The king informs the wise men that he has three cards, all of which are either black or white, at least one of which is white. He places one card, face up, behind each of the three wise men, explaining that each wise man must determine the colour of his own card. Each wise man must announce the colour of his own card as soon as he knows what it is. All know that this will happen. The room is silent; then, after a while, wise man a says "My card is white!".

For $x \in \{a, b, c\}$, let $[x]\varphi$ stand for "the wise man x believes in φ " and let p_x stand for "the card of x is white". Let g denote the group $\{a, b, c\}$ and let [g] informally stand for a certain operator of "common belief" of the group g. Let L_{wmp} be the $\mathcal{BR}eg$ logic which extends K_n (n=4 and $\mathcal{MOD}=\{g,a,b,c\})$ with the following axioms:

$$[x]\varphi \supset \langle x\rangle \varphi$$
 and $[x]\varphi \supset [x][x]\varphi$ for $x \in \{g, a, b, c\}$, $[g]\varphi \supset [x]\varphi$ and $\langle x\rangle \varphi \supset [x]\langle x\rangle \varphi$ for $x \in \{a, b, c\}$.

The wise men puzzle can be formalised as follows:

– If y sits behind x then either x's card is white or y knows that x's card is not white:

$$\varphi_1 = [g](p_a \vee [b] \neg p_a), \quad \varphi_2 = [g](p_a \vee [c] \neg p_a), \quad \varphi_3 = [g](p_b \vee [c] \neg p_b).$$

- At least one of the men has a white card:

$$\varphi_4 = [g](p_a \vee p_b \vee p_c).$$

- As b and c say nothing, all of the wise men have a common belief that each of b and c does not believe that his own card is white, which is written in the negation normal form as:

$$\varphi_5 = [g]\langle b \rangle \neg p_b, \qquad \varphi_6 = [g]\langle c \rangle \neg p_c.$$

Here, we omit the temporal aspect to make the formalisation simple.

- The question is whether a believes that his card is white $([a]p_a)$. That is, whether $(\varphi_1 \wedge \ldots \wedge \varphi_6) \supset [a]p_a$ is L_{wmp} -valid. This is equivalent to whether the formula set $\Gamma_{wmp} = \{\varphi_1, \ldots, \varphi_6, \langle a \rangle \neg p_a\}$ is L_{wmp} -unsatisfiable.

As we will see, the wise men puzzle is solvable in a regular modal logic without axioms (D) and (5). More specifically, Γ_{wmp} is unsatisfiable in the logic L'_{wmp} obtained from L_{wmp} by discarding axioms (D) and (5). So, we introduce a modified version of the wise men puzzle for which axiom (5) is necessary³: "The wise men sit in the order a, b, c, all facing the same direction. Each of the men can see the backs of the men sitting before them (e.g. c can see a and b). The king informs the wise men that he has three cards, all of which are either black or white, at least one of which is white. He places one card, face up, behind each of the three wise men, explaining that as soon as b or c knows that his own card is white or that the card of the man behind is white he must inform the man in the front about that⁴, and as soon as a knows who has a white card he must announce that. The question is whether a will know who has a white card." To formulate the new puzzle, we discard the formulae φ_5 and φ_6 and add to the formula set the following formulae:

$$\varphi_5' = [g]([c]p_c \supset [b]p_c) \quad \varphi_6' = [g]([b]p_b \supset [a]p_b) \quad \varphi_7' = [g]([b]p_c \supset [a]p_c)$$

The new formula set is thus $\Delta_1 = \{\varphi_1, \varphi_2, \varphi_3, \varphi_4, \varphi_5', \varphi_6', \varphi_7'\}$. The question is whether $\Delta_1 \supset [a]p_a \lor [a]p_b \lor [a]p_c$ is L_{wmp} -valid, or equivalently, whether $\Delta_{wmp} = \Delta_1 \cup \{\langle a \rangle \neg p_a, \langle a \rangle \neg p_b, \langle a \rangle \neg p_c\}$ is L_{wmp} -unsatisfiable.

1.2 Related Works

In the previous work [9], we gave an analytic tableau calculus for regular modal logics and presented an EXPTime decision procedure for such logics. The class $\mathcal{BR}eg$ studied in this paper extends the class of regular modal logics with useful epistemic logics for reasoning about agent beliefs.

Regular grammar logics extended with axiom (5) belong to the class of regular grammar logics with converse [7], but such a statement with (5) replaced by (D) is not true. Adding axiom (D) to regular grammar logics with converse results in a class larger than $\mathcal{BR}eg$. In [7], Demri and de Nivelle gave a translation of the satisfiability problem for grammar logics with converse into the two-variable guarded fragment GF^2 of first-order logic, and showed that the general satisfiability problem for regular grammar logics with converse is in EXPTime. Assuming that it is easy to extend the translation with axiom (D) to cope with $\mathcal{BR}eg$, we cannot compare efficiency of the two approaches (for $\mathcal{BR}eg$) yet, but our tableau decision procedure for $\mathcal{BR}eg$ is certainly worth studying and experimenting.

Our tableau decision procedure for $\mathcal{BR}eg$ uses global caching, which we have used for regular modal logics [9], description logics \mathcal{ALC} [10] and \mathcal{SHI} [11]. Our adaptation of global caching for $\mathcal{BR}eg$ only slightly differs from the one used for the other logics. We include Section 5 on global caching for $\mathcal{BR}eg$ to increase readability and do not count it as a main contribution of this paper.

³ It can be shown that the formula set Δ_{wmp} given below is L'_{wmp} -satisfiable.

⁴ It does not matter whether the 3rd man notices this or not.

Other related works are works on regular grammar logics [4,6], works on PDL-like logics (e.g. [14,5,2]), and works on epistemic logics (e.g. [13,1]). However, the first two groups often lack axioms (D) and (5) and are not devoted to reasoning about epistemic states of agents, while the third group often adopts only some specific axioms but not the wide range of inclusion axioms. The class of "incestual multimodal logics" studied by Baldoni in [3] is large and contains the class $\mathcal{BR}eg$, but the general satisfiability problem for it is undecidable. Notice that such a problem is EXPTime-complete for regular grammar/modal logics [6], regular grammar logics with converse [7], PDL and converse-PDL (see, e.g., [14]), and $KD45_n^C$ with $n \geq 2$ [13]. As $\mathcal{BR}eg$ contains all regular modal logics, our EXPTime decision procedure presented in this paper for $\mathcal{BR}eg$ is optimal.

2 Preliminaries

2.1 Definitions for Multimodal Logics

Our modal language is built from two disjoint sets: \mathcal{MOD} is a finite set of modal indices and \mathcal{PROP} is a set of primitive propositions. We use p and q for (arbitrary) elements of \mathcal{PROP} and use t and s for (arbitrary) elements of \mathcal{MOD} . Formulae of our primitive language are recursively defined using the BNF grammar:

$$\varphi ::= p \mid \neg \varphi \mid \varphi \land \varphi \mid \varphi \lor \varphi \mid \varphi \supset \varphi \mid [t]\varphi \mid \langle t \rangle \varphi.$$

A Kripke frame is a tuple $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}} \rangle$, where W is a nonempty set of possible worlds, $\tau \in W$ is the current world, and each R_t is a binary relation on W, called the accessibility relation for [t] and $\langle t \rangle$.⁵ If $R_t(w, u)$ holds then we say that the world w sees world u via R_t .

A Kripke model is a tuple $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, h \rangle$, where $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}} \rangle$ is a Kripke frame and h is a function mapping worlds to sets of primitive propositions. For $w \in W$, the set of primitive propositions "true" at w is h(w).

A model graph is a tuple $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, H \rangle$, where $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}} \rangle$ is a Kripke frame and H is a function mapping worlds to formula sets. We sometimes treat model graphs as models with the range of H restricted to \mathcal{PROP} .

Given a Kripke model $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, h \rangle$ and a world $w \in W$, the satisfaction relation \models is defined as usual for the classical connectives with two extra clauses for the modalities as below:

$$M, w \models [t]\varphi$$
 iff $\forall v \in W. \ R_t(w, v)$ implies $M, v \models \varphi$
 $M, w \models \langle t \rangle \varphi$ iff $\exists v \in W. \ R_t(w, v)$ and $M, v \models \varphi$.

We say that φ is satisfied at w in M if $M, w \models \varphi$. We say that M satisfies φ and call M a model of φ if $M, \tau \models \varphi$.

If we consider only Kripke models, with no restrictions on R_t , we obtain a normal multimodal logic with a standard Hilbert-style axiomatisation K_n .

⁵ By writing $(R_t)_{t \in \mathcal{MOD}}$ instead of using R as a function that maps t to a binary relation R_t , we emphasize that the frame is for a multimodal logic.

Note: We now assume that, if not stated otherwise, formulae are in *negation* normal form, where \supset is translated away and \neg occurs only directly before primitive propositions. It is well known that every formula φ has a logically equivalent formula φ' which is in negation normal form. We treat a finite set of formulae as the conjunction of its formulae.

2.2 A Class $\mathcal{BR}eg$ of Regular Modal Logics of Agent Beliefs

A $\mathcal{BR}eg$ logic is a normal multimodal logic L extending K_n with:

Inclusion Axioms: a set IA(L) of inclusion axioms $[t]\varphi\supset [s_1]\dots [s_k]\varphi$ with $k\geq 0$ whose corresponding grammar rules $t\to s_1\dots s_k$ jointly form a grammar RG(L) specified by finite automata $(A_s)_{s\in\mathcal{MOD}}$ such that A_s for $s\in\mathcal{MOD}$ recognises the set of words derivable from s using the rules of RG(L);⁶

Seriality Axioms: a set of seriality axioms $[t]\varphi \supset \langle t\rangle\varphi$ for every t of a set $\mathcal{DI}(L)\subseteq\mathcal{MOD}$ of D-indices;

Terminal KD45-Condition: a set of axioms $[t]\varphi\supset [t][t]\varphi\in IA(L)$ and $\langle t\rangle\varphi\supset [t]\langle t\rangle\varphi$ for every t of a set $\mathcal{EI}(L)\subseteq\mathcal{DI}(L)$ of E-indices, with the condition that IA(L) contains no other inclusion axioms of the form $[t]\varphi\supset [s_1]\ldots [s_k]\varphi$ for $t\in\mathcal{EI}(L)$.

Recall that a *finite automaton* A is a tuple $\langle \Sigma, Q, I, \delta, F \rangle$, where: Σ is the alphabet (for our case $\Sigma = \mathcal{MOD}$); Q is a finite set of states; $I \subseteq Q$ is the set of initial states; $\delta \subseteq Q \times \Sigma \times Q$ is the transition relation; and $F \subseteq Q$ is the set of accepting states. A run of A on a word $s_1 \dots s_k$ is a finite sequence of states q_0, q_1, \dots, q_k such that $q_0 \in I$ and $\delta(q_{i-1}, s_i, q_i)$ holds for every $1 \le i \le k$. It is an accepting run if $q_k \in F$. We say that A accepts word w if there exists an accepting run of A on w. The set of all words accepted/recognised by A is $\mathcal{L}(A)$.

We do not require axiom (D) for every modal index in order to allow $\mathcal{BR}eg$ to contain all regular modal logics. But, if every modal index denotes either an agent or a group of agents, then we can assume that $\mathcal{DI}(L) = \mathcal{MOD}$. We allow axiom (5) only for modal indices which satisfy the terminal KD45-condition. This restriction can be justified from practical considerations stated for $KD4I_g5_a$ in the introduction. It can be shown that the multimodal logics of belief KDI4, $KDI4_s$, $KD4I_g$, $KD4I_g5_a$ studied by Nguyen in [20, 21], as well as $KD45_{(m)}$, belong to $\mathcal{BR}eg$. The monomodal logics K, KD, T, K4, KD4, S4, KD45 belong to $\mathcal{BR}eg$, but KB, KDB, B, K5, KD5, K45, KB5 (KB4), S5 do not.

Given two binary relations R_1 and R_2 over W, their relational composition $R_1 \circ R_2 = \{(x, z) \mid \exists y \in W.R_1(x, y) \& R_2(y, z)\}$ is also a binary relation over W. The *L-frame restrictions* for a $\mathcal{BR}eg$ logic L are the following restrictions:

- $-R_{s_1} \circ \ldots \circ R_{s_k} \subseteq R_t$ if $s_1 \ldots s_k$ is accepted by A_t , where $t \in \mathcal{MOD}$ and $(A_s)_{s \in \mathcal{MOD}}$ are the finite automata specifying RG(L);
- R_t is serial (i.e. $\forall u \exists w \, R_t(u, w)$) for each D-index $t \in \mathcal{DI}(L)$;

⁶ If k = 0 then the right hand side of $t \to s_1 \dots s_k$ stands for the empty word ε . \mathcal{MOD} is used both as the set of terminal symbols and the set of grammar variables.

- R_t is transitive and euclidean (i.e. $\forall u, v, w \, R_t(u, v) \land R_t(v, w) \rightarrow R_t(u, w)$ and $\forall u, v, w \, R_t(u, v) \land R_t(u, w) \rightarrow R_t(w, v)$) for each E-index $t \in \mathcal{EI}(L)$.

A Kripke model is an L-model if its frame satisfies all L-frame restrictions. A formula φ is L-satisfiable if there exists an L-model satisfying it. A formula φ is L-valid if every L-model satisfies it. It can be shown that for a $\mathcal{BR}eg$ logic L, a formula φ is L-valid iff it is derivable using the axiomatisation of L. (See [24] for the correspondence theory.)

2.3 Some Properties of BReg Logics

Let L be a $\mathcal{BR}eg$ logic. For $t \in \mathcal{EI}(L)$, logic L contains the axiom $\langle t \rangle \varphi \supset [t] \langle t \rangle \varphi$, which can also be written as $\langle t \rangle [t] \psi \supset [t] \psi$. This latter axiom implies the inclusion axiom $[t][t] \psi \supset [t] \psi$ (because $t \in \mathcal{EI}(L) \subseteq \mathcal{DI}(L)$ and $[t][t] \psi \supset \langle t \rangle [t] \psi$ is L-valid), which corresponds to the grammar rule $tt \to t$. Let eRG(L) be the grammar extending RG(L) with rules $tt \to t$ for $t \in \mathcal{EI}(L)$. We call eRG(L) the extended grammar of L. Syntactically, eRG(L) is not a regular grammar.

Let L be a $\mathcal{BR}eg$ logic and let $(A_t)_{t\in\mathcal{MOD}}$ be the automata specifying the regular grammar RG(L). An s-path from state q_0 to state q_n in A_t is a sequence of transitions $(q_0, s, q_1), (q_1, s, q_2), \ldots, (q_{n-2}, s, q_{n-1}), (q_{n-1}, s, q_n)$ in δ_t , with $n \geq 1$. For each $t \in \mathcal{MOD} \setminus \mathcal{EI}(L)$, let A'_t be the automaton obtained from A_t by the following modification: for every $s \in \mathcal{EI}(L)$ and every s-path from state q_0 to state q_n in A_t , add the transition (q_0, s, q_n) to A'_t . We call the resulting automata A'_t , for $t \in \mathcal{MOD} \setminus \mathcal{EI}(L)$, the automata specifying eRG(L). It should be clear that, for $t \in \mathcal{MOD} \setminus \mathcal{EI}(L)$, the word $s_1 \ldots s_k$ is accepted by A'_t iff $s_1 \ldots s_k$ is derivable from t using the grammar eRG(L) since the modification simply adds "s-transitivity" for every $s \in \mathcal{EI}(L)$. Thus eRG(L) can be treated as a regular grammar for starting symbols outside $\mathcal{EI}(L)$.

Example 1. The logic L_{wmp} specified in the introduction is a $\mathcal{BR}eg$ logic with $\mathcal{DI}(L_{wmp}) = \{g, a, b, c\}$, $\mathcal{EI}(L_{wmp}) = \{a, b, c\}$, and the extended grammar $eRG(L_{wmp})$ specified by the following finite automaton

$$A_q = \langle \mathcal{MOD}, \{0, 1\}, \{0\}, \{(0, x, 0), (0, x, 1) \mid x \in \mathcal{MOD}\}, \{1\} \rangle,$$

which accepts all non-empty finite words over \mathcal{MOD} .

Example 2. The logic S4 is a $\mathcal{BR}eg$ logic with $\mathcal{DI}(S4) = \mathcal{MOD} = \{a\}, \mathcal{EI}(S4) = \emptyset$, and the regular grammar RG(S4) specified by the following finite automaton

$$A_a = \langle \{a\}, \{0\}, \{0\}, \{(0, a, 0)\}, \{0\} \rangle,$$

which accepts all finite sequences of a (in particular ε , and therefore is not an automaton for K4).

Lemma 1. Let L be a $\mathcal{BR}eg$ logic and $t \in \mathcal{MOD} \setminus \mathcal{EI}(L)$. Then, for every $n \geq 1$, and every $s_1, s_2, \dots, s_n \in \mathcal{MOD}$, if the word $s_1 \dots s_n$ is derivable from t using the grammar eRG(L) then the formula $[t]\varphi \supset [s_1] \dots [s_n]\varphi$ is L-valid.

Proof. By induction on the length of the derivation of $s_1 \dots s_k$ from t using eRG(L).

For a set Q of states of automaton A, the pair (A, Q) can be treated as the automaton obtained from A by replacing the set of initial states by Q. Thus, $\mathcal{L}(A, Q)$ denotes the language generated by (A, Q).

Let $A = \langle \mathcal{MOD}, Q_A, I_A, \delta_A, F_A \rangle$ and let ε denote the empty word. For any $Q \subseteq Q_A$, any $t \in \mathcal{MOD}$, and any word α over alphabet \mathcal{MOD} , define:

$$\begin{split} & \delta_A(Q,t) = \{q' \,|\, \exists q \in Q. (q,t,q') \in \delta_A\}, \\ & \widetilde{\delta_A}(Q,\varepsilon) = Q, \\ & \widetilde{\delta_A}(Q,\alpha t) = \delta_A(\widetilde{\delta_A}(Q,\alpha),t). \end{split}$$

For $A_s = \langle \mathcal{MOD}, Q_s, I_s, \delta_s, F_s \rangle$, we write δ_s (resp. $\widetilde{\delta_s}$) instead of δ_{A_s} (resp. $\widetilde{\delta_{A_s}}$).

Lemma 2. Let L be a $\mathcal{BR}eg$ logic, $(A_t)_{t \in \mathcal{MOD} \setminus \mathcal{EI}(L)}$ the automata specifying eRG(L), $s \in \mathcal{MOD} \setminus \mathcal{EI}(L)$, $A_s = \langle \mathcal{MOD}, Q_s, I_s, \delta_s, F_s \rangle$, and $Q = \widetilde{\delta}_s(I_s, \alpha_1) \cup \ldots \cup \widetilde{\delta}_s(I_s, \alpha_h)$ for some words $\alpha_1, \ldots \alpha_h$ over alphabet \mathcal{MOD} . Then:

- 1. If $t \to s_1 \dots s_k$ is a rule of RG(L) then $\mathcal{L}(A_s, \widetilde{\delta_s}(Q, t)) \subseteq \mathcal{L}(A_s, \widetilde{\delta_s}(Q, s_1 \dots s_k))$.
- 2. If $t \in \mathcal{EI}(L)$ then $\mathcal{L}(A_s, \widetilde{\delta_s}(Q, t)) = \mathcal{L}(A_s, \widetilde{\delta_s}(Q, tt))$.
- 3. If $\mathcal{L}(A_s, Q') \subseteq \mathcal{L}(A_s, Q'')$ then $\mathcal{L}(A_s, \widetilde{\delta_s}(Q', t)) \subseteq \mathcal{L}(A_s, \widetilde{\delta_s}(Q'', t))$.

Proof. Since $\delta_s(Q' \cup Q'', t) = \delta_s(Q', t) \cup \delta_s(Q'', t)$ for all $Q', Q'' \subseteq Q_s$, for assertions 1 and 2, we can assume $Q = \widetilde{\delta_s}(I_s, \alpha)$ for some word α .

- 1: Suppose β is a word over alphabet \mathcal{MOD} , and $\beta \in \mathcal{L}(A_s, \widetilde{\delta_s}(Q, t))$. Thus $\alpha t \beta \in \mathcal{L}(A_s)$. If $t \to s_1 \dots s_k$ is a rule of RG(L), it follows that $\alpha s_1 \dots s_k \beta \in \mathcal{L}(A_s)$. Hence $\beta \in \mathcal{L}(A_s, \widetilde{\delta_s}(Q, s_1 \dots s_k))$.
- 2: Since $t \to tt$ is a rule of RG(L) for all $t \in \mathcal{EI}(L)$, the first assertion gives one half of the inclusion. It therefore suffices to show that $\mathcal{L}(A_s, \widetilde{\delta_s}(Q, tt)) \subseteq \mathcal{L}(A_s, \widetilde{\delta_s}(Q, t))$. Let $\beta \in \mathcal{L}(A_s, \widetilde{\delta_s}(Q, tt))$. Thus $\alpha tt\beta \in \mathcal{L}(A_s)$. Because $t \in \mathcal{EI}(L)$, we have $tt \to t$ as a grammar rule of eRG(L). It follows that t is derivable from tt using the grammar eRG(L). Since A_s recognises the language derivable from s using eRG(L), it follows that $\alpha t\beta \in \mathcal{L}(A_s)$. Hence $\beta \in \mathcal{L}(A_s, \widetilde{\delta_s}(Q, t))$.
- 3: The third assertion clearly holds.

2.4 Automaton-Modal Formulae

If A is a finite automaton, Q is a subset of the states of A, and φ is a formula in the primitive language then we call [A,Q] a (universal) automaton-modal operator and $[A,Q]\varphi$ a formula in the extended language. Note that an automaton-modal

operator can appear only at the beginning of a formula. Similar constructions were previously used in [14, 15, 9].

Given a Kripke model $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, h \rangle$ and $w_0 \in W$, define that $M, w_0 \models [A, Q]\varphi$ if $M, w_k \models \varphi$ for every path $w_0 R_{s_1} w_1 \dots w_{k-1} R_{s_k} w_k$ with $k \geq 0$ and $\widetilde{\delta_A}(Q, s_1 \dots s_k) \cap F_A \neq \emptyset$ (i.e. there exists a state of Q such that A accepts the word $s_1 \dots s_k$ when starting from that state).

From now on, by a *formula* we mean either a formula in the primitive language (as defined in Section 2.1) or an automaton-modal formula.

2.5 Definitions for Tableau Calculi

As in our previous works on tableau calculi [8,19], our tableaux trace their roots to Hintikka via [23]. A tableau rule σ consists of a numerator N above the line and a (finite) list of denominators D_1, D_2, \ldots, D_k (below the line) separated by vertical bars. The numerator is a finite formula set, and so is each denominator. As we shall see later, each rule is read downwards as "if the numerator is L-satisfiable, then so is one of the denominators". The numerator of each tableau rule contains one or more distinguished formulae called the *principal formulae*. A tableau calculus CL for a logic L is a finite set of tableau rules.

A CL-tableau for a finite set X of formulae is a tree with root X whose nodes carry finite formula sets obtained from their parent nodes by instantiating a tableau rule with the proviso that if a child s carries a set S and S has already appeared on the branch from the root to S then S is an S and S has already appeared on the branch from the root to S then S is an S and S has already

Let Δ be a set of tableau rules. We say that Y is obtainable from X by applications of rules from Δ if there exists a tableau for X which uses only rules from Δ and has a node that carries Y. A node to which no rule is applicable is also an end-node. A branch in a tableau is closed if its end node carries only \bot . A tableau is closed if every one of its branches is closed. A tableau is open if it is not closed. A finite formula set X is CL-consistent if every CL-tableau for X is open. If there is a closed CL-tableau for X then X is CL-inconsistent.

A tableau calculus $\mathcal{C}L$ is *sound* if for all finite formula sets X in the primitive language, X is L-satisfiable implies X is $\mathcal{C}L$ -consistent. It is *complete* if for all finite formula sets X in the primitive language, X is $\mathcal{C}L$ -consistent implies X is L-satisfiable. We say that a rule σ of $\mathcal{C}L$ is sound w.r.t. L if for every instance σ' of σ , if the numerator of σ' is L-satisfiable then so is one of the denominators of σ' . Any calculus $\mathcal{C}L$ containing only rules sound w.r.t. L is sound.

3 A Tableau Calculus for $\mathcal{BR}eg$ Logics

Fix a $\mathcal{BR}eg$ logic L and let $(A_t = \langle \mathcal{MOD}, Q_t, I_t, \delta_t, F_t \rangle)_{t \in \mathcal{MOD} \setminus \mathcal{EI}(L)}$ be the automata specifying eRG(L). Recall that formulae are in negation normal form.

⁷ In [9] we used the notation $(A,Q).\varphi$ instead of $[A,Q]\varphi$. We change the notation because the modal operator is a "universal" modal operator according to the next definition, and one can use $\langle A,Q\rangle\varphi$ for the dual existential modal operator.

$$(\bot) \ \frac{X; p; \neg p}{\bot} \qquad (\land) \ \frac{X; \varphi \land \psi}{X; \varphi \land \psi; \varphi; \psi} \qquad (\lor) \ \frac{X; \varphi \lor \psi}{X; \varphi \lor \psi; \varphi \mid X; \varphi \lor \psi; \psi}$$

$$(D) \ \frac{X}{X; \langle t \rangle \top} \ \text{if} \ t \in \mathcal{DI}(L) \qquad (5) \ \frac{X; \langle t \rangle \varphi}{X; \langle t \rangle \varphi; [t] \langle t \rangle \varphi} \ \text{if} \ t \in \mathcal{EI}(L)$$

$$(\text{aut}) \ \frac{X; [t] \varphi}{X; [t] \varphi; [A_t, I_t] \varphi} \ \text{if} \ t \notin \mathcal{EI}(L) \qquad (\text{add}) \ \frac{X; [A_t, Q] \varphi}{X; [A_t, Q] \varphi; \varphi} \ \text{if} \ Q \cap F_t \neq \emptyset$$

$$(\text{trans}) \ \frac{X; \langle t \rangle \varphi}{\text{trans}(X, t); \varphi} \ \text{if} \ t \notin \mathcal{EI}(L) \qquad (\text{trans4}) \ \frac{X; [t] Y; \langle t \rangle \varphi}{\text{trans}(X, t); Y; [t] Y; \varphi} \ \text{if} \ t \in \mathcal{EI}(L)$$

Table 1. Tableau Rules for $\mathcal{BR}eg$ Logics

We use X, Y to denote formula sets, use [t]X to denote the set $\{[t]\varphi \mid \varphi \in X\}$, and use \top to denote the truth constant with the usual semantics. We write X; Y for $X \cup Y$, write $X; \varphi$ for $X \cup \{\varphi\}$, and $\varphi; \psi$ for $\{\varphi, \psi\}$.

The transfer of X through $\langle t \rangle$, denoted by trans(X, t), is:

$$trans(X, t) = \{ [A_s, \delta_s(Q, t)] \psi \mid [A_s, Q] \psi \in X \}.$$

The tableau calculus CL is given in Table 1. For intuition of the use of automaton-modal formulae in tableaux, we refer the reader to Section 2.3 of [9]. The last two rules (trans) and (trans₄) of the calculus are transitional rules, while the remaining rules except (\perp) are static rules. The intuition of this sorting is that static rules keep us in the same world of the Kripke model under construction, while transitional rules take us to a new Kripke successor world.

Note that we include the principal formula of the static rules in their denominators. Thus, the numerator of any static rule is a subset of every one of its denominators. A set X is closed w.r.t. a tableau rule if applying that rule to X gives back X as one of the denominators. We implicitly assume that a static rule is applied to X only when X is not closed w.r.t. that rule and treat this as an (additional) condition for applying the rule.

In comparison with the calculus given in [9] for regular modal logics, our calculus for $\mathcal{BR}eg$ contains 3 more rules (D), (5), $(\mathsf{trans_4})$; the rule (\vee) slightly changes as described in the above paragraph; and the rule (aut) is the same as (label) . Note, however, that the automata used for (trans) , (aut) , (add) are now the ones specifying the extended grammar eRG(L) but not RG(L).

A tableau calculus $\mathcal C$ has the analytic superformula property iff to every finite set X we can assign a finite set $X^*_{\mathcal C}$ which contains all formulae that may appear in any tableau for X. We write $Sf(\varphi)$ for the set of all subformulae of φ , and Sf(X) for the set $\bigcup_{\varphi \in X} Sf(\varphi) \cup \{\bot\}$. Our calculus $\mathcal CL$ has the analytic

⁸ This allows an easier proof for soundness of global caching.

superformula property, with

$$X_{\mathcal{C}L}^* = Sf(X) \cup \{ [A_t, Q]\varphi \mid [t]\varphi \in Sf(X) \& Q \subseteq Q_t \}.$$

Lemma 3. The tableau calculus CL is sound.

Proof. We show that CL contains only rules sound w.r.t. L as follows. Suppose that the numerator of the considered rule is satisfied at a world w in an L-model $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, h \rangle$. We have to show that at least one of the denominators of the rule is also L-satisfiable. For the static rules, we show that some denominator is satisfied at w itself. For the transitional rules (trans) and (trans₄), we show that its denominator is satisfied at some world reachable from w via R_t in the same L-model.

- $(\bot), (\land), (\lor), (D), (5)$: These cases are obvious.
- (aut): Suppose that $M, w \models X; [t]\varphi$. Let $w_0 = w, w_1, \ldots, w_k$ be worlds of M such that $R_{s_i}(w_{i-1}, w_i)$ holds for $1 \le i \le k$ and $s_1 \ldots s_k$ is accepted by A_t . By Lemma 1, $[t]\psi \supset [s_1]\ldots [s_k]\psi$ is L-valid. Hence $M, w_k \models \varphi$. Thus, $M, w \models [A_t, I_t]\varphi$.
- (add): Suppose that $M, w \models X$; $[A_t, Q]\varphi$ and $Q \cap F_t \neq \emptyset$. Since $\widetilde{\delta}_t(Q, \varepsilon) = Q$, we have that $\widetilde{\delta}_t(Q, \varepsilon) \cap F_t \neq \emptyset$. Since $M, w \models [A_t, Q]\varphi$, it follows that $M, w \models \varphi$.
- (trans): Suppose that $M, w \models X; \langle t \rangle \varphi$. Then there exists some u such that $R_t(w, u)$ holds and $M, u \models \varphi$. For each $[A_s, Q]\psi \in X$, we have $M, w \models [A_s, Q]\psi$, and by the semantics of automaton-modal formulae, it follows that $M, u \models [A_s, \delta_s(Q, t)]\psi$. Hence, the denominator is satisfied at u.
- (trans₄): The proof for this case is similar to the proof for the case of (trans), with an additional justification that $[t]\psi\supset [t][t]\psi$ is an axiom of L when $t\in\mathcal{EI}(L)$.

3.1 Examples

In this subsection, we present closed tableaux for the formula sets formalising the wise men puzzle. Let L be the $\mathcal{BR}eg$ logic L_{wmp} defined in the introduction. Recall that the following automaton A_g specifies eRG(L):

$$A_q = \langle \mathcal{MOD}, \{0, 1\}, \{0\}, \{(0, x, 0), (0, x, 1) \mid x \in \mathcal{MOD}\}, \{1\} \rangle$$

In Figure 3.1, we give a closed $\mathcal{C}L$ -tableau for the formula set Γ_{wmp} , which was specified in the introduction for formalising the wise men puzzle. In that tableau, for $1 \leq i \leq 6$, φ_i is the formula as in the introduction, ψ_i is the subformula of φ_i such that $\varphi_i = [g]\psi_i$, $\Gamma_1 = \{\varphi_1, \ldots, \varphi_6\}$, $\Gamma_2 = \{[A_g, \{0\}]\psi_1, \ldots, [A_g, \{0\}]\psi_6\}$, and $\Gamma_3 = \{[A_g, \{0,1\}]\psi_1, \ldots, [A_g, \{0,1\}]\psi_6\}$. Since the tableau calculus $\mathcal{C}L$ is sound, it follows that Γ_{wmp} is L-unsatisfiable.

For the modified version of the wise men puzzle, let $\varphi_1, \ldots, \varphi_4, \varphi'_5, \varphi'_6, \varphi'_7$ be the formulae as in the introduction. In the negation normal form, we have that:

$$\varphi_5' = [g](\langle c \rangle \neg p_c \vee [b]p_c) \quad \varphi_6' = [g](\langle b \rangle \neg p_b \vee [a]p_b) \quad \varphi_7' = [g](\langle b \rangle \neg p_c \vee [a]p_c)$$

Γ_{wmp} $6(aut)$							
,							
$arGamma_1; arGamma_2; \langle a angle eg p_a \ (trans_4)$							
$\Gamma_3; \neg p_a \ \ 2(add)$							
$\Gamma_3; \neg p_a; p_a \lor [b] \neg p_a; \langle b \rangle \neg p_b \ (\lor)$							
$\neg p_a; p_a;$	$\Gamma_3; \neg p_a; [b] \neg p_a; \langle b \rangle \neg p_b \ \ (trans_4)$						
	$\Gamma_3; \neg p_a; [b] \neg p_a; \neg p_b \ \ 3(add)$						
	$\Gamma_3; \neg p_a; [b] \neg p_a; \neg p_b; p_a \lor [c] \neg p_a; p_b \lor [c] \neg p_b; \langle c \rangle \neg p_c \ 2(\lor)$						
	$\neg p_a; p_a;$	$\neg p_b; p_b;$	$\boxed{\Gamma_3; \neg p_a; [b] \neg p_a; \neg p_b; [c] \neg p_a; [c] \neg p_b; \langle c \rangle \neg p_c \text{ (trans_4)}}$				
			$\Gamma_3; \neg p_a; \neg p_b; \neg p_c; [c] \neg p_a; [c] \neg p_b \text{ (add)}$				
			$\boxed{\Gamma_3; \neg p_a; \neg p_b; \neg p_c; [c] \neg p_a; [c] \neg p_b; p_a \lor p_b \lor p_c \ 2(\lor)}$				
			$\dots; \neg p_a; p_a$	$p_b; p_b$	$\dots; \neg p_c; p_c$		
			Ι Ι	Ι Τ	\perp		

$\Delta_1; \langle a \rangle \neg p_a; \langle a \rangle \neg p_b; \langle a \rangle \neg p_c \ 2(5)$						
$\varDelta_1; \varDelta_2; \langle a \rangle \neg p_a; \langle a \rangle \neg p_b; \langle a \rangle \neg p_c; [a] \langle a \rangle \neg p_b; [a] \langle a \rangle \neg p_c (trans_4)$						
$\Delta_3; \neg p_a; \langle a \rangle \neg p_b; \langle a \rangle \neg p_c; \dots \ \ 3(add)$						
$\boxed{\Delta_3; \neg p_a; \langle a \rangle \neg p_b; \langle a \rangle \neg p_c; \dots; p_a \vee [b] \neg p_a; \langle b \rangle \neg p_b \vee [a] p_b; \langle b \rangle \neg p_c \vee [a] p_c \ 3(res)}$						
$\Delta_3; \dots; [b] \neg p_a; \langle b \rangle \neg p_b; \langle b \rangle \neg p_c $ (5)						
$\Delta_3; \dots; [b] \neg p_a; \langle b \rangle \neg p_b; \langle b \rangle \neg p_c; [b] \langle b \rangle \neg p_c (trans_4)$						
$\Delta_3; \neg p_a; \neg p_b; \langle b \rangle \neg p_c; \dots \ 3(add)$						
$\Delta_3; \neg p_a; \neg p_b; \langle b \rangle \neg p_c; \dots; p_a \vee [c] \neg p_a; p_b \vee [c] \neg p_b; \langle c \rangle \neg p_c \vee [b] p_c 3(res)$						
$\Delta_3; \dots; [c] \neg p_a; [c] \neg p_b; \langle c \rangle \neg p_c (trans_4)$						
$\Delta_3;\ldots; eg p_a; eg p_b; eg p_c ext{ (add)}$						
$\Delta_3; \ldots; \neg p_a; \neg p_b; \neg p_c; p_a \lor p_b \lor p_c \ 2(\lor)$						
$\ldots; \neg p_a; p_a$	$\ldots; \neg p_b; p_b$	$\ldots; \neg p_c; p_c$				
		<u> </u>				

Fig. 1. Closed CL-Tableaux for the Wise Men Puzzle

For $1 \leq i \leq 7$, let ψ_i be the formula such that $\varphi_i = [g]\psi_i$ if $1 \leq i \leq 4$, and $\varphi_i' = [g]\psi_i$ if $i \in \{5,6,7\}$. Let $\Delta_1 = \{\varphi_1, \varphi_2, \varphi_3, \varphi_4, \varphi_5', \varphi_6', \varphi_7'\}$, $\Delta_2 = \{[A_g, \{0\}]\psi_i \mid 1 \leq i \leq 7\}$, and $\Delta_3 = \{[A_g, \{0,1\}]\psi_i \mid 1 \leq i \leq 7\}$. Let $\overline{\varphi}$ denote the negation normal form of $\neg \varphi$. Note that the following rule is "derivable" using the rules of $\mathcal{C}L$:

$$(\text{res}) \ \frac{X; \varphi \vee \psi; \overline{\varphi}}{X; \varphi \vee \psi; \overline{\varphi}; \psi} \quad \text{or} \quad \frac{X; \psi \vee \varphi; \overline{\varphi}}{X; \psi \vee \varphi; \overline{\varphi}; \psi}$$

In Figure 3.1, we also give a closed $\mathcal{C}L$ -tableau using the tableau rule (res) for the formula set $\Delta_{wmp} = \Delta_1 \cup \{\langle a \rangle \neg p_a, \langle a \rangle \neg p_b, \langle a \rangle \neg p_c\}$, which was specified in the introduction for formalising the modified version of the wise men puzzle. Since the tableau calculus $\mathcal{C}L$ is sound, it follows that Δ_{wmp} is L-unsatisfiable.

4 Completeness

4.1 Proving Completeness via Model Graphs

Let L be a $\mathcal{BR}eg$ logic. We prove completeness of our calculus via model graphs following [23, 8, 19, 9] by giving an algorithm that accepts a finite $\mathcal{C}L$ -consistent formula set X in the primitive language and constructs an L-model graph (defined below) for X that satisfies each of its formulae at the appropriate world.

For a finite CL-consistent formula set X, a formula set Y is called a CL-saturation of X if Y is a CL-consistent set obtainable from X by applications of the static rules of CL and closed w.r.t. the static rules of CL.

Lemma 4. Let X be a finite CL-consistent formula set and Y a CL-saturation of X. Then $X \subseteq Y \subseteq X_{CL}^*$. Furthermore, there is an effective procedure that, given a finite CL-consistent formula set X, constructs some CL-saturation of X.

Proof. Clearly, $X \subseteq Y \subseteq X_{\mathcal{C}L}^*$. Observe that if a static rule of $\mathcal{C}L$ is applicable to Y, then one of the corresponding instances of the denominators is $\mathcal{C}L$ -consistent. Since Y is a $\mathcal{C}L$ -saturation, Y is closed w.r.t. the static rules of $\mathcal{C}L$.

We construct a $\mathcal{C}L$ -saturation of X as follows: let Y=X; while some static rule of $\mathcal{C}L$ is applicable to Y and has a corresponding denominator instance Z which is $\mathcal{C}L$ -consistent and strictly contains Y, set Y=Z. At each iteration, $Y\subset Z\subseteq X_{\mathcal{C}L}^*$, so this process always terminates. Clearly, the resulting set Y is a $\mathcal{C}L$ -saturation of X.

A model graph is an *L*-model graph if its frame is an *L*-frame. An *L*-model graph $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, H \rangle$ is saturated if every $w \in W$ satisfies:

```
- if \varphi \wedge \psi \in H(w) then \{\varphi, \psi\} \subseteq H(w);

- if \varphi \vee \psi \in H(w) then \varphi \in H(w) or \psi \in H(w);

- if [t]\varphi \in H(w) and R_t(w, u) holds then \varphi \in H(u);

- if \langle t \rangle \varphi \in H(w) then \exists u \in W with R_t(w, u) and \varphi \in H(u).
```

A saturated model graph is *consistent* if no world contains \bot , and no world contains a pair of the form $\{p, \neg p\}$. Our model graphs are merely a data structure, while Rautenberg's are required to be saturated and consistent [23].

Lemma 5. If $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, H \rangle$ is a consistent saturated L-model graph, then M satisfies all formulae in the primitive language of $H(\tau)$.

Proof. By proving $\varphi \in H(w)$ implies $M, w \models \varphi$ via induction on the length of φ .

Given a finite $\mathcal{C}L$ -consistent set X in the primitive language, we construct a consistent saturated L-model graph $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, H \rangle$ such that $X \subseteq H(\tau)$, thereby giving an L-model for X.

4.2 Constructing Model Graphs

Given X, the compact form compact(X) of X is the smallest set such that:

- if $\varphi \in X$ and φ is not of the form $[A_t, Q]\psi$ then $\varphi \in \mathsf{compact}(X)$;
- if $[A_t,Q]\psi \in X$ and Q_1,\ldots,Q_k are all the sets such that $[A_t,Q_i]\psi \in X$ for $1 \leq i \leq k$, then $[A_t,Q_1\cup\ldots\cup Q_k]\psi \in \mathsf{compact}(X)$.

Observe that the compact form does not affect the essence of $\mathcal{C}L$ -tableaux. More specifically, if applying a $\mathcal{C}L$ -tableau rule to X gives denominators Y_1, \ldots, Y_k , then applying that rule to $\operatorname{\mathsf{compact}}(X)$ gives denominators Z_1, \ldots, Z_k such that $\operatorname{\mathsf{compact}}(Z_i) = \operatorname{\mathsf{compact}}(Y_i)$ for $1 \leq i \leq k$. In particular, "compacting" preserves $\mathcal{C}L$ -consistency and $\mathcal{C}L$ -inconsistency.

For $t \in \mathcal{EI}(L)$ and $\langle t \rangle \varphi \in X$, define

$$\mathsf{trans}_4(X,\langle t\rangle\varphi)=\mathsf{trans}(X,t)\cup\{\psi,[t]\psi\mid [t]\psi\in X\}\cup\{\varphi\}.$$

For $t \in \mathcal{EI}(L)$, define

$$\begin{aligned} \mathsf{core}_{5}(X,t) &= \{ [t]\varphi \mid [t]\varphi \in X \} \cup \{ \langle t \rangle \varphi \mid \langle t \rangle \varphi \in X \} \cup \\ &\{ [A_{s},Q]\varphi \mid \exists \alpha,Q'.[A_{s},Q']\varphi \in X \text{ and } Q = \widetilde{\delta_{s}}(I_{s},\alpha t) \subseteq Q' \}. \end{aligned}$$

As shown in the next lemma, $\mathsf{core}_5(X,t)$ can be treated as the subset of X consisting of formulae that are preserved when travelling through edges of R_t , including edges forced by the euclidean frame restriction.

Lemma 6. Let X be a CL-saturation of some formula set and Y be a CL-saturation of trans₄ $(X, \langle t \rangle \varphi)$ for some $\langle t \rangle \varphi \in X$ with $t \in \mathcal{EI}(L)$. Then $\mathsf{core}_5(X, t) \subseteq \mathsf{core}_5(Y, t)$.

Proof. Due to the static rule (5), it suffices to show that if $[A_s,Q]\xi\in\mathsf{core}_5(X,t)$ then $[A_s,Q]\xi\in\mathsf{core}_5(Y,t)$. Suppose that $[A_s,Q]\xi\in\mathsf{core}_5(X,t)$. Thus, there exist α and Q' s.t. $Q=\widetilde{\delta_s}(I_s,\alpha t)\subseteq Q'$ and $[A_s,Q']\varphi\in X$. By definition of the set trans₄, there exists $[A_s,Q'']\varphi\in Y$ s.t. $\delta_s(Q',t)\subseteq Q''$. It follows that $\widetilde{\delta_s}(I_s,\alpha tt)\subseteq Q''$. By Lemma 2, $\widetilde{\delta_s}(I_s,\alpha t)=\widetilde{\delta_s}(I_s,\alpha t)$, hence $[A_s,Q]\xi\in\mathsf{core}_5(Y,t)$.

A $\mathcal{C}L$ -consistent set X is $\mathsf{core}_5(t)$ -saturated if for every $\langle t \rangle \varphi \in X$ and every $\mathcal{C}L$ -saturation Y of $\mathsf{trans}_4(X, \langle t \rangle \varphi)$ we have $\mathsf{core}_5(Y, t) = \mathsf{core}_5(X, t)$.

Algorithm 1 given below constructs a consistent saturated L-model graph for a finite $\mathcal{C}L$ -consistent set X. In this algorithm, for each $t \in \mathcal{EI}(L)$: we find a $\mathsf{core}_5(t)$ -saturated set U which is obtainable from H(w) by applications of static $\mathcal{C}L$ -rules and rule (trans_4) with the principal formula of the form $\langle t \rangle \psi$; we then create successors of w via R'_t to satisfy $\langle t \rangle$ -formulae using $\mathsf{core}_5(U,t)$ as the content of w. But we do this in two different ways depending upon whether w has an R'_t -predecessor at this iteration. The intuitions for this dichotomy are based on the following insight from [8, Fig. 13] and [8, Pages 334-335]: the logic KD45 is sound and complete w.r.t. the class of finite frames where each frame consists

of a root which sees a possibly empty but finite strongly-connected-component or cluster.

To prove correctness of Algorithm 1, we use a data structure denoted by core_5^* to store $\mathsf{core}_5(U,t)$ in $\mathsf{core}_5^*(w,t)$. Note that core_5 is a function, while core_5^* is a table. In the algorithm, the worlds of the constructed model graph are marked either as $\mathit{unresolved}$ or as $\mathit{resolved}$.

Algorithm 1

Input: a finite $\mathcal{C}L$ -consistent set X of primitive language formulae. Output: an L-model graph $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, H \rangle$ of X.

- 1. Let $W = \{\tau\}$ and $R'_t = \emptyset$ for all $t \in \mathcal{MOD}$. Let Y be a $\mathcal{C}L$ -saturation of X and let $H(\tau) = \mathsf{compact}(Y)$. Mark τ as unresolved.
- 2. While there are unresolved worlds, take one, say w, and do:
 - (a) For every formula $\langle t \rangle \varphi$ in H(w) with $t \notin \mathcal{EI}(L)$:
 - i. Let $U = \mathsf{trans}(H(w), t) \cup \{\varphi\}$ be the result of applying rule (trans) to H(w), let Y be a $\mathcal{C}L$ -saturation of U, and let $Z = \mathsf{compact}(Y)$.
 - ii. If $\exists u \in W$ on the path from the root to w with H(u) = Z, then add the pair (w, u) to R'_t . Otherwise, add a new world u with content Z to W, mark it as unresolved, and add the pair (w, u) to R'_t .
 - (b) For every $t \in \mathcal{EI}(L)$ such that $R'_t(v, w)$ does not hold for any v:
 - i. Let U be a $\mathcal{C}L$ -saturation of trans₄ $(H(w), \langle t \rangle \top)$.
 - ii. While there exist $\langle t \rangle \varphi \in U$ and a $\mathcal{C}L$ -saturation V of $\mathsf{trans_4}(U, \langle t \rangle \varphi)$ such that $\mathsf{core_5}(U,t) \subset \mathsf{core_5}(V,t)$, let U=V.
 - iii. Let $core_5^*(w, t) = core_5(U, t)$.
 - iv. For every $\langle t \rangle \varphi \in \mathsf{core}_5^*(w,t)$: Let Y be a $\mathcal{C}L$ -saturation of $\mathsf{trans}_4(\mathsf{core}_5^*(w,t), \langle t \rangle \varphi)$, let $Z = \mathsf{compact}(Y)$, and do the same as Step 2(a)ii.
 - (c) For every $t \in \mathcal{EI}(L)$ such that $R'_t(v, w)$ holds for some v: Let $\mathsf{core}_5^*(w, t) = \mathsf{core}_5(H(w), t)$.
 - (d) Mark w as resolved.
- 3. Let $(R_t)_{t \in \mathcal{MOD}}$ be the least extension of $(R'_t)_{t \in \mathcal{MOD}}$ for $t \in \mathcal{MOD}$ such that $\langle W, \tau, (R_t)_{t \in \mathcal{MOD}} \rangle$ is an *L*-frame (note that the seriality conditions are cared by the tableau rule (D) and need not to be considered here).

This algorithm always terminates: eventually, for every w, either w contains no $\langle t \rangle$ -formulae, or there exists an ancestor with H(u) = Z at Step 2(a)ii because all $\mathcal{C}L$ -saturated sets are drawn from the finite and fixed set $X_{\mathcal{C}L}^*$.

4.3 Completeness Proof

Lemma 7. The following assertions are invariants during execution of Step 3 of Algorithm 1 (when $(R'_t)_{t \in \mathcal{MOD}}$) are extended to $(R_t)_{t \in \mathcal{MOD}}$).

- 1. If $R_t(w, u)$ holds and $t \in \mathcal{EI}(L)$ then $\mathsf{core}_5^*(w, t) = \mathsf{core}_5^*(u, t) = \mathsf{core}_5(H(u), t)$.
- 2. If $R_t(w,u)$ holds then for every formula $[A_s,Q]\varphi \in H(w)$, there exists $[A_s,Q']\varphi \in H(u)$ such that $\mathcal{L}(A_s,\delta_s(Q,t)) \subseteq \mathcal{L}(A_s,Q')$.

Proof. We first prove that if $t \in \mathcal{EI}(L)$ then the first assertion implies the second one. Hence, we need to prove the second assertion only for the case $t \notin \mathcal{EI}(L)$.

Suppose $t \in \mathcal{EI}(L)$, that the first assertion holds, and $[A_s,Q]\varphi \in H(w)$. Hence there exist words α_1,\ldots,α_k such that $Q=\widetilde{\delta_s}(I_s,\alpha_1)\cup\ldots\cup\widetilde{\delta_s}(I_s,\alpha_k)$. By the computation of $\mathsf{core}_5^*(w,t)$, we have $[A_s,\widetilde{\delta_s}(I_s,\alpha_i t)]\varphi \in \mathsf{core}_5^*(w,t)$, for $1 \leq i \leq k$. Hence $[A_s,\widetilde{\delta_s}(I_s,\alpha_i t)]\varphi \in \mathsf{core}_5(H(u),t)$ for every $1 \leq i \leq k$. It follows that there exists $[A_s,Q']\varphi \in H(u)$ such that $\delta_s(Q,t)\subseteq Q'$, and thus $\mathcal{L}(A_s,\delta_s(Q,t))\subseteq\mathcal{L}(A_s,Q')$.

We prove the assertions of the lemma by induction on the number of steps executed when extending R'_t for $t \in \mathcal{MOD}$ to R_t .

Consider the base case, when $R'_t(w,u)$ holds. For the first assertion, assume that $t \in \mathcal{EI}(L)$. Hence u must have been created from w via Step 2b. We have that $\mathsf{core}_5^*(w,t) = \mathsf{core}_5(H(u),t)$, because $\mathsf{core}_5^*(w,t)$ is $\mathsf{core}_5(t)$ -saturated and u is created from w via R'_t using $\mathsf{core}_5^*(w,t)$ as the content of w. When u is resolved, we have that $\mathsf{core}_5^*(u,t) = \mathsf{core}_5(H(u),t)$ due to Step 2c. Hence the first assertion holds. The second assertion clearly holds for the case $t \notin \mathcal{EI}(L)$.

Consider the inductive step for the first assertion. If $R_t(w,u)$ is created from $R_t(w,v)$ and $R_t(v,u)$ then, by the inductive assumption, $\operatorname{core}_5^*(w,t) = \operatorname{core}_5^*(v,t)$ and $\operatorname{core}_5^*(v,t) = \operatorname{core}_5^*(u,t) = \operatorname{core}_5(H(u),t)$, which imply the first assertion. If $R_t(w,u)$ is created from $R_t(v,w)$ and $R_t(v,u)$ then, by the inductive assumption, $\operatorname{core}_5^*(v,t) = \operatorname{core}_5^*(w,t)$ and $\operatorname{core}_5^*(v,t) = \operatorname{core}_5(H(u),t)$, which imply the first assertion.

Consider the inductive step for the second assertion and the case when $t \notin \mathcal{EI}(L)$. Suppose that $R_t(w,u)$ is created from edges $R_{s_i}(w_{i-1},w_i)$ with $1 \leq i \leq k, \ w = w_0, \ u = w_k$, due to an inclusion $R_{s_1} \circ \ldots \circ R_{s_k} \subseteq R_t$. Let $[A_s,Q]\varphi \in H(w)$. By Lemma 2(1), $\mathcal{L}(A_s,\delta_s(Q,t)) \subseteq \mathcal{L}(A_s,\widetilde{\delta_s}(Q,s_1\ldots s_k))$. Let $Q_0 = Q$. For $i=1,\ldots,k$, by the inductive assumption, there exists $[A_s,Q_i]\varphi \in H(w_i)$ such that $\mathcal{L}(A_s,\delta_s(Q_{i-1},s_i)) \subseteq \mathcal{L}(A_s,Q_i)$. For $i=2\ldots k$, by Lemma 2(3), $\mathcal{L}(A_s,\widetilde{\delta_s}(Q,s_1\ldots s_i)) \subseteq \mathcal{L}(A_s,Q_i)$ since $\mathcal{L}(A_s,\widetilde{\delta_s}(Q,s_1\ldots s_{i-1})) \subseteq \mathcal{L}(A_s,Q_{i-1})$ and $\widetilde{\delta_s}(Q,s_1\ldots s_i) = \delta_s(\widetilde{\delta_s}(Q,s_1\ldots s_{i-1}),s_i)$. Hence $\mathcal{L}(A_s,\widetilde{\delta_s}(Q,s_1\ldots s_k)) \subseteq \mathcal{L}(A_s,Q_k)$. It follows that $\mathcal{L}(A_s,\delta_s(Q,t)) \subseteq \mathcal{L}(A_s,Q_k)$. Choose $Q'=Q_k$.

Lemma 8. Let X be a finite $\mathcal{C}L$ -consistent set of formulae in the primitive language and $M = \langle W, \tau, (R_t)_{t \in \mathcal{MOD}}, H \rangle$ be the model graph for X constructed by Algorithm 1. Then M is a consistent saturated L-model graph satisfying X.

Proof. It is clear that M is an L-model graph and for any $w \in W$, the set H(w) is $\mathcal{C}L$ -consistent. We want to show that M is a saturated model graph. It suffices to show that:

- 1. For all $w, u \in W$, if $[t]\varphi \in H(w)$ and $R_t(w, u)$ holds then $\varphi \in H(u)$.
- 2. For every $w \in W$, if $\langle t \rangle \varphi \in H(w)$ and $t \in \mathcal{EI}(L)$ then there exists $u \in W$ such that $R_t(w, u)$ holds and $\varphi \in H(u)$.

For the first assertion, suppose $[t]\varphi \in H(w)$ and $R_t(w, u)$ holds.

Case $t \notin \mathcal{EI}(L)$: Since $[t]\varphi \in H(w)$, there exists $[A_t,Q]\varphi \in H(w)$ with $Q \supseteq I_t$. By Lemma 7, there exists $[A_t,Q']\varphi \in H(u)$ such that $\mathcal{L}(A_t,\delta_t(I_t,t)) \subseteq \mathcal{L}(A_t,Q')$. Since $t \in \mathcal{L}(A_t)$, we have that $\varepsilon \in \mathcal{L}(A_t,\delta_t(I_t,t))$. Hence $\varepsilon \in \mathcal{L}(A_t,Q')$, which means $Q' \cap F_t \neq \emptyset$. Since $[A_t,Q']\varphi \in H(u)$, it follows that $\varphi \in H(u)$ by rule (add).

Case $t \in \mathcal{EI}(L)$: Since $[t]\varphi \in H(w)$, we have that $[t]\varphi \in \mathsf{core}_5^*(w,t)$. Since $R_t(w,u)$ holds, there exists v such that $R_t'(v,u)$ holds. By Lemma 7, $\mathsf{core}_5^*(w,t) = \mathsf{core}_5^*(u,t) = \mathsf{core}_5^*(v,t)$. Hence $[t]\varphi \in \mathsf{core}_5^*(v,t)$. Since $R_t'(v,u)$ holds, it follows that $\varphi \in H(u)$.

We now prove the second assertion. Suppose $\langle t \rangle \varphi \in H(w)$ and $t \in \mathcal{EI}(L)$. If $R'_t(v,w)$ does not hold for any v when w is resolved then w is connected via R'_t to a world u with $\varphi \in H(u)$ at Step 2b since $\langle t \rangle \varphi \in \mathsf{core}_5^*(w,t)$. Alternatively, suppose $R'_t(v,w)$ does hold for some v when w is resolved (at Step 2c). Since $\langle t \rangle \varphi \in H(w)$, we have $\langle t \rangle \varphi \in \mathsf{core}_5(H(w),t) = \mathsf{core}_5^*(v,t)$ by Lemma 7. Now v must have been considered at Step 2b in a previous iteration since this is the only way that an edge like $R'_t(v,w)$ is created. Since $\langle t \rangle \varphi \in \mathsf{core}_5^*(v,t)$, this iteration must also create a world u with $R'_t(v,u)$ such that $\varphi \in H(u)$. Then $R_t(w,u)$ must hold after Step 3 by euclideaness.

Theorem 1. The calculus CL for BReg logics is sound and complete.

This theorem immediately follows from Lemmas 3 and 8.

We use Algorithm 1 only to prove completeness of the calculus $\mathcal{C}L$ for a $\mathcal{BR}eg$ logic L. It assumes that the input set X is $\mathcal{C}L$ -consistent and is inefficient due to the naive computation of saturations and the limited caching. In the next section, we present Algorithm 2 with global caching for checking $\mathcal{C}L$ -consistency of formula sets. Since the calculus $\mathcal{C}L$ is sound and complete, $\mathcal{C}L$ -consistency coincides with L-satisfiability. Algorithm 2 explores the search space by building an and-or graph using the tableau rules of $\mathcal{C}L$. The content (label) of a node in the graph is a formula set in the compact form. Global caching means that for each possible content, at most one node with that content in the search space is expanded, and such an expansion is done at most once for that content. Global caching is one of the most useful optimisations for tableau decision procedures for modal logics [22]. Due to global caching and the compact form of nodes, Algorithm 2 has the optimal EXPTime complexity.

5 An EXPTime Decision Procedure with Global Caching for *BReg* Logics

In this section L denotes an $\mathcal{BR}eg$ logic. In Figure 2 we give an algorithm for checking $\mathcal{C}L$ -consistency which creates an and-or graph using the tableau rules of $\mathcal{C}L$ and global caching. A node in the constructed graph is a record with three attributes:

content: the formula set carried by the node

```
status: \{unexpanded, expanded, cons, incons\}
kind: \{and-node, or-node\}
```

To check whether a given finite formula set X is $\mathcal{C}L$ -consistent, the initial node τ has content X and status unexpanded. The main while-loop continues processing nodes until the status of τ is determined to be in $\{\text{cons}, \text{incons}\}$, or until every node is expanded, whichever happens first.

The algorithm gives a preference to the rule (\bot) , then any one of the static unary rules, then the static binary rule (\lor) . If none of these are applicable, then it applies the transitional rules simultaneously. When a rule is applied, the algorithm categorises the numerator as either an or-node or an and-node with an

Algorithm 2

Input: a finite set X of primitive language formulae and an $\mathcal{BR}eg$ logic L with finite automata $(A_t)_{t \in \mathcal{MOD} \setminus \mathcal{EI}(L)}$ specifying the extended grammar eRG(L)

Output: an and-or graph $G = \langle V, E \rangle$ with $\tau \in V$ as the initial node such that $\tau.status = \mathbf{cons}$ iff X is $\mathcal{C}L$ -consistent

Remark: We use "rule" to refer to a CL-tableau rule.

- 1. create a new node τ with τ .content := X and τ .status := unexpanded; let $V := \{\tau\}$ and $E := \emptyset$;
- 2. while $\tau.status \notin \{ cons, incons \}$ and we can choose an unexpanded node $v \in V$ do:
 - (a) $\mathcal{D} := \emptyset$;
 - (b) if no rule is applicable to v.content then v.status := cons
 - (c) else if the rule (\bot) is applicable to v.content then v.status := incons
 - (d) else if some static rule with only one denominator is applicable to v.content giving denominator Y then $v.kind := \mathtt{and-node}, \, \mathcal{D} := \{Y\}$
 - (e) else if the rule (\vee) is applicable to v.content giving denominators Y_1 and Y_2 (both different from v.content) then v.kind := or-node, $\mathcal{D} := \{Y_1, Y_2\}$
 - (f) else
 - i. v.kind := and-node,
 - ii. for every transitional rule applicable to v.content and for every possible application of the rule to v.content giving denominator Y, add Y to \mathcal{D} ;
 - (g) for every denominator $Y \in \mathcal{D}$ do
 - i. let $Z = \mathsf{compact}(Y)$,
 - ii. if some $w \in V$ has w.content = Z then add edge (v, w) to E
 - iii. else let w be a new node, set w.content := Z, w.status := unexpanded, add w to V, and add edge (v, w) to E;
 - (h) if (v.kind = or-node and one of the successors of v has status cons) or (v.kind = and-node and all the successors of v have status cons) then $v.status := \text{cons}, \ propagate(G, v)$
 - (i) else if (v.kind = and-node and one of the successors of v has status incons) or (v.kind = or-node and all the successors of v have status incons) then $v.status := \text{incons}, \ propagate(G, v)$
 - (j) else v.status := expanded;
- 3. if $\tau.status \notin \{cons, incons\}$ then

for every node $v \in V$ with $v.status \neq incons$, set v.status := cons;

Fig. 2. Checking CL-Consistency Using Global Caching

```
Procedure propagate(G, v)
Parameters: an and-or graph G = \langle V, E \rangle and v \in V with v.status \in \{ cons, incons \}
Returns: a modified and-or graph G = \langle V, E \rangle

1. queue := \{v\};
2. while queue is not empty do
3. (a) extract x from queue;
(b) for every u \in V with (u, x) \in E and u.status = expanded do
i. if (u.kind = or-node and one of the successors of u has status cons) or (u.kind = and-node and all the successors of u have status cons) then u.status := cons, queue := queue \cup \{u\}
ii. else if (u.kind = and-node and one of the successors of u has status incons) or (u.kind = or-node and all the successors of u have status incons) then u.status := incons, queue := queue \cup \{u\};
```

Fig. 3. Propagating Consistency and Inconsistency Through an And-Or Graph

or-node being inconsistent if every child is inconsistent and an and-node being inconsistent if at least one child is inconsistent.

The main difference with traditional methods appears at Step 2g: here, for every denominator, we first check whether an already existing node can act as a proxy for that denominator. If so, then we do not create that denominator, but merely insert an edge from the numerator to the existing proxy.

If these steps cannot determine the status of v as cons or incons, then its status is set to expanded. But if these steps do determine the status of a node v to be cons or incons, this information is itself propagated to the predecessors of v in the and-or graph G via the routine propagate(G, v), explained shortly.

The main loop ends when the status of the initial node τ becomes cons or incons or all nodes of the graph have been expanded. In the latter case, all nodes with status \neq incons are given status cons (effectively giving the status open to tableau branches which loop).

The procedure *propagate* used in the above algorithm is specified in Figure 3. As parameters, it accepts an and-or graph G and a node v with (irrevocable) status cons or incons. The purpose is to propagate the status of v through the and-or graph and alter G to reflect the new information.

Initially, the queue contains only v. While the queue is not empty: a node x is extracted; the status of x is propagated to each predecessor u of x in an appropriate way; and if the status of u becomes (irrevocably) cons or incons then u is inserted into the queue for further propagation.

This construction thus uses both caching and propagation techniques.

Lemma 9. It is an invariant of Algorithm 2 that for every $v \in V$:

```
    if v.status = incons then
    the (⊥)-rule of CL is applicable to v.content,
    or v.kind = and-node and there exists (v, w) ∈ E such that w ≠ v and w.status = incons,
```

- or v.kind = or-node and for every $(v, w) \in E$, w.status = incons;
- 2. if v.status = cons then
 - no rule of CL is applicable to v.content,
 - or v.kind = or-node and there exists $(v, w) \in E$ with w.status = cons,
 - or v.kind = and-node and for every $(v, w) \in E$, w.status = cons.

(Since a static rule is applied to X only when X is not closed w.r.t. the rule, if v.kind = or-node and $(v, w) \in E$ then $w \neq v$ since $w.content \neq v.content$.)

Proof. Lemma 9(1) clearly holds since these are the only three ways for a node to get status incons. For Lemma 9(2) there is the possibility that the node gets status cons via Step 3 of Algorithm 2.

For a contradiction, assume that v.status becomes cons because of Step 3 of Algorithm 2 and that all three clauses of the "then" part of Lemma 9(2) fail:

- 1. First, the rule assumed to be applicable to v.content cannot be the (\perp)-rule as this would have put $v.status = \mathtt{incons}$, contradicting our assumption that $v.status = \mathtt{cons}$. Hence $v.kind = \mathtt{or-node}$ or $v.kind = \mathtt{and-node}$ after this rule application.
- 2. Second, if v.kind = or-node then v must have two successors created by the rule (V). If none of the successors has status cons then they must all have status incons. But Algorithm 2 and procedure propagate always ensure that incons is propagated whenever it is found. As soon as the incons status of the lattest of the children is found, the ensuing call to propagate would have ensured that v.status = incons, contradicting our assumption that v.status = cons.
- 3. Third, if v.kind = and-node then v has at least one successor w (say) with $(v, w) \in E$. If $w.status \neq \text{cons}$, then we must have w.status = incons. Again, when w gets status incons, procedure propagate would ensure that v.status = incons too, contradicting our assumption that v.status = cons.

Lemma 10. Let $G = \langle V, E \rangle$ be the graph constructed by Algorithm 2 for X using CL. If τ status = incons then X is CL-inconsistent.

Proof. Using Lemma 9, we can construct a closed CL-tableau for X by induction on the way a node depends on its successors and by copying nodes so that the resulting structure is a (tree) tableau rather than a graph.

Let $G = \langle V, E \rangle$ be the graph constructed by Algorithm 2 for X using $\mathcal{C}L$. For $v \in V$ with $v.status = \mathsf{cons}$, we say that $v_0 = v, v_1, \ldots, v_k$ with $k \geq 0$ is a saturation path of v in G if for each $1 \leq i \leq k$, we have $v_i.status = \mathsf{cons}$, the edge $E(v_{i-1}, v_i)$ was created by an application of a static rule, and $v_k.content$ is closed w.r.t. the static rules. Observe that if v_0, \ldots, v_k is a saturation path of v_0 in G then $v_0.content \subseteq \ldots \subseteq v_k.content$. By Lemma 9, if $v.status = \mathsf{cons}$ then there exists a saturation path of v in G.

Lemma 11. Let $G = \langle V, E \rangle$ be the graph constructed by Algorithm 2 for X using CL. If τ .status = cons then every CL-tableau for X is open.

Proof. Let T be an arbitrary $\mathcal{C}L$ -tableau for X. We maintain a current node cn of T that will follow edges of T to pin-point an open branch of T. Initially we set cn to be the root of T. We also keep a (finite) saturation path σ of the form $\sigma_0, \ldots, \sigma_k$ for some $\sigma_0 \in V$ and call σ the current saturation path in G. At the beginning, set $\sigma_0 := \tau$ and let σ be a saturation path for σ_0 in G: such a saturation path exists since τ -status = cons. We maintain the invariant cn-content $\subseteq \sigma_k$ -content, where cn-content is the set carried by cn.

Remark 1. By the definition of saturation path, $\sigma_k.status = cons$. The invariant thus implies that the (\bot) -rule is not applicable to cn.

Clearly, the invariant holds at the beginning since $\sigma_0 = \tau$ and $\tau.content = cn.content$ and $\sigma_0.content \subseteq \sigma_k.content$. Depending upon the rule applied to cn in the tableau T, we maintain the invariant by changing the value of the current node cn of T and possibly also the current saturation path σ in G:

- 1. Case the tableau rule applied to cn is a static rule. Since $cn.content \subseteq \sigma_k.content$ and $\sigma_k.content$ is closed w.r.t. the static rules, cn has a successor u in T with $u.content \subseteq \sigma_k.content$. By setting cn := u, the invariant is maintained without changing σ .
- 2. Case the tableau rule applied to cn is a transitional rule and the successor is $u \in T$. By the invariant, the rule can be applied to $\sigma_k.content$ in the same way, creating a successor node $w \in V$ with $w.content \supseteq u.content$. Moreover, σ_k is an and-node with $\sigma_k.status = cons$, hence $w.status \neq incons$, meaning that w.status = cons. Setting cn := u and setting σ to be a saturation path of w in G maintains the invariant.

By Remark 1, the branch formed by the instances of cn is an open branch of T.

Theorem 2. Let L be an $\mathcal{BR}eg$ logic whose extended grammar is specified by finite automata $(A_t)_{t \in \mathcal{MOD} \setminus \mathcal{EI}(L)}$, X a finite set of primitive language formulae, and $G = \langle V, E \rangle$ the graph constructed by Algorithm 2 for X using \mathcal{CL} , with $\tau \in V$ as the initial node. Then X is \mathcal{CL} -consistent iff τ -status = cons.

This theorem immediately follows from Lemmas 10 and 11.

Corollary 1. Algorithm 2 is an EXPTime decision procedure for $\mathcal{BR}eg$ logics.

Proof. Let L be an $\mathcal{BR}eg$ logic and X a finite formula set in the primitive language. Since $\mathcal{C}L$ is sound and complete (Theorem 1), X is L-satisfiable iff X is $\mathcal{C}L$ -consistent, and iff the execution of Algorithm 2 for X and L returns a graph with τ -status = cons (by Theorem 2).

Let n be the sum of the sizes of the formulae in X and the sizes of the automata specifying eRG(L). Assume that $n > |\mathcal{MOD}|$. There are at most n subformulae of X since X contains no automaton-modal operators, and there are at most $2^{O(n)}$ different automaton-modal operators (recall that an automaton-modal operator is of the form $[A_t, Q]$ with $t \in \mathcal{MOD}$ and $Q \subseteq Q_t$, where $|\mathcal{MOD}| < n$ and $|Q_t| < n$).

Due to the compact form, for each subformula $[t]\varphi$ of X, a node contains at most one formula of the form $[A_t,Q]\varphi$. Thus, counting formulae generated by rule (5), a node contains at most 3n i.e. O(n) formulae. Hence there are at most $(2^{O(n)})^{O(n)} = 2^{O(n^2)}$ different node contents. Due to global caching, each node in the constructed and-or graph has a unique content, so the graph has at most $2^{O(n^2)}$ nodes.

Every $v \in V$ is expanded (by Steps (2a)–(2j)) only once and such a task takes $2^{O(n^2)}$ time units without counting the execution time of the procedure propagate. When v.status becomes cons or incons, the procedure propagate executes $2^{O(n^2)}$ basic steps directly involved with v. Hence the total time of the executions of propagate is of rank $2^{O(n^2)}$. The time complexity of Algorithm 2 is therefore of rank $2^{O(n^2)}$.

6 Conclusions

We have given an analytic cut-free tableau calculus for a large class $\mathcal{BR}eg$ of epistemic logics for reasoning about agent beliefs. As demonstrated for the wise men puzzle and its modified version, $\mathcal{BR}eg$ logics are very useful for reasoning about mutual beliefs of agents. The class $\mathcal{BR}eg$ essentially extends the class of regular modal logics by allowing axioms (D) and (5) which are useful and sometimes necessary for practical applications.

Our tableau calculus for $\mathcal{BR}eg$ seems a simple extension of our tableau calculus for regular modal logics [9] using standard tableau rules to deal with axioms (D) and (5). Note, however, that non-trivial complications of the extension w.r.t. [9] lie in the use of finite automata specifying the extended grammar eRG(L) instead of RG(L) and the way of combining "regularity" of the used logic with axiom (5).

Applying global caching to our calculus, we obtain the first optimal (EXP-Time) tableau decision procedure for $\mathcal{BR}eg$, which does not use cut rules. Furthermore, it is easy to show that most of the well-known optimisation techniques for tableau decision procedures (as discussed in [12, 22]) are applicable to this decision procedure.

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 $^{^{9}}$ We are not aware of other tableau decision procedures for $\mathcal{BR}eg$.

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